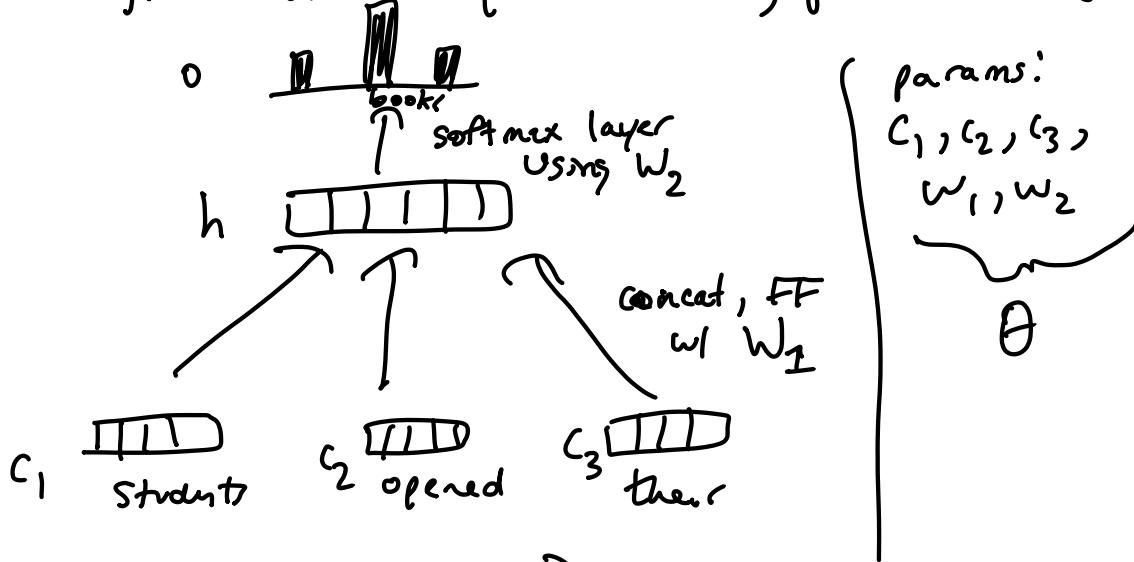


Today: gradient descent \Rightarrow cross-entropy loss
backpropagation

- \hookrightarrow FF / concat
- \hookrightarrow RNN (recurrent NN)

} single neuron

NLM: given "students opened their", predict "boots"



$$h = f(W_1 [c_1; c_2; c_3])$$

\hookrightarrow notation for concat

$$o = \text{softmax}(W_2 h)$$

how do we train this model?

- \hookrightarrow how do we adjust our model parameters θ to make better predictions of the next word?
- \hookrightarrow GRADIENT DESCENT

1. define **loss function** $L(\theta)$ that tells us how bad the model is currently doing at predicting the next word

- ↳ ideally smooth / differentiable
- ↳ cross-entropy loss

2. Given $L(\theta)$, we compute the **gradient** of L with respect to θ .

- ↳ gradient gives us the direction of steepest ascent of L

↳ same dimensionality as θ

- ↳ for each parameter j in θ , it tells you how much L would increase if you increase j by a very small amount

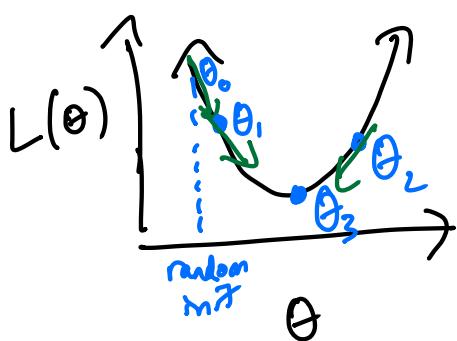
3. given gradient $\frac{dL}{d\theta}$, we take a step in the

direction of the negative gradient, thus

Minimizes L

→ learning rate,
controls step size

$$\theta_{\text{new}} = \theta_{\text{OLD}} - \eta \frac{dL}{d\theta} \quad \hookrightarrow \text{gradient}$$



- important hyperparameters:
- learning rate η
 - batch size : how many training examples do you use to estimate $\frac{dL}{d\theta}$ before taking a step

Simple example:



inputs: (x, y) e.g. $(5, 4.3)$

$$\left. \begin{array}{l} h = \tanh(w_1 x) \\ o = \tanh(w_2 h) \end{array} \right\}$$

1. compute loss fn

$$\left. \begin{array}{l} L = \frac{1}{2} (y - o)^2 \end{array} \right\} \begin{array}{l} \text{Square loss / L2 loss} \\ \text{good for regression problems} \end{array}$$

\hookrightarrow target model's prediction

2. compute gradient:

$$\frac{dL}{d\theta} : \frac{dL}{dw_1}, \frac{dL}{dw_2} \quad (2 \text{ params})$$

important: chain rule of calculus

$$\frac{d}{dx} g(f(x)) = \frac{dg}{df} \cdot \frac{df}{dx}$$

$$L = \frac{1}{2} (y - o)^2$$

$$o = \tanh(a)$$

$$a = w_2 h$$

$$h = \tanh(b)$$

$$b = w_1 x$$

let's make
intermediate vars
 $a = w_2 h, b = w_1 x$

$$\left. \begin{array}{l} \frac{d}{dx} \tanh(x) = \\ 1 - \tanh^2(x) \end{array} \right\}$$

$$\frac{dL}{dw_2} = \underbrace{\frac{dL}{do}}_{\downarrow} \cdot \underbrace{\frac{do}{da}}_{\downarrow} \cdot \underbrace{\frac{da}{dw_2}}_{\downarrow}$$

$$-(y - o) \cdot (1 - o^2) \cdot h$$

$$\frac{dL}{dw_1} = \underbrace{\frac{dL}{do} \cdot \frac{do}{da}}_{+} \cdot \underbrace{\frac{da}{dh} \cdot \frac{dh}{db}}_{+} \cdot \underbrace{\frac{db}{dw_1}}$$

backpropagation: chain rule of calculus +
Caching prev. computed derivatives

3. update params

$$\omega_{2,\text{new}} = \omega_{2,\text{old}} - \eta \frac{dL}{d\omega_2} \quad , \quad \omega_{1,\text{new}} = \omega_{1,\text{old}} - \eta \frac{dL}{d\omega_1}$$

What loss fn is used in LM?

↳ cross-entropy loss, generally useful for any classification task

Students opened their \Rightarrow books
input target, $|V|$ labels

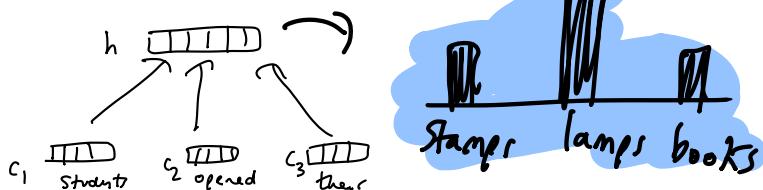
goal: maximize $\varphi(\text{books})$ "students opened their"

Minimize negative log probability of "books"

$$L = -\log(p(\text{books} | \text{"Students opened their }))$$

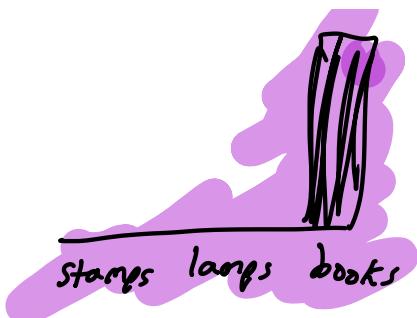
why "cross-entropy" loss?

model's predicted dist. q



data distribution P :

... students opened their



$$P(\text{books} \mid \dots) = 1.0$$

defn of cross entropy between p and q is:

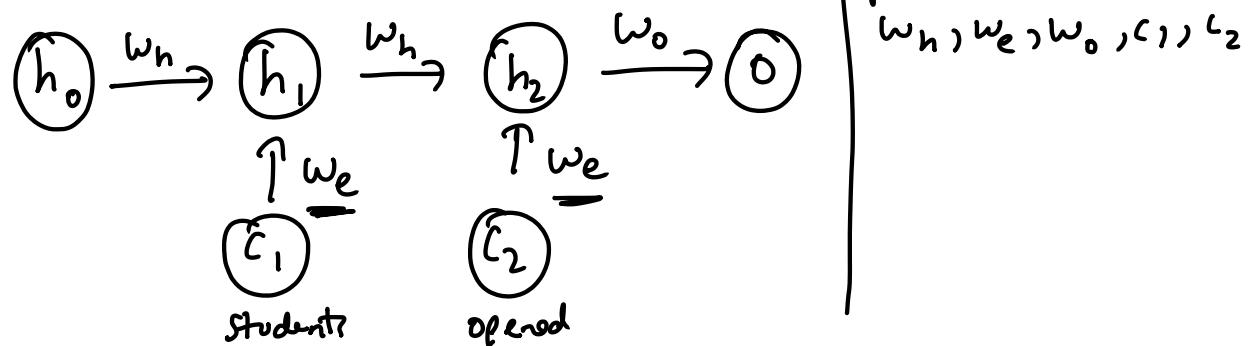
$$-\sum_{w \in V} p(w) \log q(w)$$

\hookrightarrow
1 when $w = \text{books}$
0 for every other w

$$= -\log q(\text{books} \mid \text{Students opened their})$$

neg. log prob of correct word

recurrent neural networks:



$$L = \frac{1}{2} (y - o)^2$$

$$o = w_o h_2$$

$$h_2 = \tanh(w_e c_2 + w_h h_1)$$

a

b

$$h_1 = \tanh(w_e c_1 + w_h h_0)$$

$$\frac{dL}{dw_0} = \frac{dL}{do} \cdot \frac{do}{d_{w_0}} = -(y - o) \cdot h_2$$

$$\frac{dL}{dc_2} = \frac{dL}{do} \cdot \frac{do}{dh_2} \cdot \frac{dh_2}{da} \cdot \frac{da}{dc_2} = -(y - o) \cdot w_0 \cdot (1 - h_2^2) \cdot w_e$$

$\frac{dL}{dw_e}$ and $\frac{dL}{dw_h}$ are trickier b/c they are used at multiple timesteps in the network

↳ backprop thru time allows us to compute these by summing contributions from diff. time steps

$$\begin{aligned} \frac{dL}{dw_e} &= \frac{dL}{do} \cdot \frac{do}{dh_2} \cdot \frac{dh_2}{da} \cdot \frac{da}{d_{w_e}} + \\ &\quad \left[\frac{dL}{do} \cdot \frac{do}{dh_2} \cdot \frac{dh_2}{da} \cdot \frac{da}{dh_1} \cdot \frac{dh_1}{db} \cdot \frac{db}{d_{w_e}} \right] \end{aligned}$$

We can accumulate these $\frac{dL}{d_{w_e}}$, $\frac{dL}{d_{w_h}}$ as we step back thru time

Vanishing gradient problem: these gradient contributions from faraway steps go to zero