CMSC 754 - Computational Geometry
Lecture 18: Coresets and Kernels

Approximation by Sampling:

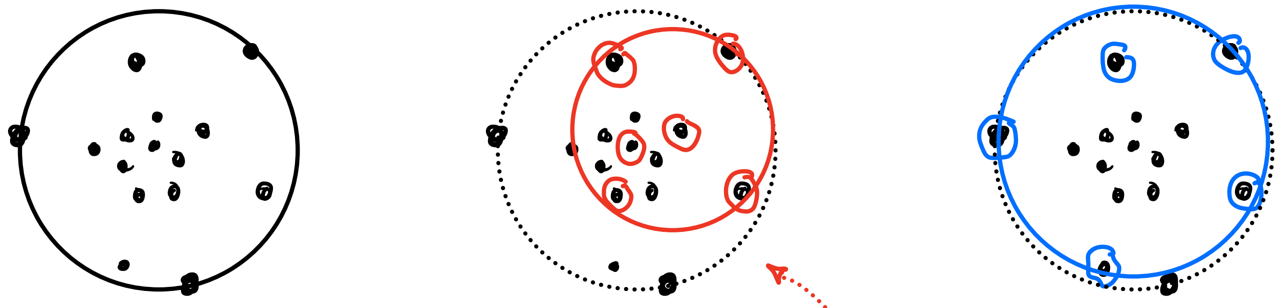
- Running time too slow?
- Maybe your data size is too large!
- Idea:
    - Extract a small subset, $P' \subseteq P$
    - Run solve problem exactly on P'
    - Prove that the answer on P' is "close" to optimal on P.

How to compute P'?

- Depends on your problem
- Random sampling is most common, but not necessarily best

Example: Minimum Enclosing Ball (MEB)

- Given a set $P = \{p_1, \dots, p_n\}$ in $\mathbb{R}^d$ compute the Euclidean ball of min. radius enclosing P.



MEB(P) — MEB(P′), P′ = random — MEB(P″), P″ = coreset

Problem with random sampling:

- MEB(P) depends on points near periphery
- Random sample extracts many irrelevant points.
- Smarter: Use a sampling method that gives priority to peripheral points

Coreset: Let P be input set.

$f^*(P) \to \mathbb{R}$ is our objective function
(eg. $f^*(P)$ = radius of MEB)

Given $\varepsilon > 0$, an ε-coreset is a subset $Q \subseteq P$ s.t.

$$1-\varepsilon \le \frac{f^*(Q)}{f^*(P)} \le 1+\varepsilon$$

The opt. soln. for Q is close to opt. for P

Questions:

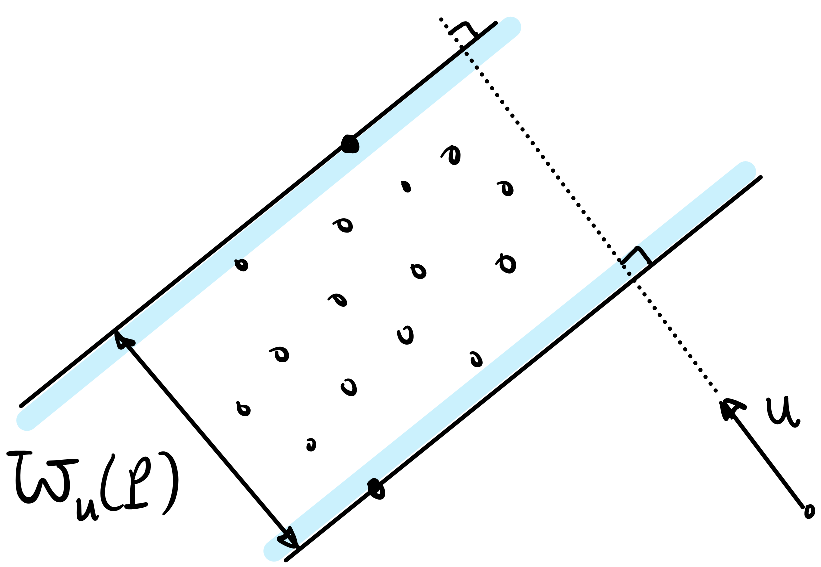
- For what optimization problems do (small) coresets exist?
- (As a function of $n + \varepsilon$) how small is the coreset?
- How fast can we compute a coreset?

Coreset for Directional Width:
(also called ε-kernel)

- Given a pt set $P \subseteq \mathbb{R}^d$
- Given a unit vector $\vec{u}$

- Directional width of P in direction $\vec{u}$ is:

$$\omega_u(P) = \max_{p \in P} (\vec{p} \cdot \vec{u}) - \min_{p \in P} (\vec{p} \cdot \vec{u})$$



Given $\varepsilon > 0$, an ε-coreset for direc. width (also called ε-kernel) is a subset $R \subseteq P$ s.t.

$\forall$ unit vect. $\vec{u}$:

Trivially true since $R \subseteq P$

$$(1-\varepsilon)\,\omega_u(P) \le \omega_u(R) \le \omega_u(P)$$

Getting this is the objective

Aside: When computing approx. lower bounds we sometimes write:

$$(1-\varepsilon)\cdot \text{exact} \le \text{approx}$$

and other times:

$$\frac{\text{exact}}{1+\varepsilon} \le \text{approx}$$

Does the form matter?

Not really. If $0 < \varepsilon < 1$, then

$$1-\varepsilon \le \frac{1}{1+\varepsilon} \le 1 - \varepsilon/2$$

- Only constant factors are affected

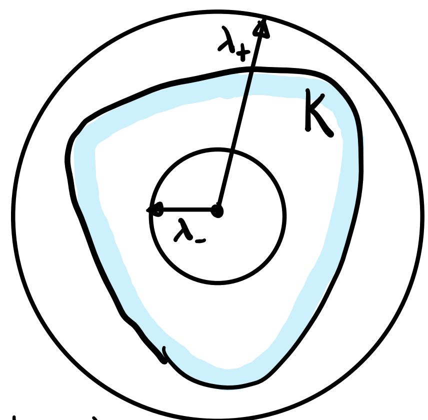
Useful facts:

Chain Property: If X is an ε-kernel for Y
and Y is an ε'-kernel for Z
then X is an $(\varepsilon+\varepsilon')$-kernel for Z

Union Property: If X is an ε-kernel for P,
X' is an ε-kernel for P'
then $X \cup X'$ is an ε-kernel for $P \cup P'$

Canonical Position:
We like fat things...

Fat: Given $0 \leq \alpha \leq 1$, a convex body K is
is α-fat if K can be sandwiched
between two concentric balls of radii
$\lambda_- \leq \lambda_+$ where
$\alpha = \lambda_- / \lambda_+$



Canonical Position: Convex body K is in
α-canonical form if it is sandwiched
between balls of radius $\lambda_- = 1/2\alpha$ & $\lambda_+ = 1/2$
centered at the origin.

Why $\frac{1}{2}$? $\Rightarrow$ K's diameter ≤ 1

A point set P is $\left\{ \begin{array}{l} \alpha\text{-fat} \\ \\ \alpha\text{-canonical form} \end{array} \right\}$ if $\text{conv}(P)$ is.

We can convert any pt set into canonical form.

Affine Transformation: Is a
linear transformation
(scaling + rotation + shearing)
+ translation

Lemma: Given any n-element pt. set $P \subseteq \mathbb{R}^d$, there exists an affine transformation T that maps P into $(1/d)$-canonical form

- $R \subseteq P$ is an ε-kernel for P iff $T(R)$ is an ε-kernel for $T(P)$
- T can be computed in $O(n)$ time

Proof makes use of important fact: (1948)

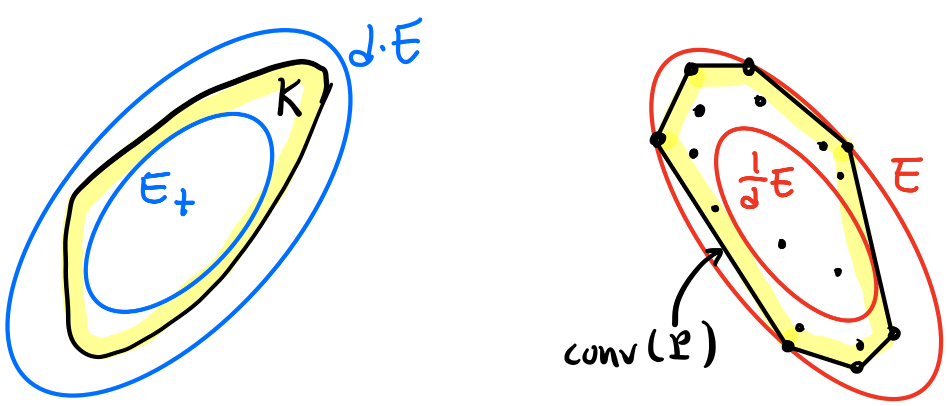
John's Theorem: Given any convex body $K \subseteq \mathbb{R}^d$, let E be max volume ellipsoid contained in K, then

$$E \subseteq K \subseteq d \cdot E$$

where $d \cdot E$ is a factor-d scaling E about its center.

Equiv: Given pt. set P, let E be min vol. ellipsoid containing P, then

$$\frac{1}{d} E \subseteq \mathrm{conv}(P) \subseteq E$$



- The ellipsoid is called the John Ellipsoid or Löwner-John Ellipsoid
- Can compute it in $O(n)$ time (randomized incremental)

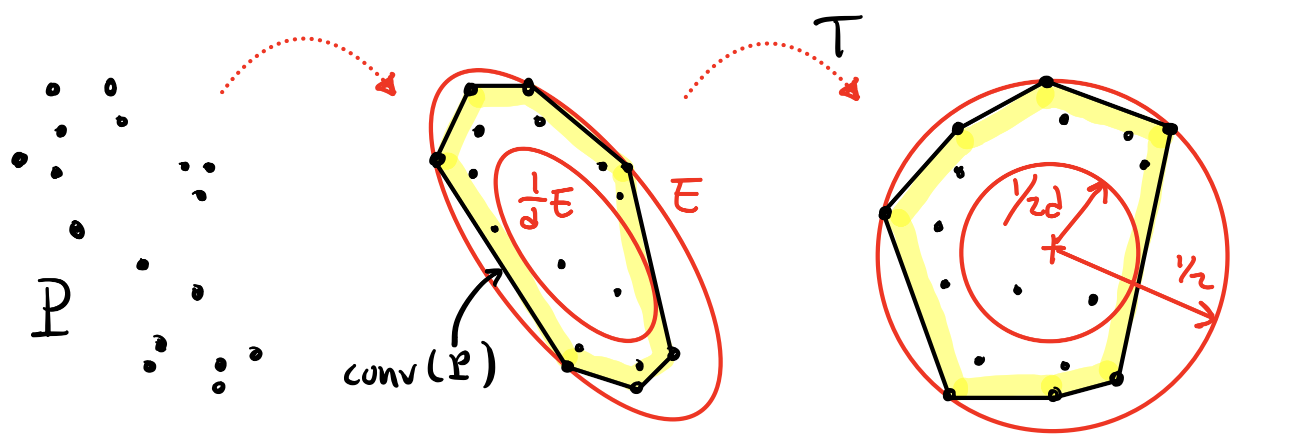
Fact: Given any ellipsoid E, there exists an affine transformation that maps E to a unit ball, centered at origin.

Proof (of canonical form lemma):

① Compute P's outer John ellipsoid E

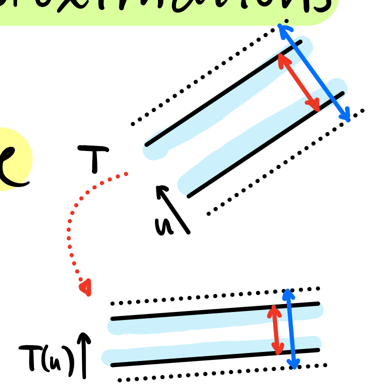
② Find affine transformation mapping E to unit ball centered at origin

③ Scale by $1/2$ → output resulting transformation T



Why are directional width approximations preserved?

- Affine transformations preserve ratios of parallel lengths (Details omitted)



Quick + Dirty Kernel: Simple but not optimal size $- O(1/\varepsilon^d)$

Given $P \subseteq \mathbb{R}^d$ + $\varepsilon > 0$:

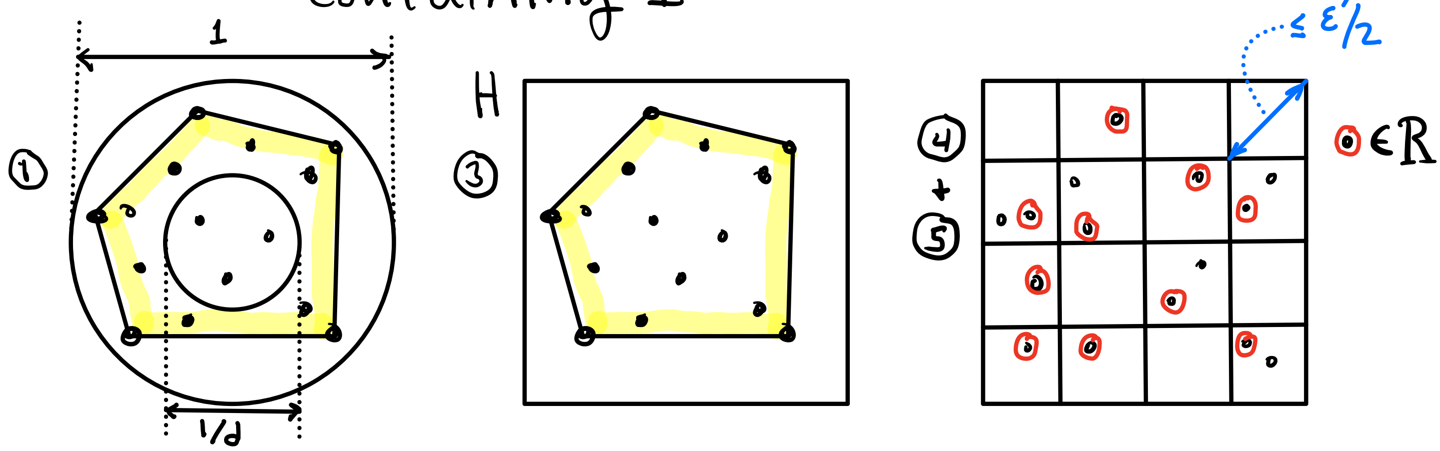
1. Map P to $1/d$-canonical position

   Note: $\forall u,\ 1/d \leq \omega_u(P) \leq 1$

   $\Rightarrow$ absolute error of $\varepsilon/d \Rightarrow$ rel. error $\leq \varepsilon$

2. Let $\varepsilon' = \varepsilon/d$

3. Let $H = [-1/2, +1/2]^d$ be unit hypercube containing P



4. Subdivide H into square grid of diameter $\leq \varepsilon'/2$ (equiv., side length $= \varepsilon'/2\sqrt{d}$)

   Note: No. of grid cells is $\left(\frac{1}{\varepsilon'/2\sqrt{d}}\right)^d = O(1/\varepsilon^d)$

5. $R \leftarrow$ take one pt of P from each occupied cell

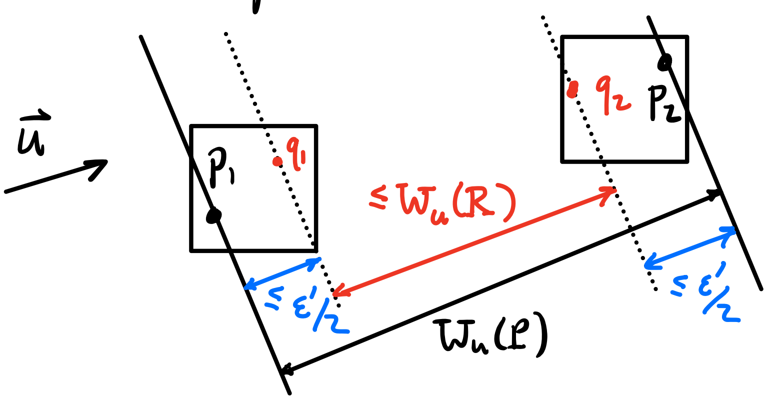
   Note: $|R| = O(1/\varepsilon^d)$. Computable in $O(n)$ time

Running time: $O(n + 1/\varepsilon^d)$

- Canonical position - $O(n)$
- Place pts in grid cells - $O(n)$
  [integer division + hashing]
- Output R - $O(1/\varepsilon^d)$

Correctness:

- Given any direction $\vec{u}$, let $p_1, p_2 \in P$ be pts that define $\omega_u(P)$
- Let $q_1, q_2 \in R$ be corresponding representatives from p_1 + p_2's cells



- Since cell diameter $\le \varepsilon'/2$, it follows that

$$\omega_u(P) \le \varepsilon'/2 + \omega_u(R) + \varepsilon'/2$$
$$= \varepsilon' + \omega_u(R) = \varepsilon/d + \omega_u(R)$$

- By canonical form, $\omega_u(P) \ge 1/d$

$$\omega_u(P) \le \varepsilon \cdot \omega_u(P) + \omega_u(R)$$
$$\Rightarrow (1-\varepsilon)\,\omega_u(P) \le \omega_u(R) \le \omega_u(P)$$

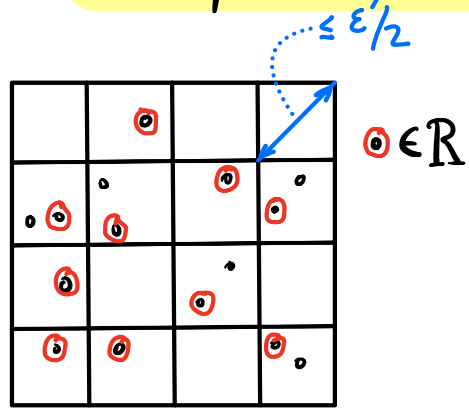
since $R \subseteq P$

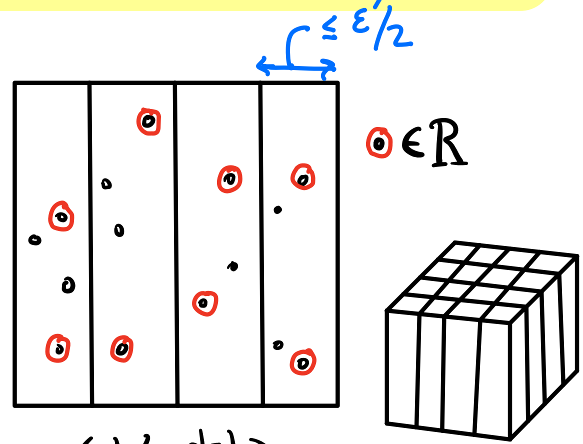
$\Rightarrow$ R is an ε-kernel

$\square$

Small Improvement: $\cancel{O(1/\varepsilon^{d})} \rightarrow O(1/\varepsilon^{d-1})$

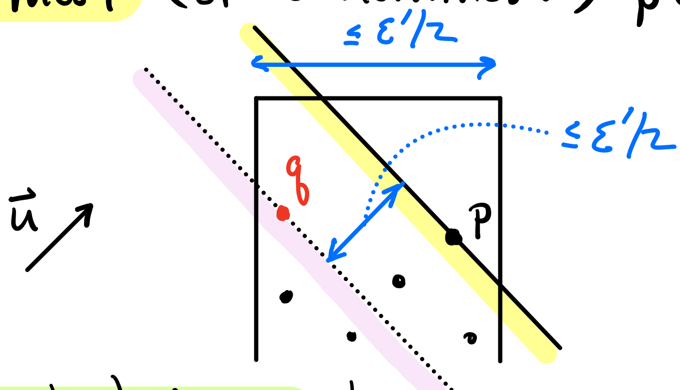
- Quick + dirty's grid includes many internal points → wasteful
- Rather than take:
  - one representative per cell, instead
  - two per column – toppmost + bottommost





- How many? Top grid has $O(1/\varepsilon^{d-1})$ cells

  $|R| = 2 \cdot O(1/\varepsilon^{d-1}) = O(1/\varepsilon^{d-1})$
- Correctness? Let p be extreme pt in direction $\vec{u}$ + let $q \in R$ be topmost (or bottommost) pt in column



Directional distance betw. q + p is $\le \varepsilon/2$

... remaining details omitted

Big Improvement – ε-kernel of size $O(1/\varepsilon^{\frac{d-1}{2}})$
[optimal in the worst case]

Construction based on idea discovered (independently) by Dudley + Bronsteyn + Ivanov (~1974)

① Map P to $1/d$-canonical position

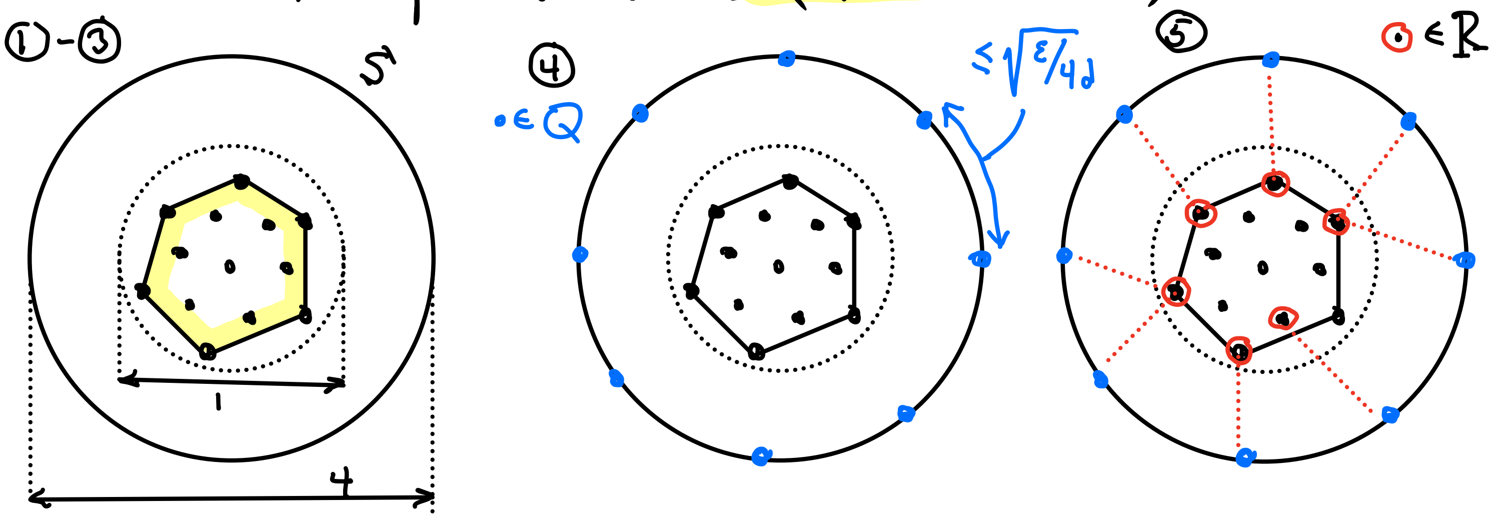
Note: $\forall u,\ 1/d \leq \omega_u(P) \leq 1$

$\Rightarrow$ absolute error of $\varepsilon/d \Rightarrow$ rel. error $\leq \varepsilon$

② Let $\varepsilon' = \varepsilon/d$

③ Let S = sphere of radius 2 centered at origin, let $\delta = \sqrt{\varepsilon/4d}$

④ Let Q be a set of points on S s.t. any point of S is within distance δ of some pt of Q. (Q is "δ-dense")



⑤ For each $q \in Q$, let $nn(q) \in P$ be its closest pt.

Return: $R = \bigcup_{q \in Q} nn(q)$

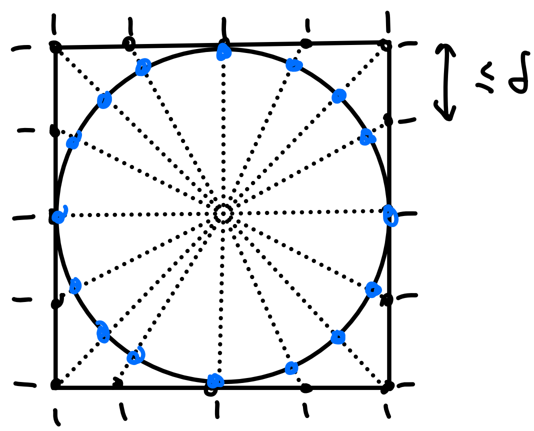
Size: $|R| \leq |Q|$

- Claim that $|Q| = O((1/\sqrt{\varepsilon})^{d-1}) = O(1/\varepsilon^{\frac{d-1}{2}})$
- **Intuition:** Each $q \in Q$ covers a spherical cap of radius $\delta \cong \sqrt{\varepsilon}$
  - Such a cap has surface area $\approx \delta^{d-1} \approx \sqrt{\varepsilon}^{\,d-1} \approx \varepsilon^{(d-1)/2}$
  - S has constant radius $\Rightarrow$ constant area
  - No. caps needed to cover S $\approx \text{const}/\varepsilon^{(d-1)/2} = O(1/\varepsilon^{(d-1)/2})$

$\Rightarrow |R| = O(1/\varepsilon^{(d-1)/2})$

Running Time:

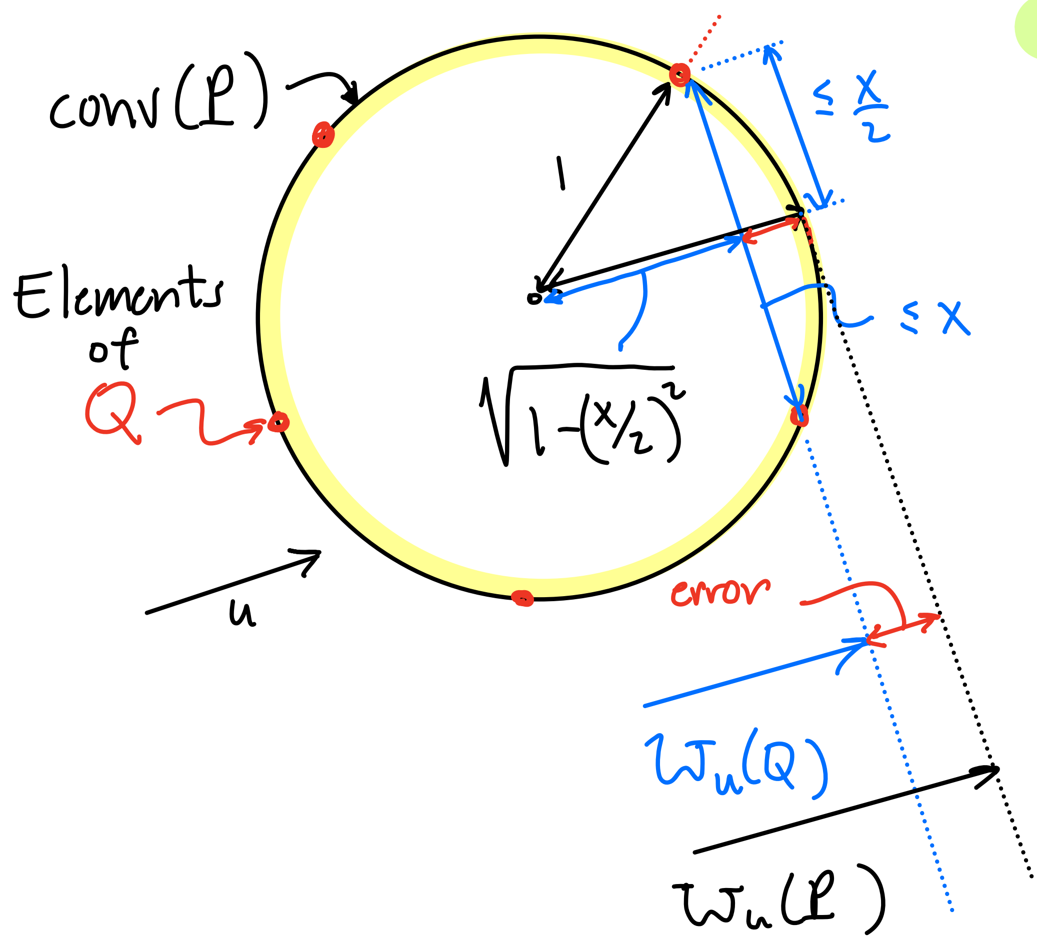
- Canonical position: $O(n)$
- Computing δ-dense Q
  $O(|Q|) = O(1/\varepsilon^{(d-1)/2})$
  How? Enclose S in a hypercube
  Cover hypercube with grid $\sim \delta$
  Project onto S
- Compute $nn(q)$
  - Suffices to use approx nn
  - $O(\text{poly}(1/\varepsilon) \cdot \log n)$



Correctness: (Complex — See latex notes)

We'll consider a simpler question:

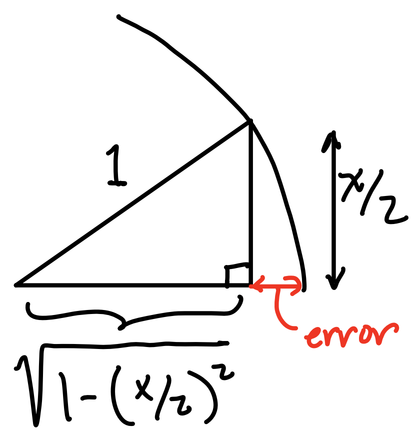
Why $\sqrt{\varepsilon}$ spacing? Simple case: Suppose **conv($\mathcal{P}$)** is a **unit ball**



To generate a large error select u to hit conv($\mathcal{P}$) midway between pts of Q.

By **Pythagorean Thm:**

$$\text{error} \le 1 - \sqrt{1-(x/2)^2}$$



We want

$$\text{error} \le \varepsilon$$

That is, want x s.t.

$$1-\sqrt{1-(x/2)^2} \leq \varepsilon$$

Solving for x, we have:

$$\Leftrightarrow \quad 1-(x/2)^2 \geq (1-\varepsilon)^2 = 1-2\varepsilon+\varepsilon^2$$

if $\varepsilon \leq 1$, then $\varepsilon^2 \leq \varepsilon \Rightarrow 1-2\varepsilon+\varepsilon^2 \leq 1-\varepsilon$

$$\Leftarrow \quad 1-(x/2)^2 \geq 1-\varepsilon$$

$$\Leftrightarrow \quad x/2 \leq \sqrt{\varepsilon}$$

$$x \leq 2\sqrt{\varepsilon}$$

- This explains why spacing $\sim \sqrt{\varepsilon}$ is the right thing to do

- Notice this is tight up to constant factors.