

**CMSC 631 – Program Analysis and Understanding  
Spring 2009**

Type Systems

## The Need for a Type System

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- Consider the (untyped) lambda calculus
  - false =  $\lambda x.\lambda y.x$
  - 0 (Scott) =  $\lambda x.\lambda y.x$
- Everything is encoded as a function
  - So we can easily misuse combinators
    - false 0 if 0 then ... etc...
  - This is no better than assembly language!

## What is a Type System?

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- A *type system* is some mechanism for distinguishing good programs from bad
  - Good programs = well typed
  - Bad programs = ill typed or not typable
- Examples:
  - `0 + 1` // well typed
  - `false 0` // ill-typed: can't apply a boolean
  - `1 + (if true then 0 else false)` // ill-typed: can't add boolean to integer

## A Definition of Type Systems

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“A type system is a tractable syntactic method for proving the absence of certain program behaviors by classifying phrases according to the kinds of values they compute.”

– Benjamin Pierce, *Types and Programming Languages*

## Simply-Typed Lambda Calculus

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- $e ::= n \mid x \mid \lambda x:t.e \mid e e$ 
  - Functions include the type of their argument
  - We don't really need this, but it will come in handy
- $t ::= \text{int} \mid t \rightarrow t$ 
  - $t1 \rightarrow t2$  is the type of a function that, given an argument of type  $t1$ , returns a result of type  $t2$ 
    - $t1$  is the *domain*, and  $t2$  is the *range*

## Type Judgments

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- Our type system will prove *judgments* of the form
  - $A \vdash e : t$
  - “In type environment  $A$ , expression  $e$  has type  $t$ ”

## Type Environments

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- A *type environment* is a map from variables to types (a kind of symbol table)
  - $\emptyset$  is the empty type environment
    - A closed term  $e$  is *well-typed* if  $\emptyset \vdash e : t$  for some  $t$
    - We'll abbreviate this as  $\vdash e : t$
  - $A, x:t$  is just like  $A$ , except  $x$  now has type  $t$ 
    - The type of  $x$  in  $A, x:t$  is  $t$
    - The type of  $z \neq x$  in  $A, x:t$  is the type of  $z$  in  $A$
- When we see a variable in a program, we look in the type environment to find its type

## Type Rules

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$$\frac{}{A \vdash n : \text{int}} \qquad \frac{x \in \text{dom}(A)}{A \vdash x : A(x)}$$
$$\frac{A, x:t \vdash e : t'}{A \vdash \lambda x:t.e : t \rightarrow t'} \qquad \frac{A \vdash e1 : t \rightarrow t' \quad A \vdash e2 : t}{A \vdash e1 e2 : t'}$$

## Example

$A = - : \text{int} \rightarrow \text{int}$

$$\frac{\frac{-\in \text{dom}(A)}{A \vdash - : \text{int} \rightarrow \text{int}} \quad A \vdash 3 : \text{int}}{A \vdash - 3 : \text{int}}$$

## Another Example

$A = + : \text{int} \rightarrow \text{int} \rightarrow \text{int}$

$B = A, x : \text{int}$

$$\frac{\frac{\frac{+\in \text{dom}(B)}{B \vdash + :} \quad \frac{x \in \text{dom}(B)}{B \vdash x : \text{int}}}{B \vdash + x : \text{int} \rightarrow \text{int}} \quad B \vdash 3 : \text{int}}{B \vdash + x 3 : \text{int}} \quad A \vdash 4 : \text{int}}{A \vdash (\lambda x : \text{int}. + x 3) : \text{int} \rightarrow \text{int}} \quad A \vdash (\lambda x : \text{int}. + x 3) 4 : \text{int}}$$

We'd usually use infix  $x + 3$

## An Algorithm for Type Checking

- Our type rules are deterministic
  - For each syntactic form, only one possible rule
- They define a natural type checking algorithm

- $\text{TypeCheck} : \text{type env} \times \text{expression} \rightarrow \text{type}$

$\text{TypeCheck}(A, n) = \text{int}$

$\text{TypeCheck}(A, x) = \text{if } x \text{ in } \text{dom}(A) \text{ then } A(x) \text{ else fail}$

$\text{TypeCheck}(A, \lambda x : t. e) = t \rightarrow (\text{TypeCheck}((A, x : t), e))$

$\text{TypeCheck}(A, e_1 e_2) =$

let  $t_1 = \text{TypeCheck}(A, e_1)$  in

let  $t_2 = \text{TypeCheck}(A, e_2)$  in

if  $\text{dom}(t_1) = t_2$  then  $\text{range}(t_1)$  else fail

## Semantics

- Here is a small-step, call-by-value semantics
  - If an expression can't be evaluated any more and is not a value, then it is *stuck*

$$\frac{}{(\lambda x : t. e_1) v_2 \rightarrow e_1[v_2/x]} \quad \frac{e_1 \rightarrow e_1'}{e_1 e_2 \rightarrow e_1' e_2}$$

$$\frac{e_2 \rightarrow e_2'}{v_1 e_2 \rightarrow v_1 e_2'}$$

$e ::= v \mid x \mid e e$

$v ::= n \mid \lambda x : t. e$  values – not evaluated

## Progress

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- Suppose  $\vdash e : t$ . Then either  $e$  is a value, or there exists  $e'$  such that  $e \rightarrow e'$
- Proof by induction on  $e$ 
  - Base cases  $n, \lambda x.e$  – these are values, so we're done
  - Base case  $x$  – can't happen (empty type environment)
  - Inductive case  $e_1 e_2$  – If  $e_1$  is not a value, then by induction we can evaluate it, so we're done, and similarly for  $e_2$ . Otherwise both  $e_1$  and  $e_2$  are values. Inspection of the type rules shows that  $e_1$  must have a function type, and therefore must be a lambda since it's a value. Therefore we can make progress.

## Preservation

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- If  $\vdash e : t$  and  $e \rightarrow e'$  then  $\vdash e' : t$
- Proof by induction on  $e \rightarrow e'$ 
  - Induction (easier than the base case!). Expression  $e$  must have the form  $e_1 e_2$ .
  - Assume  $\vdash e_1 e_2 : t$  and  $e_1 e_2 \rightarrow e'$ . Then we have  $\vdash e_1 : t' \rightarrow t$  and  $\vdash e_2 : t'$ .
  - Then there are three cases.
    - If  $e_1 \rightarrow e_1'$ , then by induction  $\vdash e_1' : t' \rightarrow t$ , so  $e_1' e_2$  has type  $t$
    - If reduction inside  $e_2$ , similar

## Preservation, cont'd

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- Otherwise  $(\lambda x:t'.e) v \rightarrow e[v/x]$ . Then we have

$$\frac{x:t' \vdash e : t}{\vdash \lambda x:t'.e : t' \rightarrow t}$$

- Thus we have
  - $x:t' \vdash e : t$
  - $\vdash v : t'$
- Then by the substitution lemma (not shown) we have
  - $\vdash e[v/x] : t$
- And so we have preservation

## Substitution Lemma

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- If  $A \vdash v : t$  and  $A, x:t \vdash e : t'$ , then  $A \vdash e[v/x] : t'$
- Proof: Induction on the structure of  $e$
- For lazy semantics, we'd prove
  - If  $A \vdash e_1 : t$  and  $A, x:t \vdash e : t'$ , then  $A \vdash e[e_1/x] : t'$

## Soundness

- So we have
  - Progress: Suppose  $\vdash e : t$ . Then either  $e$  is a value, or there exists  $e'$  such that  $e \rightarrow e'$
  - Preservation: If  $\vdash e : t$  and  $e \rightarrow e'$  then  $\vdash e' : t$
- Putting these together, we get soundness
  - If  $\vdash e : t$  then either there exists a value  $v$  such that  $e \rightarrow^* v$ , or  $e$  diverges (doesn't terminate).
- What does this mean?
  - Evaluation getting stuck is bad, so
  - "Well-typed programs don't go wrong"

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## Product Types (Tuples)

$e ::= \dots \mid (e, e) \mid \text{fst } e \mid \text{snd } e$

$$\frac{A \vdash e_1 : t \quad A \vdash e_2 : t'}{A \vdash (e_1, e_2) : t \times t'}$$

$$\frac{A \vdash e : t \times t'}{A \vdash \text{fst } e : t} \quad \frac{A \vdash e : t \times t'}{A \vdash \text{snd } e : t'}$$

- Or, maybe, just add functions
  - $\text{pair} : t \rightarrow t' \rightarrow t \times t'$
  - $\text{fst} : t \times t' \rightarrow t$
  - $\text{snd} : t \times t' \rightarrow t'$

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## Sum Types (Tagged Unions)

$e ::= \dots \mid \text{inL}_{t_2} e \mid \text{inR}_{t_1} e$

$\mid (\text{case } e \text{ of } x_1 : t_1 \rightarrow e_1 \mid x_2 : t_2 \rightarrow e_2)$

$$\frac{A \vdash e : t_1}{A \vdash \text{inL}_{t_2} e : t_1 + t_2} \quad \frac{A \vdash e : t_2}{A \vdash \text{inR}_{t_1} e : t_1 + t_2}$$

$$\frac{A \vdash e : t_1 + t_2 \quad A, x_1 : t_1 \vdash e_1 : t \quad A, x_2 : t_2 \vdash e_2 : t}{A \vdash (\text{case } e \text{ of } x_1 : t_1 \rightarrow e_1 \mid x_2 : t_2 \rightarrow e_2) : t}$$

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## Self Application and Types

- Self application is not checkable in our system

$$\frac{\frac{A, x : ? \vdash x : t \rightarrow t' \quad A, x : ? \vdash x : t}{A, x : ? \vdash x x : \dots}}{A \vdash \lambda x : ?. x x : \dots}$$

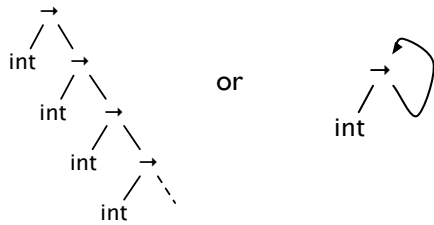
- It would require a type  $t$  such that  $t = t \rightarrow t'$ 
  - (We'll see this next, but so far...)
- The simply-typed lambda calculus is *strongly normalizing*
  - Every program has a normal form
  - I.e., every program halts!

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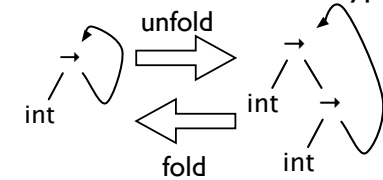
## Recursive Types

- We can type self application if we have a type to represent the solution to equations like  $t = t \rightarrow t'$ 
  - We define the type  $\mu\alpha.t$  to be the solution to the (recursive) equation  $\alpha = t$
  - Example:  $\mu\alpha.int \rightarrow \alpha$



## Folding and Unfolding

- We can check type equivalence with the previous definition (*equi-recursive types*)
  - Standard unification, omit occurs checks
- Alternative solution (*iso-recursive types*):
  - The programmer puts in explicit *fold* and *unfold* operations to expand/contract one “level” of the type trees
    - $unfold \mu\alpha.t = t[\mu\alpha.t/\alpha]$
    - $fold t[\mu\alpha.t/\alpha] = \mu\alpha.t$



## Iso-recursive Types

- $e ::= \dots \mid fold\ e \mid unfold\ e$

$$\frac{A \vdash e : t[\mu\alpha.t/\alpha]}{A \vdash fold\ e : \mu\alpha.t} \qquad \frac{A \vdash e : \mu\alpha.t}{A \vdash unfold\ e : t[\mu\alpha.t/\alpha]}$$

## ML Datatypes

- Combines iso-recursive and sum types
  - Each occurrence of a type constructor when producing a value corresponds to occurrences of *inL/inR* and, when recursion is involved, *fold*
  - Each occurrence of a type constructor in a pattern match corresponds to a *case* and, when recursion is involved, (at least one) *unfold*

## ML Datatypes Example

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- `type intlist = Int of int | Cons of int * intlist`
  - Equivalent to  $\mu\alpha.int+(int \times \alpha)$
- `(Int 3)` equivalent to
  - `fold (inLint×μβ.int+(int×β) 3)`
- `(Cons (2,(Int 3)))` equivalent to
  - `fold (inRint (2, fold (inLint×μβ.int+(int×β) 3)))`
- `match e with Int x -> e1 | Cons x -> e2` same as
  - `case (unfold e)`
    - `x:int → e1`
    - `| x: int×(μβ.int+(int×β)) → e2`

## Discussion

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- In the pure lambda calculus, every term is typable with recursive types
  - (Pure = variables, functions, applications only)
- Most languages have some kind of “recursive” type
  - E.g., for data structures like lists, tree, etc.
- However, usually two recursive types that define the same structure but use a different name are considered different
  - E.g., `struct foo { int x; struct foo *next; }` is different from `struct bar { int x; struct bar *next; }`

## Recap

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- We’ve discussed simple types so far
  - Integers, functions, pairs, unions
  - Extensions for recursive types and updatable refs
- Type systems have nice properties
  - Type checking is straightforward (needs annotations)
  - Well typed programs don’t go “wrong”
    - They don’t get stuck in the operational semantics
- But...We can’t type check all good programs

## Up Next: Improving Types

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- How can we build more flexible type systems?
  - More programs type check
  - Type checking is still tractable
- How can reduce the annotation burden?
  - Type inference

## Parametric Polymorphism

- Observation:  $\lambda x.x$  returns its argument exactly and places no constraints on the type of  $x$ 
  - The identity function works for any argument type
- We can express this with *universal quantification*:
  - $\lambda x.x : \forall \alpha. \alpha \rightarrow \alpha$
  - For any type  $\alpha$ , the identity function has type  $\alpha \rightarrow \alpha$
  - This is also known as *parametric polymorphism*

## System F: annotated polymorphism

- Let's extend our system as follows:
  - $t ::= \alpha \mid \text{int} \mid t \rightarrow t \mid \forall \alpha. t$
  - $e ::= n \mid x \mid \lambda x. e \mid e e \mid \Lambda \alpha. e \mid e [t]$
- That is, we add polymorphic types, and we add explicit *type abstraction (generalization)* ...
  - Annotated code locations at which a value of polymorphic type is created
- ... and *type application (instantiation)*
  - Explicitly annotated code locations at which a value of polymorphic type is used
- This system due to Girard, concurrently Reynolds

## Defining Polymorphic Functions

- Polymorphic functions map types to terms
  - Normal functions map terms to terms
- Examples
  - $\Lambda \alpha. \lambda x: \alpha. x : \forall \alpha. \alpha \rightarrow \alpha$
  - $\Lambda \alpha. \Lambda \beta. \lambda x: \alpha. \lambda y: \beta. x : \forall \alpha. \forall \beta. \alpha \rightarrow \beta \rightarrow \alpha$
  - $\Lambda \alpha. \Lambda \beta. \lambda x: \alpha. \lambda y: \beta. y : \forall \alpha. \forall \beta. \alpha \rightarrow \beta \rightarrow \beta$

## Instantiation

- When we use a parametric polymorphic type, we *apply (or instantiate)* it with a particular type
  - In System F this is done by hand:
    - $(\Lambda \alpha. \lambda x: \alpha. x)[t1] : t1 \rightarrow t1$
    - $(\Lambda \alpha. \lambda x: \alpha. x)[t2] : t2 \rightarrow t2$
- This is where the term *parametric* comes from
  - The type  $\forall \alpha. \alpha \rightarrow \alpha$  is a “function” in the domain of types, and it is passed a parameter at instantiation time

## Type Rules

$$\frac{A, \alpha \vdash e : t}{A \vdash \Lambda \alpha. e : \forall \alpha. t} \qquad \frac{A \vdash e : \forall \alpha. t}{A \vdash e[t'] : t[t' \backslash \alpha]}$$

- Notice that there are no constructs for manipulating values of polymorphic type
  - This justifies instantiation with *any* type—that's what the forall means!
- Note also that we are adding  $\alpha$  to  $A$ ; we could (should?) use this to ensure types are well-formed

## Small-step Semantics Rules

$$\frac{}{(\Lambda \alpha. e)[t] \rightarrow e[t \backslash \alpha]} \text{ (type-app)} \qquad \frac{e \rightarrow e'}{e[t] \rightarrow e'[t]} \text{ (tapp-cong)}$$

- We have to extend substitution to include types; that's up next ... !

## Free Variables, Again

- We're going to need to perform substitutions on quantified types
  - So just like with lambda calculus, we need to worry about free variables and capture-free substitution
- Define the free variables of a type
  - $FV(\alpha) = \{\alpha\}$
  - $FV(c) = \emptyset$
  - $FV(t \rightarrow t') = FV(t) \cup FV(t')$
  - $FV(\forall \alpha. t) = FV(t) - \{\alpha\}$

## Substitution, Again

- Define  $t[u \backslash \alpha]$  as
  - $\alpha[u \backslash \alpha] = u$
  - $\beta[u \backslash \alpha] = \beta$  where  $\beta \neq \alpha$
  - $(t \rightarrow t')[u \backslash \alpha] = t[u \backslash \alpha] \rightarrow t'[u \backslash \alpha]$
  - $(\forall \beta. t)[u \backslash \alpha] = \forall \beta. (t[u \backslash \alpha])$  where  $\beta \neq \alpha$  and  $\beta \notin FV(u)$
- Define  $e[u \backslash \alpha]$  as
  - $(\lambda x : t. e)[u \backslash \alpha] = \lambda x : t[u \backslash \alpha]. e[u \backslash \alpha]$
  - $(\Lambda \beta. e)[u \backslash \alpha] = \Lambda \beta. e[u \backslash \alpha]$  where  $\beta \neq \alpha$  and  $\beta \notin FV(u)$
  - $(e_1 \ e_2)[u \backslash \alpha] = e_1[u \backslash \alpha] \ e_2[u \backslash \alpha]$
  - $x[u \backslash \alpha] = x$  and  $n[u \backslash \alpha] = n$

## An Imperative Language

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$e ::= x \mid \lambda x.e \mid e e$   
|  $\text{ref } e$             allocation  
|  $!e$                 dereference  
|  $e := e$             assignment  
|  $e; e$               sequencing

- Notice that this is not C
  - Variables cannot be updated; only references can
  - I.e., there are no l-values or r-values
- This is a language with *updatable references*

## Examples

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$!(\text{ref } 0)$

let  $x = \text{ref } 0$  in  
 $x := !x + 1$

let  $x = \text{ref } 0$  in  
 $\lambda y. x := !x + 1; !x$

## Type Checking Rules

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- $t ::= \dots \mid \text{ref } t$ 
  - Note: in ML this type is written  $t \text{ ref}$

$$\frac{A \vdash e : t}{A \vdash \text{ref } e : \text{ref } t} \qquad \frac{A \vdash e : \text{ref } t}{A \vdash !e : t}$$

$$\frac{A \vdash e_1 : \text{ref } t \quad A \vdash e_2 : t}{A \vdash e_1 := e_2 : t}$$

## Unit and the Unit Type

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- Sometimes in imperative programs we write expressions that have some *side effect* but no interesting result
- To represent this directly, use *unit*:
  - $e ::= \dots \mid ()$
  - $t ::= \dots \mid \text{unit}$

$$\frac{}{A \vdash () : \text{unit}} \qquad \frac{A \vdash e_1 : \text{ref } t \quad A \vdash e_2 : t}{A \vdash e_1 := e_2 : \text{unit}}$$

## Operational Semantics

- Now we need to keep track of memory
  - State is a map from locations to values
  - Our redexes will be tuples  $\langle \text{State}, \text{expression} \rangle$
  - As a consequence, order of evaluation matters
- As before, evaluation will yield a fully-evaluated term, also called a *value*
  - $v ::= x \mid \lambda x.e$
  - $e ::= v \mid e e \mid \text{ref } e \mid !e \mid e := e$

## Operational Semantics (cont'd)

$$\frac{}{\langle S, (\lambda x.e) \rangle \rightarrow \langle S, (\lambda x.e) \rangle}$$

$$\frac{\langle S, e_1 \rangle \rightarrow \langle S', v_1 \rangle \quad \langle S', e_2 \rangle \rightarrow \langle S'', v_2 \rangle}{\langle S, e_1; e_2 \rangle \rightarrow \langle S'', v_2 \rangle}$$

$$\frac{\langle S, e \rangle \rightarrow \langle S', v \rangle \quad \text{loc fresh}}{\langle S, \text{ref } e \rangle \rightarrow \langle S[v \setminus \text{loc}], \text{loc} \rangle}$$

## Operational Semantics (cont'd)

$$\frac{\langle S, e \rangle \rightarrow \langle S', \text{loc} \rangle}{\langle S, !e \rangle \rightarrow \langle S', S'(\text{loc}) \rangle}$$

$$\frac{\langle S, e_1 \rangle \rightarrow \langle S', \text{loc} \rangle \quad \langle S', e_2 \rangle \rightarrow \langle S'', v \rangle}{\langle S, e_1 := e_2 \rangle \rightarrow \langle S''[v \setminus \text{loc}], v \rangle}$$

$$\frac{\langle S, e_1 \rangle \rightarrow \langle S', \lambda x.e \rangle \quad \langle S', e_2 \rangle \rightarrow \langle S'', v \rangle \quad \langle S'', e[v \setminus x] \rangle \rightarrow \langle S''', v' \rangle}{\langle S, e_1 e_2 \rangle \rightarrow \langle S''', v' \rangle}$$