

CMSC 828S, Spring 2005

Presentation on

**MULTIDIMENSIONAL
LINEAR HASHING**

by

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MULTIDIMENSIONAL LINEAR HASHING

- Introduction & basic principles
- Linear Hashing with Reversed Bit Interleaving (LHRBI)
- Multidimensional Extendible Hashing (MDEH)
- Comparison of LHRBI and MDEH
- Quantile Hashing
- Piecewise Linear Order Preserving (PLOP)
- Dynamic Z Hashing
- Linear Hashing with Partial Expansions (LHPE)

➔ Introduction, some basic principles

Linear Hashing with Reversed Bit Interleaving (LHRBI)

Multidimensional Extendible Hashing (MDEH)

Comparison of LHRBI and MDEH

Quantile Hashing

Piecewise Linear Order Preserving (PLOP)

Dynamic Z Hashing

Linear Hashing with Partial Expansions (LHPE)

Linear Hashing in general:

Create **one** additional cell at a time

May be based on

Overflow of bucket or cell, or

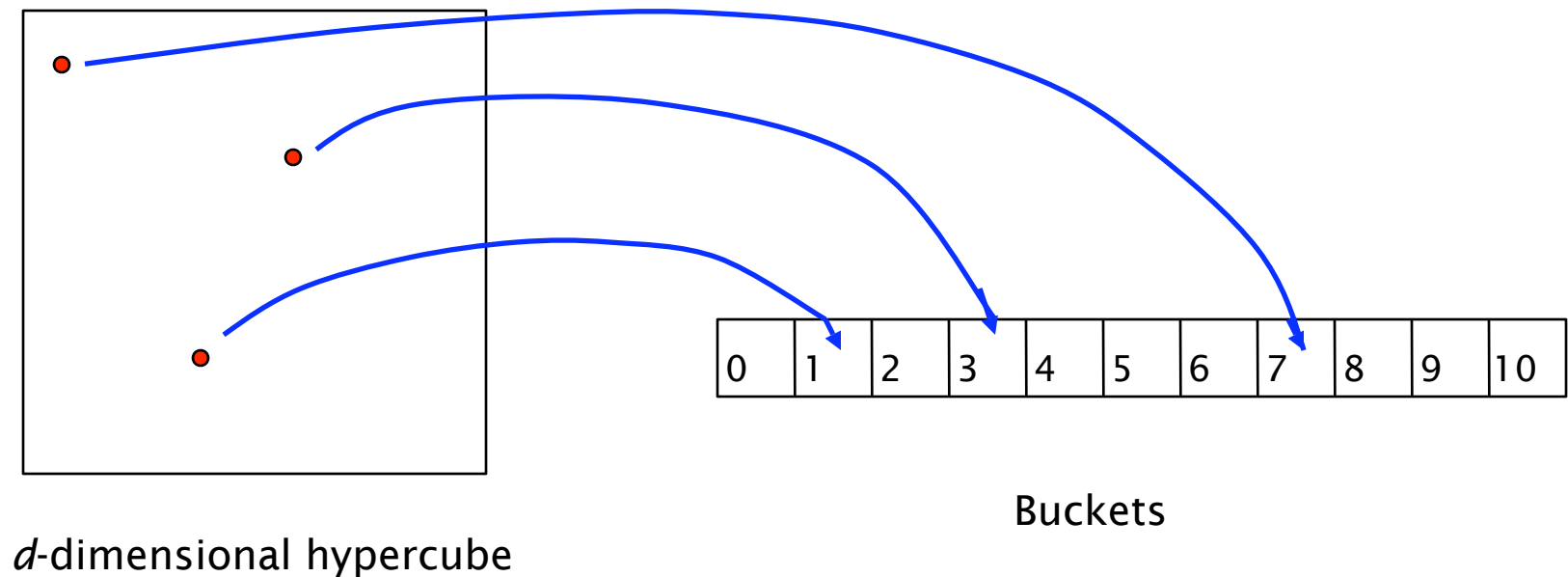
Storage Utilization Factor

Linear Hashing in dimension $d > 1$

d -dimensional **hypervolume** is subdivided into
 d -dimensional cells

Cells are linearly ordered, typically in order of
creation

The **hashing function** must map points in d -space to a unique cell/bucket number



Total grid partition: number of cells is doubled

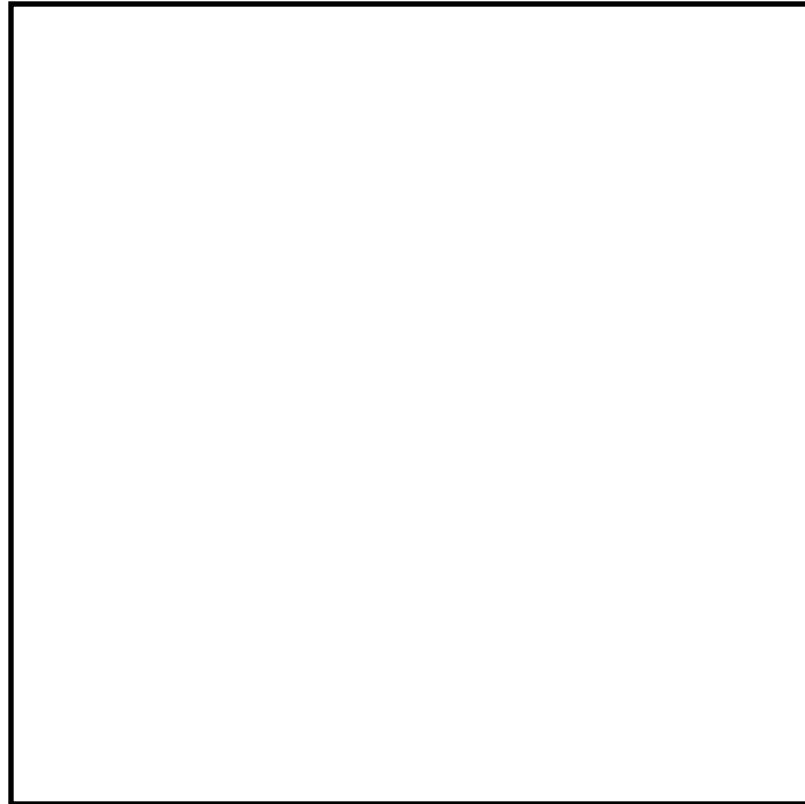
(But cells have same shape as original only every d th total grid partition (tgp)).

Example $d = 2$.

Number of cells = 1

Total grid partition 0

Cell is square



Total grid partition: number of cells is doubled

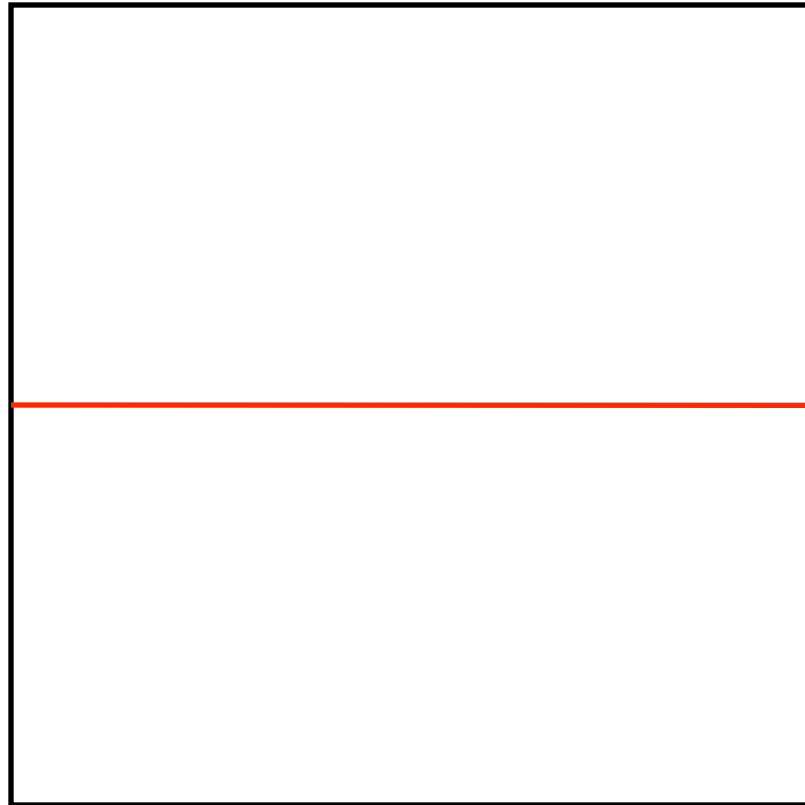
(But cells have same shape as original only every d th total grid partition (tgp)).

Example $d = 2$.

Number of cells = 2

Total grid partition 1

Cells are not square

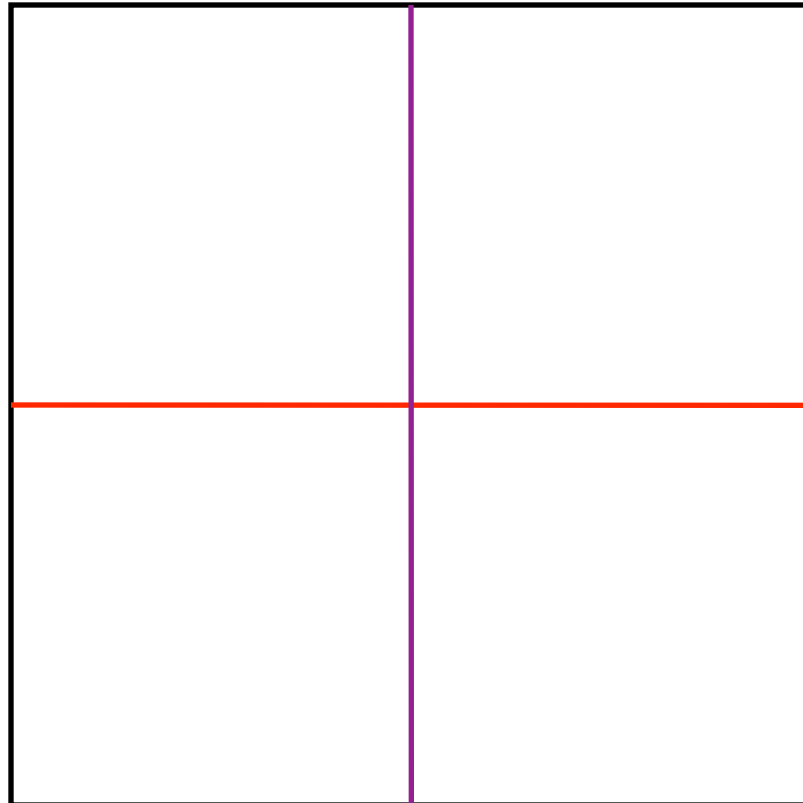


Total grid partition: number of cells is doubled

(But cells have same shape as original only every d th total grid partition (tgp)).

Example $d = 2$.

Number of cells = 4
Total grid partition 2
Cells are square



Total grid partition: number of cells is doubled

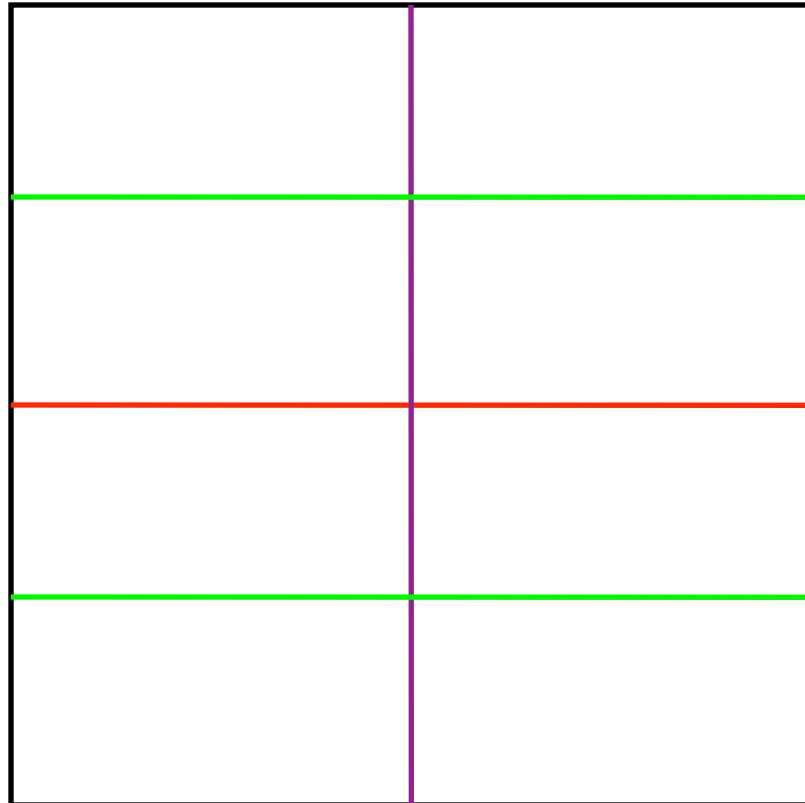
(But cells have same shape as original only every d th total grid partition (tgp)).

Example $d = 2$.

Number of cells = 8

Total grid partition 3

Cells are not square

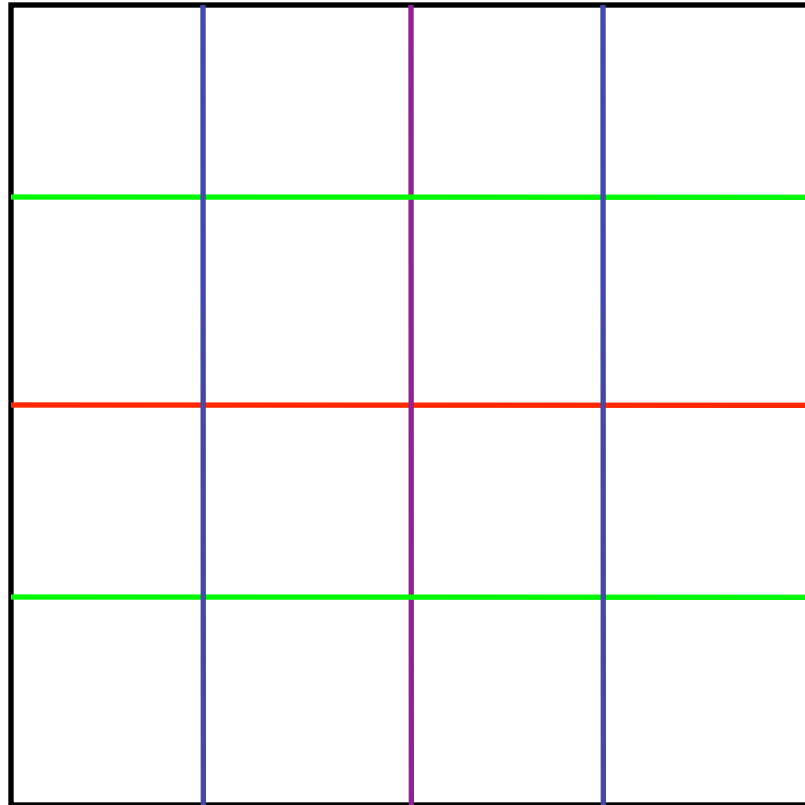


Total grid partition: number of cells is doubled

(But cells have same shape as original only every d th total grid partition (tgp)).

Example $d = 2$.

Number of cells = 16
Total grid partition 4
Cells are square



Bit Operations

Bit Concatonation: $(4, 3)_{10} = (100, 011)_2$

$$\begin{array}{cc} \downarrow & \downarrow \\ (100011)_2 & = (35)_{10} \end{array}$$

y-first Bit Interleaving: $(4, 3)_{10} = (100, 011)_2$

$$\begin{array}{cc} \downarrow & \downarrow \\ (011010)_2 & = (26)_{10} \end{array}$$

y-first Reversed Bit Interleaving: $(4, 3)_{10} = (100, 011)_2$

(reverse the previous one)

$$\begin{array}{cc} \downarrow & \downarrow \\ (010110)_2 & = (22)_{10} \end{array}$$

Outline

Introduction, some basic principles

➔ **Linear Hashing with Reversed Bit Interleaving (LHRBI)**

Multidimensional Extendible Hashing (MDEH)

Comparison of LHRBI and MDEH

Quantile Hashing

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Dynamic Z Hashing

Linear Hashing with Partial Expansions (LHPE)

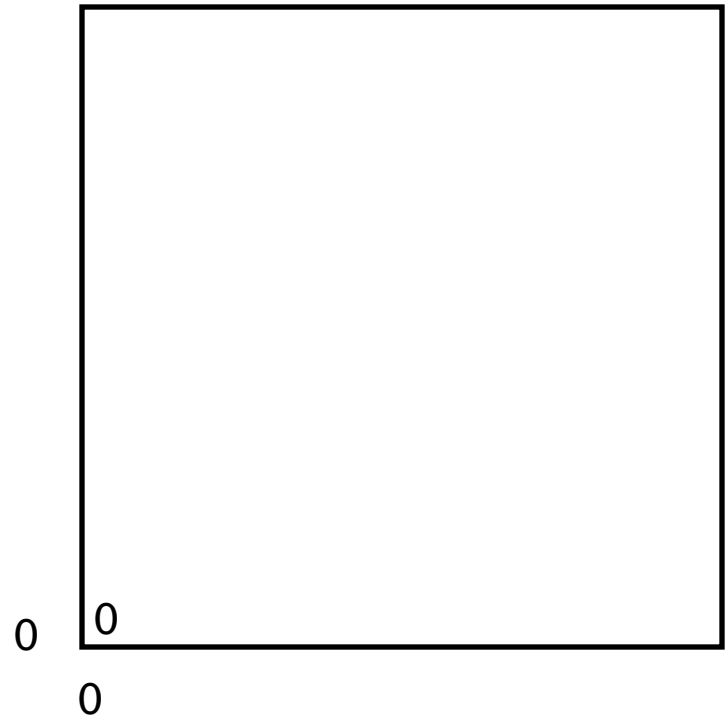
MAIN POINTS:

Decouple cell overflow from cell split by having chosen the order of splitting in advance.

Order preserving.

The Specifics:

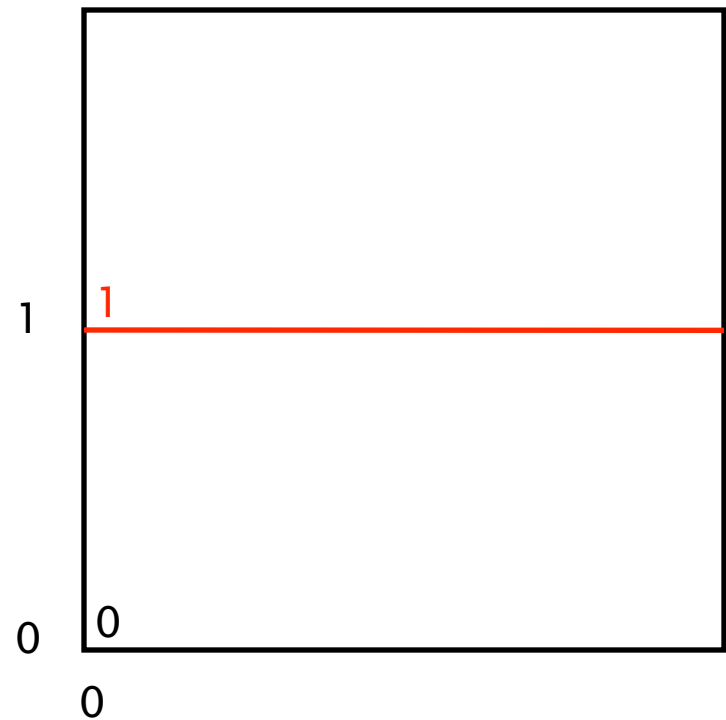
1. Embedding space-based
2. Always split next smallest-numbered cell.
3. *y-first reversed bit interleaving*
on partition indices
4. Count partition indices
by distance from origin



Key Points:

1. **Order preserving**, i.e., always split next smallest-numbered cell.
2. **y-first reversed bit interleaving** on partition indices
3. Count partition indices by distance from origin

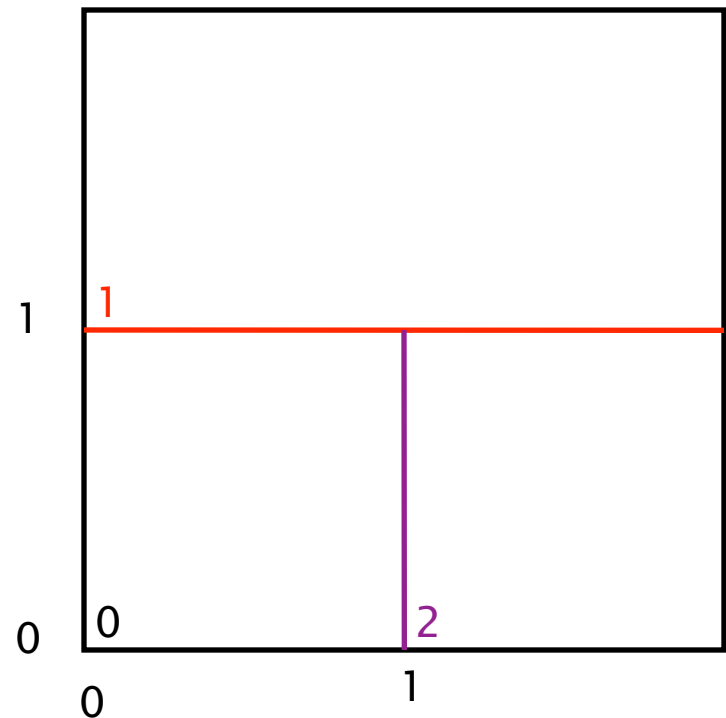
Split cell 0



Key Points:

1. **Order preserving**, i.e., always split next smallest-numbered cell.
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3. Count partition indices by distance from origin

Split cell 0

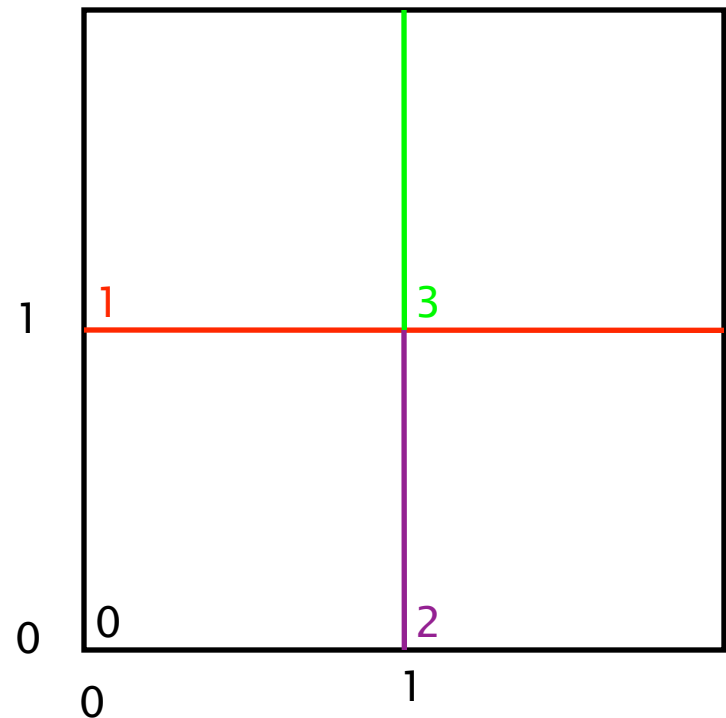


Key Points:

1. **Order preserving**, i.e., always split next smallest-numbered cell.
2. **y-first reversed bit interleaving** on partition indices
3. Count partition indices by distance from origin

Split cell 1

Finish total grid partition 2



Key Points:

1. **Order preserving**, i.e., always split next smallest-numbered cell.
2. **y-first reversed bit interleaving** on partition indices
3. Count partition indices by distance from origin

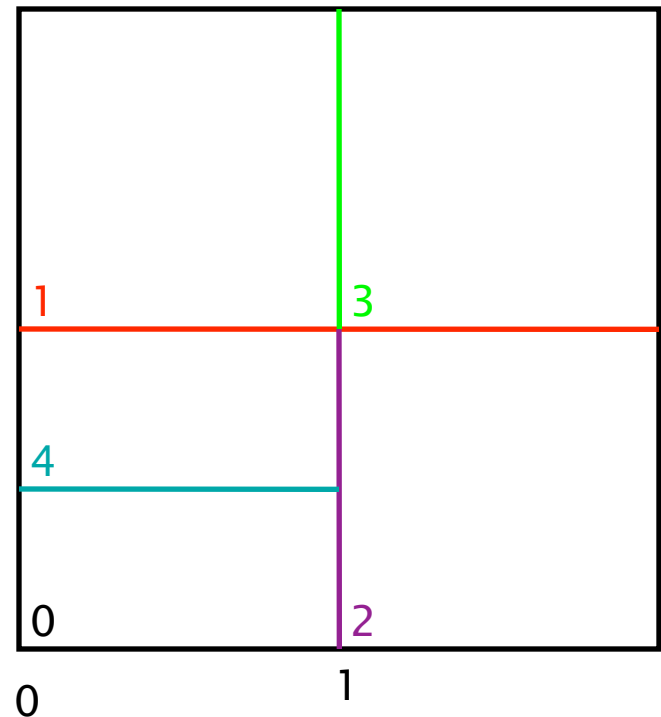
Split cell 0

Notice

2

1

0

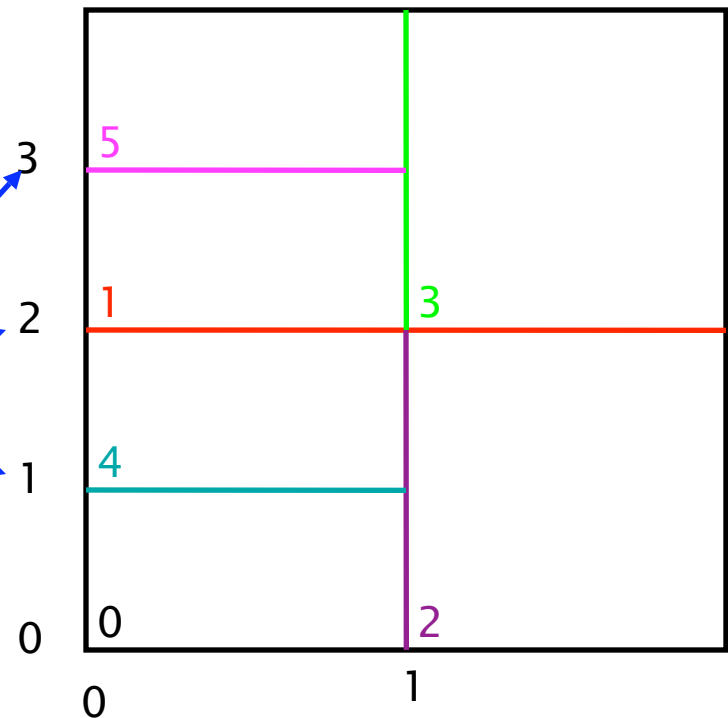


Key Points:

1. **Order preserving**, i.e., always split next smallest-numbered cell.
2. **y-first reversed bit interleaving** on partition indices
3. Count partition indices by distance from origin

Split cell 1

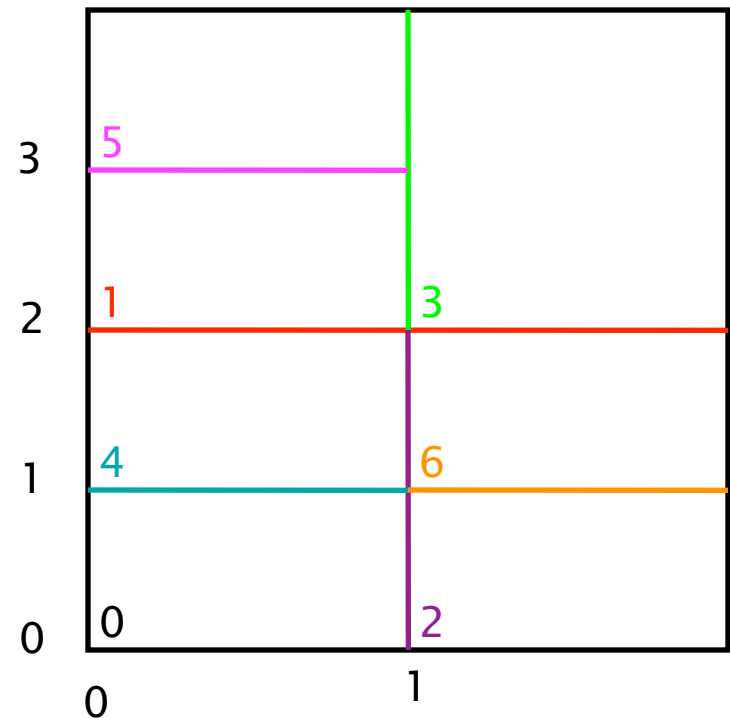
Notice



Key Points:

1. **Order preserving**, i.e., always split next smallest-numbered cell.
2. **y-first reversed bit interleaving** on partition indices
3. Count partition indices by distance from origin

Split cell 2

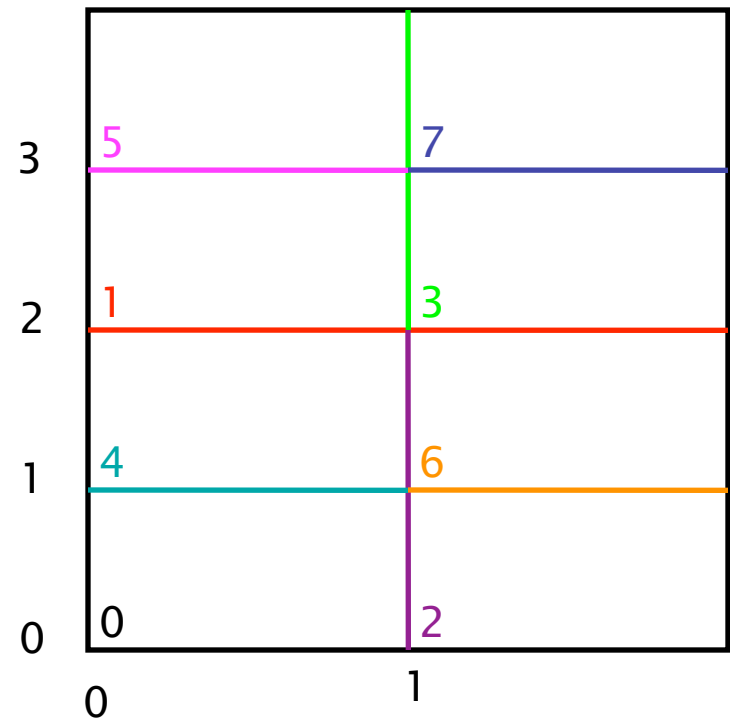


Key Points:

1. **Order preserving**, i.e., always split next smallest-numbered cell.
2. **y-first reversed bit interleaving** on partition indices
3. Count partition indices by distance from origin

Split cell 3

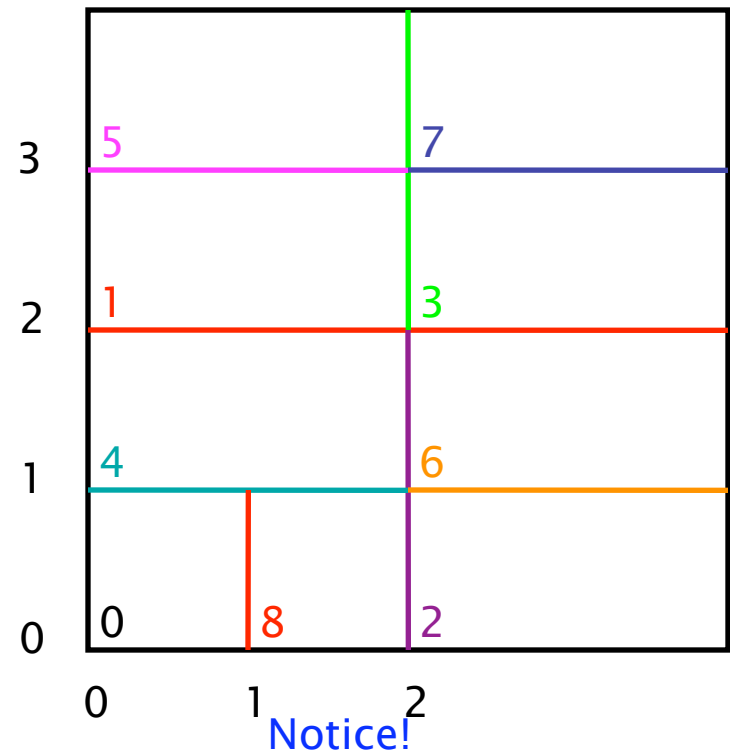
Finish total grid partition 3



Key Points:

1. **Order preserving**, i.e., always split next smallest-numbered cell.
2. **y-first reversed bit interleaving** on partition indices
3. Count partition indices by distance from origin

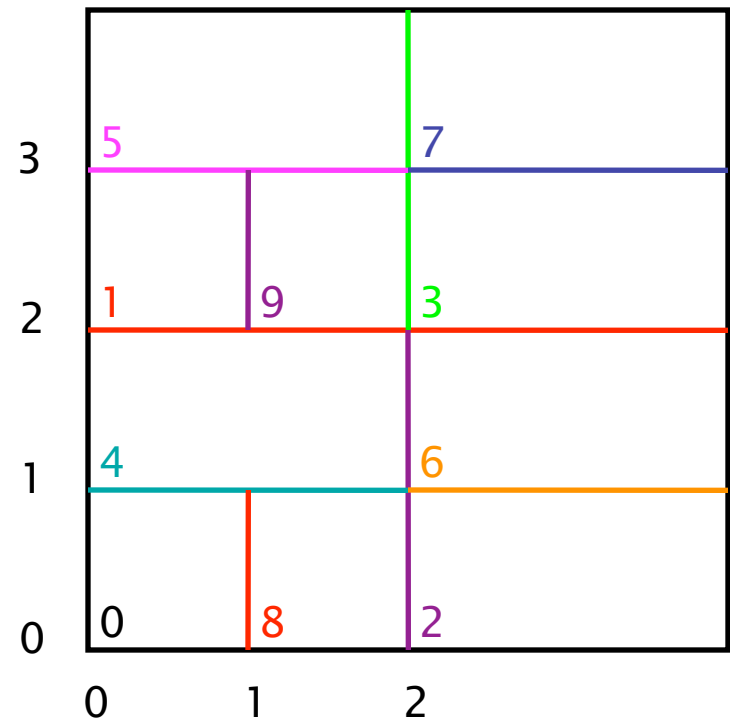
Split cell 0



Key Points:

1. **Order preserving**, i.e., always split next smallest-numbered cell.
2. **y-first reversed bit interleaving** on partition indices
3. Count partition indices by distance from origin

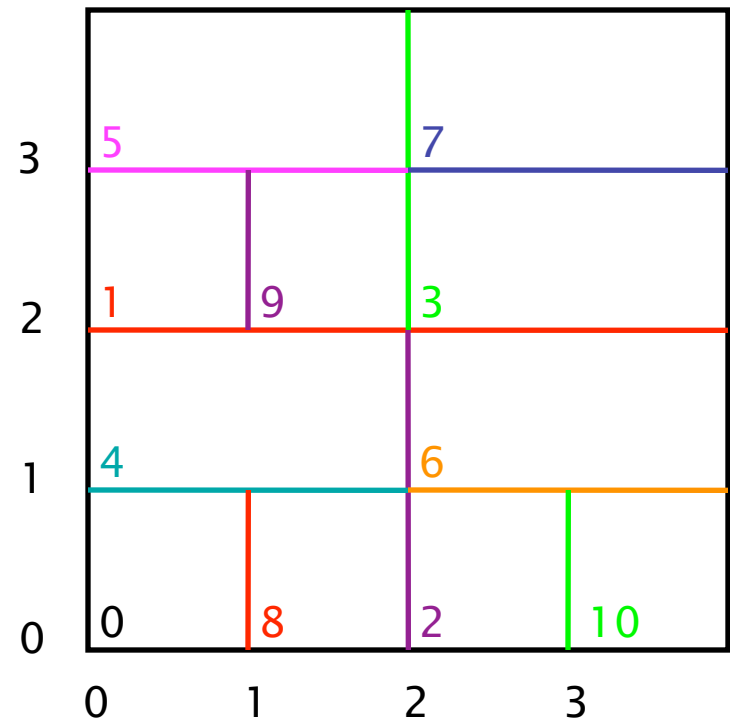
Split cell 1



Key Points:

1. **Order preserving**, i.e., always split next smallest-numbered cell.
2. **y-first reversed bit interleaving** on partition indices
3. Count partition indices by distance from origin

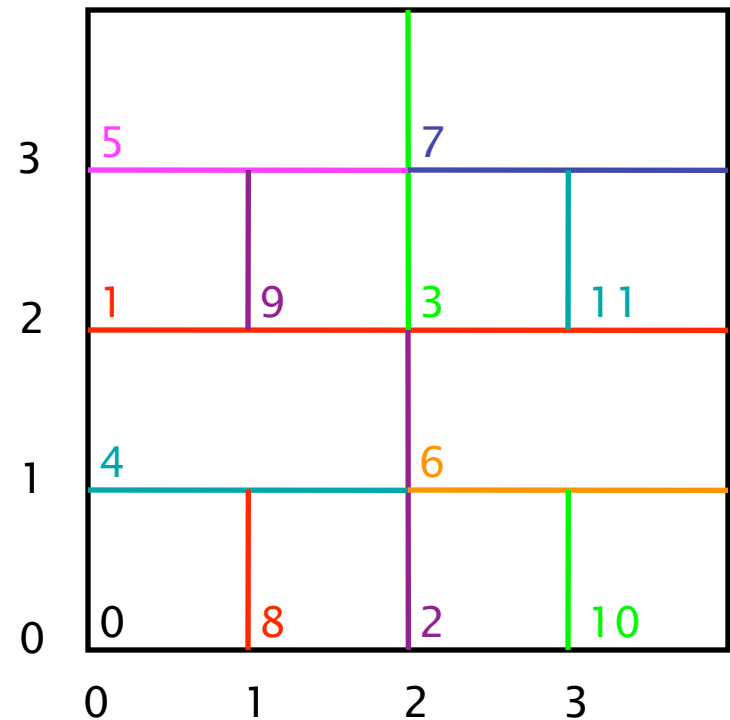
Split cell 2



Key Points:

1. **Order preserving**, i.e., always split next smallest-numbered cell.
2. **y-first reversed bit interleaving** on partition indices
3. Count partition indices by distance from origin

Split cell 3



1. **Order preserving**, i.e., always split next smallest-numbered cell.
2. **y-first reversed bit interleaving** on partition indices
3. Count partition indices by distance from origin

A 4x4 grid with rows and columns indexed 0 to 3. The grid contains numbers in various cells, and several colored lines are drawn across it:

- Row 0:** 0 (black), 8 (red), 2 (purple), 10 (green)
- Row 1:** 4 (teal), 12 (magenta), 6 (orange)
- Row 2:** 1 (red), 9 (purple), 3 (green), 11 (teal)
- Row 3:** 5 (magenta), 7 (blue)

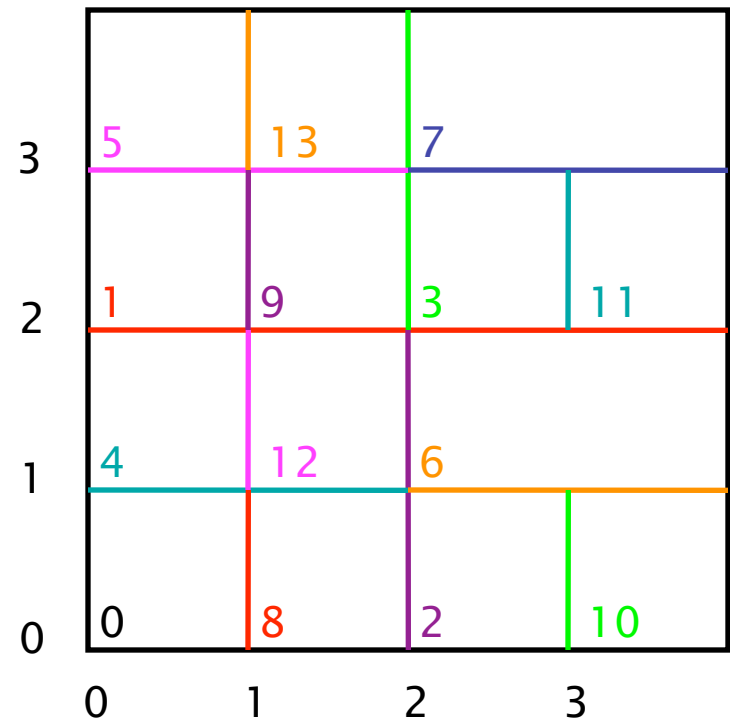
Colored lines:

- Red:** Horizontal line between rows 1 and 2; vertical line between columns 0 and 1.
- Green:** Horizontal line between rows 2 and 3; vertical line between columns 2 and 3.
- Blue:** Horizontal line between rows 3 and 4.
- Teal:** Horizontal line between rows 0 and 1; vertical line between columns 3 and 4.
- Magenta:** Horizontal line between rows 2 and 3; vertical line between columns 1 and 2.
- Orange:** Horizontal line between rows 1 and 2.
- Purple:** Vertical line between columns 2 and 3.

Key Points:

1. **Order preserving**, i.e., always split next smallest-numbered cell.
2. **y-first reversed bit interleaving** on partition indices
3. Count partition indices by distance from origin

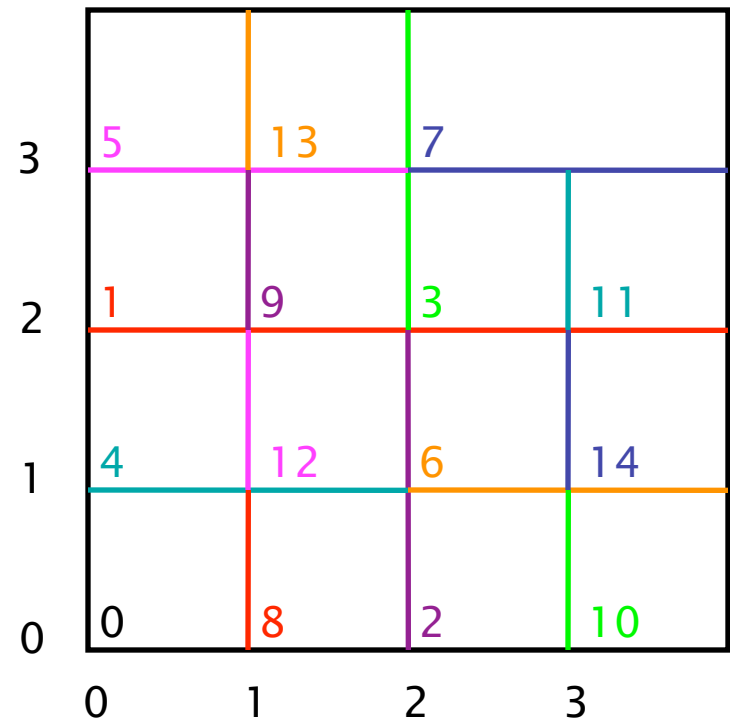
Split cell 5



Key Points:

1. **Order preserving**, i.e., always split next smallest-numbered cell.
2. **y-first reversed bit interleaving** on partition indices
3. Count partition indices by distance from origin

Split cell 6

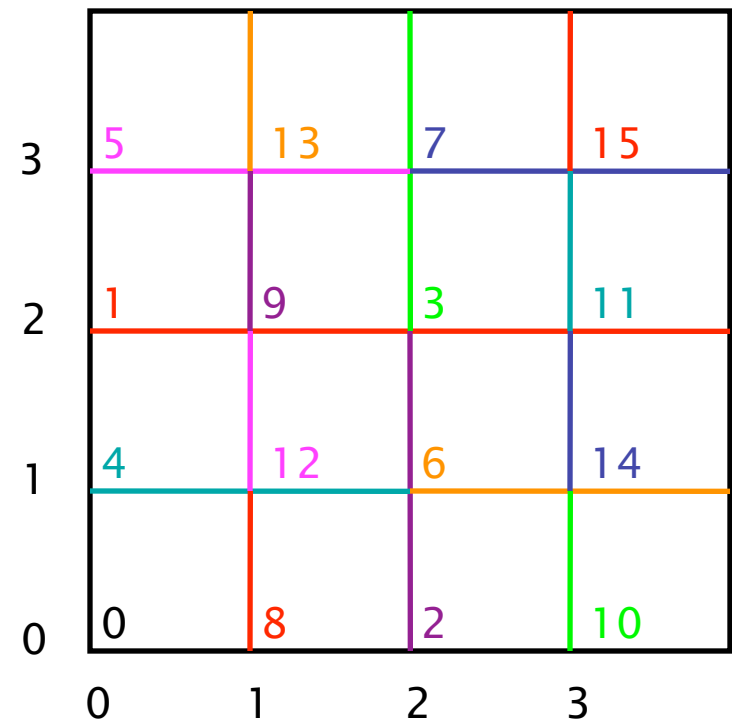


Key Points:

1. **Order preserving**, i.e., always split next smallest-numbered cell.
2. **y-first reversed bit interleaving** on partition indices
3. Count partition indices by distance from origin

Split cell 7

Total grid partition 4



Key Points:

1. **Order preserving**, i.e., always split next smallest-numbered cell.
2. **y-first reversed bit interleaving** on partition indices
3. Count partition indices by distance from origin

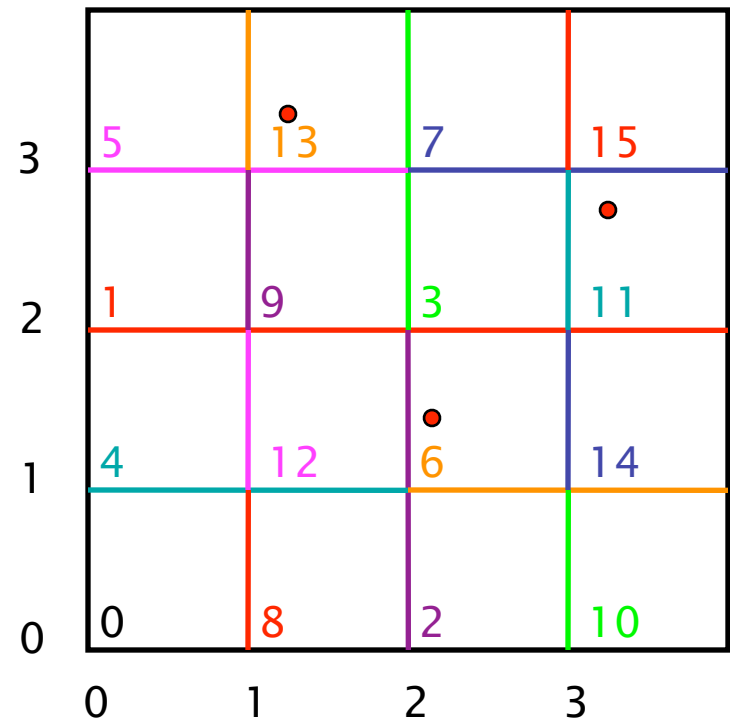
In what cell does (0.8, 0.7) lie?

x-partition index = $(3)_{10} = (11)_2$

y-partition index = $(2)_{10} = (10)_2$

Reverse bit interleave

$$= (1011)_2 = (11)_{10}$$



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MAIN POINTS:

Variant of Linear Hashing

Split a slice completely before any cell in another slice.

Multidimensional Extendible Hashing (MDEH)

Properties:

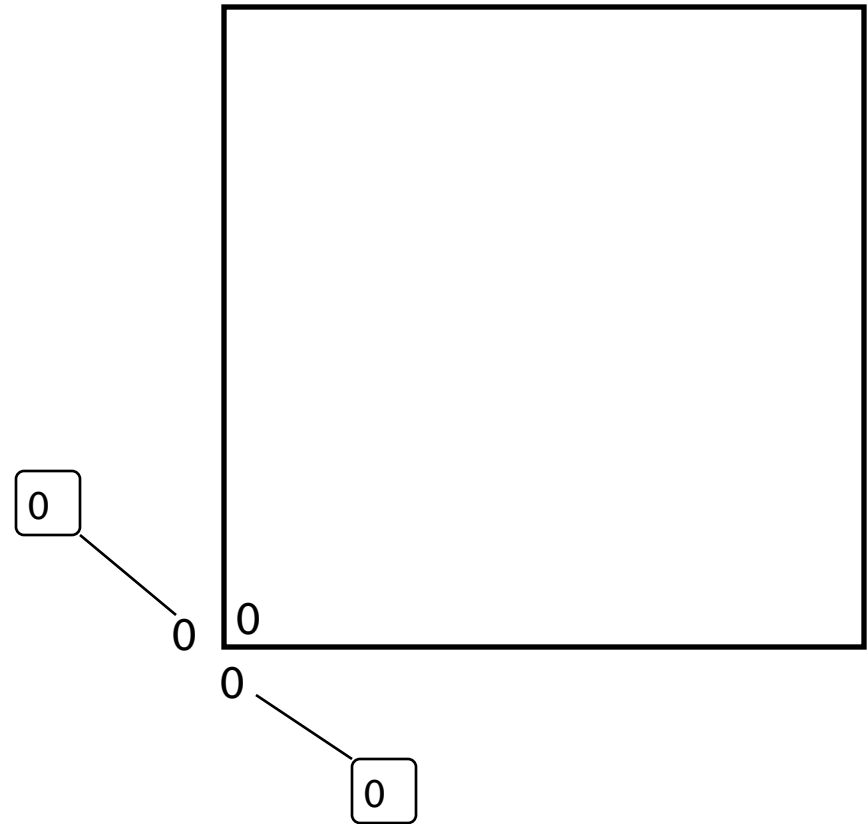
1. Linear hashing, split one cell at a time.
2. Complete one slice before starting the next.
3. Complete splitting along an axis before starting next.
4. Cycle through axes.
5. Embedding space based decomposition.
6. Split based on storage utilization factor threshold.
7. Partition Indices don't change from order of creation.
8. Use Linear Scales (tries) to track partition indices.
9. An *Expansion Index* points to next cell to be split.

MDEH

Linear scale on y -axis

Expansion index $(e_y, e_x) = (0, 0)$

Next to be split is cell 0.



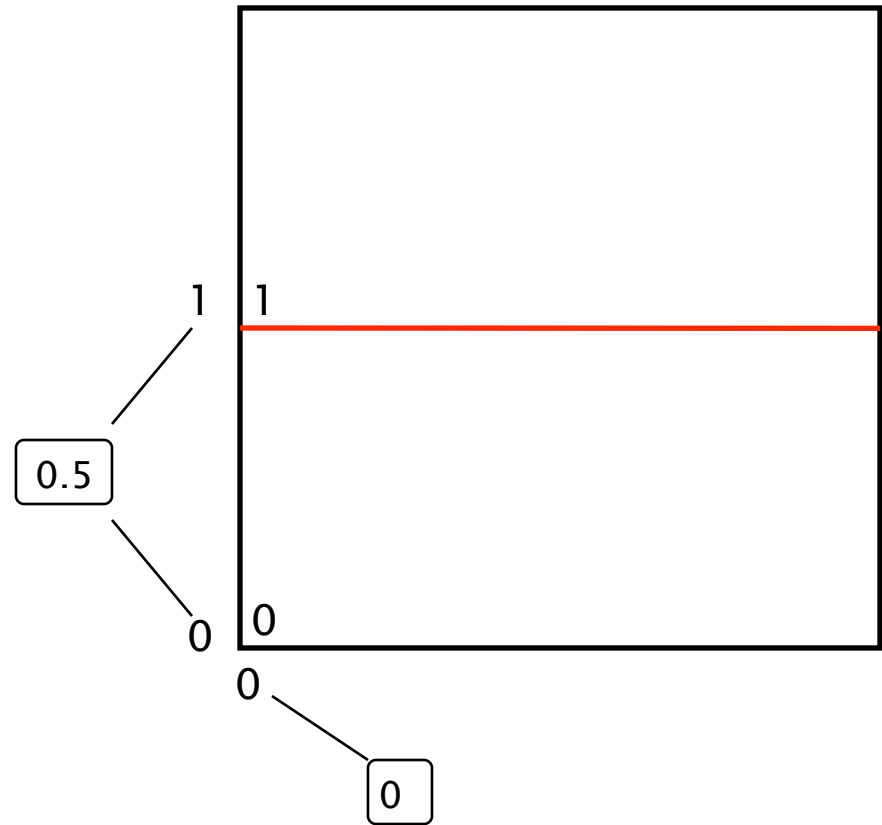
Linear scale on x -axis

MDEH

Linear scale on y -axis

Expansion index $(e_y, e_x) = (0, 0)$

Next to be split is cell 0.



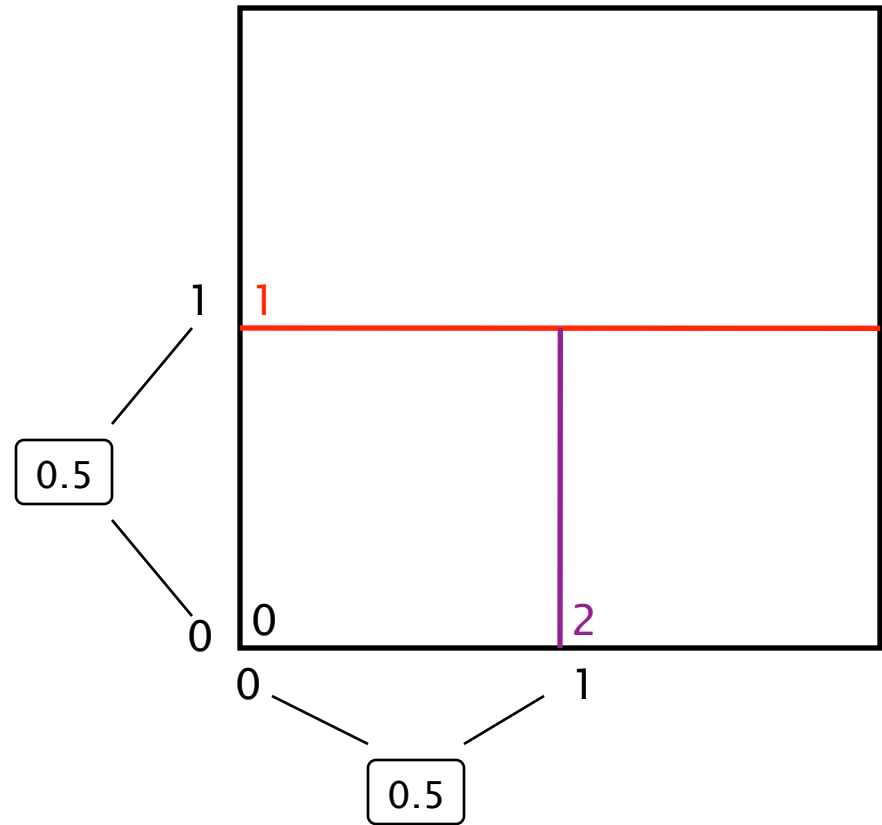
Linear scale on x -axis

MDEH

Linear scale on y -axis

Expansion index $(e_y, e_x) = (1, 0)$

Next to be split is cell 1.

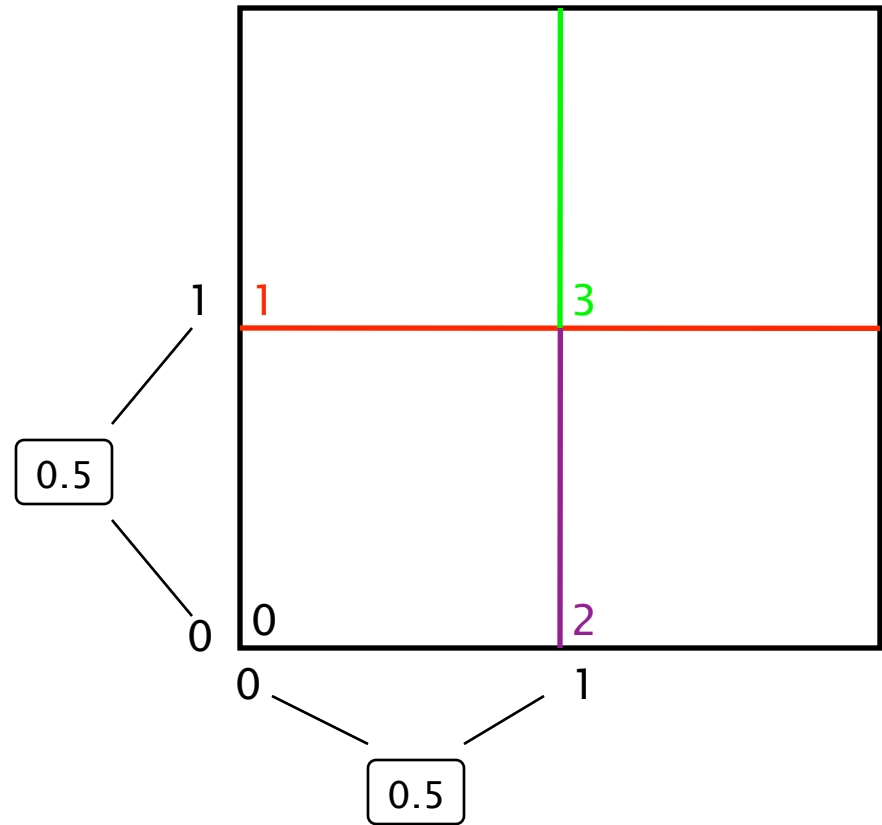


Linear scale on x -axis

Linear scale on y -axis

Expansion index $(e_y, e_x) = (0, 0)$

Next to be split is cell 0.

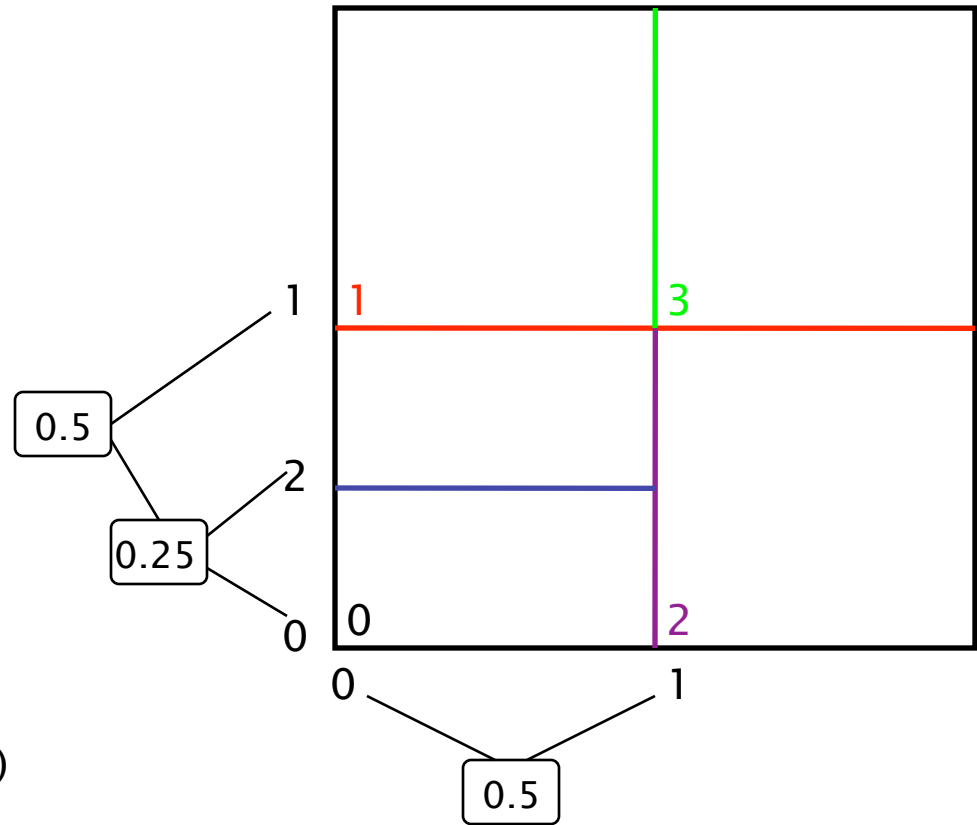


Linear scale on x -axis

Linear scale on y -axis

Expansion index $(e_y, e_x) = (0, 1)$

Next to be split is cell 2.

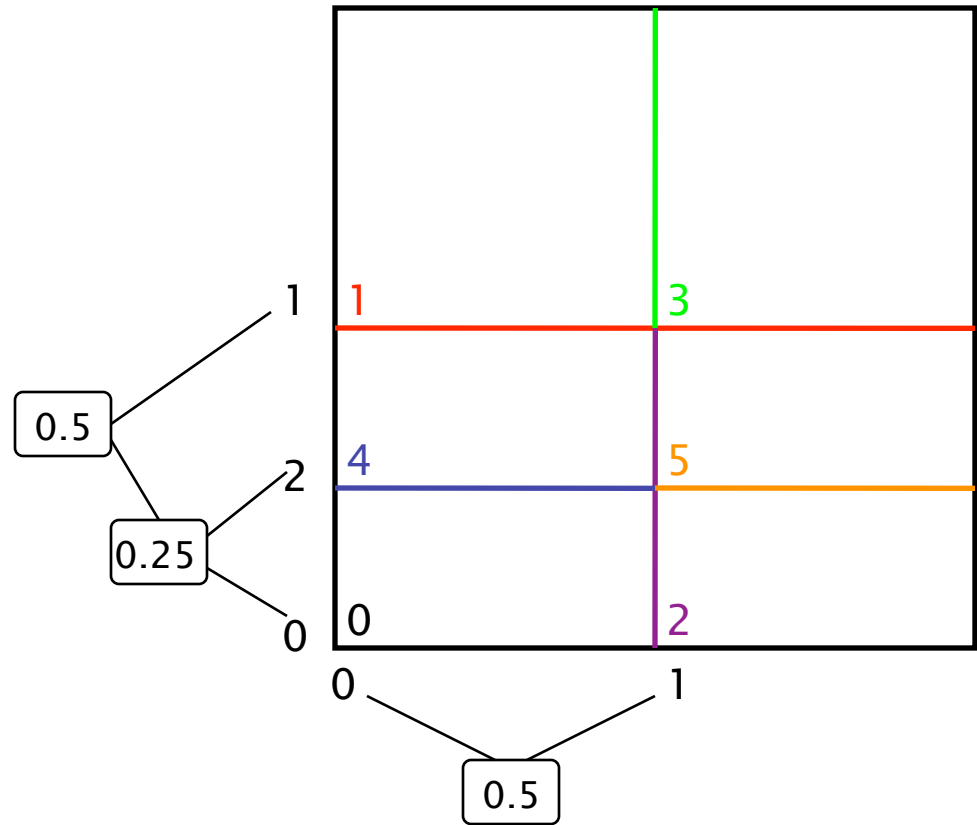


Linear scale on x -axis

Linear scale on y-axis

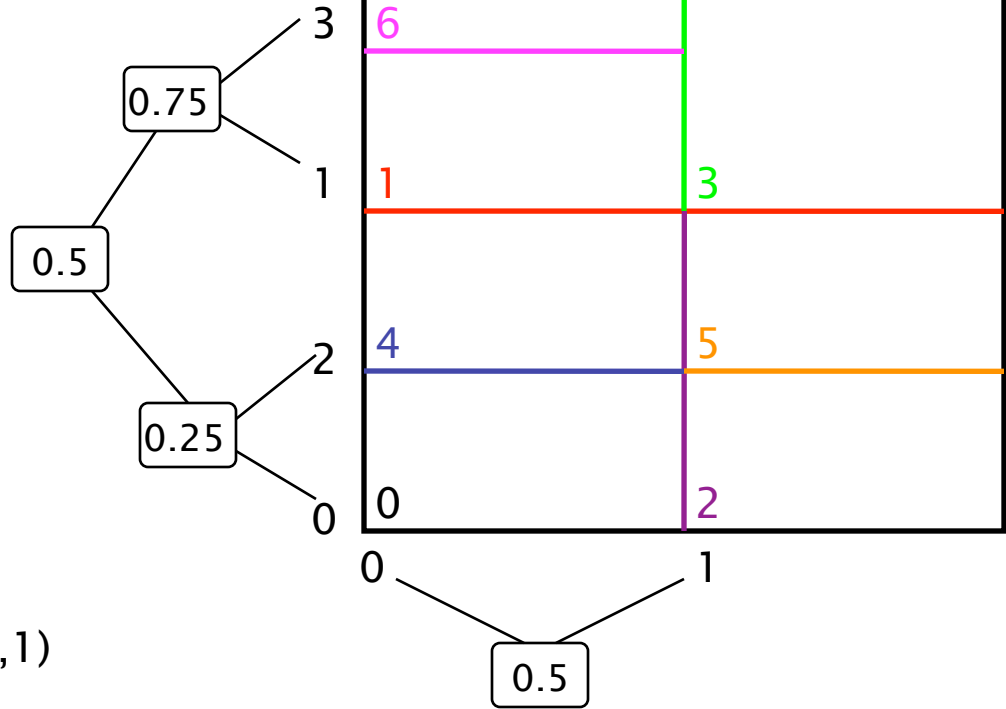
Expansion index $(e_y, e_x) = (1, 0)$

Next to be split is cell 1.



Linear scale on x-axis

Linear scale on y-axis

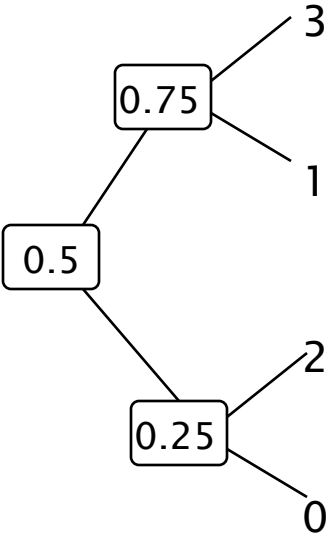


Expansion index $(e_y, e_x) = (01, 1)$

Next to be split is cell 3.

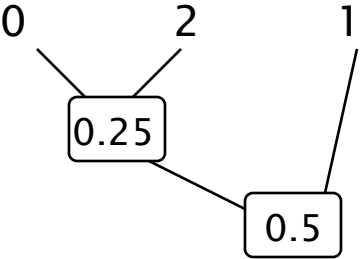
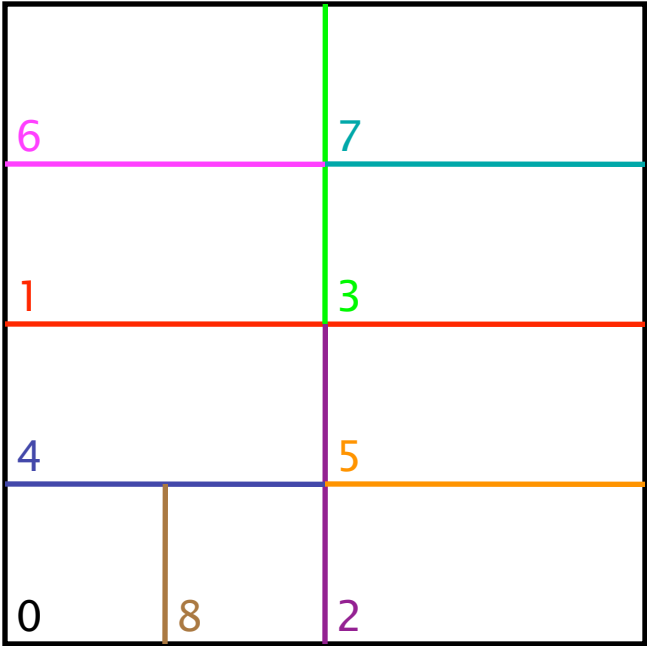
Linear scale on x-axis

Linear scale on y-axis



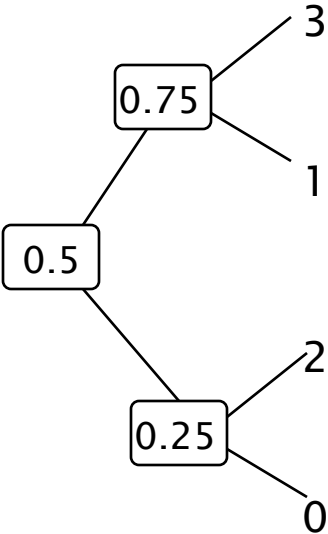
Expansion index $(e_y, e_x) = (01,0)$

Next to be split is cell 1.



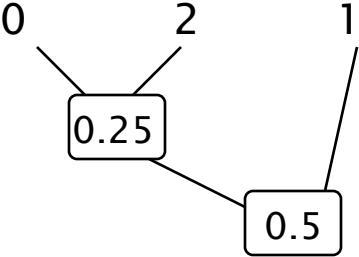
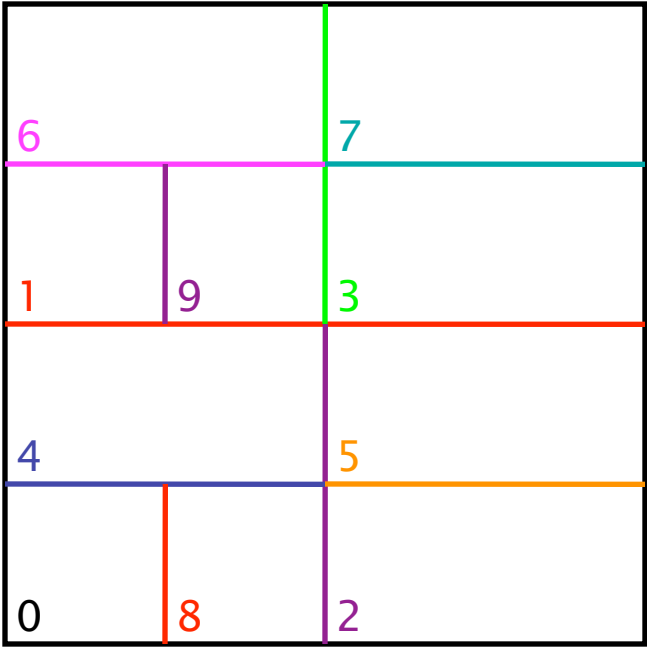
Linear scale on x-axis

Linear scale on y-axis



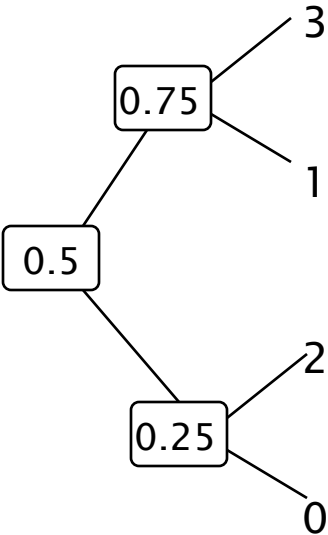
Expansion index $(e_y, e_x) = (10,0)$

Next to be split is cell 4.



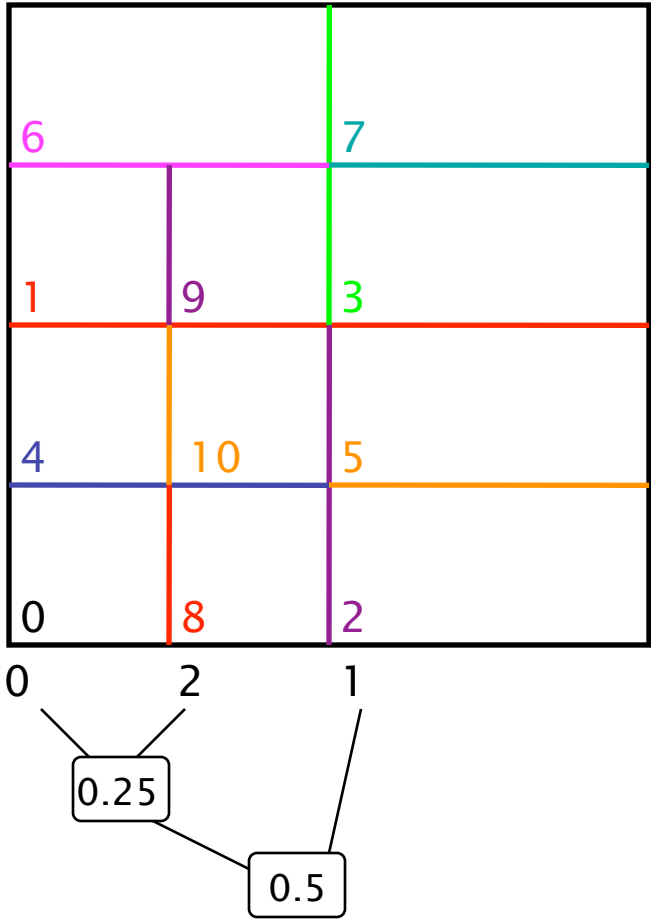
Linear scale on x-axis

Linear scale on y-axis



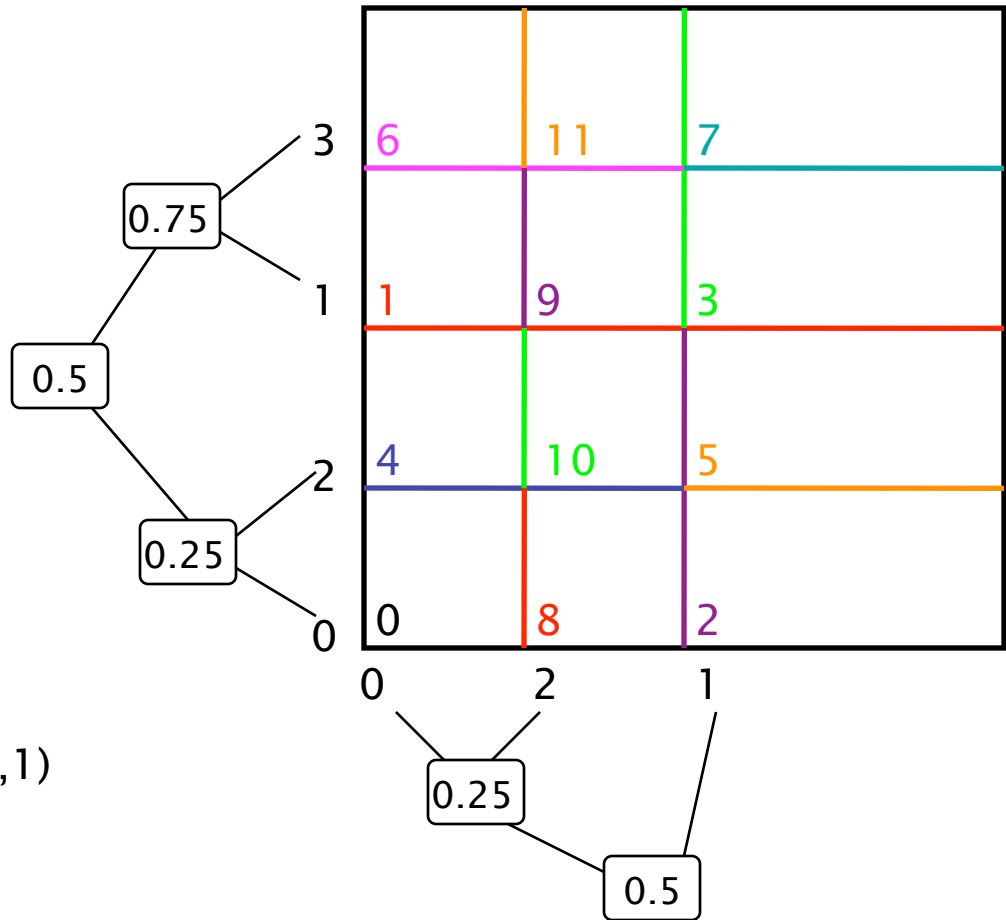
Expansion index $(e_y, e_x) = (11, 0)$

Next to be split is cell 6.



Linear scale on x-axis

Linear scale on y-axis



Expansion index $(e_y, e_x) = (0, 1)$

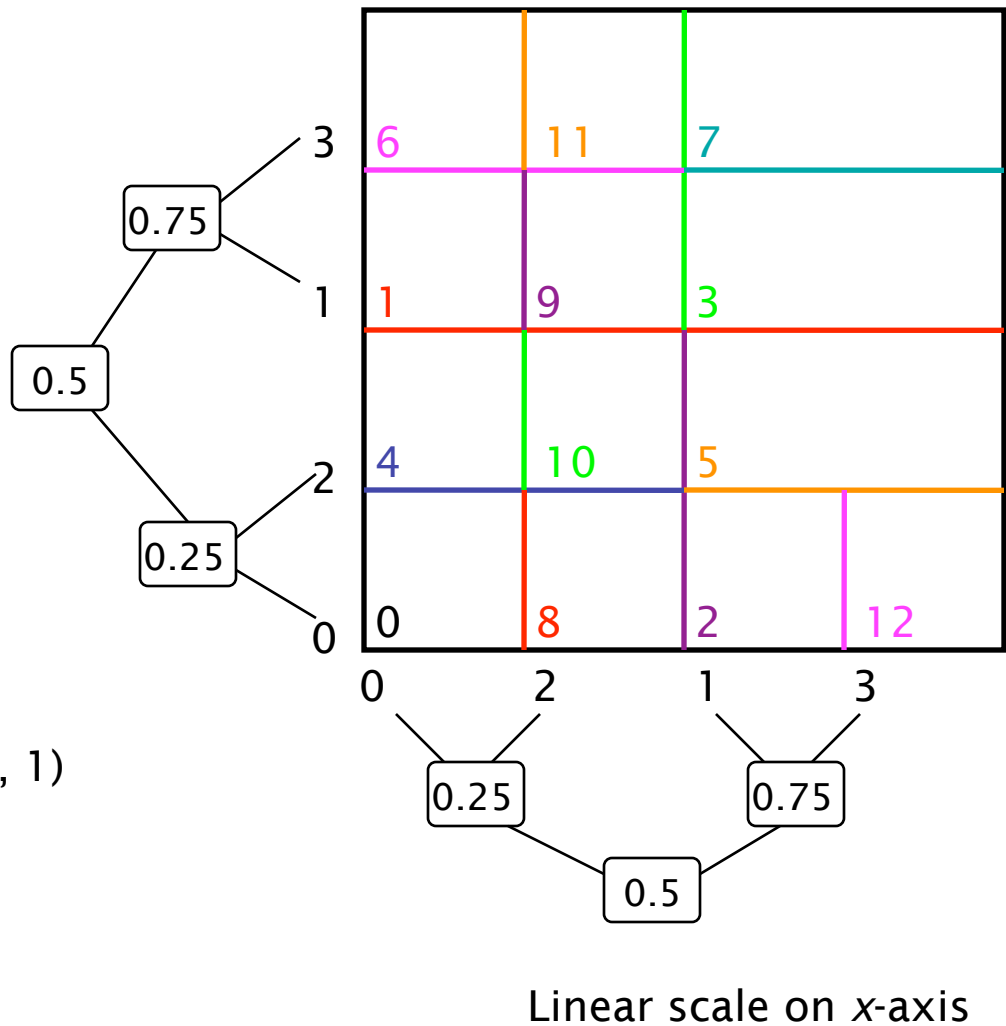
Next to be split is cell 2.

Linear scale on x-axis

Linear scale on y-axis

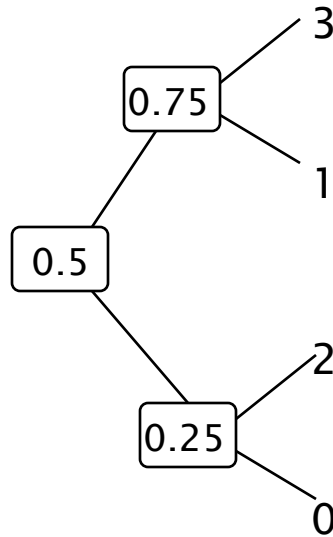
Expansion index $(e_y, e_x) = (01, 1)$

Next to be split is cell 3.



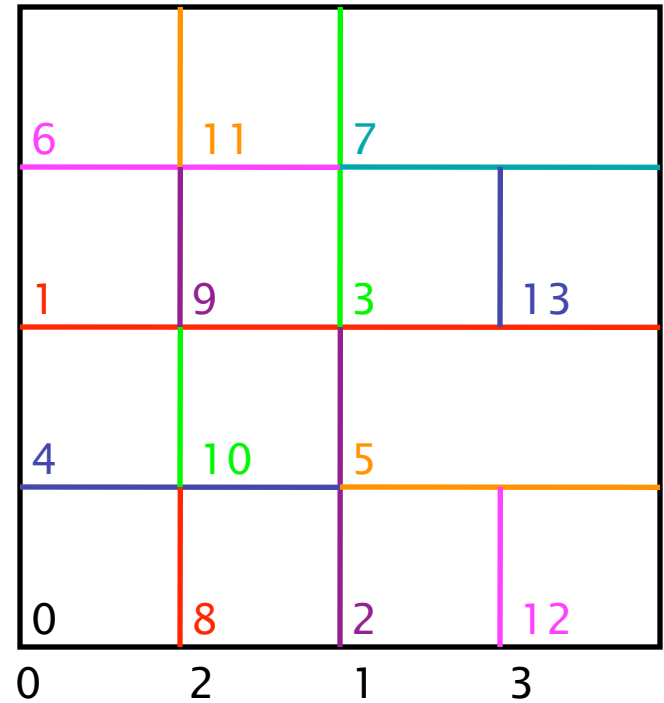
MDEH

Linear scale on y-axis

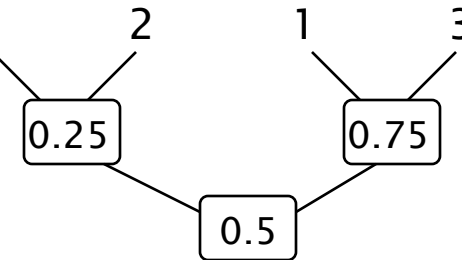


Expansion index $(e_y, e_x) = (10, 1)$

Next to be split is cell 5.

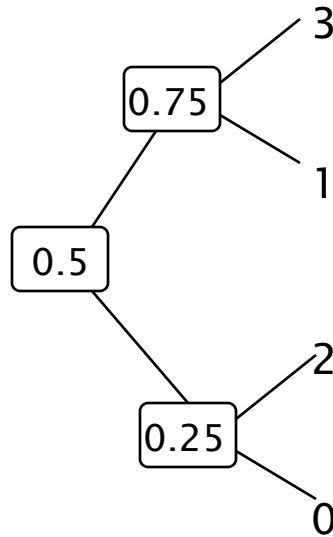


Linear scale on x-axis



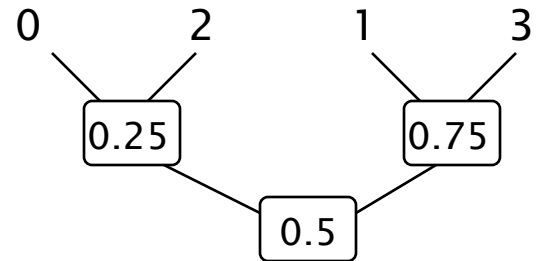
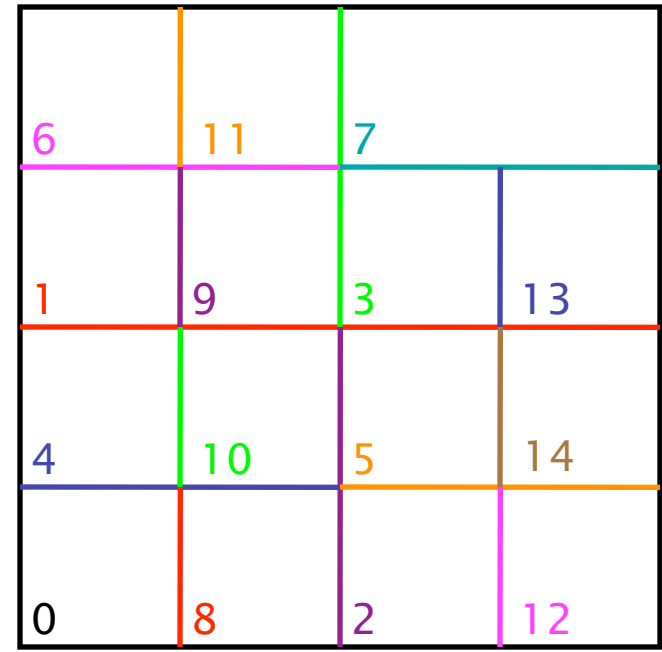
MDEH

Linear scale on y-axis



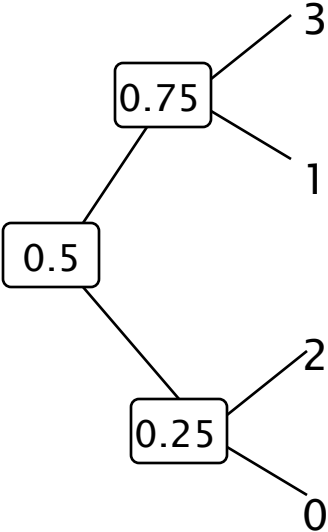
Expansion index $(e_y, e_x) = (11, 1)$

Next to be split is cell 7.



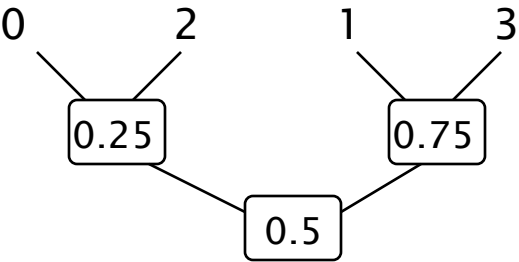
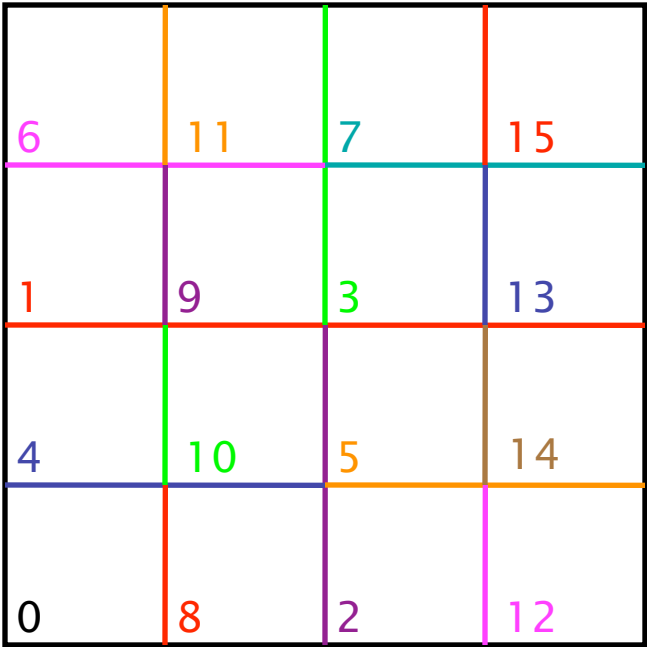
Linear scale on x-axis

Linear scale on y-axis



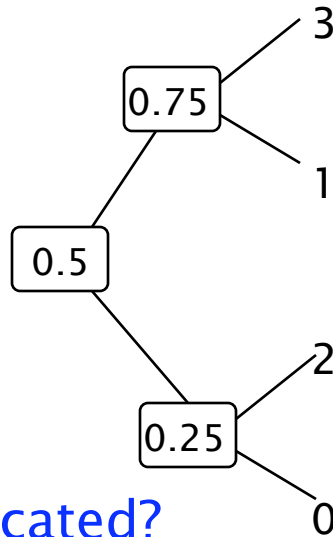
Expansion index $(e_y, e_x) = (00, 00)$

Next to be split is cell 0.



Linear scale on x-axis

Linear scale on y-axis



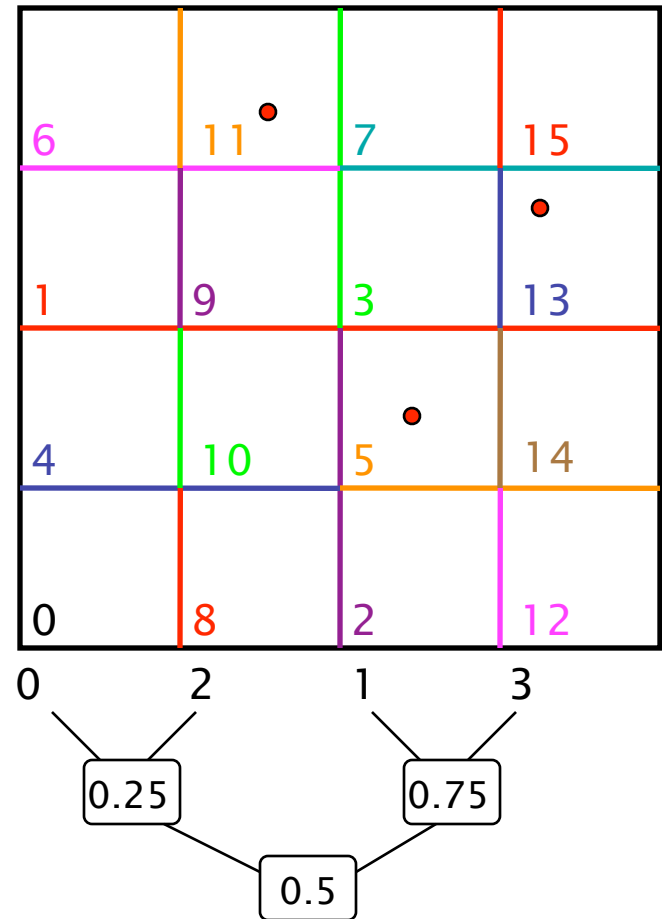
In what cell is (0.8, 0.7) located?

Linear scales lead to

x-partition index = $(3)_{10} = (11)_2$

y-partition index = $1 = (01)_2$

Concatenate: $(1101)_2 = (13)_{10}$



Linear scale on x-axis

Outline

Introduction, some basic principles

Linear Hashing with Reversed Bit Interleaving (LHRBI)

Multidimensional Extendible Hashing (MDEH)

 **Comparison of LHRBI and MDEH**

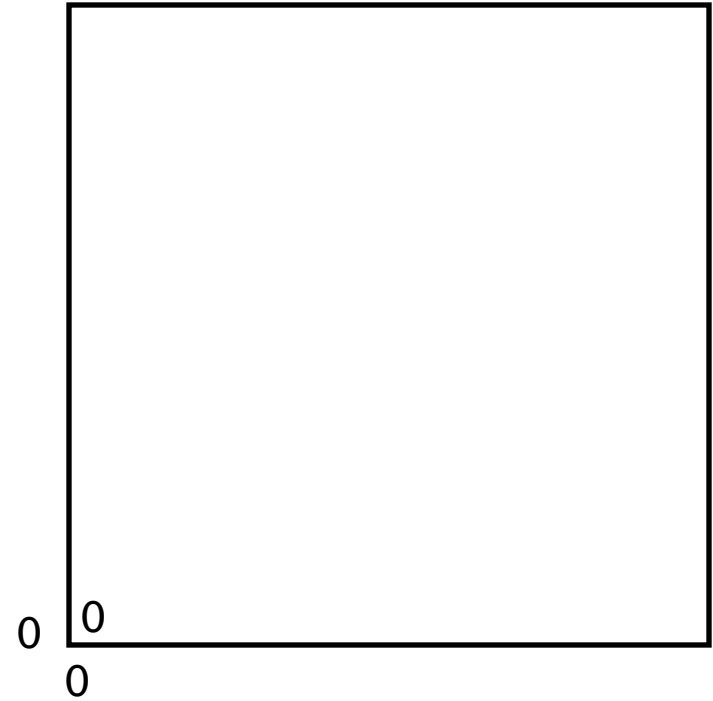
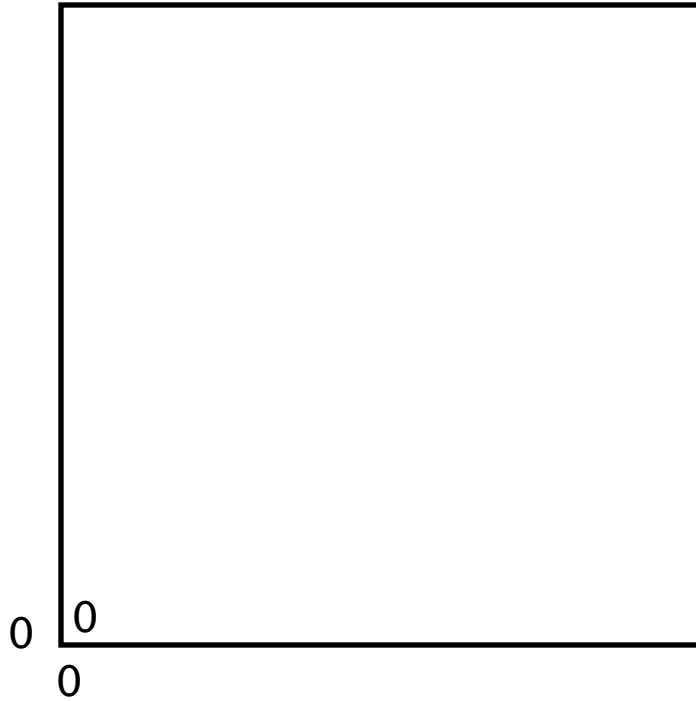
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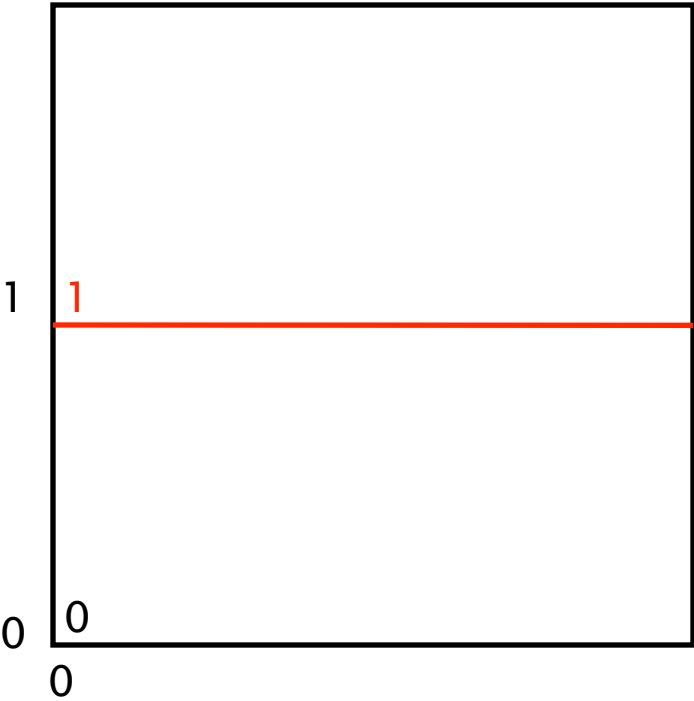
LHRBI vs. MDEH



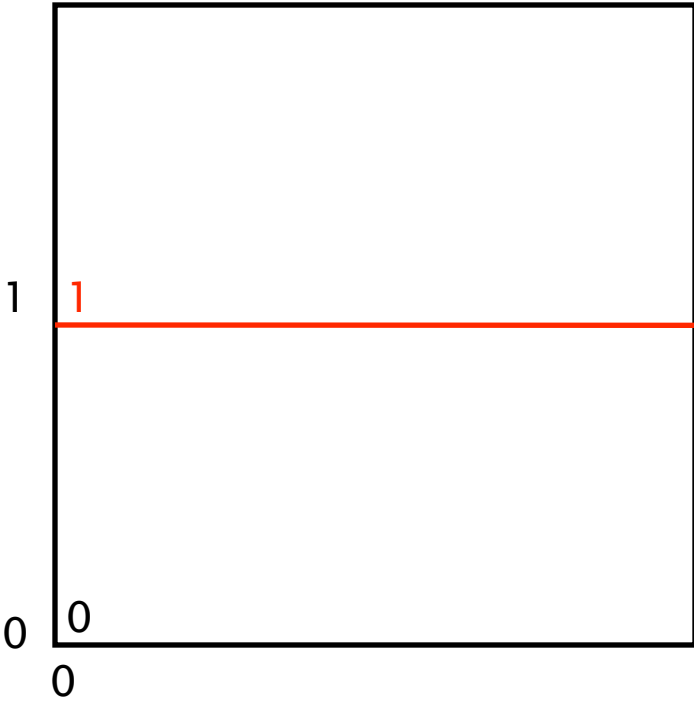
Key Point:

**Differences due to choice of how to
order cells/splittings.**

LHRBI vs. MDEH

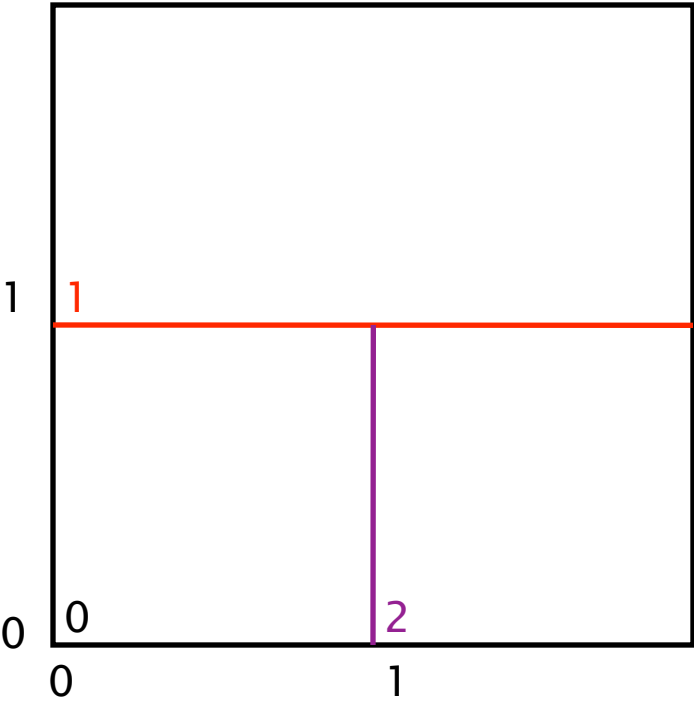


LHRB
I

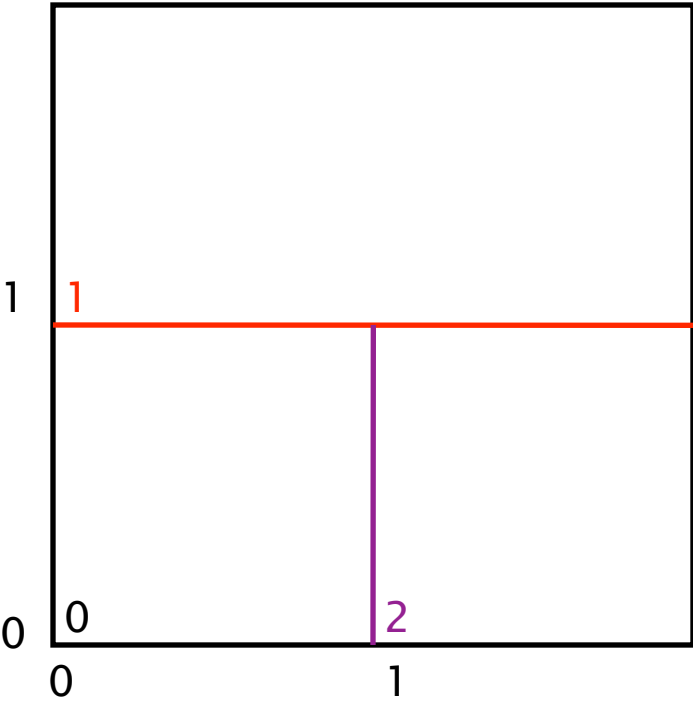


MDE
H

LHRBI vs. MDEH

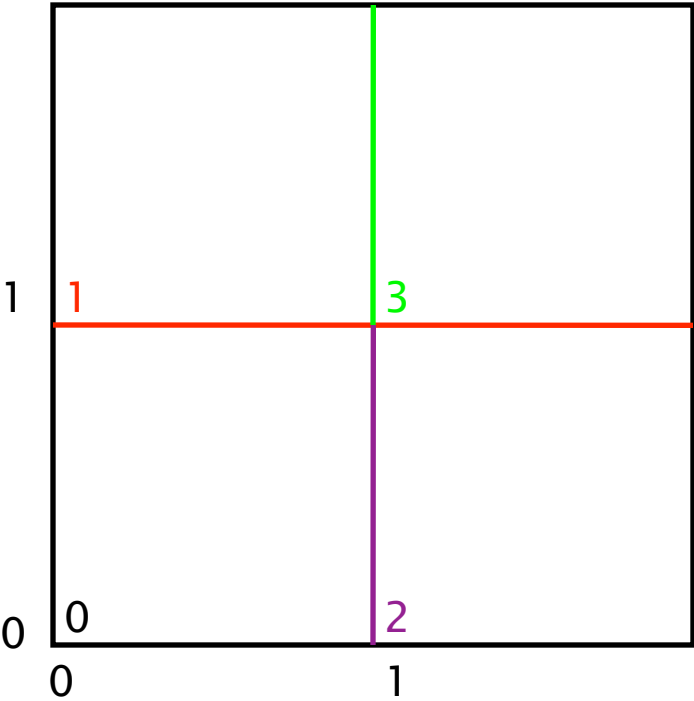


LHRB
I

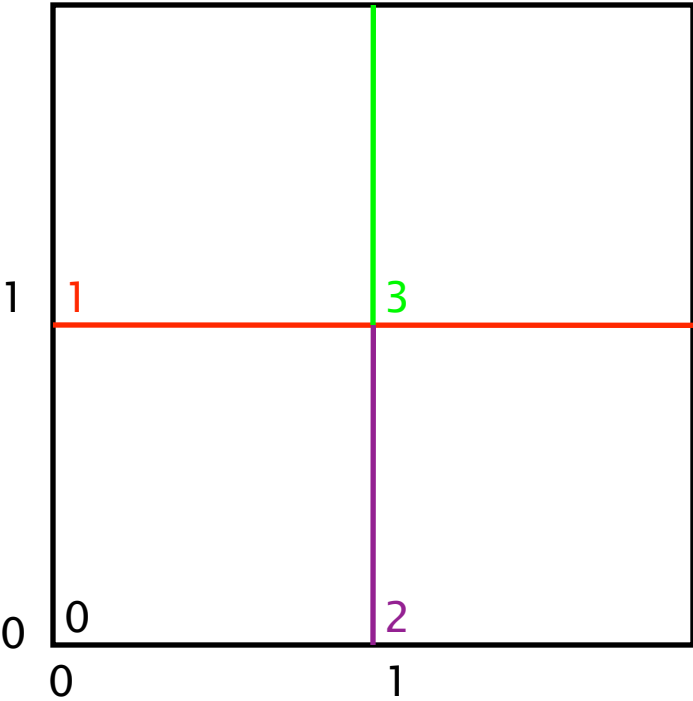


MDE
H

LHRBI vs. MDEH

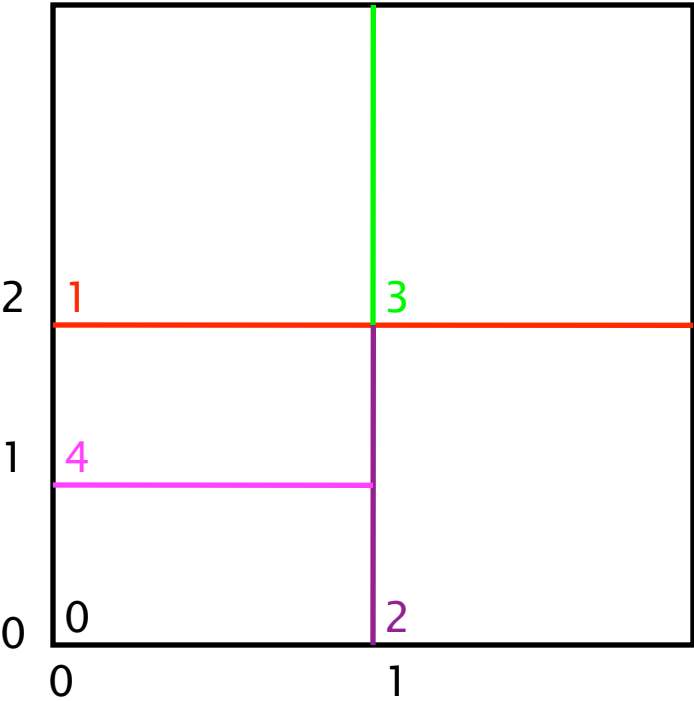


LHRB
I

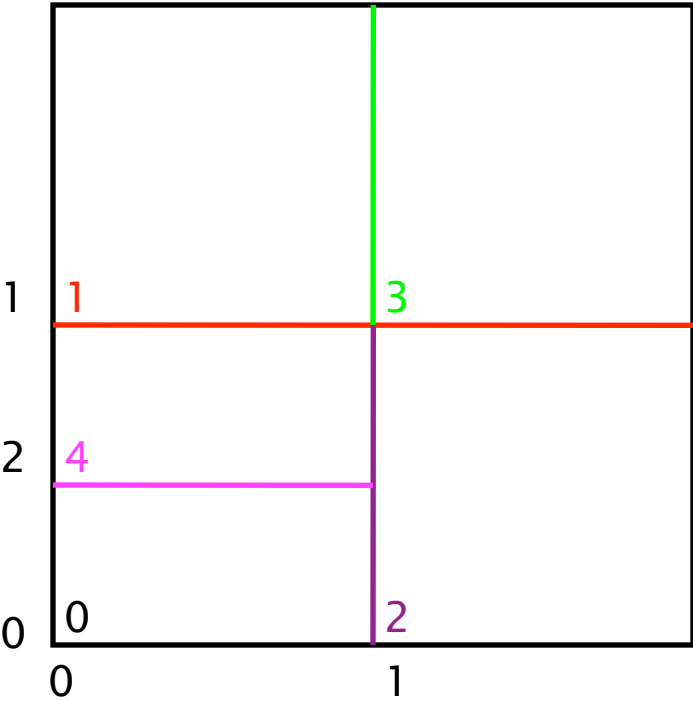


MDE
H

LHRBI vs. MDEH

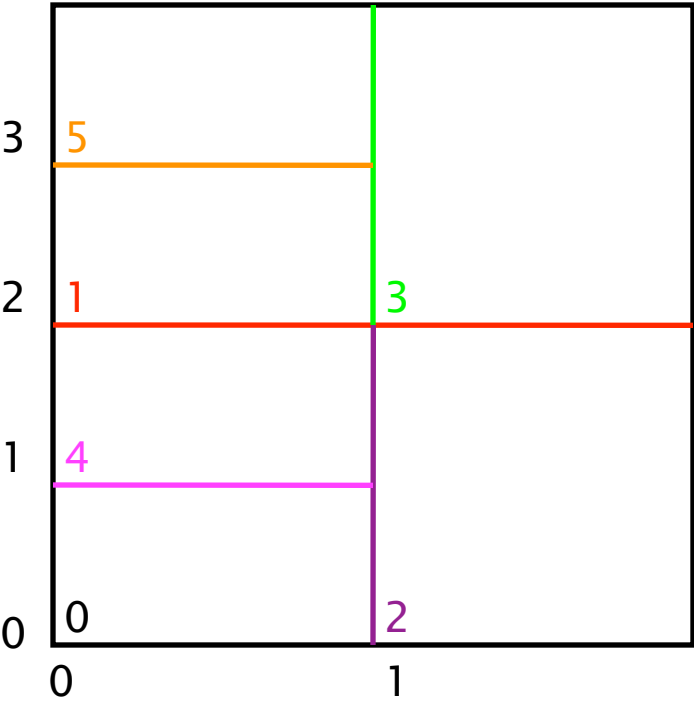


LHRB
I

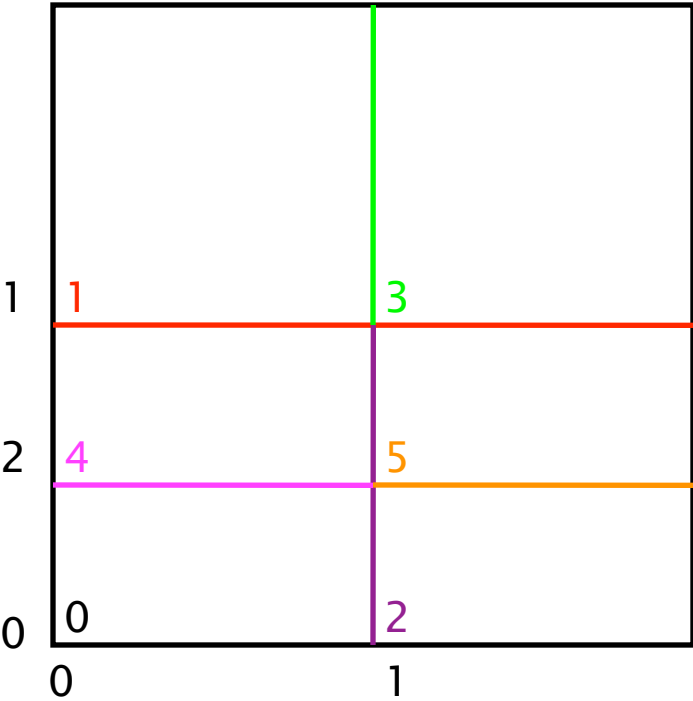


MDEH
H

LHRBI vs. MDEH

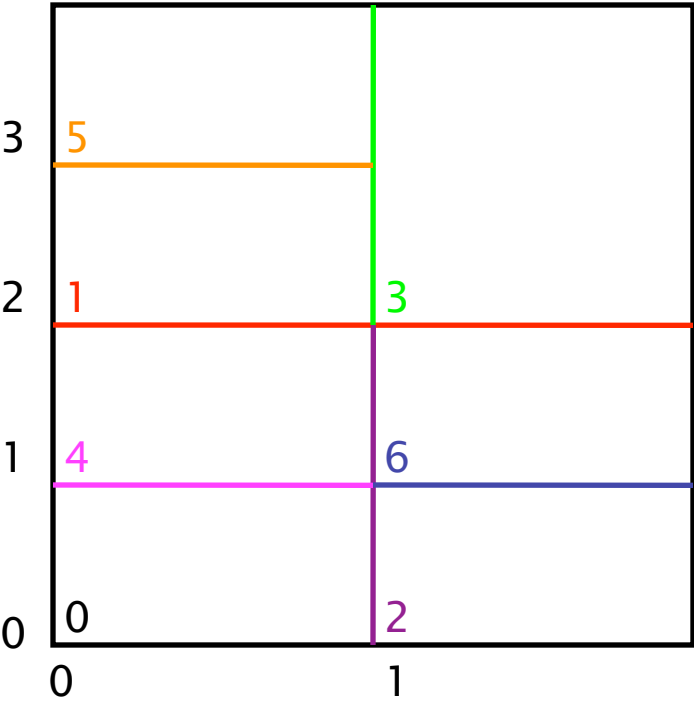


LHRB
I

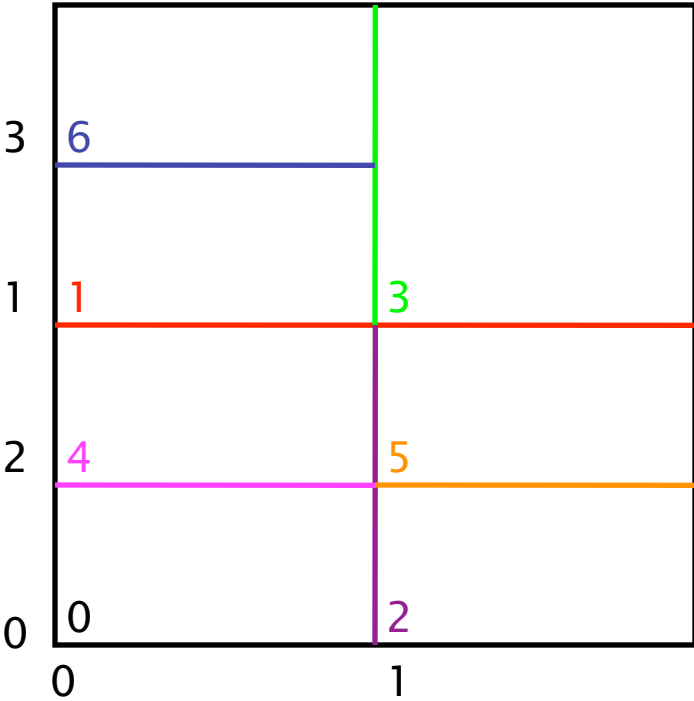


MDE
H

LHRBI vs. MDEH

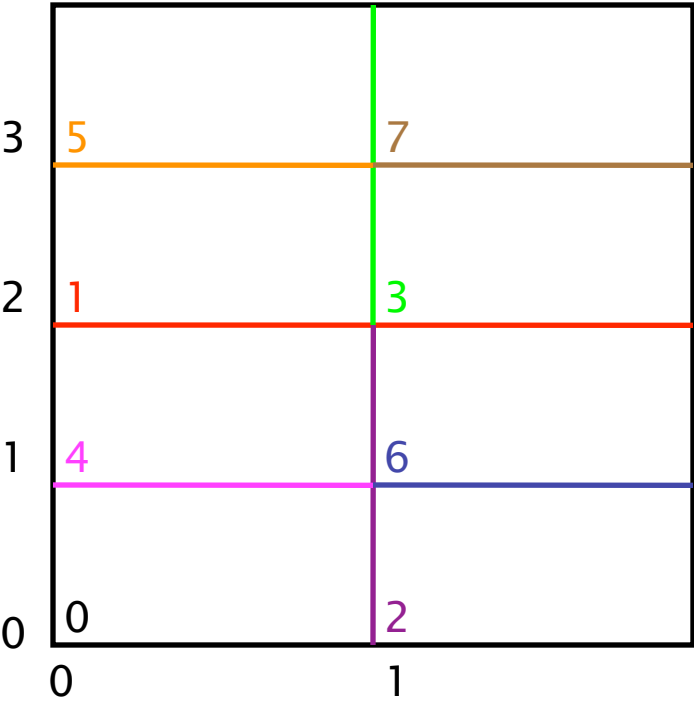


LHRB
I

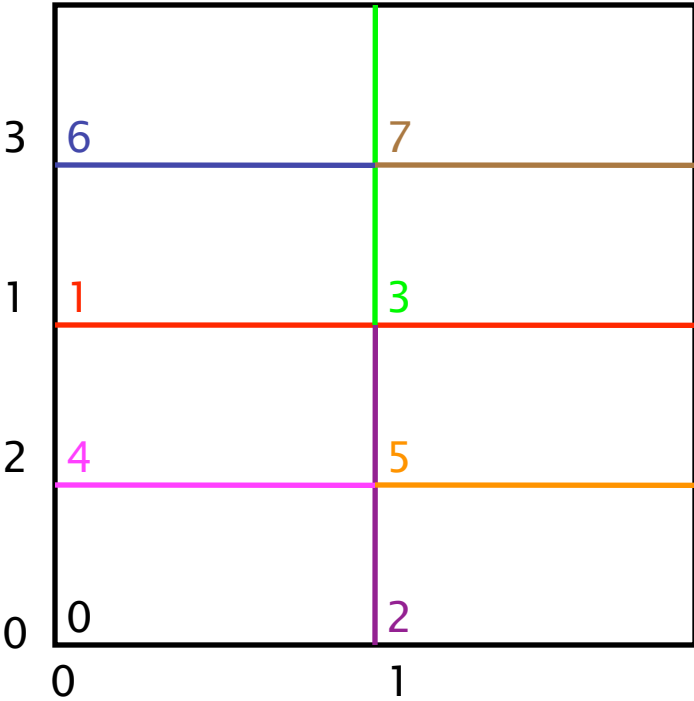


MDE
H

LHRBI vs. MDEH

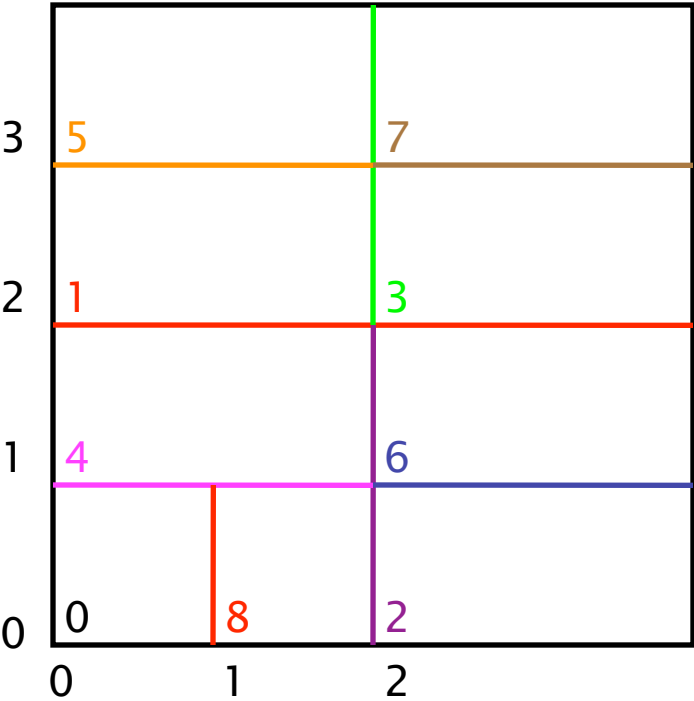


LHRB
I

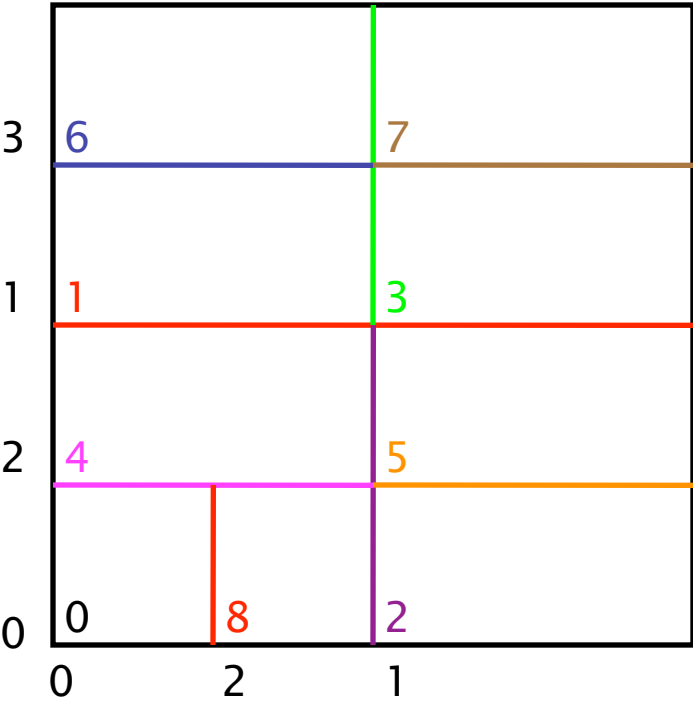


MDE
H

LHRBI vs. MDEH

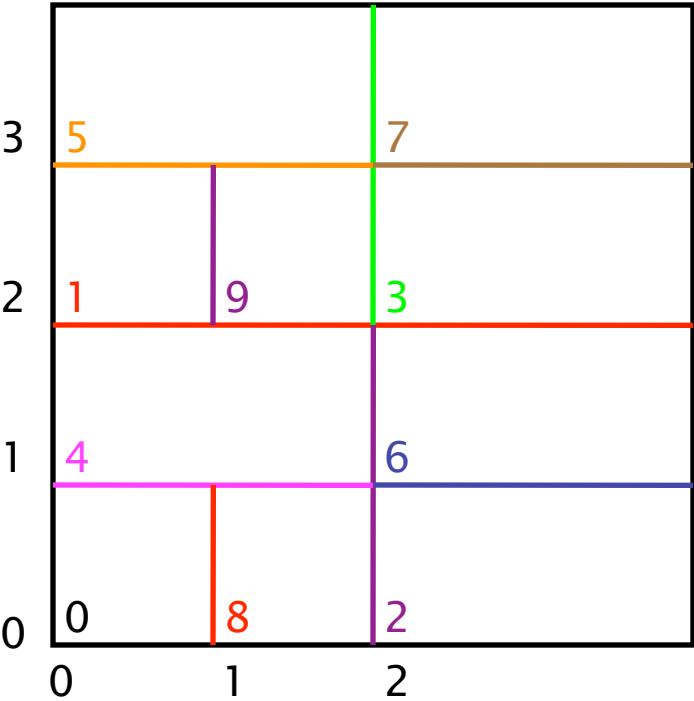


LHRB
I

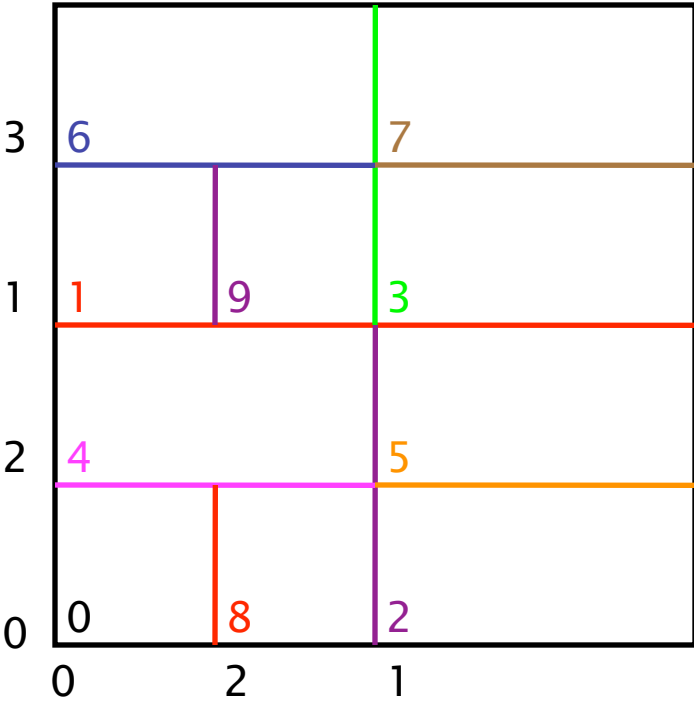


MDE
H

LHRBI vs. MDEH

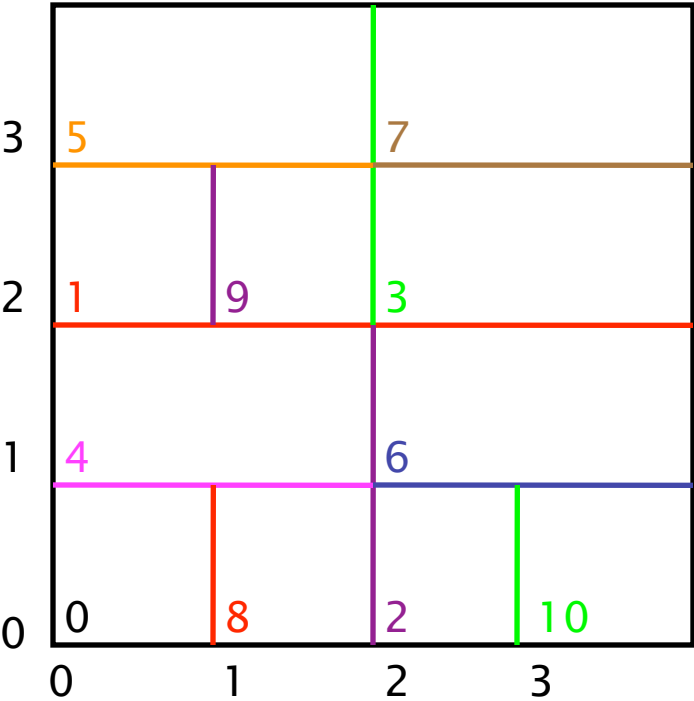


LHRB
I

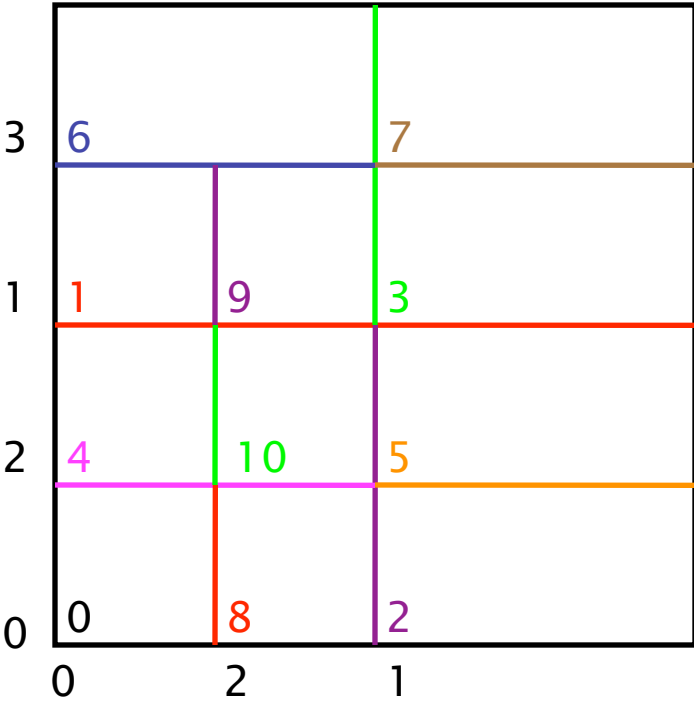


MDE
H

LHRBI vs. MDEH

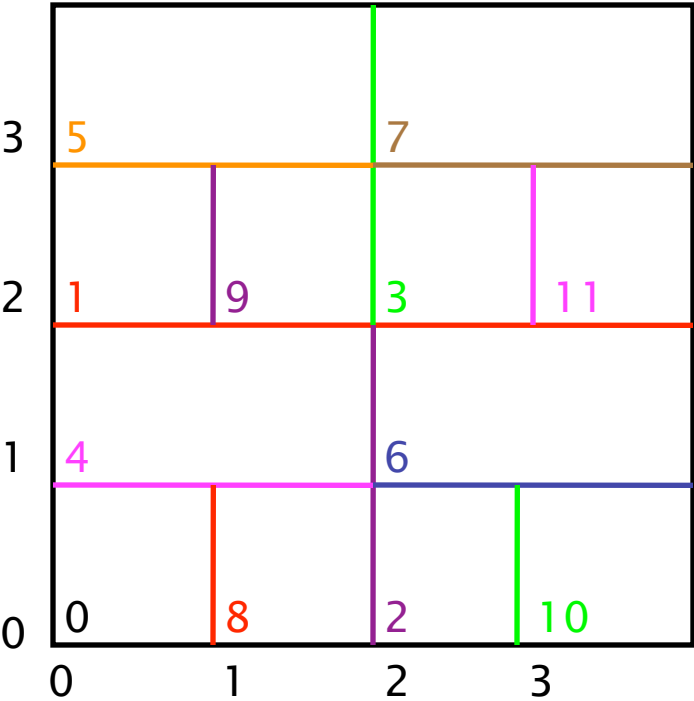


LHRB
I

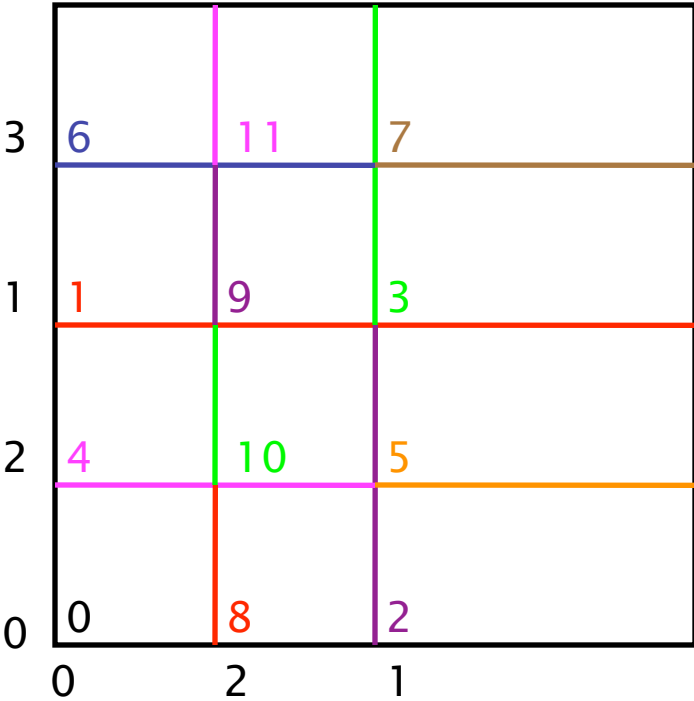


MDE
H

LHRBI vs. MDEH

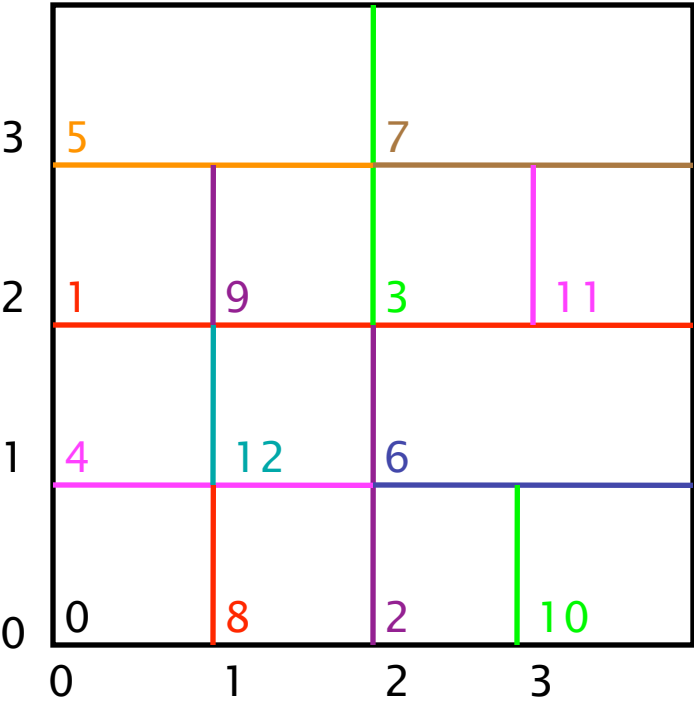


LHRB
I

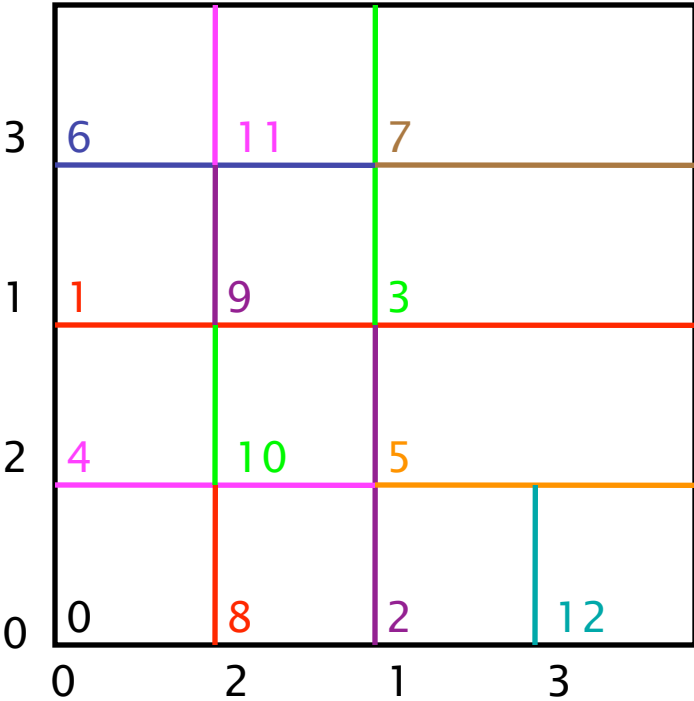


MDE
H

LHRBI vs. MDEH

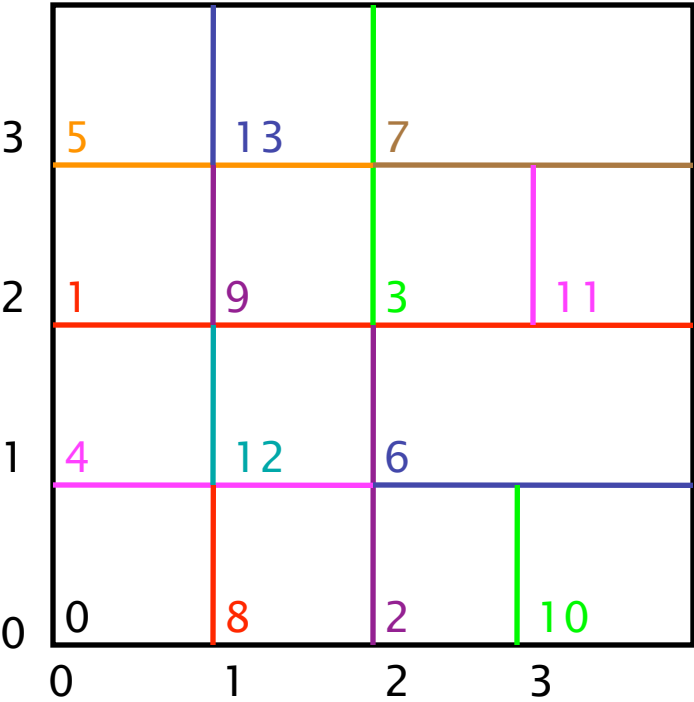


LHRB
I

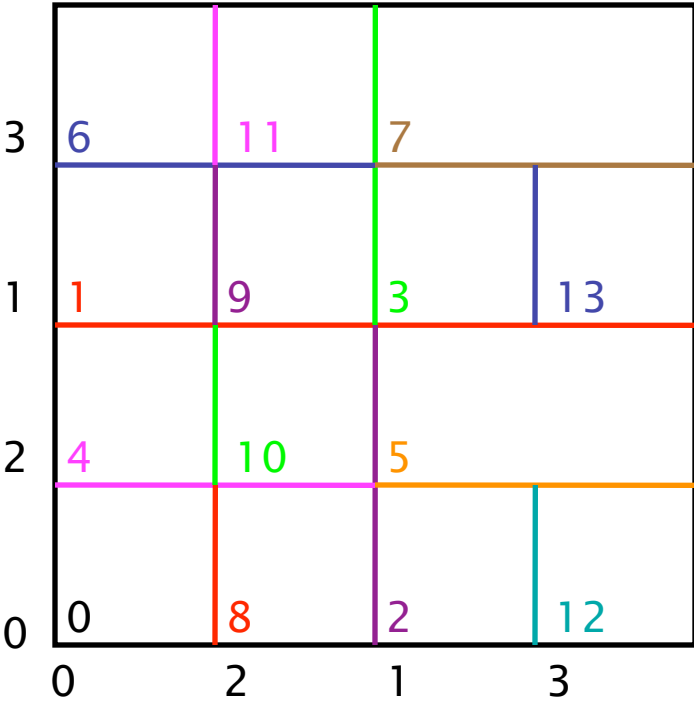


MDE
H

LHRBI vs. MDEH

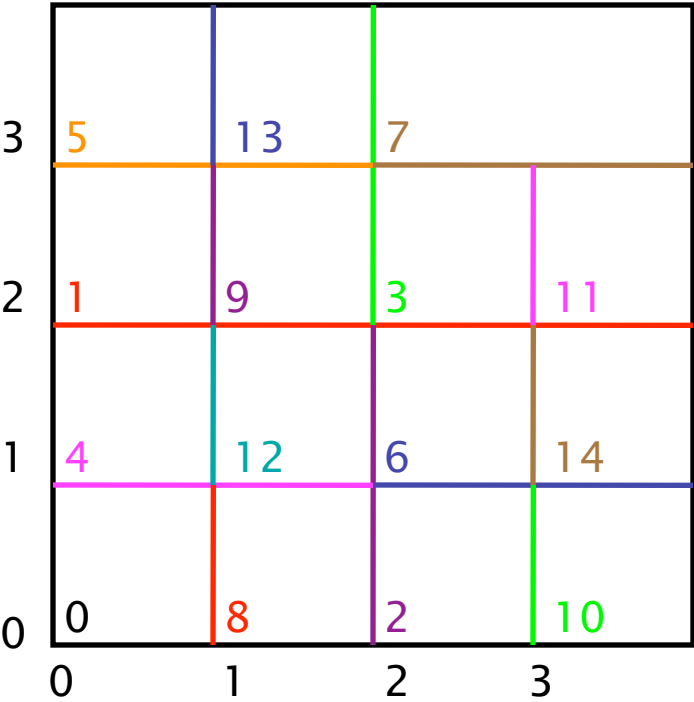


LHRB
I

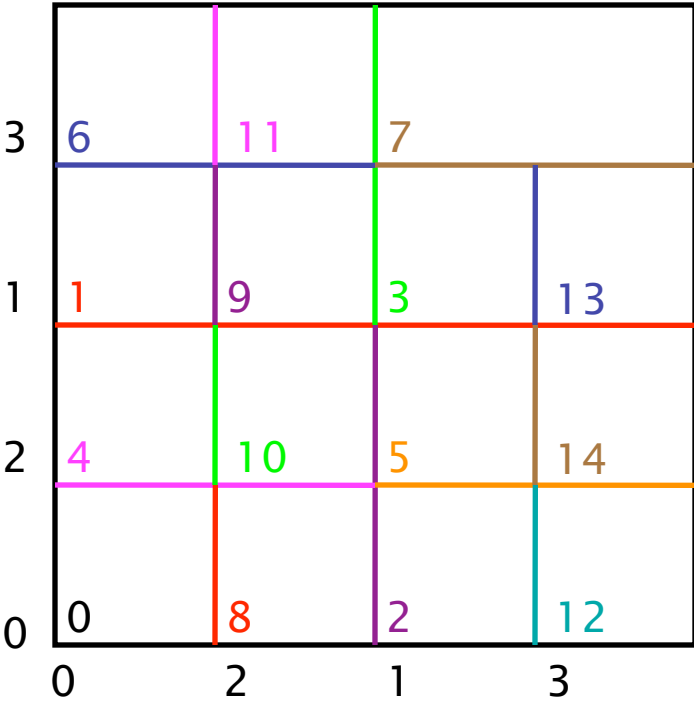


MDE
H

LHRBI vs. MDEH

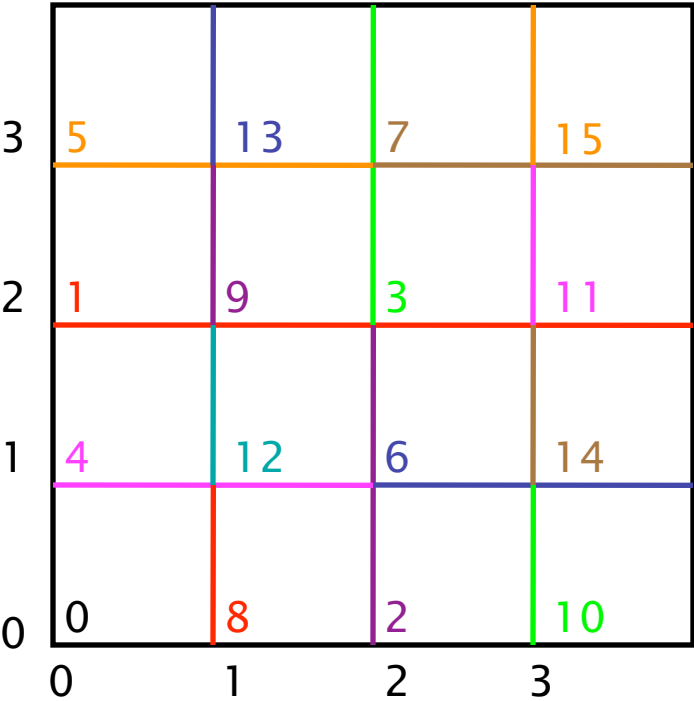


LHRB
I

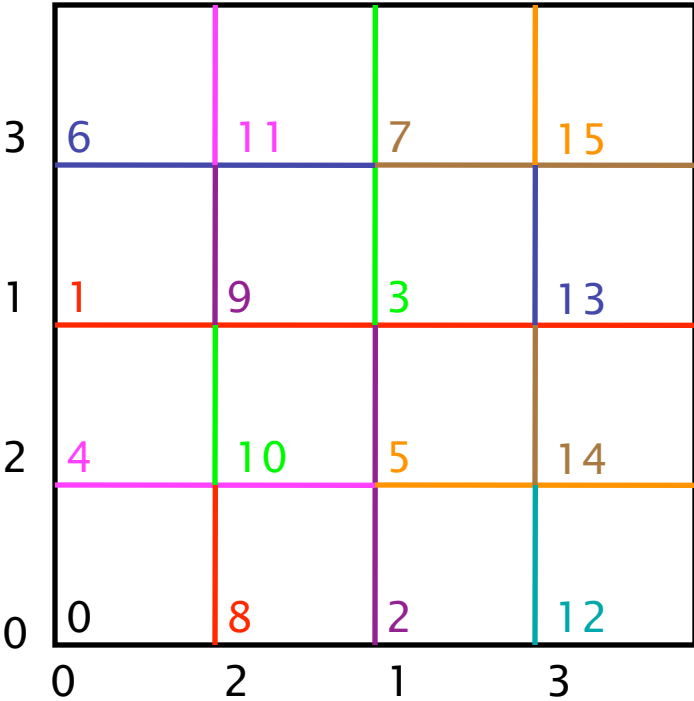


MDE
H

LHRBI vs. MDEH



LHRB
I



MDE
H

Outline

Introduction, some basic principles

Linear Hashing with Reversed Bit Interleaving (LHRBI)

Multidimensional Extendible Hashing (MDEH)

Comparison of LHRBI and MDEH

Quantile Hashing



Piecewise Linear Order Preserving (PLOP)

Dynamic Z Hashing

Linear Hashing with Partial Expansions (LHPE)

Quantile Hashing

MAIN POINTS.

Adaptive Variant of MDEH

Each Slice-Cut Divides Data in Half

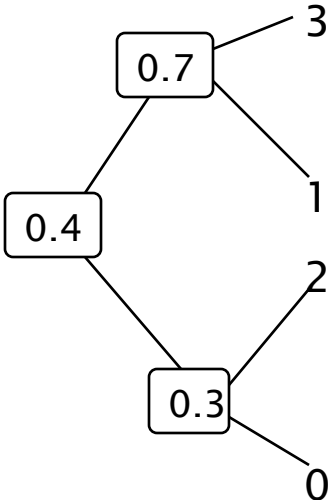
Quantile Hashing

The Specifics.

1. Splits and slices in same relative position and order.
2. Instead of midpoint, cut at estimated data median.
3. Cuts' locations in non-leaf nodes of linear scale.
4. Data based decomposition.

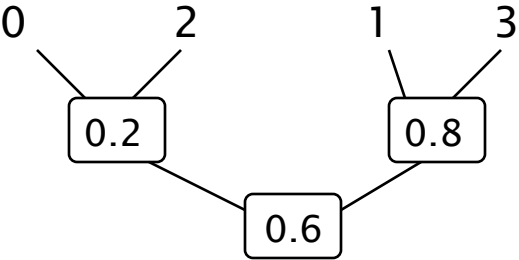
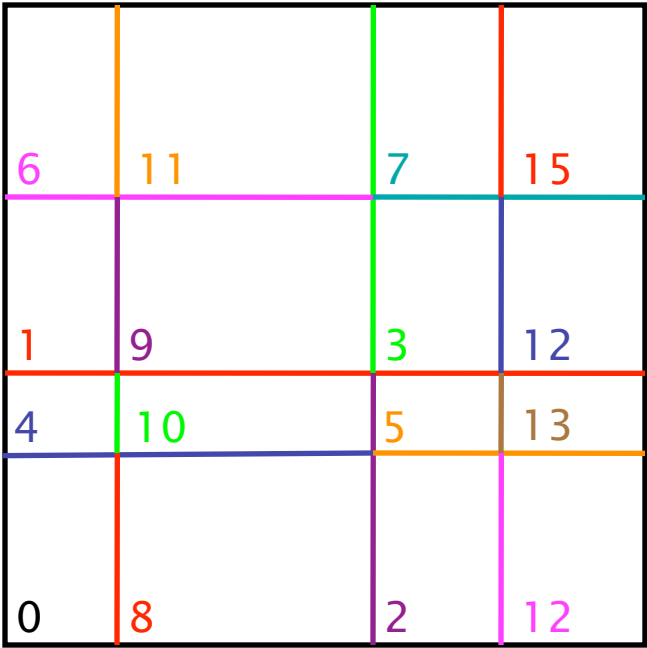
Quantile Hashing

Linear scale on y-axis



Expansion index $(e_y, e_x) = (00, 00)$

Next to be split is cell 0.



Linear scale on x-axis

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Dynamic Z Hashing

Linear Hashing with Partial Expansions (LHPE)

Piecewise Linear Order Preserving Hashing

MAIN POINTS.

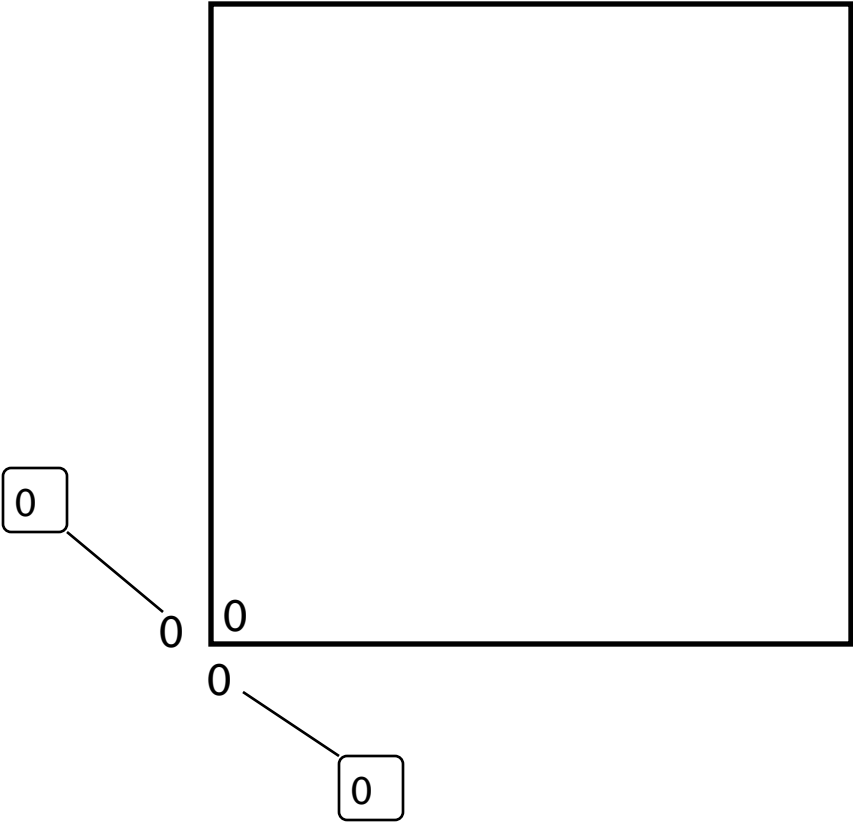
**Adaptive Generalization of Quantile Hashing
hence of MDEH.**

**May Split the Same Slice More than Once
During a Cycle**

Piecewise Linear Order Preserving Hashing

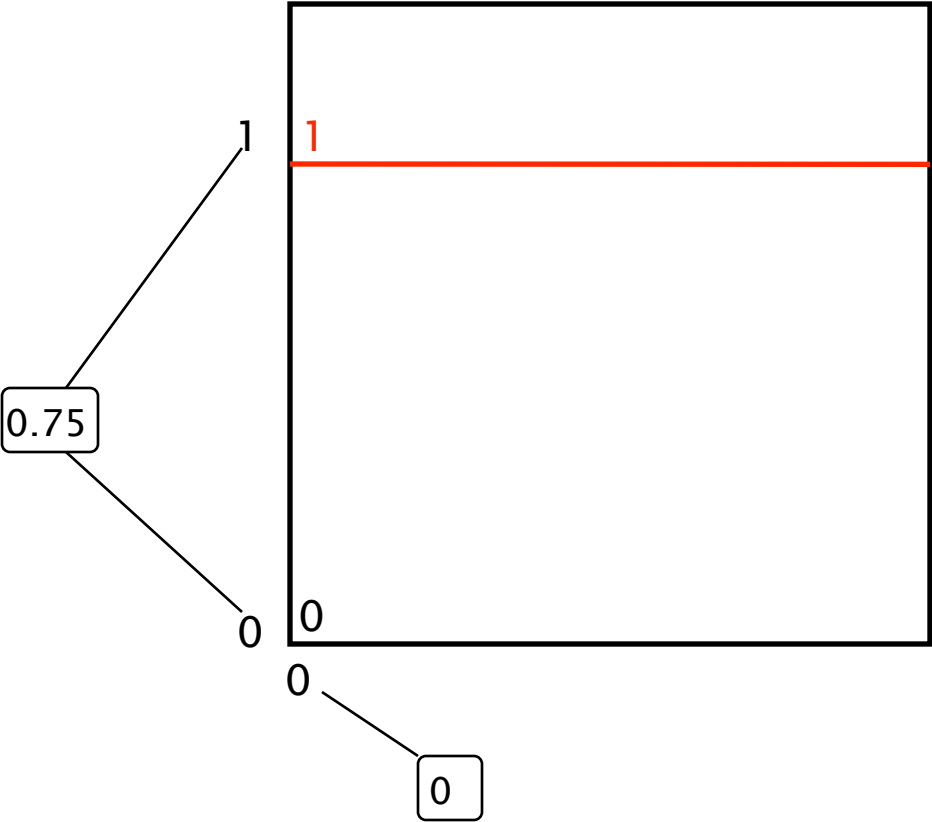
1. Data based decomposition.
2. Generalization of Quantile Hashing, more adaptive
3. Cycle through axes.
4. Each axis-cycle doubles number of cells.
5. Finish a slices before starting another (like MDEH).
6. Otherwise, slice-cuts are allowed anywhere.

Linear scale on y-axis



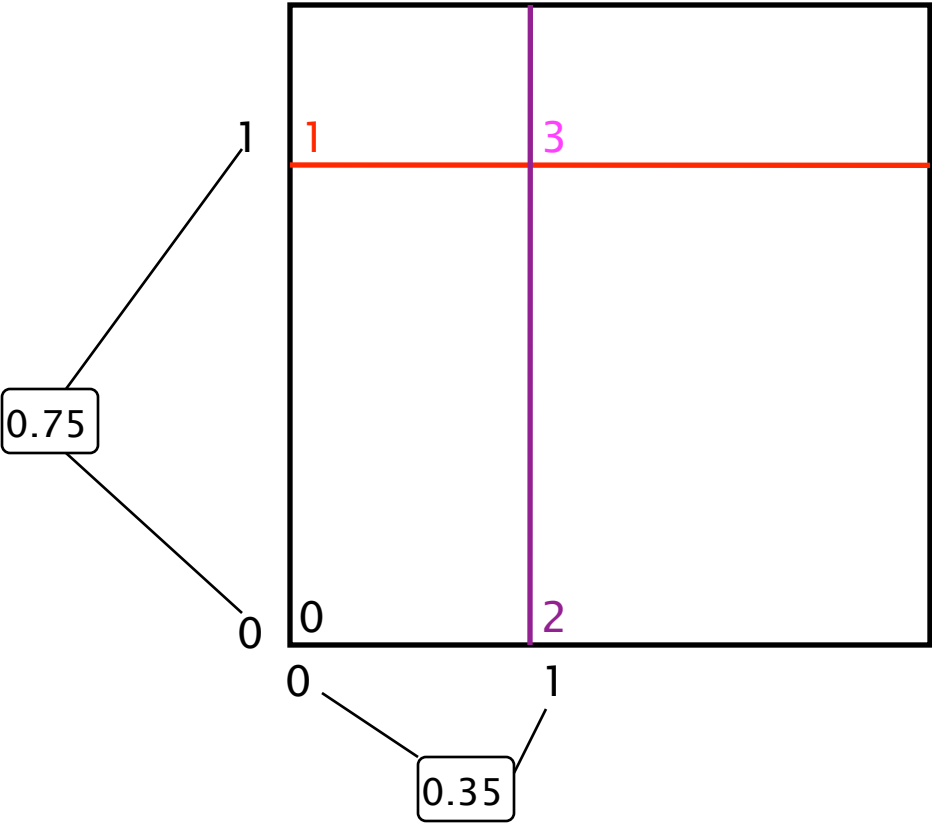
Linear scale on x-axis

Linear scale on y-axis



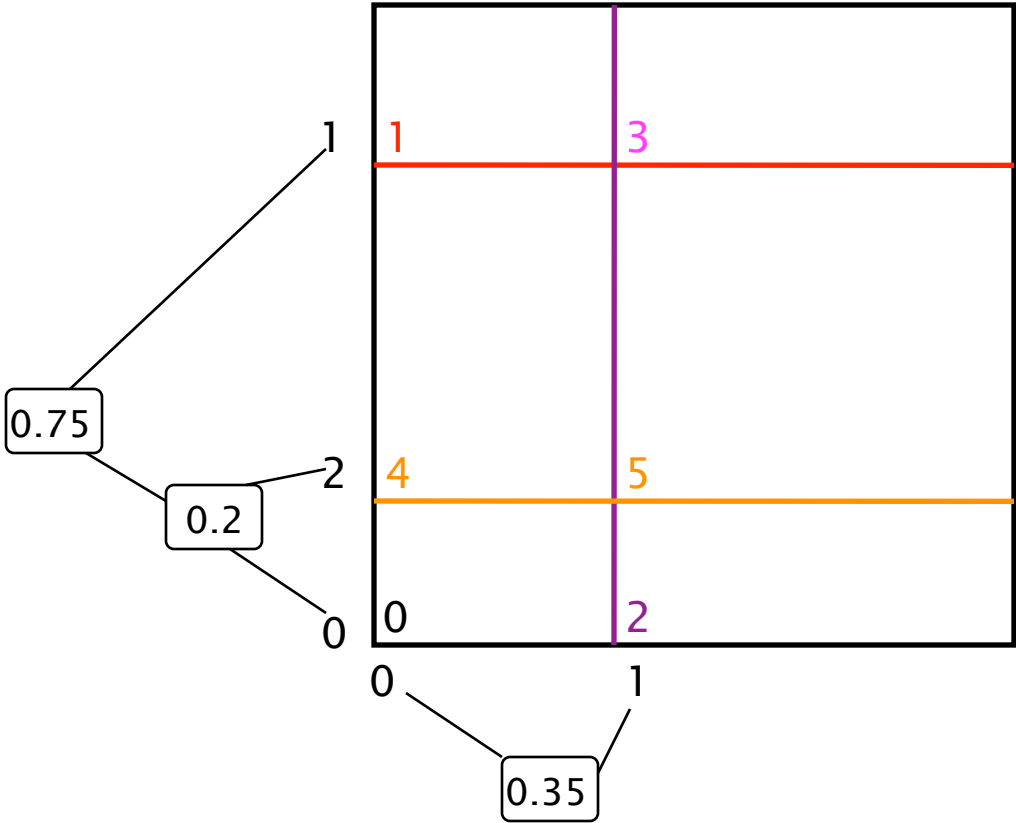
Linear scale on x-axis

Linear scale on y-axis



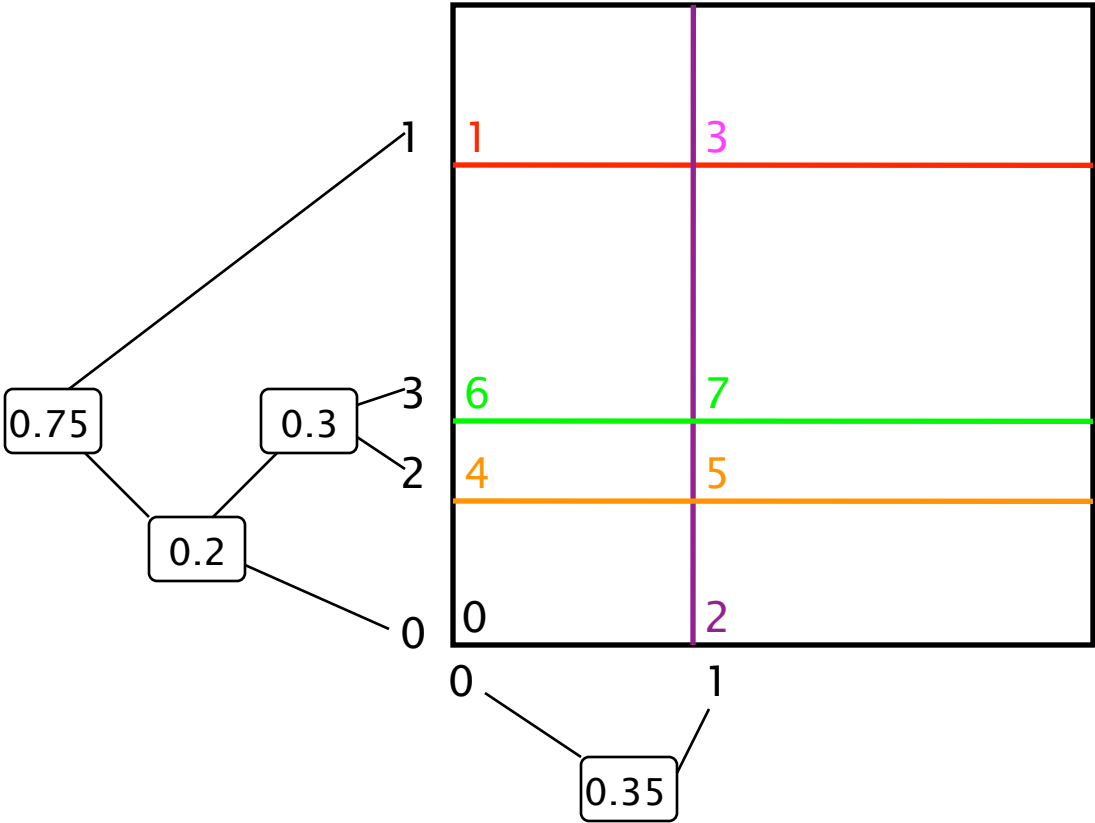
Linear scale on x-axis

Linear scale on y-axis



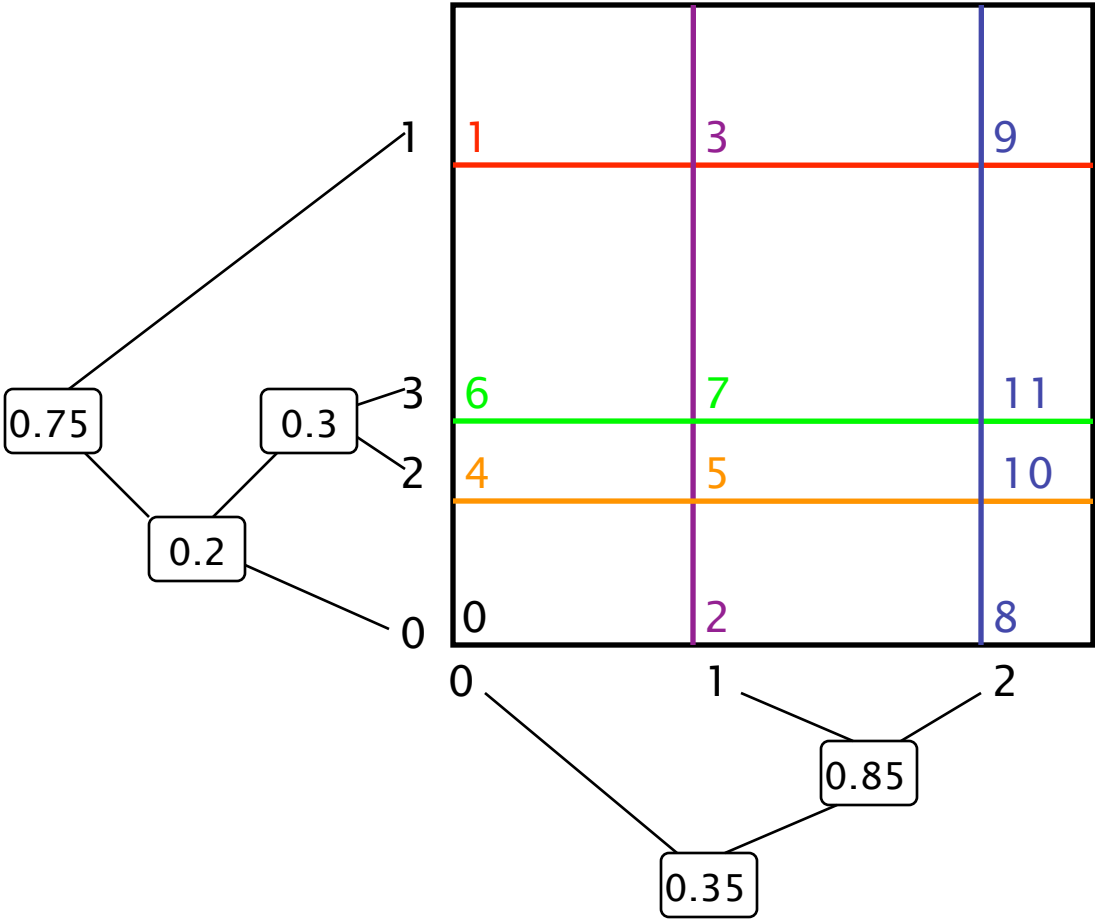
Linear scale on x-axis

Linear scale on y-axis



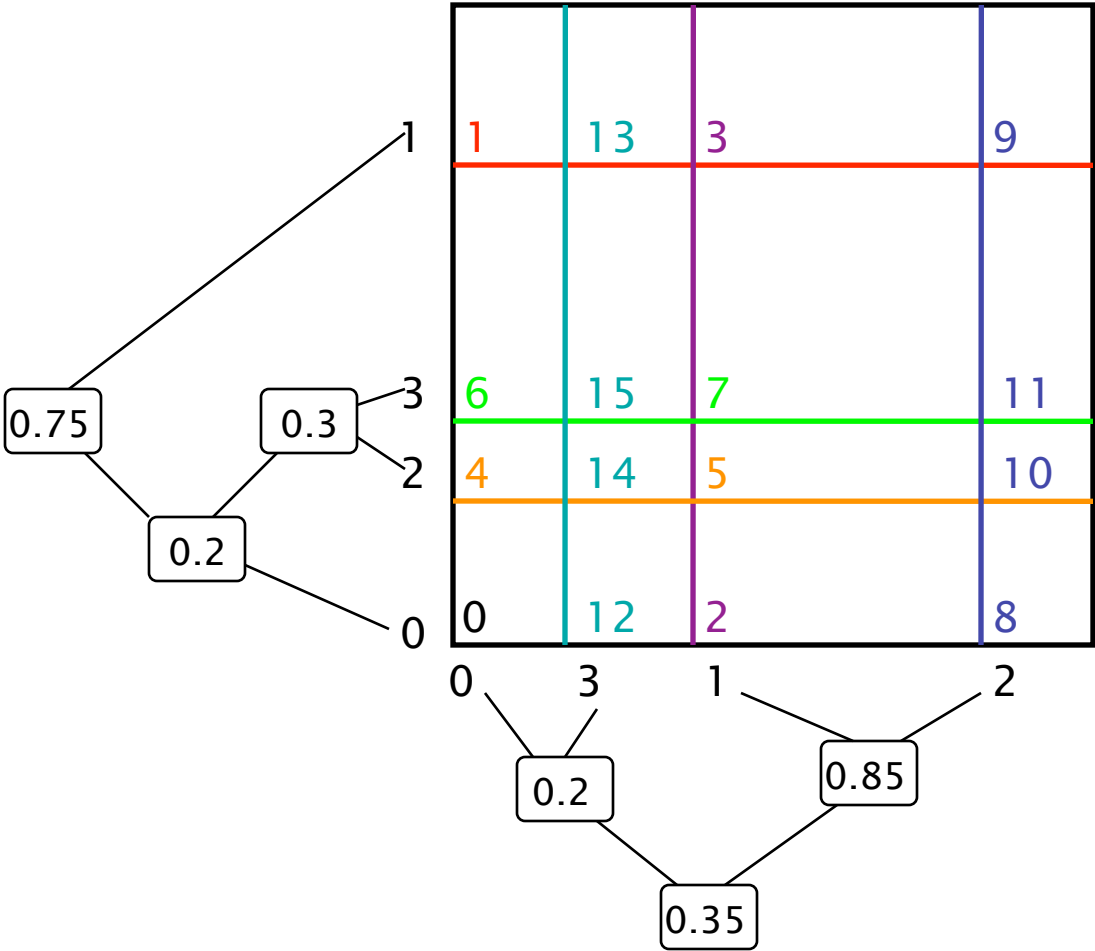
Linear scale on x-axis

Linear scale on y-axis



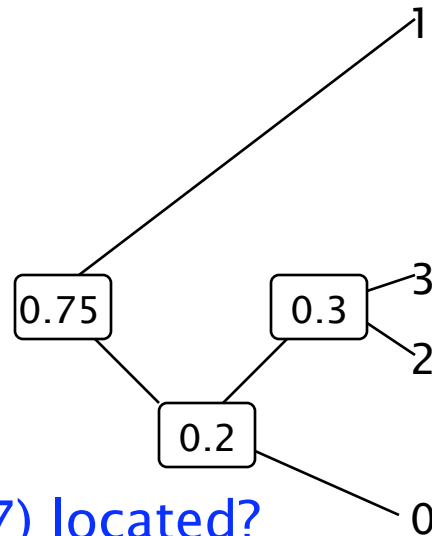
Linear scale on x-axis

Linear scale on y-axis



Linear scale on x-axis

Linear scale on y-axis



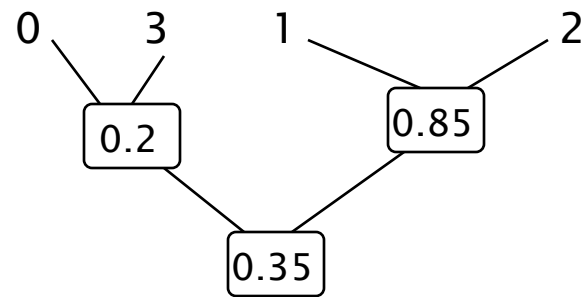
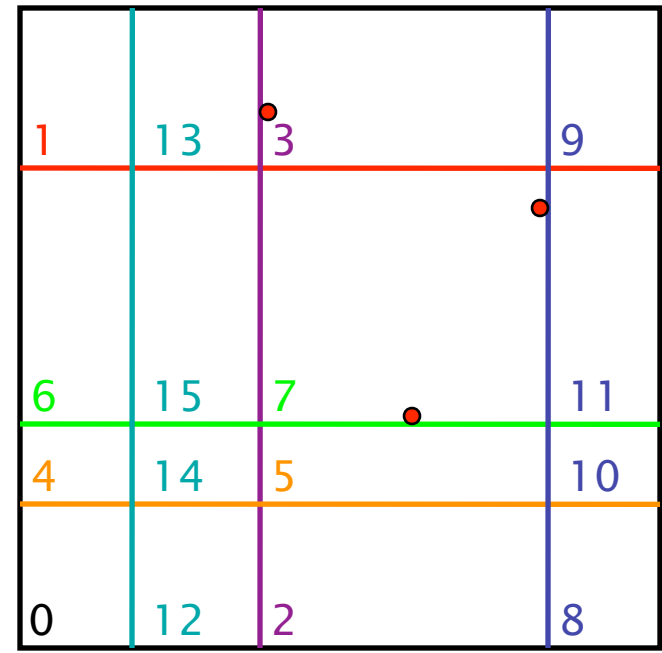
In what cell is (0.8, 0.7) located?

Linear scales lead to

x-partition index = $(1)_{10} = (01)_2$

y-partition index = $(3)_{10} = (11)_2$

Concatenate: $(0111)_2 = (7)_{10}$



Linear scale on x-axis

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Linear Hashing with Partial Expansions (LHPE)

Dynamic Z Hashing

MAIN POINTS.

**Spatially Nearby Cells have Sequentially
Nearby Numbers/Addresses.**

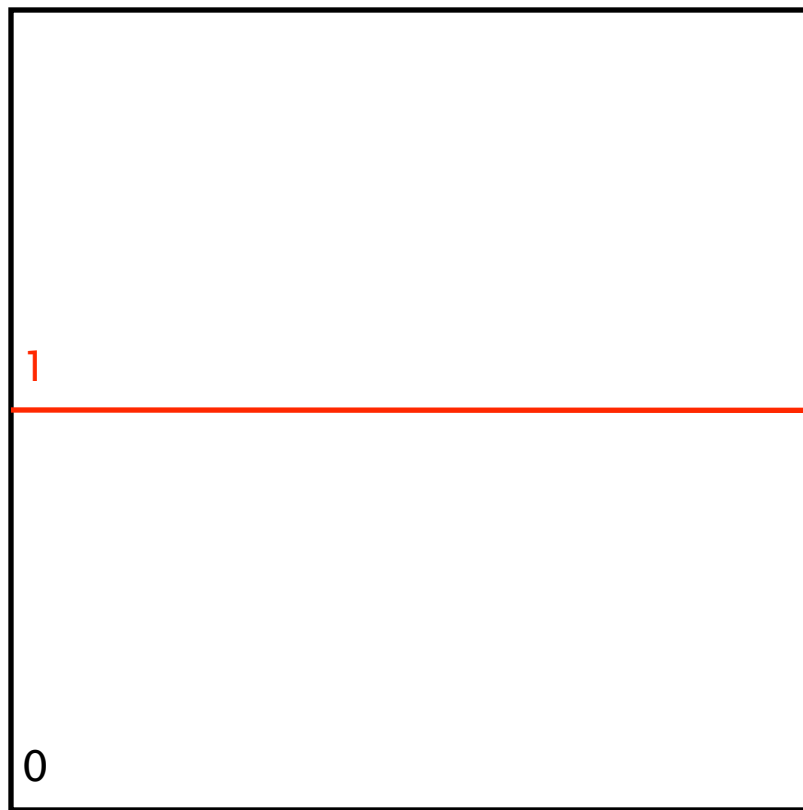
**Each Round (2-power number of cells) is
Order-Preserving.**

Dynamic Z Hashing

1. Embedding space-based decomposition.
2. Better than LHRBI or MDEH at keeping spatially close cells sequentially close.
3. Splitting process creates gaps.
4. Hence lower storage utilization factor.
5. With $4t$ cells currently, split cell $2t$ then $2t+1$, then cell t .

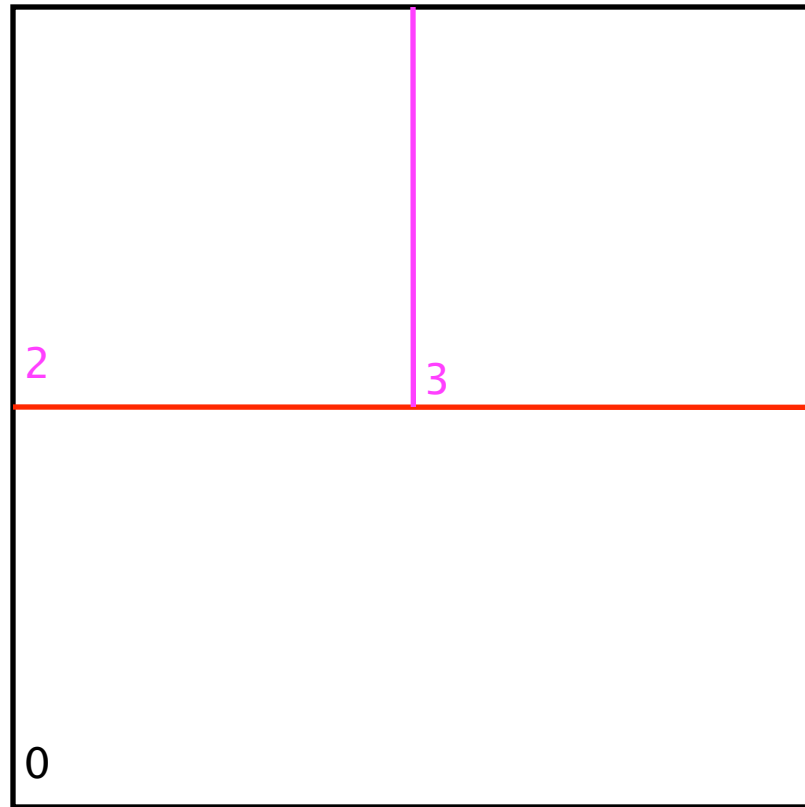
Dynamic Z

To start $t = 0$, so we split
 $2t = 0$,



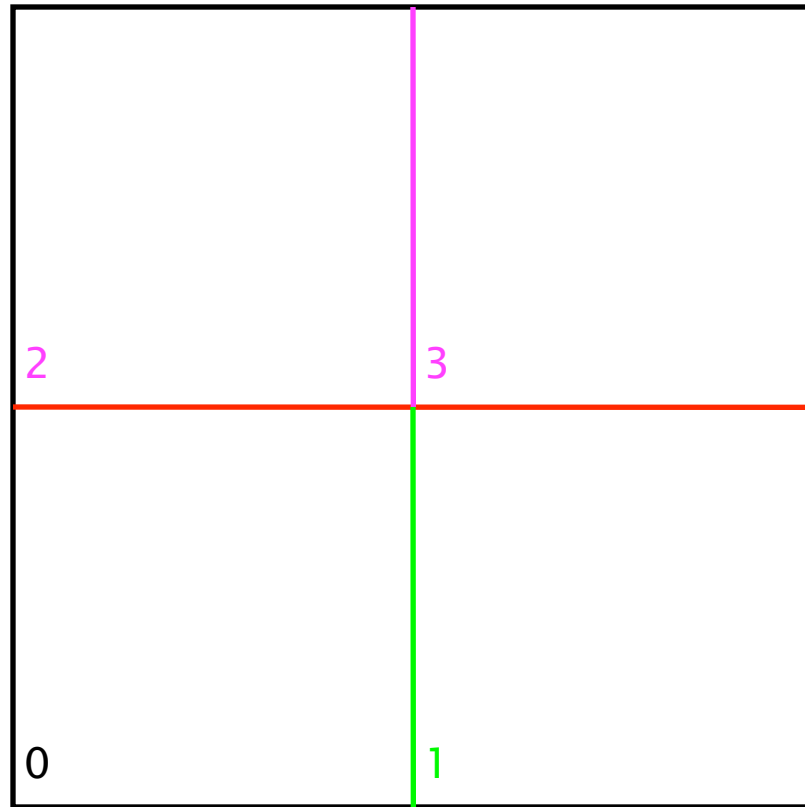
Dynamic Z

To start $t = 0$, so we split
 $2t = 0$, then $2t+1=1$, and
renumber.



Dynamic Z

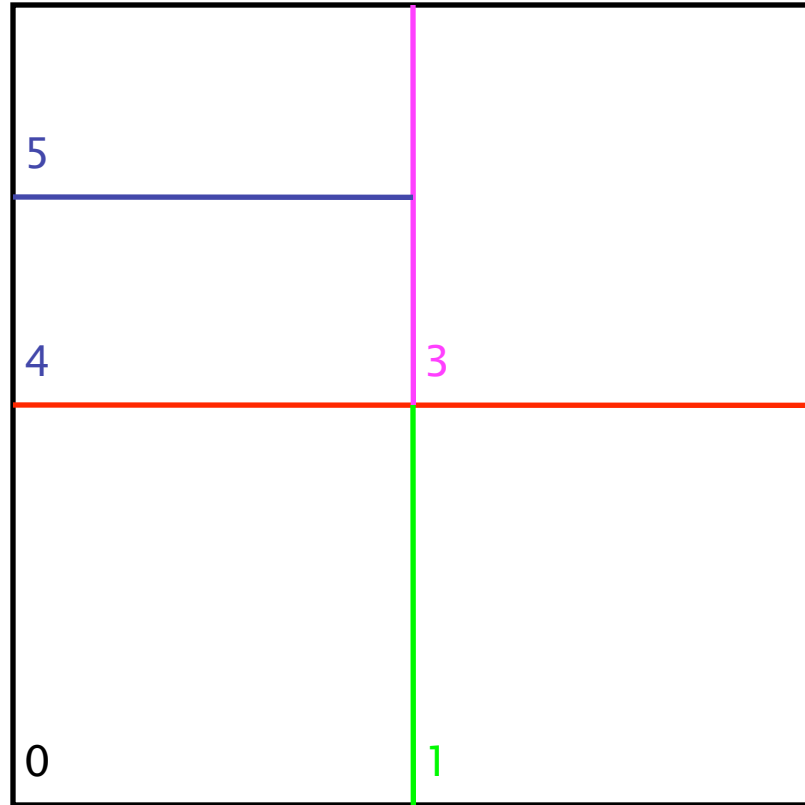
To start $t = 0$, so we split $2t = 0$, then $2t+1=1$, and renumber. Next split t , and return unused number 1 to use.



Dynamic Z

To start $t = 0$, so we split $2t = 0$, then $2t+1=1$, and renumber. Next split t , and return unused number 1 to use.

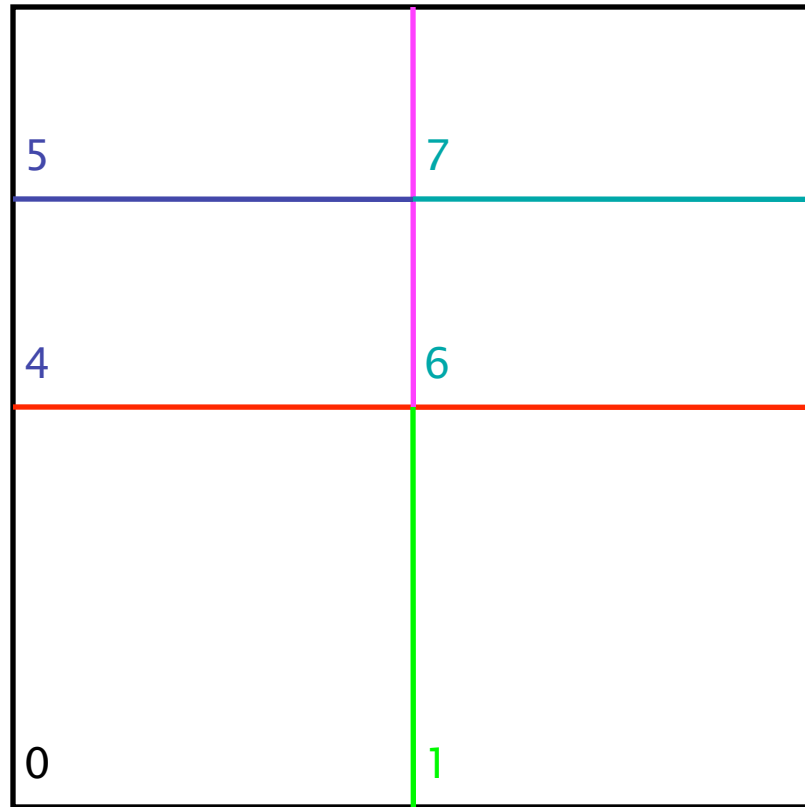
Now $t = 1$, so we split $2t = 2$ first, and renumber.



Dynamic Z

To start $t = 0$, so we split $2t = 0$, then $2t+1=1$, and renumber. Next split t , and return unused number 1 to use.

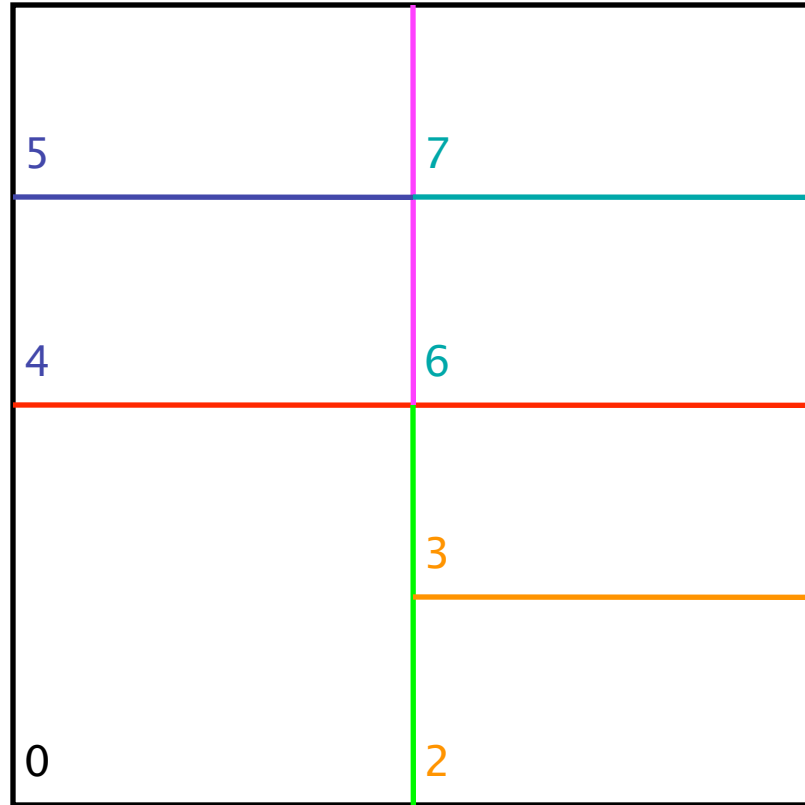
Now $t = 1$, so we split $2t = 2$ first, and renumber. Then split $2t+1 = 3$ and renumber.



Dynamic Z

To start $t = 0$, so we split $2t = 0$, then $2t+1=1$, and renumber. Next split t , and return unused number 1 to use.

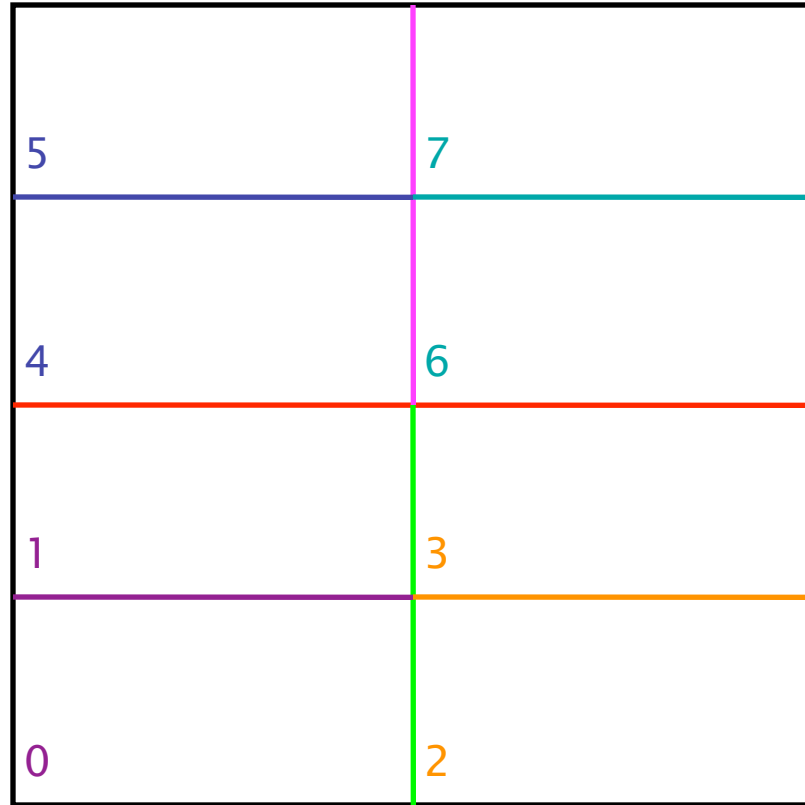
Now $t = 1$, so we split $2t = 2$ first, and renumber. Then split $2t+1 = 3$ and renumber. Next split cell $t = 1$



Dynamic Z

To start $t = 0$, so we split $2t = 0$, then $2t+1=1$, and renumber. Next split t , and return unused number 1 to use.

Now $t = 1$, so we split $2t = 2$ first, and renumber. Then split $2t+1 = 3$ and renumber. Next split cell $t = 1$, and finally cell 0.

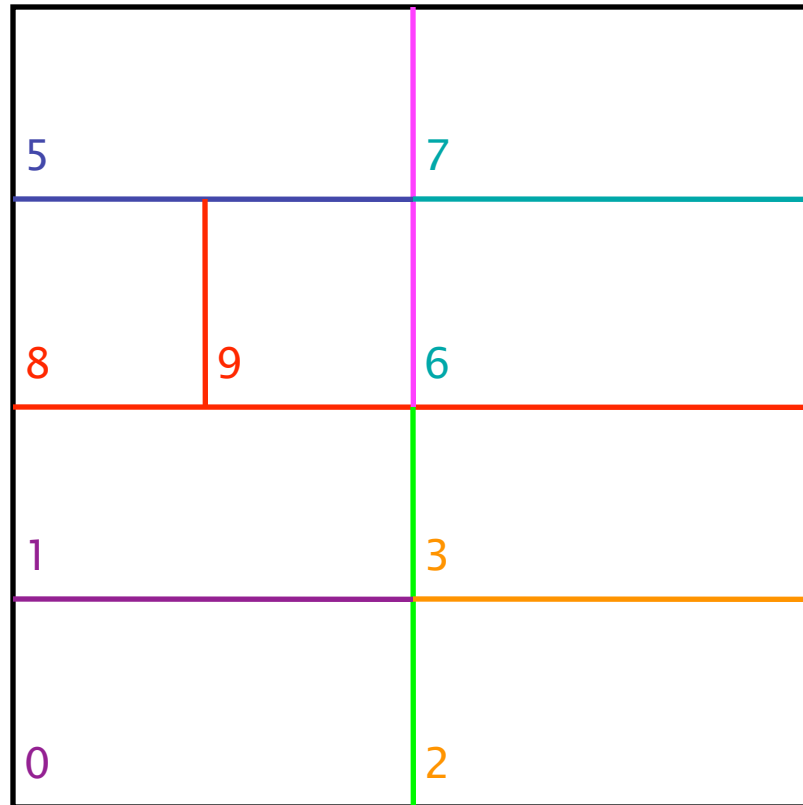


Dynamic Z

To start $t = 0$, so we split $2t = 0$, then $2t+1=1$, and renumber. Next split t , and return unused number 1 to use.

Now $t = 1$, so we split $2t = 2$ first, and renumber. Then split $2t+1 = 3$ and renumber. Next split cell $t = 1$, and finally cell 0.

Next $t = 2$, so we split cell $2t = 4$.

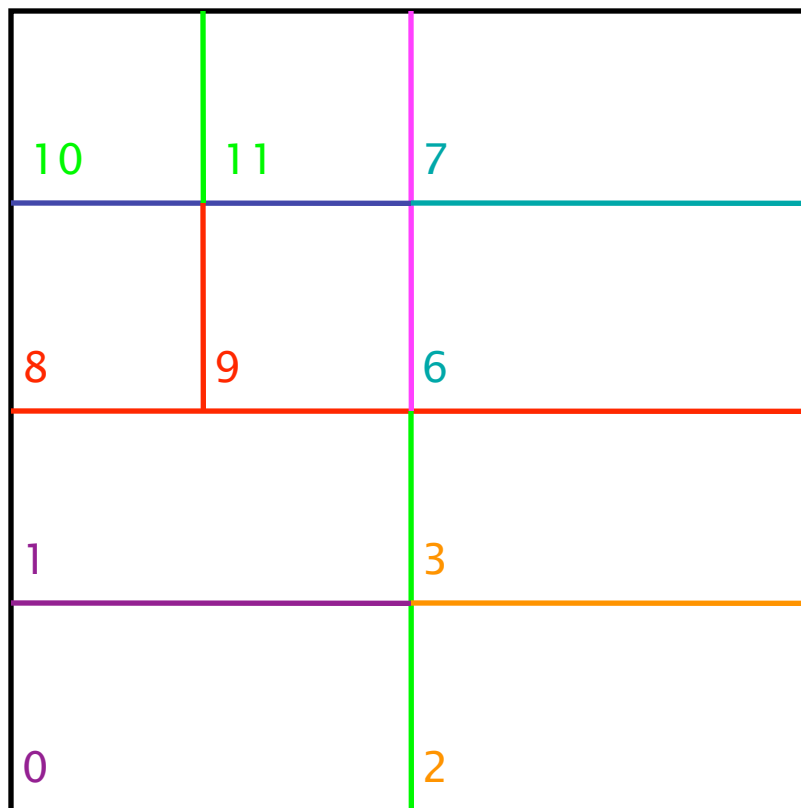


Dynamic Z

To start $t = 0$, so we split $2t = 0$, then $2t+1=1$, and renumber. Next split t , and return unused number 1 to use.

Now $t = 1$, so we split $2t = 2$ first, and renumber. Then split $2t+1 = 3$ and renumber. Next split cell $t = 1$, and finally cell 0.

Next $t = 2$, so we split cell $2t = 4$. Then $2t+1 = 5$.

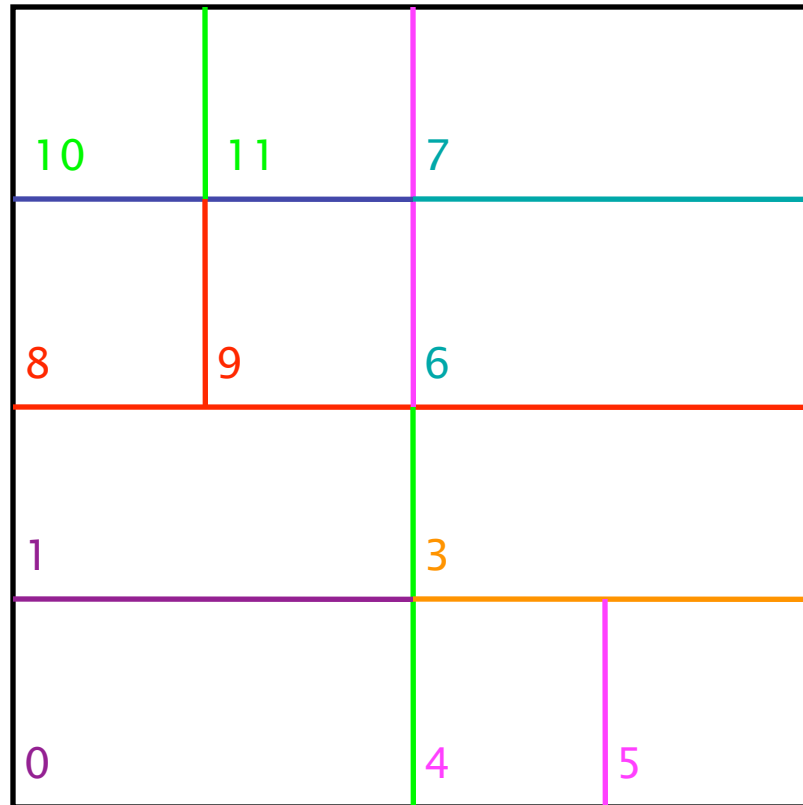


Dynamic Z

To start $t = 0$, so we split $2t = 0$, then $2t+1=1$, and renumber. Next split t , and return unused number 1 to use.

Now $t = 1$, so we split $2t = 2$ first, and renumber. Then split $2t+1 = 3$ and renumber. Next split cell $t = 1$, and finally cell 0.

Next $t = 2$, so we split cell $2t = 4$. Then $2t+1 = 5$. Then $t = 2$.

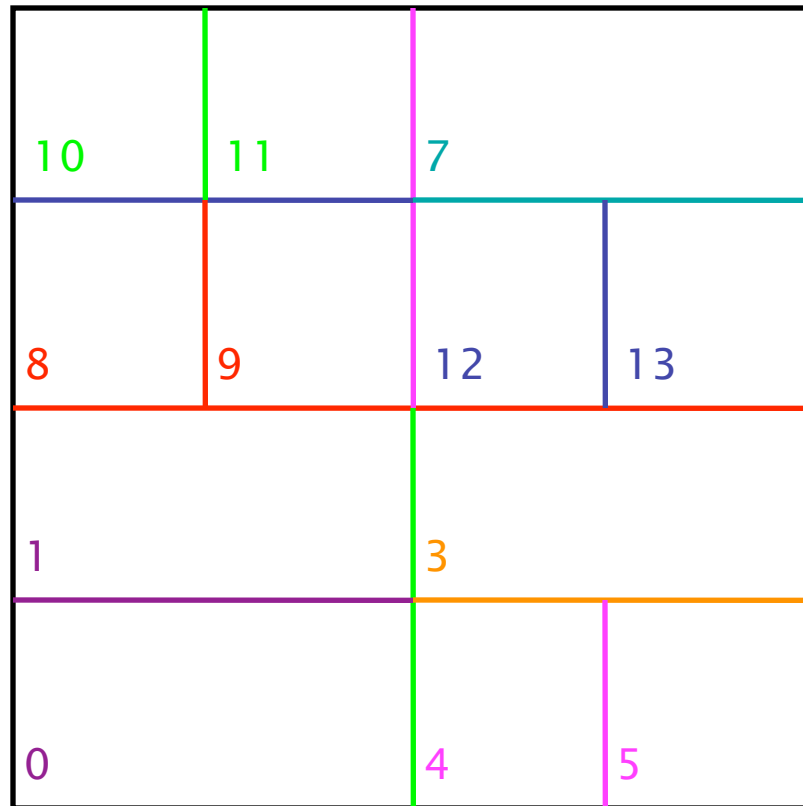


Dynamic Z

To start $t = 0$, so we split $2t = 0$, then $2t+1=1$, and renumber. Next split t , and return unused number 1 to use.

Now $t = 1$, so we split $2t = 2$ first, and renumber. Then split $2t+1 = 3$ and renumber. Next split cell $t = 1$, and finally cell 0.

Next $t = 2$, so we split cell $2t = 4$. Then $2t+1 = 5$. Then $t = 2$. Cell 6 is split next.

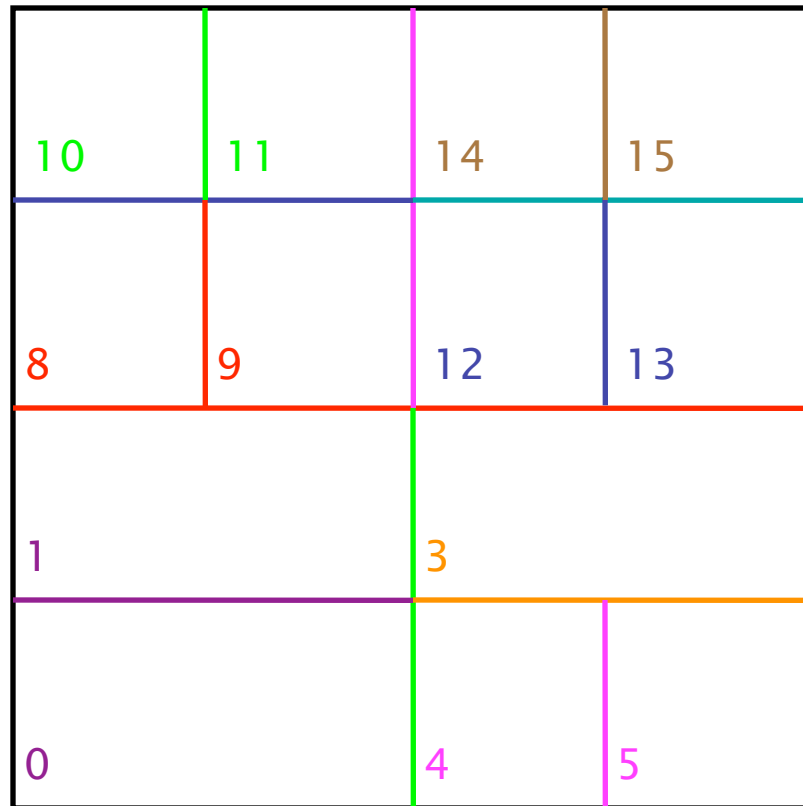


Dynamic Z

To start $t = 0$, so we split $2t = 0$, then $2t+1=1$, and renumber. Next split t , and return unused number 1 to use.

Now $t = 1$, so we split $2t = 2$ first, and renumber. Then split $2t+1 = 3$ and renumber. Next split cell $t = 1$, and finally cell 0.

Next $t = 2$, so we split cell $2t = 4$. Then $2t+1 = 5$. Then $t = 2$. Cell 6 is split next, then cell 7.

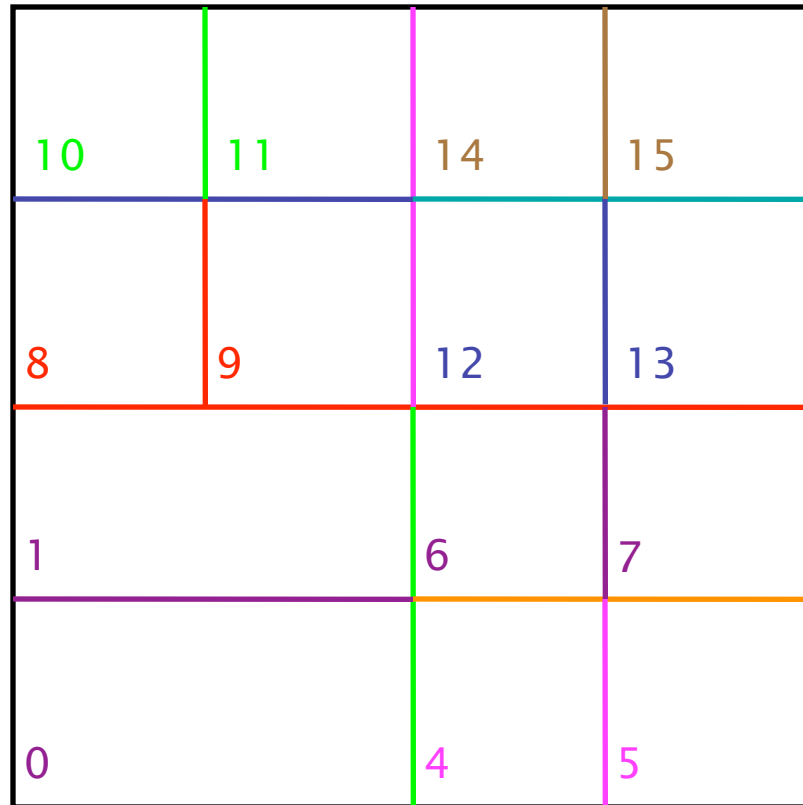


Dynamic Z

To start $t = 0$, so we split $2t = 0$, then $2t+1=1$, and renumber. Next split t , and return unused number 1 to use.

Now $t = 1$, so we split $2t = 2$ first, and renumber. Then split $2t+1 = 3$ and renumber. Next split cell $t = 1$, and finally cell 0.

Next $t = 2$, so we split cell $2t = 4$. Then $2t+1 = 5$. Then $t = 2$. Cell 6 is split next, then cell 7. Now 3 can be split.

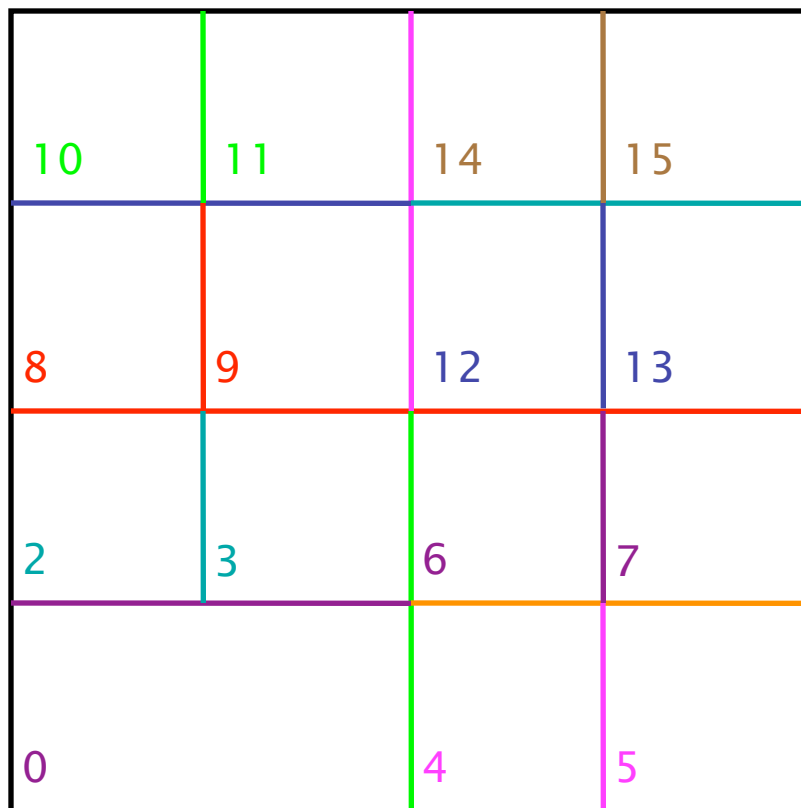


Dynamic Z

To start $t = 0$, so we split $2t = 0$, then $2t+1=1$, and renumber. Next split t , and return unused number 1 to use.

Now $t = 1$, so we split $2t = 2$ first, and renumber. Then split $2t+1 = 3$ and renumber. Next split cell $t = 1$, and finally cell 0.

Next $t = 2$, so we split cell $2t = 4$. Then $2t+1 = 5$. Then $t = 2$. Cell 6 is split next, then cell 7. Now 3 can be split, then 1.



Dynamic Z

To start $t = 0$, so we split $2t = 0$, then $2t+1=1$, and renumber. Next split t , and return unused number 1 to use.

Now $t = 1$, so we split $2t = 2$ first, and renumber. Then split $2t+1 = 3$ and renumber. Next split cell $t = 1$, and finally cell 0.

Next $t = 2$, so we split cell $2t = 4$. Then $2t+1 = 5$. Then $t = 2$. Cell 6 is split next, then cell 7. Now 3 can be split, then 1, and finally 0.

10	11	14	15
8	9	12	13
2	3	6	7
0	1	4	5

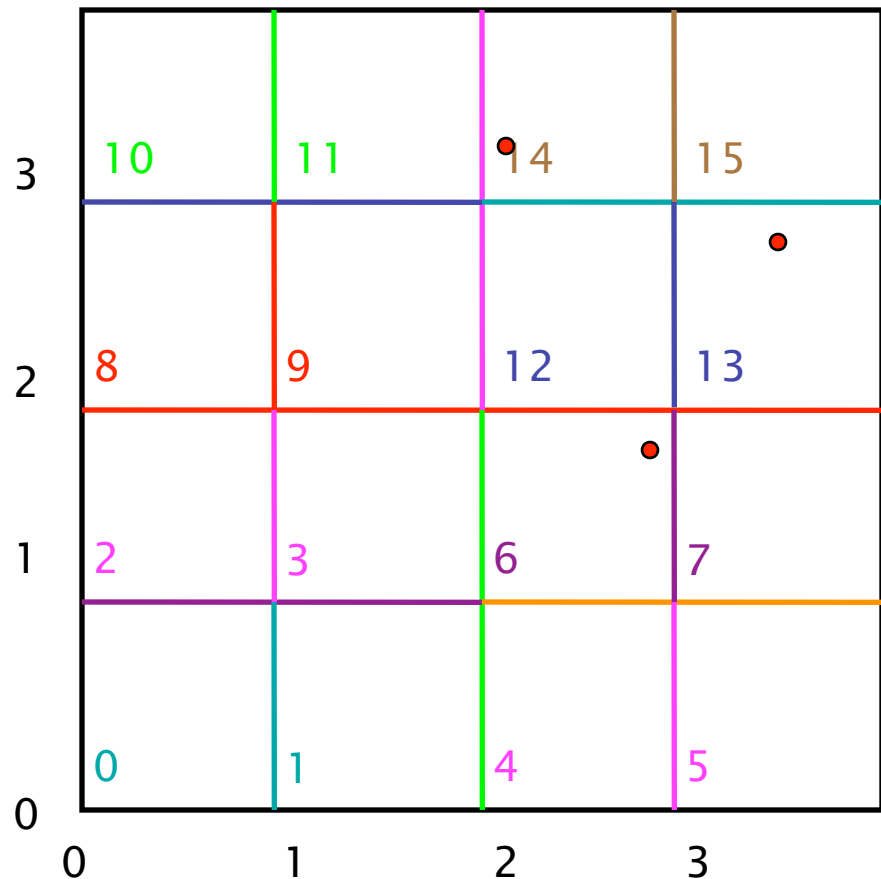
In what cell is $(0.87, 0.7)$ located?

With partition indices ordered by distance from origin,

x-partition index = $(11)_2$,

y-partition index = $(10)_2$,

y-first interleaving implies $(1101)_2 = (13)_{10}$.



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Linear Hashing with Partial Expansion (LHPE)

MAIN POINTS.

A Variation on Linear Hashing that May Be Used with Any (space-based) Method.

Number of Cells Doubles More Gradually.

Linear Hashing with Partial Expansion (LHPE)

The Specifics.

1. Not itself a hashing function.
2. Not so relevant to data-based splitting approaches
3. Used with order-preserving (or other) linear hashing.
4. Doubles in two steps
 - a. First split 2 cells into 3.
 - b. Then 3 cells into 4.

LHPE

Example.

0	1	2	3
---	---	---	---

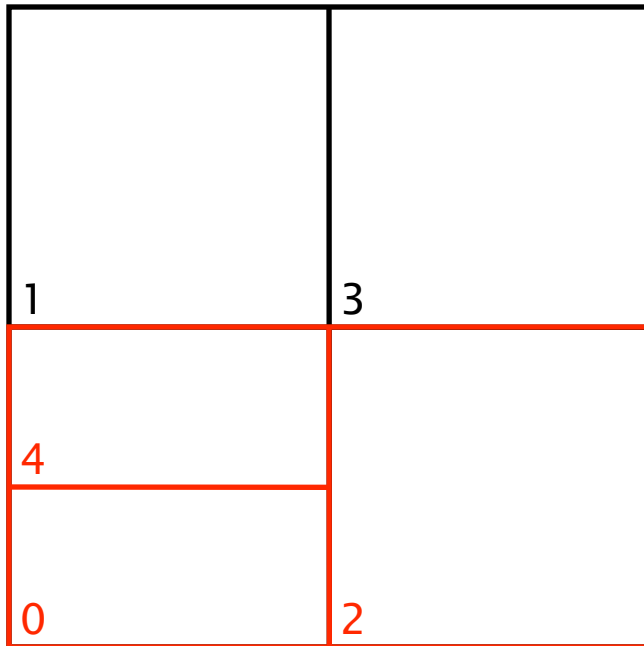
Starting with 4

1	3
0	2

Example.



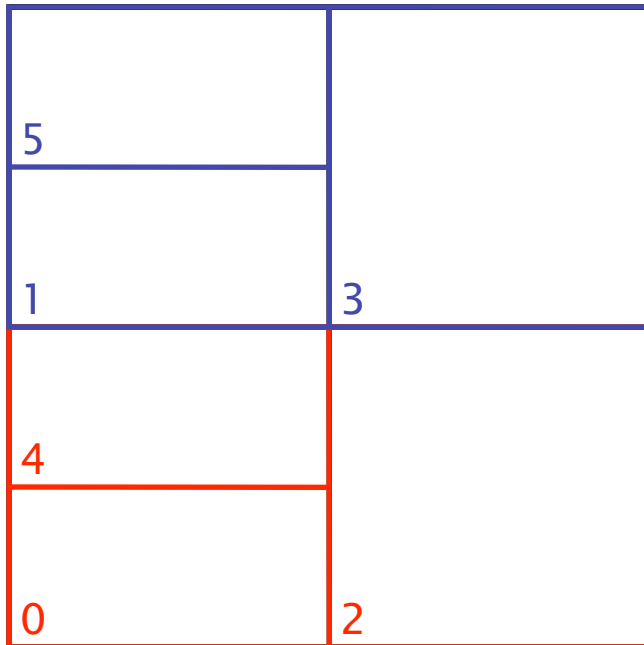
Split 2 into 3



Example.



Split 2 into 3



Example.

0	1	2	3	4	5	6
---	---	---	---	---	---	---

Split 3 into 4

5		
1		
4	3	6
0	2	

Example.

0	1	2	3	4	5	6	7
---	---	---	---	---	---	---	---

5	7
1	3
4	6
0	2

Split 3 into 4

Notice that 2D
decomposition-construction
is that of LHRBI

And so forth

SUMMARY

- Linear Hashing—add one cell/bucket at a time
 - Total grid partition
 - Bit operations—concatenation, (reversed) interleaving
- LHRBI Linear Hashing with Reversed Bit Interleaving
 - Embedding space-based decomposition
 - Order preserving
 - Partition indices ordered by distance from origin
 - Hash function— y -first reversed bit interleaving on partition indices

Summary

- Multidimensional Extendible Hashing
 - Embedding space-based decomposition
 - Cycle through axes
 - Complete each slice and each axis before going to next
 - Partition indices numbered in order of creation, and tracked using linear scales
 - Expansion Index points to next split
 - Hash function— x -first concatenation on partition indices

Summary

- Quantile Hashing
 - Data-based decomposition
 - Just like MDEH, except
 - Slice-cut location may vary
 - Each slice-cut attempts to divide enclosed data in half
- Piecewise-Linear Order-Preserving Hashing
 - Data-based decomposition
 - Slice location is arbitrary
 - Complete slice and axis before doing next
 - Cycle through axes
 - More adaptive than Quantile Hashing

Summary

- Dynamic Z Hashing
 - Embedding space-based decomposition
 - Spatially close cells are numerically close
 - Splitting process produces gaps, hence lower storage utilization factor
 - Hash function— y -first interleaving
- Linear Hashing with Partial Expansion
 - Use with embedding space decompositions
 - Double in two steps—split 2 into 3, then 3 into 4