

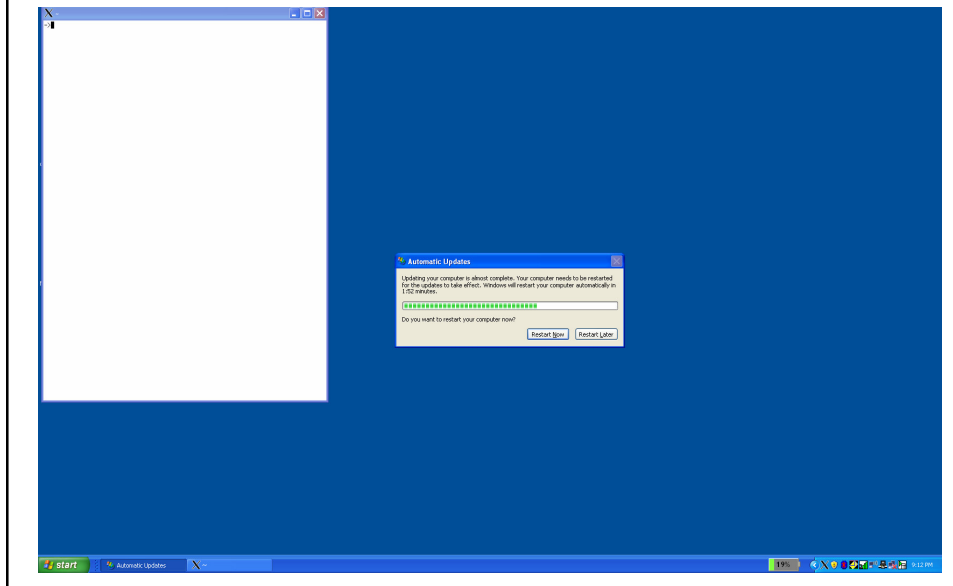
Dynamic Software Updating

Iulian Neamtiu
(sitting in for Dr. Hicks)

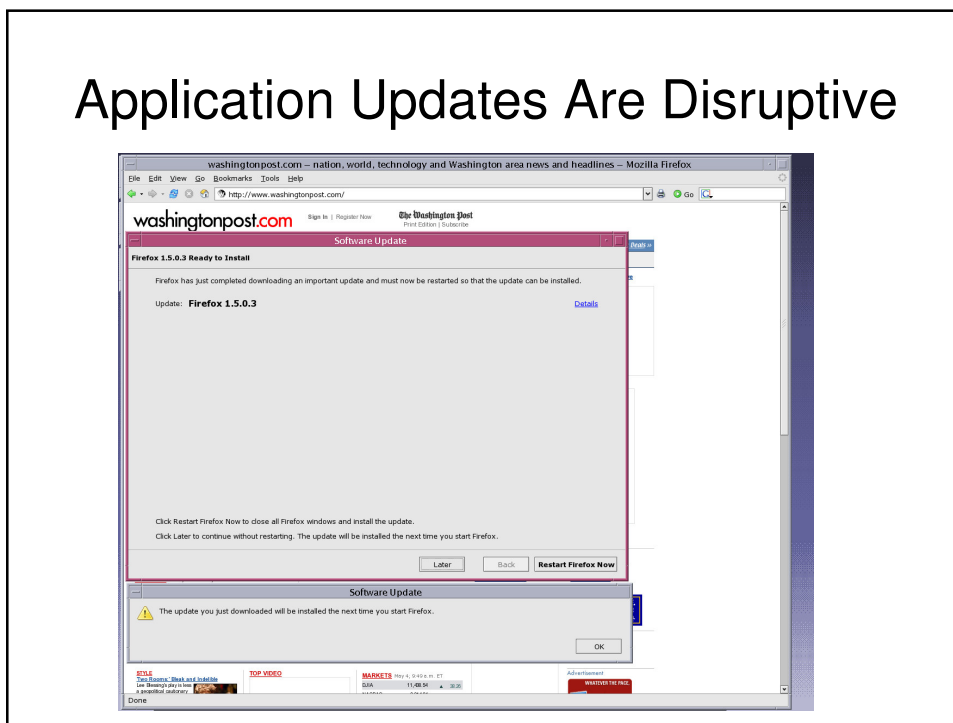
Outline

- The software updating problem
- What is *Dynamic Software Updating* ? Why is DSU useful ?
- How can we build a DSU system ? What are the challenges ?
- Ginseng – a DSU system for userspace apps, developed at UMD
- DSU for operating systems

OS Updates Are Disruptive

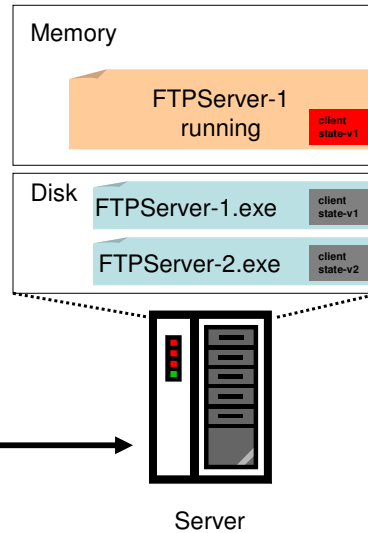


Application Updates Are Disruptive



Case Study: Updating an FTP Server

Goal: update the FTP server
without disrupting service to client



Dynamic Software Updating (DSU)

- Update a **running** program with new code and data
 - Preserves state and processing
- Critical for non-stop systems
 - Air-traffic control, financial transaction processing, network components, ...
- Convenient for other systems
 - No need to reboot your OS after a patch!

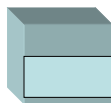
Advantages

- General-purpose
 - Preserves arbitrary application state between updates (requires no state externalization - DB, file system)
- No service disruption
- No redundant hardware
 - Application is updated in place

Developing for DSU

```
accept.c  
cold.c  
common.c  
data.c  
file.c  
libhttpd.c  
loop.c  
main.c  
maint.c  
match.c  
name.c  
nameconvert.c  
readreq.c  
tdate_parse.c  
timer.c
```

- Start: existing source

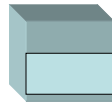


Running system

Developing for DSU

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timer.c
dir_slave.c

- Start: existing source
- Modify program as needed



Running system

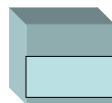
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- Start: existing source
- Modify program as needed
- Compile it and test it



New version

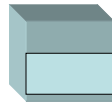


Running system

Developing for DSU

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- Start: existing source
- Modify program as needed
- Compile it and test it
- Develop dynamic patches



Running system

Developing for DSU

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timer.c
dir_slave.c

- Start: existing source
- Modify program as needed
- Compile it and test it
- Develop dynamic patches
- Apply patches to running system



Running system

How can we support/implement dynamic updating ?

DSU for a Hypothetical FTP Server

```
struct clientState {
    sock_t socket;
};

void sendFile(sock_t s){
    buffer b = readFile();
    send(s,b);
}

void server() {
    struct clientState *c = accept();

    while(1) {
        switch (getRequest(c)) {
            case GET_FILE:
                sendFile(c->socket);
            case ...:
        }
        update(); // magic
    }
}
```

Server code, version 1

```
struct clientState {
    stat_s statistics;
    sock_t socket;
};

void sendFile(sock_t s){
    buffer b = readFile();
    if (! errorState(b))
        send(s,b);
}

. . .
```

Server code, version 2

**What do we want to achieve ?
What are the challenges ?**

Challenges

- Flexibility
 - The changes I make to the source code I want to make on-line
- Safety
 - My program shouldn't fail when I do it!
- Efficiency
 - Ease of Use
 - No need for unusual app restructuring.
 - Minimize per-update programmer work.
 - Performance

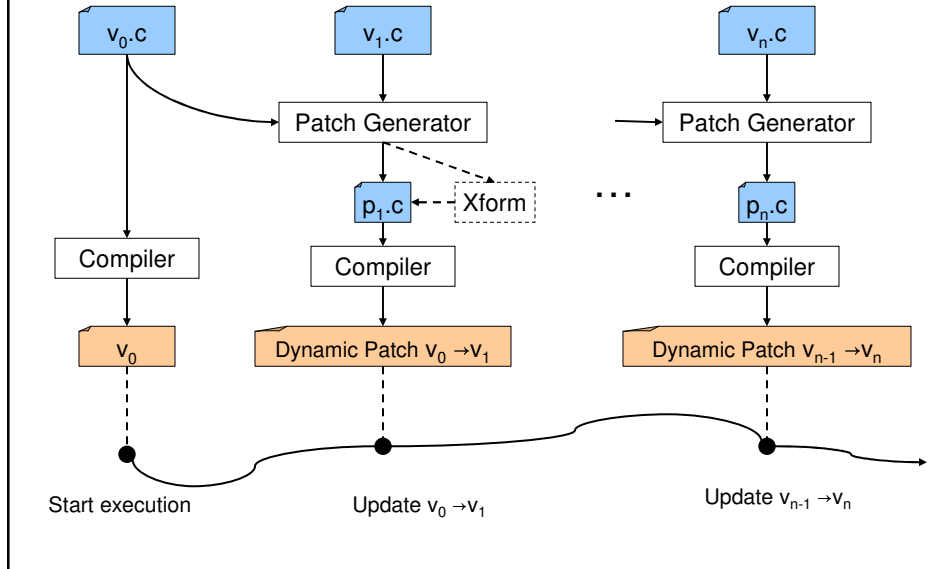
Can We Use Existing Mechanisms for DSU ?

- Kernel modules
 - Kernel extensions
 - Load/unload at runtime
- Dynamically linked libraries (.dll/.so)
 - Implement common services (e.g., `printf`, GUI)
 - Linked into process address space at loadtime

Ginseng

- System for building DSU software
www.cs.umd.edu/projects/dsu
- Approach is practical
 - Broad range of updates to C programs
 - Minimal changes to applications
 - Updates easy to write, mostly automatically
 - Strong safety guarantees
- Validated on realistic applications
 - OpenSSH, VsFTPD, Zebra
 - Three years worth of updates
 - Low performance overhead

Ginseng Architecture



Compilation Techniques

- **Type wrapping**: compiler makes accesses to values of named type to be through special functions
 - Must run type transformers on the accessed value if its type has been updated
- **Function indirection**: compiler adds an indirection between each caller and called function
 - Each function call will always be to the most recent version

Example

```
struct T { int x; int y; };  
void foo(int* x) { *x = 1; }  
void call() {  
    struct T t = {1,2};  
    foo(&t.x);  
}
```

Example: Type wrapping

```
struct __T0 { int x; int y; };  
struct T {  
    unsigned int version;  
    union { struct __T0 data;  
            char slop[...]; } u;  
};  
struct __T0* __con_T(struct T* abs){  
    __DSU_transform(abs);  
    return &abs->u.data;  
}
```

Example: Accessing Types

```
void call() {  
    struct T t = {1,2};  
    foo(&t.x);  
}
```

Example: Accessing Types

```
void call() {  
    struct T t =  
        { 0, {.data={1,2}} };  
    foo(&t.x);  
}
```


Example: Accessing Types

```
void call() {
    struct T t =
        { 0, {.data={1,2}} };
    foo(&(__con_T(&t))->x);
}
```

Type Transformers

```
struct __T0 {
    int    x;
    int    y;
}; //version 0

struct __T1 {
    int    x;
    int    y;
    int    z;
}; //version 1
```



```
void tt_T(__T0 *xin, __T1 *xout) {
    xout->x = xin->x;
    xout->y = xin->y;
    xout->z = 0;
} // type transformer
```

Example: Function Indirection

```
void foo(int* x) { *x = 1; }

void call() {
    struct T t = ...;
    foo(&(con_T(&t))->x);
}
```

Example: Function Indirection

```
void foo_v0(int* x) { *x = 1; }

void call_v0() {
    struct T t = ...;
    foo(&(con_T(&t))->x);
}
```

Example: Function Indirection

```
void* foo_fptr = foo_v0;

void foo_v0(int* x) { *x = 1; }

void call_v0() {
    struct T t = ...;
    foo_fptr(&(con_T(&t))->x);
}
```

Example: Function Indirection

```
void* foo_fptr = foo_v1;
void foo_v1(int* x) { . . . }
void foo_v0(int* x) { . . . }

void call_v0() {
    struct T t = ...;
    foo_fptr(&(con_T(&t))->x);
}
```

Problem: Bad Timing

- Updating `t` when some existing code still expects the old representation could lead to a type error.
 - This situation is timing dependent.

Question: when during a program's execution is it safe to update the representation of a type `t`?

Example: version 1

```
struct T { int x; int y; };  
void foo(int* x) { *x = 1; }  
void call() {  
    struct T t = {1,2};  
    foo(&t.x);  
}
```

Example: version 2

```
struct T { int *x; int y; };  
void foo(int* x) { *x = 1; }  
  
void call() {  
    int z = 1;  
    struct T t = {&z, 2};  
    foo(t.x);  
}
```

Starting execution

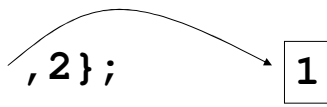
```
struct T { int x; int y; };  
    struct T { int *x; int y; };  
void foo(int* x) { *x = 1; }  
  
void call() {  
> struct T t = {1, 2};  
    foo(&t.x);  
}
```

Attempting update now

```
struct T { int x; int y; };  
    struct T { int *x; int y; };  
void foo(int* x) { *x = 1; }  
  
void call() {  
    struct T t = {1,2};  
    > foo(&t.x);  
}
```

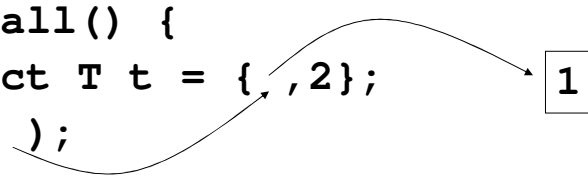
Run type transformer

```
struct T { int *x; int y; };  
  
void foo(int* x) { *x = 1; }  
  
void call() {  
    struct T t = { ,2};  
    > foo(&t.x);  
}
```



Taking the address

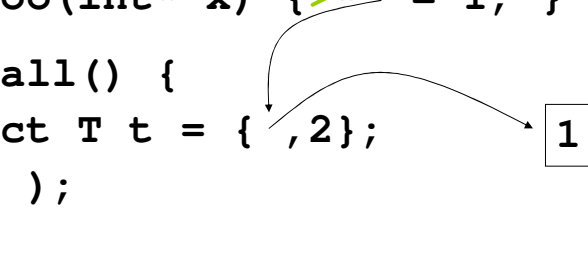
```
struct T { int *x; int y; };  
  
void foo(int* x) { *x = 1; }  
  
void call() {  
    struct T t = { ,2};  
    > foo( );  
}
```



The diagram shows a box containing the number 1. An arrow points from the address-of operator (&) in the call() function to this box. Another arrow points from the first element of the struct initialization { ,2} to the same box.

Call foo()

```
struct T { int *x; int y; };  
  
void foo(int* x) { >* = 1; }  
  
void call() {  
    struct T t = { ,2};  
    foo( );  
}
```



The diagram shows a box containing the number 1. An arrow points from the dereference operator (*) in the foo() function to this box. Another arrow points from the first element of the struct initialization { ,2} in the call() function to the same box.

Doing the assignment: error!

```
struct T { int *x; int y; };  
  
void foo(int* x) {>* = 1; }  
void call() {  
    struct T t = {1,2};  
    foo( );  
}  
foo: expected int*, got int **
```

The problem

- The new program was type correct
- But the old version of `call` was active at the time of the update, and expected the *old* `struct T` rep
 - It uses it *concretely*
- A similar situation occurs when changing the types of functions or global variables

Our Approach: Safety Analysis

- *con_T* functions identify when a type is used **concretely**
- Dynamically prevent updates that could lead to old code concretely using a transformed value
 - Calculate dependencies at compile-time
 - Apply same idea to function calls, global variable references

Example revisited

```
void foo(int* x) {  
  1  *x = 1;  
  2  
}  
  
void call() {  
  struct T t = {1,2};  
  3  foo(&t.x);  
  4  
}
```

Example revisited

```
void foo(int* x) {  
  1 *x = 1;  
  2  
}
```

```
void call() {  
  struct T t = {1,2};  
  3 {T,foo} ←  
  foo(&t.x);  
  4  
}
```

Dependence on type of
T and foo

Example revisited

```
void foo(int* x) {  
  1 {T} ←  
  *x = 1;  
  2 {T} ←  
}
```

```
void call() {  
  struct T t = {1,2};  
  3 {T,foo} ←  
  foo(&t.x);  
  4 {}  
}
```

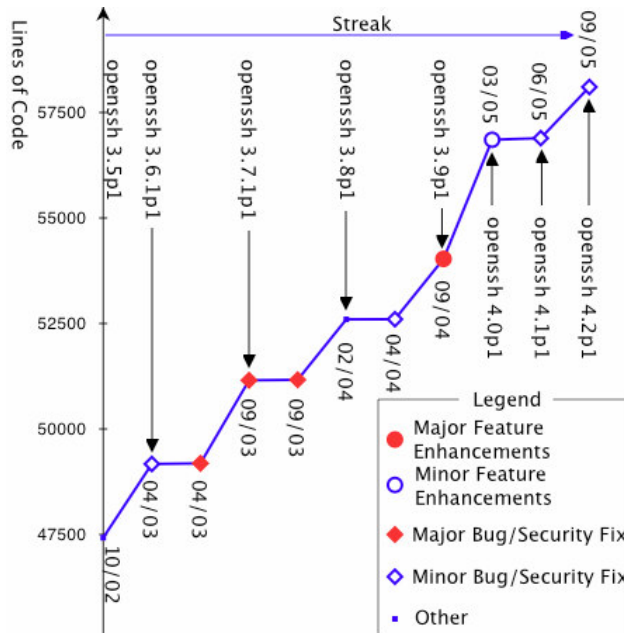
Dependence on type of T

Application Experience

Last 3 years' worth of updates for 3 apps:

- Very secure FTP daemon
 - 10K-17K LOC, 13 releases
 - 6 type changes, 308 function body changes, 33 function proto changes
- OpenSSH daemon
 - 47K-58K LOC, 11 releases
 - 19 type changes, 752 function body changes, 85 function proto changes
- Zebra routing daemon
 - 41K-45K LOC, 6 releases
 - 4 type changes, 321 function body changes, 13 function prototype changes

OpenSSH update summary



Writing Updateable Apps

- Choose *update points*
 - Updates only permitted at conclusion of main event loops
 - two in vsftpd, one in sshd, one in zebra
- Make small application changes
 - Adjustments to potentially unsafe idioms; overrode analysis in a few cases (1-2 per app)
 - Relax application invariants to accommodate updateability
 - Total: 40-50 lines total per app for all three years

Writing Dynamic Patches

- Type transformers
 - Typical change was to add new fields; wrote initializers for these
 - Most frequent was loop state
 - Initialize storage for new variables
 - Carry old state forward
- Update-time initialization
 - Routines normally called in `main()` called at update-time

Experiments

- Throughput
 - Transfer rate in `vsftpd`, `sshd`: **unaffected**
- Overhead
 - Connection setup+tear in `vsftpd`, `sshd`: 0..32%
 - Route setup/route redistribution in `zebra`: 4..12%
- Memory footprint
 - 0..40%
- Update application time
 - Linear with patch size; less than 5 ms

DSU for Operating Systems

- Motivation
 - Application-friendly (no app restart)
 - Preserve state (network, HW)
 - User-friendly (servers)
- Problems
 - Size, complexity, concurrency, low-level
 - DSU-specific: indirection, wrapping

Selective Indirection

- Performance/flexibility trade-off
- Types
 - Fixed representation/no change expected
 - E.g., page table entry, IP address
 - Non-indirected types updated manually
- Functions
 - Indirection/patch size trade-off

When is it safe to update the OS ?

Linux Kernel Modus Operandi

- Mostly: run user processes
- Exceptions: process inline
- “Short” interrupts: process inline
- “Long” interrupts: top half + bottom half
 - Example: timer
- No bottom halves pending ? `schedule()`

Linux Kernel as Event Processor

```
while(1) {  
    switch(event) :  
        interrupt: do_interrupt(); break;  
  
        exception: do_exception(); break;  
  
        bottom_half: do_bottom_half(); break;  
  
        default: schedule();  
}
```

Identify “transactions” (one or more events)
Updates to **T** only permitted outside transactions using **τ**

Performing an OS Update

- Dynamic patch = kernel module
- Update signaling
- Wait for safe update point
- Patch loading
 - Block interrupts
 - Load module, redirect
 - Unblock interrupts

Related Work

- Instrumenting or changing running code
 - Unsanity Application Enhancer (APE)
 - Used to fix Apple security bugs on-the-fly, rather than wait for monthly patch
 - Fix-and-continue language environments
 - In .NET, the JVM, Smalltalk, Common Lisp
 - Dynamic Instrumentation (e.g., DynInst)
- Lack/partial safety analysis, limited flexibility (updates fairly simple)

Conclusions

- Software updates disruptive
- Approaches: checkpointing, DSU, redundant HW, binary rewriting
- DSU can be practical (Ginseng)
 - Can support changes to applications as they occur in practice
 - Process is largely automated
 - Performance overhead negligible for I/O-bound applications
- OSes harder, but not infeasible