CMSC 430 (Spring’06)
Practice Problems 2 Solutions

Use the following 3-address code and and Java stack code instructions for answering code generation questions.

<table>
<thead>
<tr>
<th>3-address Instruction</th>
<th>Effect</th>
</tr>
</thead>
<tbody>
<tr>
<td>load R1 x</td>
<td>R1 ← x</td>
</tr>
<tr>
<td>store x R1</td>
<td>x ← R1</td>
</tr>
<tr>
<td>add R1 R2 R3</td>
<td>R1 ← R2 + R3</td>
</tr>
<tr>
<td>sub R1 R2 R3</td>
<td>R1 ← R2 - R3</td>
</tr>
<tr>
<td>mult R1 R2 R3</td>
<td>R1 ← R2 * R3</td>
</tr>
<tr>
<td>neg R1 R2</td>
<td>R1 ← -(R2)</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Java Stack Code</th>
<th>Effect</th>
</tr>
</thead>
<tbody>
<tr>
<td>nop</td>
<td>none</td>
</tr>
<tr>
<td>ldc int c</td>
<td>push constant c onto stack</td>
</tr>
<tr>
<td>iload index(x)</td>
<td>push local variable X onto stack</td>
</tr>
<tr>
<td>istore index(x)</td>
<td>pop stack, store in local variable X</td>
</tr>
<tr>
<td>iadd</td>
<td>pop 2 elems off stack, add, push</td>
</tr>
<tr>
<td>isub</td>
<td>pop 2 elems off stack, subtract, push</td>
</tr>
<tr>
<td>imult</td>
<td>pop 2 elems off stack, multiply, push</td>
</tr>
<tr>
<td>ineg</td>
<td>pop stack, negate, push</td>
</tr>
<tr>
<td>goto L</td>
<td>jump to handle L</td>
</tr>
<tr>
<td>ifeq L</td>
<td>pop stack, jump to handle L if zero</td>
</tr>
<tr>
<td>if_icmpeq L</td>
<td>pop 2 elems, jump to L if equal</td>
</tr>
<tr>
<td>if_icmpgt L</td>
<td>pop 2 elems, jump to L if l1st greater</td>
</tr>
<tr>
<td>dup</td>
<td>duplicate top of stack</td>
</tr>
<tr>
<td>pop</td>
<td>pop top of stack</td>
</tr>
<tr>
<td>swap</td>
<td>swap top two positions of stack</td>
</tr>
</tbody>
</table>


You are generating code for a Java stack machine. You are given the following grammar attributes and helper functions:

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Holds</th>
</tr>
</thead>
<tbody>
<tr>
<td>AstNode.code</td>
<td>list of instructions</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Function</th>
<th>Effect</th>
</tr>
</thead>
<tbody>
<tr>
<td>genInstr( X )</td>
<td>create new instruction X</td>
</tr>
<tr>
<td></td>
<td>returns handle to instruction</td>
</tr>
<tr>
<td>append( ... )</td>
<td>concatenates lists of instructions</td>
</tr>
</tbody>
</table>

(a) What grammar actions needed to generate code for a C-style IF statement in the following production?

\[
\text{stmt} \rightarrow \text{IF ( exp ) stmtList} ;
\]

\[
\{ \text{stmt.code = ??; } \}
\]

Answer:

\[
\text{stmt := IF (exp) stmtList ;}
\]

\[
\{ \text{Handle h1 = genInstr( NOP );}
\]

\[
\text{stmt.code = append (}
\]

\[
\text{exp.code,}
\]

\[
\text{genInstr ( IFEQ( h1 ) ),}
\]

\[
\text{stmtList.code,}
\]

\[
\text{h1}
\}

(b) What grammar actions needed to generate code for a C-style FOR loop in the following production?

\[
\text{stmt} \rightarrow \text{FOR (stmt ; exp ; stmt) stmt ;}
\]

\[
\{ \text{stmt.code = ??; } \}
\]

Answer:

\[
\text{stmt := FOR (stmt1 ; exp ; stmt2) stmt3 ;}
\]

\[
\{ \text{Handle h1 = genInstr( NOP );}
\]

\[
\text{Handle h2 = genInstr( NOP );}
\]

\[
\text{stmtt.code = append (}
\]

\[
\text{stmt1.code,}
\]

\[
\text{h1,}
\]

\[
\text{exp.code,}
\]

\[
\text{genInstr ( IFEQ( h2 ) ),}
\]

\[
\text{stmt3.code,}
\]

\[
\text{stmt2.code,}
\]

\[
\text{genInstr ( GOTO( h1 ) ),}
\]

\[
\text{h2}
\}

\)

(c) Write grammar actions needed to generate control code for an AND expression in the following production, using numerical value representation of booleans. Use short circuiting.

\[
\text{exp} \rightarrow \text{exp1 AND exp2}
\]

\[
\{ \text{exp.code = ??; } \}
\]

Answer:

\[
\text{exp := exp1 AND exp2}
\]

\[
\{ \text{Handle h1 = genInstr( NOP );}
\]

\[
\text{exp1.code = append (}
\]

\[
\text{exp1.code,}
\]

\[
\text{dup,}
\]

\[
\text{genInstr ( IFEQ( h1 ) ),}
\]

\[
\text{pop,}
\]

\[
\text{exp2.code,}
\]

\[
\text{h1}
\}

(d) Write grammar actions needed to generate control code for an NOR expression in the following production, using numerical value representation of booleans. Use short circuiting.

\[
\text{exp} \rightarrow \text{exp1 NOR exp2}
\]

\[
\{ \text{exp.code = ??; } \}
\]

Answer:

\[
\text{exp := exp1 NOR exp2}
\]

\[
\{ \text{Handle h1 = genInstr( NOP );}
\]

\[
\text{Handle h2 = genInstr( NOP );}
\]

\[
\text{Handle h3 = genInstr( NOP );}
\]

\[
\text{Handle h4 = genInstr( NOP );}
\]

\[
\text{exp.code = append (}
\]

\[
\text{exp1.code,}
\]

\[
\text{exp2.code,}
\]

\[
\}
(e) Write grammar actions needed to generate control code for an ≥ (GEQ) expression in the following production, using numerical value representation of booleans.

```c
exp → exp1 GEQ exp2
{ exp.code = ??; }

Answer:

exp := exp1 >= exp2
{
  Handle h1 = genInst( NOP );
  Handle h2 = genInst( NOP );
  exp.code = append (
    exp1.code,
    exp2.code,
    genInst( IF_ICMPGE( h1 ) ),
    exp1.code,
    exp2.code,
    genInst( IF_ICMPGT( h1 ) ),
    genInst( LDC_0( 0 ) ),
    genInst( GOTO( h2 ) ),
    h1,
    genInst( LDC_1( 1 ) ),
    h2
  );
}
```

2. Complex code generation.

(a) Name two issues and solutions to generating code for function calls in C.

*Function call could occur in an expression (e.g., 4 + foo()), need to calculate value of function and use return value in expression*

*Function argument could be an expression (e.g., foo(4+x)), need to evaluate expression first and pass as argument*

(b) Name two issues and solutions to generating code for array references in C.

*Could have multidimensional arrays, need to convert indices into memory location by flattening the array in either row or column major order*

*Could have arrays or array elements as arguments (e.g., foo(a[i], foo(a[i])), need to decide whether to pass value or address depending on whether call-by-reference or call-by-value*

(c) What code must the compiler generate for the code

```c
int i, a[ 100 ];
...
```

```c
a[ i + 5 ] = 4 ;
```

*For a[ i+5 ] = 4, compiler must generate code to calculate i+5, (adjusting by first array index, usually 0 or 1) multiply result by size of elements of array, then add to base address of a to find address of array element*

(d) What code must the compiler generate for the code

```c
int foo ( int x ) ;
...
```

```c
x = foo( i + 2 ) ;
```

1. Assuming foo() is call-by-value?

   *If foo() is call-by-value, calculate i+2 and use value as argument*

2. Assuming foo() is call-by-reference?

   *If foo() is call-by-reference, calculate i+2, store in temporary variable, then pass address of temp var as argument*

3. Optimizations

(a) How can compiler transformations improve a program?

*By reducing program size or number of instructions executed, taking advantage of redundant computations, customizing general purpose code, or undoing high-level abstractions.*

(b) What does the compiler need to consider when applying optimizations?

*Safety, profitability, and applicability.*

(c) What are the different scopes of compiler optimizations? What are the tradeoffs when considering what scope of optimizations to use?

*Peephole, local, global, or interprocedural. The basic tradeoff is more complexity and compile time for optimizations with greater scope.*

4. Local optimizations

Consider the following code.

(1) a := 1
(2) b := f + a
(3) c := a
(4) d := f + a
(5) e := f + c
(6) f := b
(7) g := f + a

(a) Build a DAG for the code.
5. Control flow analysis

For the following problems, consider this code:

\[
\begin{align*}
\text{<S1> } & \quad a := 1 \\
\text{<S2> } & \quad b := 2 \\
\text{<S3> } & \quad \text{L1: } c := a + b \\
\text{<S4> } & \quad d := c - a \\
\text{<S5> } & \quad \text{if (...) goto L3} \\
\text{<S6> } & \quad \text{L2: } d := b \times d \\
\text{<S7> } & \quad \text{if (...) goto L3} \\
\text{<S8> } & \quad d := a + b \\
\text{<S9> } & \quad e := e + 1 \\
\text{<S10> } & \quad \text{goto L2} \\
\text{<S11> } & \quad \text{L3: } b := a + b \\
\text{<S12> } & \quad e := c - a \\
\text{<S13> } & \quad \text{if (...) goto L1} \\
\text{<S14> } & \quad a := b \times d \\
\text{<S15> } & \quad b := a - d
\end{align*}
\]

(a) What are the basic blocks?
\[
\begin{align*}
\text{B1} & \quad = \{ \text{S1, S2} \} \\
\text{B2} & \quad = \{ \text{S3, S4, S5} \} \\
\text{B3} & \quad = \{ \text{S6, S7} \} \\
\text{B4} & \quad = \{ \text{S8, S9, S10} \} \\
\text{B5} & \quad = \{ \text{S11, S12, S13} \} \\
\text{B6} & \quad = \{ \text{S14, S15} \}
\end{align*}
\]

(b) What is the control flow graph?

(c) Depth-first order selects nodes in the order they are visited (start by visiting the root node) and then recursively visiting every child of each node (if the child has not been visited before). Note that the order in which children are visited is random.

What are all the possible results of depth-first traversal on the control flow graph?
\[
\begin{align*}
\text{B1, B2, B3, B4, B5, B6} \\
\text{B1, B2, B5, B6, B3, B4} \\
\text{B1, B2, B3, B5, B6, B4}
\end{align*}
\]

(d) Using depth-first order, is it possible to visit a child before its parent? For which depth-first ordering(s) of the control flow graph does this occur?
\[
\begin{align*}
\text{B1, B2, B5, B6, B3, B4}
\end{align*}
\]

(e) Postorder selects nodes (starting from root) after visiting every child of that node (if the child has not been visited before). Note that the order in which children are visited is random.

What are all the possible results of Postorder traversal for the control flow graph?
\[
\begin{align*}
\text{B6, B5, B4, B3, B2, B1} \\
\text{B4, B6, B5, B3, B2, B1}
\end{align*}
\]

(f) Reverse Postorder simply reverses the node ordering found by a Postorder traversal of the graph. What are the possible Reverse Postorder traversals of the control flow graph?
\[
\begin{align*}
\text{B1, B2, B3, B4, B5, B6} \\
\text{B1, B2, B3, B5, B6, B4}
\end{align*}
\]

(g) Using Reverse Postorder, is it possible to visit a child before its parent? Why or why not?

Yes, because not all parents can be visited first if there are loops (cycles) in the control flow graph.
6. Reaching definitions

Reaching definitions for a point in the program p is defined as the set of definitions of a variable for which there is some path from the definition to p with no other definition of that variable. Calculate reaching definitions for the code in the control-flow graph problem.

(a) What is the dataflow equation for REACH?

\[ \text{REACH}(b) = \bigcup_{x \in \text{pred}(b)} (\text{GEN}(x) \cup (R \text{EACH}(x) - \text{KILL}(x))) \]

(b) In what direction is REACH calculated? I.e., does information flow forwards or backwards in the CFG?

Forwards.

(c) Calculate GEN, KILL for each basic block.

Note: For reaching definitions, we append to each variable definition its location to distinguish between multiple definitions to the same variable.

<table>
<thead>
<tr>
<th>Block</th>
<th>GEN</th>
<th>KILL</th>
</tr>
</thead>
<tbody>
<tr>
<td>B1</td>
<td>a1,b2</td>
<td>a1,b2,b11,a14,b15</td>
</tr>
<tr>
<td>B2</td>
<td>c3,d4</td>
<td>c3,d4,d6,d8</td>
</tr>
<tr>
<td>B3</td>
<td>d6</td>
<td>d4,d6,d8</td>
</tr>
<tr>
<td>B4</td>
<td>d8,e9</td>
<td>d4,d6,d8,e9,e12</td>
</tr>
<tr>
<td>B5</td>
<td>b11,e12</td>
<td>b2,e9,b11,e12,b15</td>
</tr>
<tr>
<td>B6</td>
<td>a14,b15</td>
<td>a1,b2,b11,a14,b15</td>
</tr>
</tbody>
</table>

(d) What is a good initial value for REACH for each basic block?

REACH for each basic block is initialized to \( \emptyset \) (no reaching definitions).

(e) Solve the data-flow equations in reverse Postorder. Show your work.

Solving the data flow equations in reverse postorder (B1,B2,B3,B4,B5,B6), we get the following (IN, OUT initially all set to \( \emptyset \)):

<table>
<thead>
<tr>
<th>Block</th>
<th>Data</th>
<th>Pass1</th>
<th>Pass2</th>
</tr>
</thead>
<tbody>
<tr>
<td>B1</td>
<td>IN</td>
<td>a1,b2</td>
<td>a1,b2</td>
</tr>
<tr>
<td></td>
<td>OUT</td>
<td></td>
<td></td>
</tr>
<tr>
<td>B2</td>
<td>IN</td>
<td>a1,b2</td>
<td>a1,b2,b11,a14,b15</td>
</tr>
<tr>
<td></td>
<td>OUT</td>
<td></td>
<td>a1,b2,b11,a14,b15</td>
</tr>
<tr>
<td>B3</td>
<td>IN</td>
<td>a1,b2,c3,d4</td>
<td>a1,b2,c3,d4,d6,b11,e12</td>
</tr>
<tr>
<td></td>
<td>OUT</td>
<td></td>
<td>a1,b2,c3,d4,d6,b11,e12</td>
</tr>
<tr>
<td>B4</td>
<td>IN</td>
<td>a1,b2,c3,d6</td>
<td>a1,b2,c3,d4,d6,e9,b11,e12</td>
</tr>
<tr>
<td></td>
<td>OUT</td>
<td></td>
<td>a1,b2,c3,d4,d6,e9,b11,e12</td>
</tr>
<tr>
<td>B5</td>
<td>IN</td>
<td>a1,b2,c3,d,6</td>
<td>a1,b2,c3,d,6,d6,b11,e12</td>
</tr>
<tr>
<td></td>
<td>OUT</td>
<td></td>
<td>a1,b2,c3,d,6,d6,b11,e12</td>
</tr>
<tr>
<td>B6</td>
<td>IN</td>
<td>a1,c3,d,6</td>
<td>a1,c3,d,6,d6,b11,e12</td>
</tr>
<tr>
<td></td>
<td>OUT</td>
<td></td>
<td>a1,c3,d,6,d6,b11,e12</td>
</tr>
<tr>
<td></td>
<td></td>
<td>c3,d4,d6,e12,a14,b15</td>
<td>c3,d4,d6,e12,a14,b15</td>
</tr>
</tbody>
</table>

8. Available expressions

Available expressions is a data-flow analysis problem whose solution is used to guide global common subexpression. It calculates AVAIL, the expressions available at the beginning of each basic block.

Consider the following code. Assume that \( b+c \) is the only expression of interest:

7. Live variables

Live variables for a point in the program p is defined as the set of variables x for which there is some path from p to a use of x with no definition to x on the path. Calculate live variables for the code in the control-flow graph problem.
(a) What is the data-flow equation for AVAIL?

\[ AVAIL(b) = \bigcap_{x \in \text{pred}(b)} (GEN(x) \cup (AVAIL(x) - KILL(x))) \]

(b) Give GEN and KILL (needed by AVAIL) for each basic block.

<table>
<thead>
<tr>
<th>Block</th>
<th>GEN</th>
<th>KILL</th>
</tr>
</thead>
<tbody>
<tr>
<td>B1</td>
<td>b+c</td>
<td>\emptyset</td>
</tr>
<tr>
<td>B2</td>
<td>b+c</td>
<td>\emptyset</td>
</tr>
<tr>
<td>B3</td>
<td>\emptyset</td>
<td>b+c</td>
</tr>
<tr>
<td>B4</td>
<td>\emptyset</td>
<td>\emptyset</td>
</tr>
</tbody>
</table>

(c) What is a good initial value for AVAIL for each basic block?

Initialize AVAIL to \( \emptyset \) (no expressions available) for all basic blocks.

(d) Calculate AVAIL. Show all steps, including values for AVAIL and the order basic blocks are analyzed.

Solving the data flow equations in reverse postorder (B1,B2,B3,B4), we get the following:

<table>
<thead>
<tr>
<th>Block</th>
<th>Data</th>
<th>Init</th>
<th>Pass1</th>
<th>Pass2</th>
</tr>
</thead>
<tbody>
<tr>
<td>B1</td>
<td>IN</td>
<td>\emptyset</td>
<td>\emptyset</td>
<td>\emptyset</td>
</tr>
<tr>
<td></td>
<td>OUT</td>
<td>b+c</td>
<td>\emptyset</td>
<td>\emptyset</td>
</tr>
<tr>
<td>B2</td>
<td>IN</td>
<td>\emptyset</td>
<td>\emptyset</td>
<td>\emptyset</td>
</tr>
<tr>
<td></td>
<td>OUT</td>
<td>b+c</td>
<td>\emptyset</td>
<td>\emptyset</td>
</tr>
<tr>
<td>B3</td>
<td>IN</td>
<td>\emptyset</td>
<td>b+c</td>
<td>\emptyset</td>
</tr>
<tr>
<td></td>
<td>OUT</td>
<td>\emptyset</td>
<td>\emptyset</td>
<td>\emptyset</td>
</tr>
<tr>
<td>B4</td>
<td>IN</td>
<td>\emptyset</td>
<td>\emptyset</td>
<td>\emptyset</td>
</tr>
<tr>
<td></td>
<td>OUT</td>
<td>\emptyset</td>
<td>\emptyset</td>
<td>\emptyset</td>
</tr>
</tbody>
</table>

In more detail, the solution was calculated as follows (where AVAIL = IN):

Pass 1

\[ AVAIL(B1) = \emptyset \]

\[ AVAIL(B2) = (GEN(B1) \cup (AVAIL(B1) - KILL(B1))) \]
\[ \cap (GEN(B3) \cup (AVAIL(B3) - KILL(B3))) \]
\[ = (\emptyset \cup \emptyset) \cap (\emptyset \cup \emptyset) \]
\[ = \emptyset \]

\[ AVAIL(B3) = (GEN(B1) \cup (AVAIL(B1) - KILL(B1))) \]
\[ = (\emptyset \cup \emptyset) \]
\[ = \emptyset \]

9. Data-flow lattices

Prove the following properties of lattices:

(a) Show that \( a \leq b \) and \( b \leq c \) implies \( a \leq c \)

First, by definition of \( \leq \), we see \( a \leq b \) gives us \( a \wedge b = a \).

Similarly, from \( b \leq c \) we get \( b \wedge c = b \).

Taking \( a \wedge b = a \) and replacing \( b \) with \( b \wedge c \), we get
\[ a \wedge (b \wedge c) = a. \]

Since \( \wedge \) is associative, we find \( a \wedge (b \wedge c) = (a \wedge b) \wedge c = a \wedge c. \)

But since we also have \( a \wedge (b \wedge c) = a \), this implies \( a \wedge c = a. \)

By definition of \( \leq \), this implies \( a \leq c \).

(b) Show that \( a \leq (b \wedge c) \) implies \( a \leq b \)

First, we show \( b \wedge c \leq b \).

By definition of \( \leq \), this is true if \( b \wedge (b \wedge c) = b \wedge c \).

Since \( \wedge \) is associative, we prove it using \( b \wedge (b \wedge c) = (b \wedge b) \wedge c = b \wedge c. \)

Now combining \( a \leq (b \wedge c) \) and \( (b \wedge c) \leq b \) gives us \( a \leq b \), using the solution to the previous problem.
10. Data-flow frameworks

(a) When estimating each of the following sets, tell whether too-large or too-small estimates are conservative. Explain your answer in terms of the intended use of information.

i. Available expressions
   *Too-small estimates are conservative ($\bot = \emptyset$).*
   *Common subexpression elimination would not replace some expressions if the estimate is too small, but the answer would still be correct. In comparison, performing CSE when an expression is not available may yield incorrect results.*

ii. Reaching definitions
   *Too-large estimates are conservative ($\bot = \{ \text{ all copy statements } \}$).
   *Copy propagation would be restricted if the estimate of copy statements reaching a point is too large, but the result would still be correct. In comparison, estimating too few copy statements reach a given point may enable copy propagation when the right-hand side of a missing copy statement differs from the right-hand side of the copy statements found, yielding incorrect results.*

iii. Live variables
   *Too-small estimates are conservative ($\bot = \emptyset$).
   *The opposite of variables changed by a procedure. Variables not modified by a procedure are left out of the KILL set for available expressions. Adding too few variables would result in a too-small estimate for available expressions, yielding a conservative approach to common subexpression elimination.*

(b) What properties are necessary to ensure an iterative data-flow analysis framework terminates?

*The dataflow problem must be monotonic,* i.e., $f(x \wedge y) \leq f(x) \wedge f(y)$. *All chains (sequences of less-than orderings) in the lattice must also have finite length (true for any lattice with finite height).*

(c) What properties are necessary to ensure an iterative data-flow analysis framework terminates with the meet-over-all-paths solution?

*The dataflow problem must be distributive,* i.e., $f(x \wedge y) = f(x) \wedge f(y)$.

11. Instruction scheduling

Consider scheduling the code below using list scheduling. All instructions must complete before executing the `jmp` instruction. Assume the following instruction latencies:

- 2-cycle latency for load
- 1-cycle latency otherwise

```
<op> <dst, s1, s2>
1  load  r1, a
2  add  r2, r1, #4
3  store  x, r2
4  load  r3, b
5  mult  r4, r3, r2
6  load  r1, c
7  add  r5, r1, r3
8  store  y, r5
9  load  r6, d
10 mult  r7, r5, #1
11 store  z, r7
12 jmp
```

(a) Build the precedence graph for the instructions. Mark dependences as flow, anti, or output. You can ignore transitive dependences.

(b) Calculate the critical path for the instructions.

*The following graph shows the critical path for a node as a number next to the node. The number inside a node indicates the latency of its instruction.*
(c) Schedule the instructions for a single-issue processor, using forward list scheduling. Show candidates at each cycle. Prioritize candidates using 1) critical path, 2) latency of instruction, 3) number of children.

<table>
<thead>
<tr>
<th>Time</th>
<th>I-issue</th>
<th>2-issue</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Cand</td>
<td>Inst</td>
</tr>
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<td>1</td>
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<td>1,4,9</td>
</tr>
<tr>
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<td>4,9</td>
<td>4</td>
</tr>
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<tr>
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<td>3</td>
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<td>8</td>
</tr>
<tr>
<td>12</td>
<td>12</td>
<td>12</td>
</tr>
</tbody>
</table>

(d) Schedule the instructions as above, for a two-issue VLIW processor.

See above. Results show that issuing two instructions per cycle is sufficient to achieve maximum performance (equal to critical path).

(e) How could you change register assignments to improve instruction schedules in the code?

Using a new register instead of r1 in instruction 6 & 7 would avoid an antidependence between instruction 2 & 6.

12. Register allocation

Consider the flow graph below. Each statement is labeled by its statement number and each basic block is labeled in the upper right hand corner.

(a) What are the live ranges for a global top-down allocator?

(b) Draw the interference graph for the live ranges.
(c) Use the graph-simplification method to find a coloring for this graph. 
Assume we need 4 registers (since each node has at least 3 neighbors). Begin simplification of the graph by iteratively removing all nodes with fewer than 4 neighbors as follows:

Since we simplify the graph down to a single node, we know 4 colors are sufficient. We can now assign colors to nodes in reverse order. For instance, one assignment would be: b=r1, d=r2, a=r3, c=r4, e=r4.

(d) Can you color this graph with fewer colors? 
No, since nodes a, b, c, d are completely connected. They will thus require at least 4 colors.

(e) If spilling is needed, which live range would be spilled first? Why? 
Live range for b, since its spill cost is lowest due to its references not being in the loop (spill cost of instruction containing use or def is multiplied by loop nesting depth of instruction).

(f) Draw the spill code needed if the value for c is spilled.

3: c = 2+a 
   store mem[c], c // spill c
   load c, mem[c] // reload c
4: d = c+a 
   load c, mem[c] // reload c
5: if c<d goto L2 
   load c, mem[c] // reload c
6: e = c