

CMSC 420: Short Reference Guide

This document contains a short summary of information about algorithm analysis and data structures, which may be useful later in the semester.

Asymptotic Forms: The following gives both the formal “ c and n_0 ” definitions and an equivalent limit definition for the standard asymptotic forms. Assume that f and g are nonnegative functions.

Asymptotic Form	Relationship	Limit Form	Formal Definition
$f(n) \in \Theta(g(n))$	$f(n) \equiv g(n)$	$0 < \lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} < \infty$	$\exists c_1, c_2, n_0, \forall n \geq n_0, 0 \leq c_1 g(n) \leq f(n) \leq c_2 g(n).$
$f(n) \in O(g(n))$	$f(n) \preceq g(n)$	$\lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} < \infty$	$\exists c, n_0, \forall n \geq n_0, 0 \leq f(n) \leq c g(n).$
$f(n) \in \Omega(g(n))$	$f(n) \succeq g(n)$	$\lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} > 0$	$\exists c, n_0, \forall n \geq n_0, 0 \leq c g(n) \leq f(n).$
$f(n) \in o(g(n))$	$f(n) \prec g(n)$	$\lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} = 0$	$\forall c, \exists n_0, \forall n \geq n_0, 0 \leq f(n) \leq c g(n).$
$f(n) \in \omega(g(n))$	$f(n) \succ g(n)$	$\lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} = \infty$	$\forall c, \exists n_0, \forall n \geq n_0, 0 \leq c g(n) \leq f(n).$

Polylog-Polynomial-Exponential: For any constants a , b , and c , where $b > 0$ and $c > 1$.

$$\log^a n \prec n^b \prec c^n.$$

Common Summations: Let c be any constant, $c \neq 1$, and $n \geq 0$.

Name of Series	Formula	Closed-Form Solution	Asymptotic
Constant Series	$\sum_{i=a}^b 1$	$= \max(b - a + 1, 0)$	$\Theta(b - a)$
Arithmetic Series	$\sum_{i=0}^n i = 0 + 1 + 2 + \dots + n$	$= \frac{n(n+1)}{2}$	$\Theta(n^2)$
Geometric Series	$\sum_{i=0}^n c^i = 1 + c + c^2 + \dots + c^n$	$= \frac{c^{n+1} - 1}{c - 1}$	$\begin{cases} \Theta(c^n) & (c > 1) \\ \Theta(1) & (c < 1) \end{cases}$
Quadratic Series	$\sum_{i=0}^n i^2 = 1^2 + 2^2 + \dots + n^2$	$= \frac{2n^3 + 3n^2 + n}{6}$	$\Theta(n^3)$
Linear-geom. Series	$\sum_{i=0}^{n-1} i c^i = c + 2c^2 + 3c^3 \dots + n c^n$	$= \frac{(n-1)c^{(n+1)} - n c^n + c}{(c-1)^2}$	$\Theta(n c^n)$
Harmonic Series	$\sum_{i=1}^n \frac{1}{i} = 1 + \frac{1}{2} + \frac{1}{3} + \dots + \frac{1}{n}$	$\approx \ln n$	$\Theta(\log n)$

Recurrences: Recursive algorithms (especially those based on divide-and-conquer) can often be analyzed using the so-called *Master Theorem*, which states that given constants $a > 0$, $b > 1$, and $d \geq 0$, the function $T(n) = aT(n/b) + O(n^d)$, has the following asymptotic form:

$$T(n) = \begin{cases} O(n^d) & \text{if } d > \log_b a \\ O(n^d \log n) & \text{if } d = \log_b a \\ O(n^{\log_b a}) & \text{if } d < \log_b a. \end{cases}$$

Sorting: The following algorithms sort a set of n keys over a totally ordered domain. Let $[m]$ denote the set $\{0, \dots, m\}$, and let $[m]^k$ denote the set of ordered k -tuples, where each element is taken from $[m]$.

A sorting algorithm is *stable* if it preserves the relative order of equal elements. A sorting algorithm is *in-place* if it uses no additional array storage other than the input array (although $O(\log n)$ additional space is allowed for the recursion stack). The *comparison-based algorithms* (Insertion-, Merge-, Heap-, and QuickSort) operate under the general assumption that there is a *comparator function* $f(x, y)$ that takes two elements x and y and determines whether $x < y$, $x = y$, or $x > y$.

Algorithm	Domain	Time	Space	Stable	In-place
CountingSort	Integers $[m]$	$O(n + m)$	$O(n + m)$	Yes	No
RadixSort	Integers $[m]^k$ or $[m^k]$	$O(k(n + m))$	$O(kn + m)$	Yes	No
InsertionSort	Total order	$O(n^2)$	$O(n)$	Yes	Yes
MergeSort	Total order	$O(n \log n)$	$O(n)$	Yes	No
HeapSort				No	Yes
QuickSort				Yes/No*	No/Yes

*There are two versions of QuickSort, one which is stable but not in-place, and one which is in-place but not stable.

Order statistics: For any k , $1 \leq k \leq n$, the k th smallest element of a set of size n (over a totally ordered domain) can be computed in $O(n)$ time.

Useful Data Structures: All the following data structures use $O(n)$ space to store n objects:

Unordered Dictionary: (by hashing) Insert, delete, and find in $O(1)$ expected time each. (Note that you can find an element exactly, but you cannot quickly find its predecessor or successor.)

Ordered Dictionary: (by balanced binary trees or sliplists) Insert, delete, find, predecessor, successor, merge, split in $O(\log n)$ time each. (Merge means combining the contents of two dictionaries, where the elements of one dictionary are all smaller than the elements of the other. Split means splitting a dictionary into two about a given value x , where one dictionary contains all the items less than or equal to x and the other contains the items greater than x .) Given the location of an item x in the data structure, it is possible to locate a given element y in time $O(\log k)$, where k is the number of elements between x and y (inclusive).

Priority Queues: (by binary heaps) Insert, delete, extract-min, union, decrease/increase-key in $O(\log n)$ time. Find-min in $O(1)$ time each. Make-heap from n keys in $O(n)$ time.

Priority Queues: (by Fibonacci heaps) Supports insert, find-min, decrease-key all in $O(1)$ amortized time. (That is, a sequence of length m takes $O(m)$ total time.) Extract-min and delete take $O(\log n)$ worst-case time, where n is the number of items in the heap.

Disjoint Set Union-Find: (by inverted trees with path compression) Union of two disjoint sets and find the set containing an element in $O(\log n)$ time each. A sequence of m operations can be done in $O(\alpha(m, n))$ amortized time. That is, the entire sequence can be done in $O(m \cdot \alpha(m, n))$ time. (α is the *extremely* slow growing inverse-Ackerman function.)