CMSC 714 High Performance Computing Lecture 2 - Introduction

http://www.cs.umd.edu/class/fall2018/cmsc714

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Notes

Accounts handed out and first assignment probably late next week

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Last time

- Why parallel computing?
 - speed, cost
- Parallel computing basics
 - Processing elements, memory, network, disks
 - SIMD, MIMD, SPMD, dataflow
 - networks
 - bus, ring, tree, mesh (2D or 3D), hypercube
 - memory
 - latency and throughput (bandwidth)
 - shared vs. distributed (physically and logically)
 - UMA vs. NUMA

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Coordination

- Since parallelism in our view is processors working *together* to solve a problem
- Synchronization
 - protection of a single object (e.g., locks)
 - coordination of processors (e.g., barriers)
- Size of a unit of work by a processor
 - need to manage two issues
 - load balance processors have equal work
 - \bullet coordination overhead communication and synchronization
 - often called "grain" size coarse grain vs. fine grain

Sources of Parallelism

- Statements
 - called "control parallel"
 - can perform a series of steps in parallel
 - basis of dataflow computers
- Loops
 - called "data parallel"
 - most common source of parallelism for most programs
 - each processor gets one (or more) iterations to perform

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Examples of Parallelism

- Easy (embarrassingly parallel)
 - multiple independent jobs (i.e..., different simulations)
- Scientific
 - dense linear algebra (divide up matrix)
 - physical system simulations (divide physical space)
- Databases
 - biggest success of parallel computing (divide tuples)
 - · exploits semantics of relational algebra
- Λ I
 - search problems (divide search space)
 - pattern recognition and image processing (divide image)

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Metrics in Application Performance

- Speedup
 - ratio of time on one node to time on *n* nodes
 - hold problem size fixed
 - should really compare to best serial time
 - goal is linear speedup
 - super-linear speedup is possible due to:
 - adding more memory/cache
 - search problems
- Iso-Speedup (or scaled speedup)
 - scale data size up with number of nodes
 - goal is a flat horizontal curve
- Amdahl's Law
 - max speedup is 1/(serial fraction of time), or 1 / (1 f + f/s) as s $\rightarrow \infty$
- Computation to Communication Ratio
 - goal is to maximize this ratio

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How to Write Parallel Programs

- Use old serial code
 - compiler converts it to parallel
 - called the dusty deck problem
- Serial Language plus Communication Library
 - no compiler changes required!
- PVM and MPI use this approach
- New language for parallel computing
 - requires all code to be re-written
 - hard to create a language that provides high performance on different platforms
- Hybrid Approach old language(s), new constructs
 - HPF add data distribution commands to code
 - add parallel loops and synchronization operations

Application Example - Weather

- Typical of many scientific codes
 - computes results for three dimensional space
 - compute results at multiple time steps
 - uses equations to describe physics/chemistry of the
 - grids are used to discretize continuous space • granularity of grids is important to speed/accuracy
- Simplifications (for example, not in real code)
 - earth is flat (no mountains)
 - · earth is round (poles are really flat, earth bulges at equator)
 - second order properties

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Grid Points

- Divide Continuous space into discrete parts
 - for this code, grid size is fixed and uniform
 - possible to change grid size or use multiple grids
 - use three dimensional grid
 - two for latitude and longitude
 - one for elevation
 - Total of M * N * L points
- Design Choice: where is the grid point?
 - left, right, or center of the interval for a grid element



- in multiple dimensions this multiplies:
 - for 3 dimensions have 27 possible positions

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Variables

- One dimensional
- m geo-potential (gravitational effects)
- Two dimensional
 - pi "shifted" surface pressure
 - sigmadot vertical component of the wind velocity
- Three dimensional (primary variables)
 - <u,v> wind velocity/direction vector
 - T temperature
 - q specific humidity
 - p pressure
- Not included
 - clouds
 - precipitation
 - can be derived from others

Serial Computation

- Convert equations to discrete form
- Update from time t to $t + \delta_t$

$$\begin{split} &\text{for each longitude, latitude, altitude} \\ &\text{ustar[i,j,k]} = n * pi[i,j] * u[i,j,k] \\ &\text{vstar[i,j,k]} = m[j] * pi[i,j] * v[i,j,k] \\ &\text{sdot[i,j,k]} = pi[i,j] * sigmadot[i,j] \end{split}$$

eno foreach longitude, latitude altitude $D=4~^*\left((ustar[i,j,k]+ustar[i-1,j,k])~^*\left(q[i,j,k]+q[i-1,j,k]\right)+terms in \{i,j,k]\{+,\}\{1,2\}$ piq[i,j,k] = piq[i,j,k] + D * delat similar terms for piu, piv, piT, and pi

foreach longitude, latitude, altitude q[i,j,k] = piq[i,j,k]/pi[i,j,k] u[i,j,k] = piu[i,j,k]/pi[i,j,k]v[i,j,k] = piv[i,j,k]/pi[i,j,k] $\mathsf{T}[\mathsf{i},\mathsf{j},\mathsf{k}] = \mathsf{piT}[\mathsf{i},\mathsf{j},\mathsf{k}]/\mathsf{pi}[\mathsf{i},\mathsf{j},\mathsf{k}]$

Shared Memory Version

- in each loop nest, iterations are independent
- use a parallel for-loop for each loop nest
- synchronize (barrier) after each loop nest
 - this is overly conservative, but works
 - could use a single sync variable per element, but would incur excessive overhead
- potential parallelism is M * N * L
- private variables: D, i, j, k
- Advantages of shared memory
 - easier to get something working (ignoring performance)
- Hard to debug
 - other processors can modify shared data

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Distributed Memory Version

- · decompose data to specific processors
 - · assign a cube to each processor
 - · maximize volume to surface ratio
 - which minimizes communication/computation ratio
 - called a <block,block,block> distribution
- need to communicate {i,j,k}{+,-}{1,2} terms at boundaries
 - · use send/receive to move the data
 - no need for barriers, send/receive operations provide sync
 - · do sends earlier in computation to hide communication time
- Advantages
 - easier to debug? maybe
 - consider data locality explicitly with data decomposition
- better performance/scaling
- Problems
 - · harder to get the code running

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Database Applications

- Too much data to fit in memory (or sometimes disk)
 - data mining applications (K-Mart had a 4-5TB database several years ago)
 - imaging applications (NASA and others have sites with multiple petabytes)
 - use a fork lift to load tapes by the pallet
- Sources of parallelism
 - within a large transaction
 - among multiple transactions
- Join operation
 - form a single table from two tables based on a common field
 - try to split join attribute into disjoint buckets
 - if know data distribution is uniform its easy
 - if not, try hashing

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Parallel Search (TSP)

- may appear to be faster than 1/n
 - but this is not really the case either
- Algorithm
 - compute a path on a processor
 - if our path is shorter than the shortest one, send it to the others.
 - stop searching a path when it is longer than the shortest.
 - before computing next path, check for word of a new min path
 - stop when all paths have been explored.
- Why it appears to be faster than 1/n speedup
 - we found the path that was shorter sooner
 - however, the reason for this is a different search order!

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Ensuring a fair speedup

- T_{serial} = fastest of
 best known serial algorithm
 simulation of parallel computation
 - use parallel algorithm
 - run all processes on one processor
 - parallel algorithm run on one processor
- If speedup appears to be super-linear
 - check for memory hierarchy effects
 - increased cache or real memory may be reason
 - verify order of operations is the same in parallel and serial cases