

CMSC 132: Object-Oriented Programming II

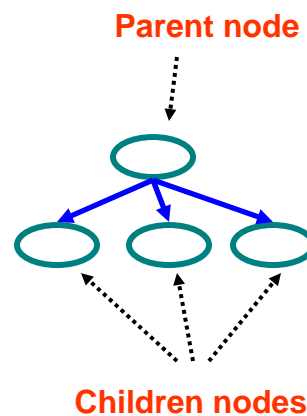


Trees & Binary Search Trees

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Trees

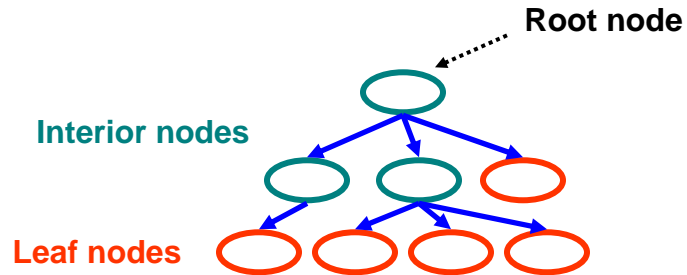
- Trees are hierarchical data structures
 - One-to-many relationship between elements
- Tree node / element
 - Contains data
 - Referred to by only 1 (**parent**) node
 - Contains links to any number of (**children**) nodes



Trees

■ Terminology

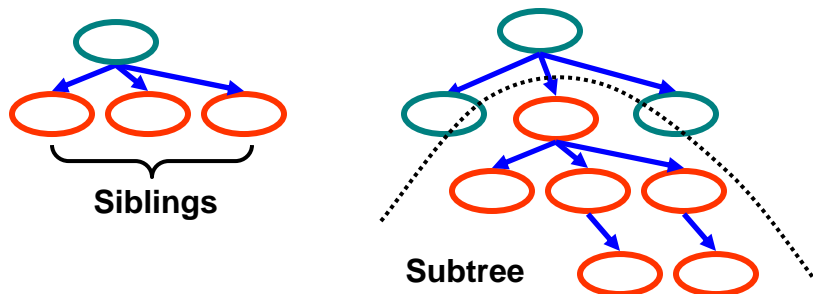
- Root \Rightarrow node with no parent
- Leaf \Rightarrow all nodes with no children
- Interior \Rightarrow all nodes with children



Trees

■ Terminology

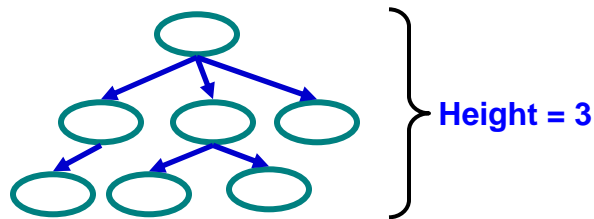
- Sibling \Rightarrow node with same parent
- Descendent \Rightarrow children nodes & their descendants
- Subtree \Rightarrow portion of tree that is a tree by itself
 \Rightarrow a node and its descendants



Trees

■ Terminology

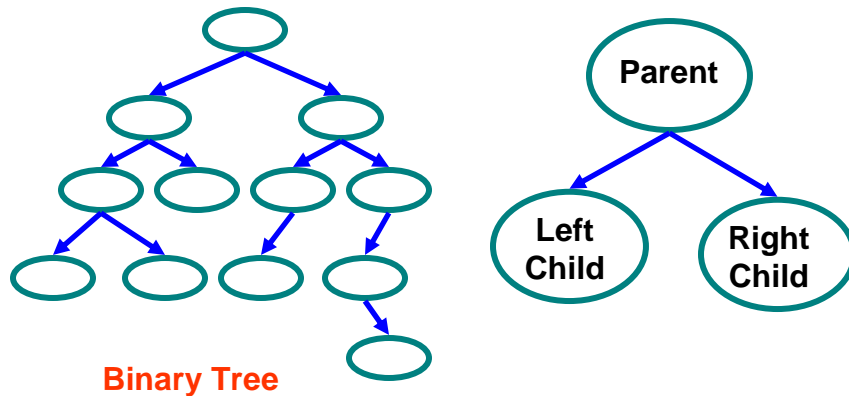
- Level \Rightarrow is a measure of a node's distance from root
- Definition of level
 - If node is the root of the tree, its level is 1
 - Else, the node's level is 1 + its parent's level
- Height (depth) \Rightarrow max level of any node in tree



Binary Trees

■ Binary tree

- Tree with 0–2 children per node
 - Left & right child / subtree



Tree Traversal

- Often we want to
 1. Find all nodes in tree
 2. Determine their relationship

- Can do this by
 1. Walking through the tree in a prescribed order
 2. Visiting the nodes as they are encountered

- Process is called **tree traversal**

Tree Traversal

- Goal
 - Visit every node in binary tree

- Approaches
 - Depth first
 - Preorder ⇒ parent before children
 - Inorder ⇒ left child, parent, right child
 - Postorder ⇒ children before parent
 - Breadth first ⇒ closer nodes first

Tree Traversal Methods

■ Pre-order

1. Visit **node** // first
2. Recursively visit left subtree
3. Recursively visit right subtree

■ In-order

1. Recursively visit left subtree
2. Visit **node** // second
3. Recursively right subtree

■ Post-order

1. Recursively visit left subtree
2. Recursively visit right subtree
3. Visit **node** // last

Tree Traversal Methods

■ Breadth-first

```
BFS(Node n) {  
    Queue Q = new Queue();  
    Q.enqueue(n);           // insert node into Q  
    while ( !Q.empty() ) {  
        n = Q.dequeue();    // remove next node  
        if ( !n.isEmpty() ) {  
            visit(n);       // visit node  
            Q.enqueue(n.Left()); // insert left subtree in Q  
            Q.enqueue(n.Right()); // insert right subtree in Q  
        }  
    }  
}
```

Tree Traversal Examples

■ Pre-order (prefix)

■ $+ \times 2 3 / 8 4$

■ In-order (infix)

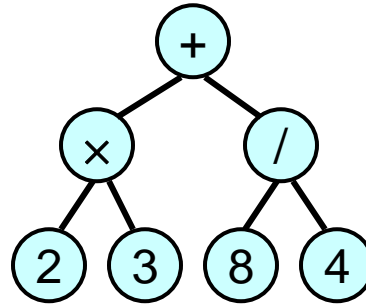
■ $2 \times 3 + 8 / 4$

■ Post-order (postfix)

■ $2 3 \times 8 4 / +$

■ Breadth-first

■ $+ \times / 2 3 8 4$



Expression tree

Tree Traversal Examples

■ Pre-order

■ 44, 17, 32, 78,
50, 48, 62, 88

■ In-order

■ 17, 32, 44, 48,
50, 62, 78, 88

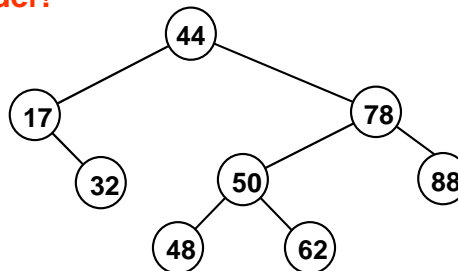
■ Post-order

■ 32, 17, 48, 62,
50, 88, 78, 44

■ Breadth-first

■ 44, 17, 78, 32,
50, 88, 48, 62

Sorted
order!

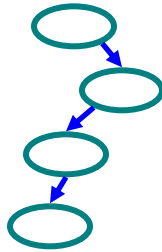


Binary search tree

Types of Binary Trees

■ Degenerate

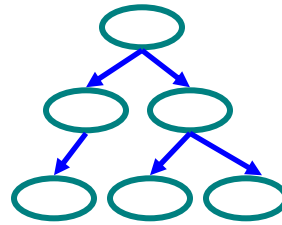
- Mostly 1 child / node
- Height = $O(n)$
- Similar to linear list



Degenerate
binary tree

■ Balanced

- Mostly 2 child / node
- Height = $O(\log(n))$
- Useful for searches



Balanced
binary tree

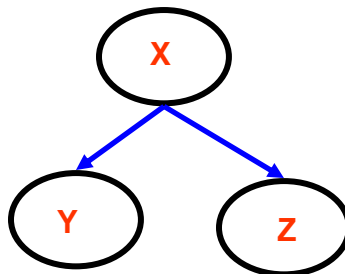
Binary Search Trees

■ Key property

- Value at node
 - Smaller values in left subtree
 - Larger values in right subtree

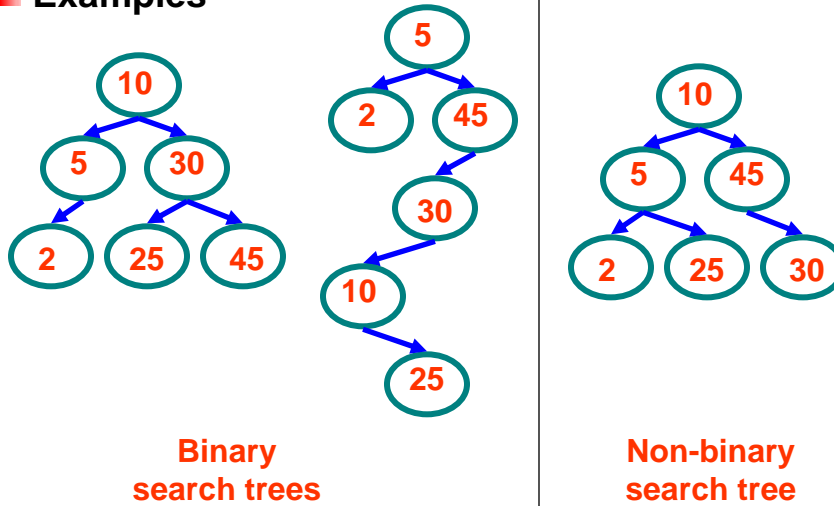
■ Example

- $X > Y$
- $X < Z$



Binary Search Trees

■ Examples



Binary Tree Implementation

```
Class Node {  
    Value data;  
    Node left, right; // null if empty  
  
    void insert ( Value data1 ) { ... }  
    void delete ( Value data2 ) { ... }  
    Node find ( Value data3 ) { ... }  
    ...  
}
```

Iterative Search of Binary Tree

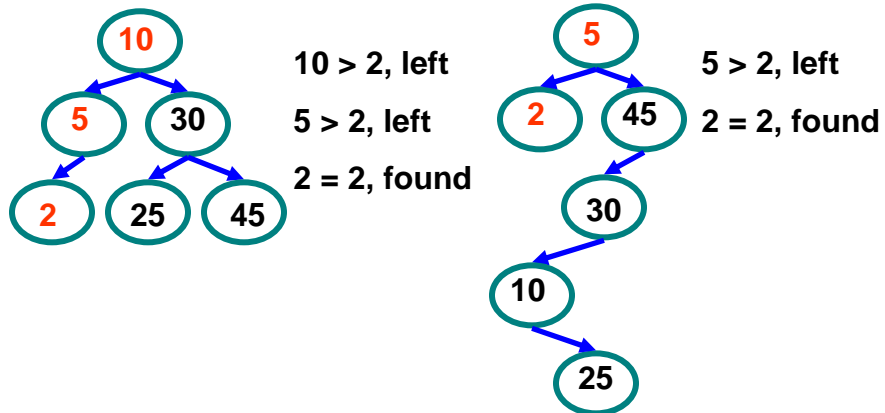
```
Node Find( Node n, Value key) {
    while (n != null) {
        if (n.data == key)    // Found it
            return n;
        if (n.data > key)    // In left subtree
            n = n.left;
        else                  // In right subtree
            n = n.right;
    }
    return null;
}
Find( root, keyValue );
```

Recursive Search of Binary Tree

```
Node Find( Node n, Value key) {
    if (n == null)          // Not found
        return( n );
    else if (n.data == key) // Found it
        return( n );
    else if (n.data > key)  // In left subtree
        return Find( n.left, key );
    else                    // In right subtree
        return Find( n.right, key );
}
Find( root, keyValue );
```

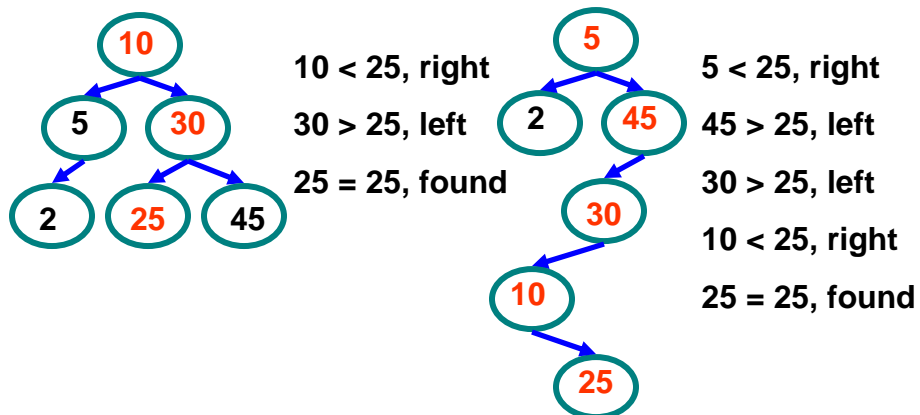
Example Binary Searches

■ Find (2)



Example Binary Searches

■ Find (25)



Binary Search Properties

- Time of search
 - Proportional to height of tree
 - Balanced binary tree
 - $O(\log(n))$ time
 - Degenerate tree
 - $O(n)$ time
 - Like searching linked list / unsorted array
- Requires
 - Ability to compare key values

Binary Search Tree Construction

- How to build & maintain binary trees?
 - Insertion
 - Deletion
- Maintain key property (invariant)
 - Smaller values in left subtree
 - Larger values in right subtree

Binary Search Tree – Insertion

■ Algorithm

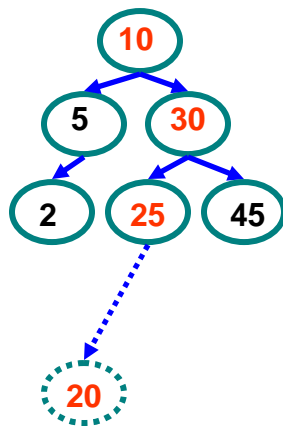
1. Perform search for value X
2. Search will end at node Y (if X not in tree)
3. If $X < Y$, insert new leaf X as new left subtree for Y
4. If $X > Y$, insert new leaf X as new right subtree for Y

■ Observations

- $O(\log(n))$ operation for balanced tree
- Insertions may unbalance tree

Example Insertion

■ Insert (20)



10 < 20, right

30 > 20, left

25 > 20, left

Insert 20 on left

Binary Search Tree – Deletion

■ Algorithm

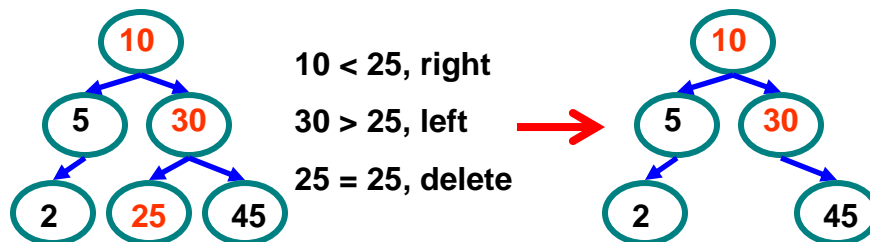
1. Perform search for value X
2. If X is a leaf, delete X
3. Else // must delete internal node
 - a) Replace with largest value Y on left subtree
OR smallest value Z on right subtree
 - b) Delete replacement value (Y or Z) from subtree

■ Observation

- $O(\log(n))$ operation for balanced tree
- Deletions may unbalance tree

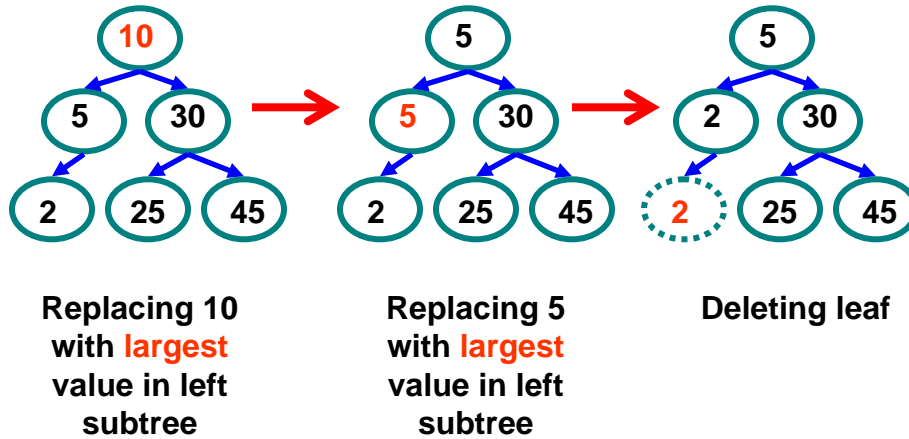
Example Deletion (Leaf)

■ Delete (25)



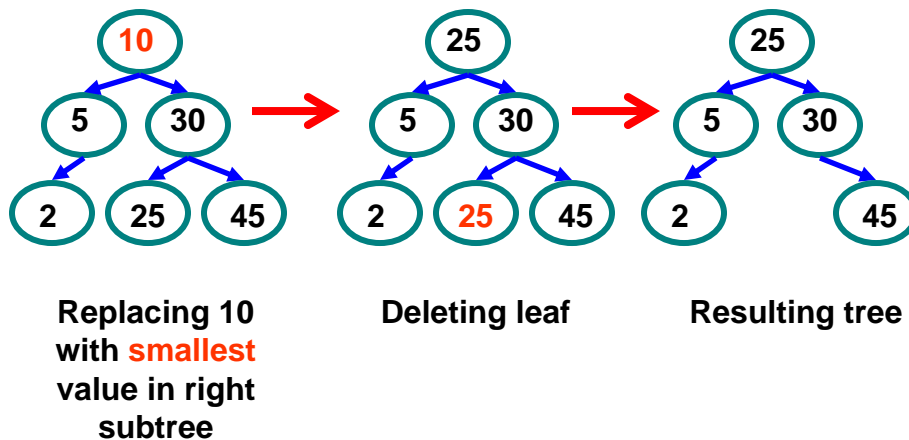
Example Deletion (Internal Node)

■ Delete (10)



Example Deletion (Internal Node)

■ Delete (10)



Building Maps w/ Search Trees

- Search trees often used to implement maps
 - Each non-empty node contains
 - Key
 - Value
 - Left and right child
- Need to be able to compare keys
 - Generic type `<K extends Comparable<K>>`
 - Denotes any type K that can be compared to K's

Polymorphic Binary Search Trees

- What do we mean by polymorphic?
- Implement two subtypes of Tree
 1. EmptyTree
 2. NonEmptyTree
- Use EmptyTree to represent the empty tree
 - Rather than null
- Invoke methods on tree nodes
 - Without checking for null
 - Get empty or nonempty functionality
 - Selected by type of tree node

Polymorphic Binary Tree Implement.

```
Interface Tree {  
    Tree insert ( Value data1 ) { ... }  
}  
Class EmptyTree implements Tree {  
    Tree insert ( Value data1 ) { ... }  
}  
Class NonEmptyTree implements Tree {  
    Value data;  
    Tree left, right; // Either Empty or NonEmpty  
    Tree insert ( Value data1 ) { ... }  
}
```