

CMSC 631 – Program Analysis and Understanding Spring 2013

Type Systems

The Need for a Type System

- Consider the (untyped) lambda calculus
 - $\text{false} = \lambda x. \lambda y. x$
 - $0 \text{ (Scott)} = \lambda x. \lambda y. x$
- Everything is encoded as a function
 - So we can easily misuse combinators
 - $\text{false } 0$ $\text{if } 0 \text{ then ...}$ etc...
 - This is no better than assembly language!

What is a Type System?

- A *type system* is some mechanism for distinguishing good programs from bad
 - Good programs = well typed
 - Bad programs = ill typed or not typable
- Examples:
 - `0 + 1` // well typed
 - `false 0` // ill-typed: can't apply a boolean
 - `1 + (if true then 0 else false)` // ill-typed: can't add boolean to integer

A Definition of Type Systems

“A type system is a tractable syntactic method for proving the absence of certain program behaviors by classifying phrases according to the kinds of values they compute.”

– Benjamin Pierce, *Types and Programming Languages*

Simply-Typed Lambda Calculus

- $e ::= n \mid x \mid \lambda x:t.e \mid e e$
 - Functions include the type of their argument
 - We don't really need this, but it will come in handy
- $t ::= \text{int} \mid t \rightarrow t$
 - $t1 \rightarrow t2$ is the type of a function that, given an argument of type $t1$, returns a result of type $t2$
 - $t1$ is the *domain*, and $t2$ is the *range*

Type Judgments

- Our type system will prove *judgments* of the form
 - $A \vdash e : t$
 - “In type environment A , expression e has type t ”

Type Environments

- A *type environment* is a map from variables to types (a kind of symbol table)
 - $\emptyset$ is the empty type environment
 - A closed term e is *well-typed* if $\emptyset \vdash e : t$ for some t
 - We'll abbreviate this as $\vdash e : t$
 - $A, x:t$ is just like A , except x now has type t
 - The type of x in $A, x:t$ is t
 - The type of $z \neq x$ in $A, x:t$ is the type of z in A
- When we see a variable in a program, we look in the type environment to find its type

Type Rules

$$\frac{}{A \vdash n : \text{int}}$$
$$x \in \text{dom}(A)$$
$$\frac{}{A \vdash x : A(x)}$$
$$A, x:t \vdash e : t'$$
$$\frac{}{A \vdash \lambda x:t. e : t \rightarrow t'}$$
$$A \vdash e_1 : t \rightarrow t' \quad A \vdash e_2 : t$$
$$\frac{}{A \vdash e_1 e_2 : t'}$$

Example

$A = - : \text{int} \rightarrow \text{int}$

$$\frac{\frac{- \in \text{dom}(A)}{A \vdash - : \text{int} \rightarrow \text{int}} \quad A \vdash 3 : \text{int}}{A \vdash - 3 : \text{int}}$$

Another Example

$A = + : \text{int} \rightarrow \text{int} \rightarrow \text{int}$

$B = A, x : \text{int}$

$$\frac{\frac{\frac{+ \in \text{dom}(B)}{B \vdash + :} \quad \frac{x \in \text{dom}(B)}{B \vdash x : \text{int}}}{B \vdash + x : \text{int} \rightarrow \text{int}} \quad B \vdash 3 : \text{int}}{B \vdash + x 3 : \text{int}} \quad A \vdash 4 : \text{int}}{A \vdash (\lambda x : \text{int}. + x 3) : \text{int} \rightarrow \text{int}} \quad A \vdash (\lambda x : \text{int}. + x 3) 4 : \text{int}$$

We'd usually use infix $x + 3$

An Algorithm for Type Checking

- Our type rules are deterministic
 - For each syntactic form, only one possible rule
- They define a natural type checking algorithm

- $\text{TypeCheck} : \text{type env} \times \text{expression} \rightarrow \text{type}$

$\text{TypeCheck}(A, n) = \text{int}$

$\text{TypeCheck}(A, x) = \text{if } x \text{ in dom}(A) \text{ then } A(x) \text{ else fail}$

$\text{TypeCheck}(A, \lambda x:t.e) = t \rightarrow (\text{TypeCheck}((A, x:t), e))$

$\text{TypeCheck}(A, e1 \ e2) =$

 let $t1 = \text{TypeCheck}(A, e1)$ in

 let $t2 = \text{TypeCheck}(A, e2)$ in

 if $\text{dom}(t1) = t2$ then $\text{range}(t1)$ else fail

Semantics

- Here is a small-step, call-by-value semantics
 - If an expression can't be evaluated any more and is not a value, then it is *stuck*

$$\frac{}{(\lambda x:t.e1) v2 \rightarrow e1[x \mapsto v2]} \qquad \frac{e1 \rightarrow e1'}{e1 e2 \rightarrow e1' e2}$$

$$\frac{e2 \rightarrow e2'}{v1 e2 \rightarrow v1 e2'}$$

$$e ::= v \mid x \mid e e$$

$$v ::= n \mid \lambda x:t.e \quad \text{values – not evaluated}$$

Progress

- Suppose $\vdash e : t$. Then either e is a value, or there exists e' such that $e \rightarrow e'$
- Proof by induction on e
 - Base cases $n, \lambda x.e$ – these are values, so we're done
 - Base case x – can't happen (empty type environment)
 - Inductive case $e_1 e_2$ – If e_1 is not a value, then by induction we can evaluate it, so we're done, and similarly for e_2 . Otherwise both e_1 and e_2 are values. Inspection of the type rules shows that e_1 must have a function type, and therefore must be a lambda since it's a value. Therefore we can make progress.

Preservation

- If $\vdash e : t$ and $e \rightarrow e'$ then $\vdash e' : t$
- Proof by induction on $e \rightarrow e'$
 - Induction (easier than the base case!). Expression e must have the form $e_1 \mid e_2$.
 - Assume $\vdash e_1 \mid e_2 : t$ and $e_1 \mid e_2 \rightarrow e'$. Then we have $\vdash e_1 : t' \rightarrow t$ and $\vdash e_2 : t'$.
 - Then there are three cases.
 - If $e_1 \rightarrow e_1'$, then by induction $\vdash e_1' : t' \rightarrow t$, so $e_1' \mid e_2$ has type t
 - If reduction inside e_2 , similar

Preservation, cont'd

- Otherwise $(\lambda x:t'.e) v \rightarrow e[x \mapsto v]$. Then we have

$$\frac{x:t' \vdash e:t}{\vdash \lambda x:t'.e : t' \rightarrow t}$$

- Thus we have
 - $x:t' \vdash e:t$
 - $\vdash v:t'$
- Then by the substitution lemma (not shown) we have
 - $\vdash e[x \mapsto v] : t$
- And so we have preservation

Substitution Lemma

- If $A \vdash v : t$ and $A, x:t \vdash e : t'$, then $A \vdash e[x \mapsto v] : t'$
- Proof: Induction on the structure of e
- For lazy semantics, we'd prove
 - If $A \vdash e_l : t$ and $A, x:t \vdash e : t'$, then $A \vdash e[x \mapsto e_l] : t'$

Soundness

- So we have
 - Progress: Suppose $\vdash e : t$. Then either e is a value, or there exists e' such that $e \rightarrow e'$
 - Preservation: If $\vdash e : t$ and $e \rightarrow e'$ then $\vdash e' : t$
- Putting these together, we get soundness
 - If $\vdash e : t$ then either there exists a value v such that $e \rightarrow^* v$, or e diverges (doesn't terminate).
- What does this mean?
 - Evaluation getting stuck is bad, so
 - “Well-typed programs don't go wrong”

Product Types (Tuples)

$e ::= \dots \mid (e, e) \mid \text{fst } e \mid \text{snd } e$

$$\frac{A \vdash e_1 : t \quad A \vdash e_2 : t'}{A \vdash (e_1, e_2) : t \times t'}$$

$$\frac{A \vdash e : t \times t'}{A \vdash \text{fst } e : t} \qquad \frac{A \vdash e : t \times t'}{A \vdash \text{snd } e : t'}$$

- Or, maybe, just add functions
 - $\text{pair} : t \rightarrow t' \rightarrow t \times t'$
 - $\text{fst} : t \times t' \rightarrow t$
 - $\text{snd} : t \times t' \rightarrow t'$

Sum Types (Tagged Unions)

$$e ::= \dots \mid \text{inL}_{t_2} e \mid \text{inR}_{t_1} e \\ \mid (\text{case } e \text{ of } x_1:t_1 \rightarrow e_1 \mid x_2:t_2 \rightarrow e_2)$$

$$\frac{A \vdash e : t_1}{A \vdash \text{inL}_{t_2} e : t_1 + t_2} \quad \frac{A \vdash e : t_2}{A \vdash \text{inR}_{t_1} e : t_1 + t_2}$$

$$\frac{\begin{array}{c} A \vdash e : t_1 + t_2 \\ A, x_1:t_1 \vdash e_1 : t \quad A, x_2:t_2 \vdash e_2 : t \end{array}}{A \vdash (\text{case } e \text{ of } x_1:t_1 \rightarrow e_1 \mid x_2:t_2 \rightarrow e_2) : t}$$

Self Application and Types

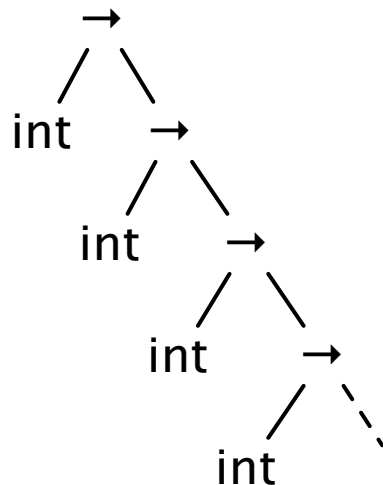
- Self application is not checkable in our system

$$\frac{\frac{A, x:? \vdash x : t \rightarrow t' \quad A, x:? \vdash x : t}{A, x:? \vdash x x : \dots}}{A \vdash \lambda x:?.x x : \dots}$$

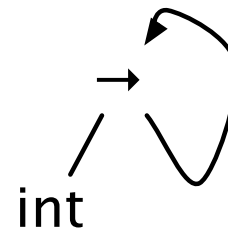
- It would require a type t such that $t = t \rightarrow t'$
 - (We'll see this next, but so far...)
- The simply-typed lambda calculus is *strongly normalizing*
 - Every program has a normal form
 - I.e., every program halts!

Recursive Types

- We can type self application if we have a type to represent the solution to equations like $t = t \rightarrow t'$
 - We define the type $\mu\alpha.t$ to be the solution to the (recursive) equation $\alpha = t$
 - Example: $\mu\alpha.\text{int} \rightarrow \alpha$

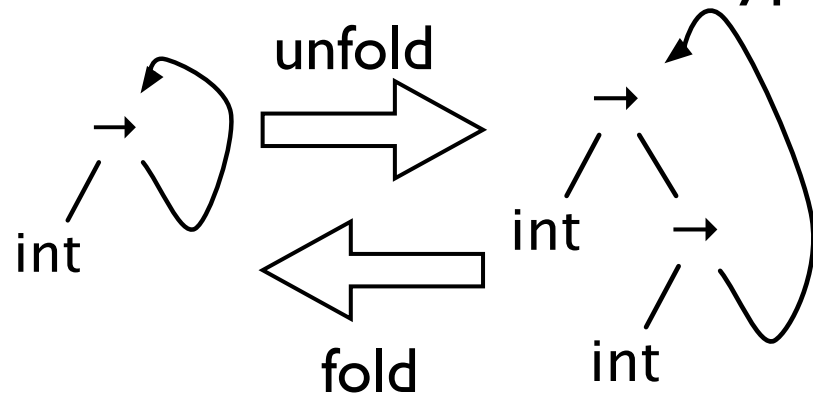


or



Folding and Unfolding

- We can check type equivalence with the previous definition (*equi-recursive types*)
 - Standard unification, omit occurs checks
- Alternative solution (*iso-recursive types*):
 - The programmer puts in explicit *fold* and *unfold* operations to expand/contract one “level” of the type trees
 - $\text{unfold } \mu\alpha.t = t[\alpha \mapsto \mu\alpha.t]$
 - $\text{fold } t[\alpha \mapsto \mu\alpha.t] = \mu\alpha.t$



Iso-recursive Types

- $e ::= \dots \mid \text{fold } e \mid \text{unfold } e$

$$A \vdash e : t[\alpha \mapsto \mu\alpha.t]$$

$$A \vdash \text{fold } e : \mu\alpha.t$$
$$A \vdash e : \mu\alpha.t$$

$$A \vdash \text{unfold } e : t[\alpha \mapsto \mu\alpha.t]$$

ML Datatypes

- Combines iso-recursive and sum types
 - Each occurrence of a type constructor when producing a value corresponds to occurrences of **inL/inR** and, when recursion is involved, **fold**
 - Each occurrence of a type constructor in a pattern match corresponds to a **case** and, when recursion is involved, (at least one) **unfold**

ML Datatypes Example

- $\text{type intlist} = \text{Int of int} \mid \text{Cons of int} * \text{intlist}$
 - Equivalent to $\mu\alpha.\text{int} + (\text{int} \times \alpha)$
- $(\text{Int } 3)$ equivalent to
 - $\text{fold } (\text{inL}_{\text{int} \times \mu\beta.\text{int} + (\text{int} \times \beta)}) \ 3)$
- $(\text{Cons } (2, (\text{Int } 3)))$ equivalent to
 - $\text{fold } (\text{inR}_{\text{int}} \ (2, \text{fold } (\text{inL}_{\text{int} \times \mu\beta.\text{int} + (\text{int} \times \beta)}) \ 3)))$
- $\text{match } e \text{ with } \text{Int } x \rightarrow e1 \mid \text{Cons } x \rightarrow e2$ same as
 - $\text{case } (\text{unfold } e)$
 - $x:\text{int} \rightarrow e1$
 - $\mid x:\text{int} \times (\mu\beta.\text{int} + (\text{int} \times \beta)) \rightarrow e2$

Discussion

- In the pure lambda calculus, every term is typable with recursive types
 - (Pure = variables, functions, applications only)
- Most languages have some kind of “recursive” type
 - E.g., for data structures like lists, tree, etc.
- However, usually two recursive types that define the same structure but use a different name are considered different
 - E.g., `struct foo { int x; struct foo *next; }` is different from `struct bar { int x; struct bar *next; }`

Recap

- We've discussed simple types so far
 - Integers, functions, pairs, unions
 - Extensions for recursive types and updatable refs
- Type systems have nice properties
 - Type checking is straightforward (needs annotations)
 - Well typed programs don't go "wrong"
 - They don't get stuck in the operational semantics
- But...We can't type check all good programs

Up Next: Improving Types

- How can we build more flexible type systems?
 - More programs type check
 - Type checking is still tractable
- How can reduce the annotation burden?
 - Type inference

Parametric Polymorphism

- Observation: $\lambda x.x$ returns its argument exactly and places no constraints on the type of x
 - The identity function works for any argument type
- We can express this with *universal quantification*:
 - $\lambda x.x : \forall \alpha. \alpha \rightarrow \alpha$
 - For any type α , the identity function has type $\alpha \rightarrow \alpha$
 - This is also known as *parametric polymorphism*

System F: annotated polymorphism

- Let's extend our system as follows:
 - $t ::= \alpha \mid \text{int} \mid t \rightarrow t \mid \forall \alpha. t$
 - $e ::= n \mid x \mid \lambda x. e \mid e e \mid \Lambda \alpha. e \mid e [t]$
- That is, we add polymorphic types, and we add explicit *type abstraction (generalization)* ...
 - Annotated code locations at which a value of polymorphic type is created
- ... and *type application (instantiation)*
 - Explicitly annotated code locations at which a value of polymorphic type is used
- This system due to Girard, concurrently Reynolds

Defining Polymorphic Functions

- Polymorphic functions map types to terms
 - Normal functions map terms to terms
- Examples
 - $\lambda\alpha.\lambda x:\alpha.x : \forall\alpha.\alpha \rightarrow \alpha$
 - $\lambda\alpha.\lambda\beta.\lambda x:\alpha.\lambda y:\beta.x : \forall\alpha.\forall\beta.\alpha \rightarrow \beta \rightarrow \alpha$
 - $\lambda\alpha.\lambda\beta.\lambda x:\alpha.\lambda y:\beta.y : \forall\alpha.\forall\beta.\alpha \rightarrow \beta \rightarrow \beta$

Instantiation

- When we use a parametric polymorphic type, we *apply* (or *instantiate*) it with a particular type
 - In System F this is done by hand:
 - $(\lambda\alpha.\lambda x:\alpha.x)[t1] : t1 \rightarrow t1$
 - $(\lambda\alpha.\lambda x:\alpha.x)[t2] : t2 \rightarrow t2$
- This is where the term *parametric* comes from
 - The type $\forall\alpha.\alpha \rightarrow \alpha$ is a “function” in the domain of types, and it is passed a parameter at instantiation time

Type Rules

$$\frac{A, \alpha \vdash e : t}{A \vdash \lambda \alpha. e : \forall \alpha. t}$$

$$\frac{A \vdash e : \forall \alpha. t}{A \vdash e[t'] : t[\alpha \mapsto t']}$$

- Notice that there are no constructs for manipulating values of polymorphic type
 - This justifies instantiation with *any* type—that's what the forall means!
- Note also that we are adding α to A ; we could (should?) use this to ensure types are well-formed

Small-step Semantics Rules

$$\frac{}{(\Lambda\alpha.e)[t] \rightarrow e[\alpha \mapsto t]} \text{ (type-app)} \qquad \frac{e \rightarrow e'}{e[t] \rightarrow e'[t]} \text{ (tapp-cong)}$$

- We have to extend substitution to include types; that's up next ... !

Free Variables, Again

- We're going to need to perform substitutions on quantified types
 - So just like with lambda calculus, we need to worry about free variables and capture-free substitution
- Define the free variables of a type
 - $FV(\alpha) = \{\alpha\}$
 - $FV(c) = \emptyset$
 - $FV(t \rightarrow t') = FV(t) \cup FV(t')$
 - $FV(\forall \alpha. t) = FV(t) - \{\alpha\}$

Substitution, Again

- Define $t[\alpha \mapsto u]$ as
 - $\alpha[\alpha \mapsto u] = u$
 - $\beta[\alpha \mapsto u] = \beta$ where $\beta \neq \alpha$
 - $(t \rightarrow t')[\alpha \mapsto u] = t[\alpha \mapsto u] \rightarrow t'[\alpha \mapsto u]$
 - $(\forall \beta. t)[\alpha \mapsto u] = \forall \beta. (t[\alpha \mapsto u])$ where $\beta \neq \alpha$ and $\beta \notin FV(u)$
- Define $e[\alpha \mapsto u]$ as
 - $(\lambda x:t. e)[\alpha \mapsto u] = \lambda x:t[\alpha \mapsto u]. e[\alpha \mapsto u]$
 - $(\Lambda \beta. e)[\alpha \mapsto u] = \Lambda \beta. e[\alpha \mapsto u]$ where $\beta \neq \alpha$ and $\beta \notin FV(u)$
 - $(e_1 \mid e_2)[\alpha \mapsto u] = e_1[\alpha \mapsto u] \mid e_2[\alpha \mapsto u]$
 - $x[\alpha \mapsto u] = x$ and $n[\alpha \mapsto u] = n$

An Imperative Language

$e ::= x \mid \lambda x.e \mid e e$

| $\text{ref } e$

allocation

| $!e$

dereference

| $e := e$

assignment

| $e; e$

sequencing

- Notice that this is not C
 - Variables cannot be updated; only references can
 - I.e., there are no l-values or r-values
- This is a language with *updatable references*

Examples

$!(\text{ref } 0)$

let $x = \text{ref } 0$ in
 $x := !x + 1$

let $x = \text{ref } 0$ in
 $\lambda y. x := !x + 1; !x$

Type Checking Rules

- $t ::= \dots \mid \text{ref } t$
 - Note: in ML this type is written $t \text{ ref}$

$$\frac{A \vdash e : t}{A \vdash \text{ref } e : \text{ref } t}$$

$$\frac{A \vdash e : \text{ref } t}{A \vdash !e : t}$$

$$\frac{A \vdash e1 : \text{ref } t \quad A \vdash e2 : t}{A \vdash e1 := e2 : t}$$

Unit and the Unit Type

- Sometimes in imperative programs we write expressions that have some *side effect* but no interesting result
- To represent this directly, use *unit*:
 - $e ::= \dots \mid ()$
 - $t ::= \dots \mid \text{unit}$

$$A \vdash () : \text{unit}$$

$$A \vdash e1 : \text{ref } t \quad A \vdash e2 : t$$

$$A \vdash e1 := e2 : \text{unit}$$

Operational Semantics

- Now we need to keep track of memory
 - State is a map from locations to values
 - Our redexes will be tuples $\langle \text{State}, \text{expression} \rangle$
 - As a consequence, order of evaluation matters
- As before, evaluation will yield a fully-evaluated term, also called a *value*
 - $v ::= x \mid \lambda x.e$
 - $e ::= v \mid e e \mid \text{ref } e \mid !e \mid e := e$

Operational Semantics (cont'd)

$$\langle S, (\lambda x. e1) \rangle \rightarrow \langle S, (\lambda x. e1) \rangle$$

$$\langle S, e1 \rangle \rightarrow \langle S', v1 \rangle \quad \langle S', e2 \rangle \rightarrow \langle S'', v2 \rangle$$

$$\langle S, e1; e2 \rangle \rightarrow \langle S'', v2 \rangle$$

$$\langle S, e \rangle \rightarrow \langle S', v \rangle \quad \text{loc fresh}$$

$$\langle S, \text{ref } e \rangle \rightarrow \langle S[\text{loc} \mapsto v], \text{loc} \rangle$$

Operational Semantics (cont'd)

$$\frac{\langle S, e \rangle \rightarrow \langle S', \text{loc} \rangle}{\langle S, !e \rangle \rightarrow \langle S', S'(\text{loc}) \rangle}$$

$$\frac{\langle S, e1 \rangle \rightarrow \langle S', \text{loc} \rangle \quad \langle S', e2 \rangle \rightarrow \langle S'', v \rangle}{\langle S, e1 := e2 \rangle \rightarrow \langle S''[\text{loc} \mapsto v], v \rangle}$$

$$\frac{\langle S, e1 \rangle \rightarrow \langle S', \lambda x.e \rangle \quad \langle S', e2 \rangle \rightarrow \langle S'', v \rangle \quad \langle S'', e[x \mapsto v] \rangle \rightarrow \langle S''', v' \rangle}{\langle S, e1 \ e2 \rangle \rightarrow \langle S''', v' \rangle}$$

Type Inference

- Let's reconsider the simply typed lambda calculus with integers
 - $e ::= n \mid x \mid \lambda x:t.e \mid e e$
 - (No parametric polymorphism)
- *Type inference*: Given a bare term (with no type annotations), can we reconstruct a valid typing for it, or show that it has no valid typing?

Type Language

- Problem: Consider the rule for functions

$$\frac{A, x:t \vdash e : t'}{A \vdash \lambda x:t. e : t \rightarrow t'}$$

- Without type annotations, where do we get t ?
 - We'll use *type variables* to stand for as-yet-unknown types
 - $t ::= \alpha \mid \text{int} \mid t \rightarrow t$
 - We'll generate *equality constraints* $t = t$ among the types and type variables
 - And then we'll solve the constraints to compute a typing

Type Inference Rules

$$\frac{}{A \vdash n : \text{int}}$$
$$\frac{x \in \text{dom}(A)}{A \vdash x : A(x)}$$
$$\frac{A, x:\alpha \vdash e : t' \quad \alpha \text{ fresh}}{A \vdash \lambda x.e : \alpha \rightarrow t'}$$
$$A \vdash e_1 : t_1 \quad A \vdash e_2 : t_2$$
$$\boxed{t_1 = t_2 \rightarrow \beta} \quad \beta \text{ fresh}$$
$$\frac{}{A \vdash e_1 e_2 : \beta}$$

“Generated” constraint

Example

$$\frac{\frac{A, x:\alpha \vdash x:\alpha}{A \vdash (\lambda x.x) : \alpha \rightarrow \alpha} \quad A \vdash 3 : \text{int} \quad \alpha \rightarrow \alpha = \text{int} \rightarrow \beta}{A \vdash (\lambda x.x) 3 : \beta}$$

- We collect all constraints appearing in the derivation into some set C to be solved
- Here, C contains just $\alpha \rightarrow \alpha = \text{int} \rightarrow \beta$
 - Solution: $\alpha = \text{int} = \beta$
- Thus this program is typable, and we can derive a typing by replacing α and β by int in the proof

Solving Equality Constraints

- We can solve the equality constraints using the following rewrite rules, which reduce a larger set of constraints to a smaller set
 - $C \cup \{\text{int}=\text{int}\} \Rightarrow C$
 - $C \cup \{\alpha=t\} \Rightarrow C[\alpha \mapsto t]$
 - $C \cup \{t=\alpha\} \Rightarrow C[\alpha \mapsto t]$
 - $C \cup \{t_1 \rightarrow t_2 = t_1' \rightarrow t_2'\} \Rightarrow C \cup \{t_1 = t_1'\} \cup \{t_2 = t_2'\}$
 - $C \cup \{\text{int} = t_1 \rightarrow t_2\} \Rightarrow \text{unsatisfiable}$
 - $C \cup \{t_1 \rightarrow t_2 = \text{int}\} \Rightarrow \text{unsatisfiable}$

Termination

- We can prove that the constraint solving algorithm terminates.
- For each rewriting rule, either
 - We reduce the size of the constraint set
 - We reduce the number of “arrow” constructors in the constraint set
- As a result, the constraint always gets “smaller” and eventually becomes empty
 - A similar argument is made for strong normalization in the simply-typed lambda calculus

Occurs Check

- We don't have recursive types, so we shouldn't infer them
- So in the operation $C[\alpha \mapsto t]$, require that $\alpha \notin FV(t)$
 - (Except if $t = a$, in which case there's no recursion in the types, so unification should succeed)
- In practice, it may be better to allow $\alpha \in FV(t)$ and do the occurs check at the end
 - But that can be awkward to implement

Unifying a Variable and a Type

- Computing $C[\alpha \mapsto t]$ by substitution is inefficient
- Instead, use a union-find data structure to represent equal types
 - The terms are in a union-find forest
 - When a variable and a term are equated, we union them so they have the same ECR (equivalence class representative)
 - Want the ECR to be the concrete type with which variables have been unified, if one exists. Can read off solution by reading the ECR of each set.

Example



$\alpha = \text{int} \rightarrow \beta$
 $\gamma = \text{int} \rightarrow \text{int}$
 $\alpha = \gamma$

Unification

- The process of finding a solution to a set of equality constraints is called *unification*
 - Original algorithm due to Robinson
 - But his algorithm was inefficient
 - Often written out in different form
 - See Algorithm W
 - Constraints usually solved on-line
 - As type inference rules applied

Discussion

- The algorithm we've given finds the *most general type* of a term
 - Any other valid type is “more specific,” e.g.,
 - $\lambda x.x : \text{int} \rightarrow \text{int}$
 - Formally, any other valid type can be gotten from the most general type by applying a substitution to the type variables
- This is still a *monomorphic* type system
 - α stands for “some particular type, but it doesn't matter exactly which type it is”

Inference for Polymorphism

- We would like to have the power of System F, and the ease of use of type inference
 - In short: given an untyped lambda calculus term, can we discover the annotations necessary for typing the term in System F, if such a typing is possible?
 - Unfortunately, no. This problem has been shown to be undecidable.
- Can we at least perform some type inference for parametric polymorphism?
 - Yes. A sweet spot was found by Hindley and Milner
 - But first, let's consider the general case ...

Attempting Type Inference

- Let's extend simply-typed calculus as follows:
 - $t ::= \alpha \mid \text{int} \mid t \rightarrow t \mid \forall \alpha. t$
 - $e ::= n \mid x \mid \lambda x. e \mid e e$
- Type inference will automatically infer where to generalize a term, to introduce polymorphic types, and where to instantiate them

Instantiation

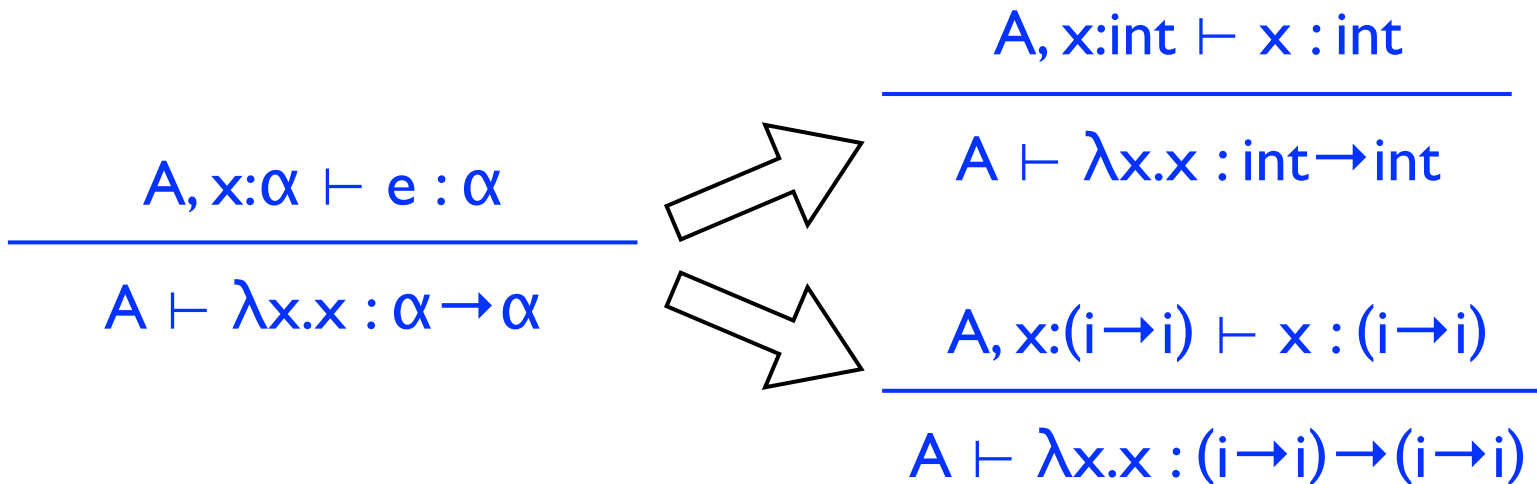
$$\frac{A \vdash e : \forall \alpha. t}{A \vdash e : t[\alpha \mapsto t']}$$

- This rule is exactly the same as System F, but we just “magically” pick which t to instantiate with
 - You’re surely wondering about algorithmics. We’ll get to that ...

Generalization

- Question: When is it safe to generalize (quantify) a type variable α in the type of expression e ?
- Answer: Whenever we can redo the typing proof for e , choosing α to be anything we want, and still have a valid typing proof.

Examples



- The choice of the type of x is purely local to type checking $\lambda x.x$
 - There is no interaction with the outside environment
 - Thus we can generalize the type of x

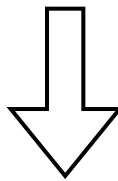
Examples (cont'd)

$$\frac{A, x:\text{int} \vdash x : \text{int}}{A \vdash \lambda x. x+3 : \text{int} \rightarrow \text{int}}$$

- The function restricts the type of x , so we cannot introduce a type variable
 - Thus we cannot generalize the type of x
 - We can only generalize when the function doesn't “look at” its parameter

Examples (cont'd)

$$\frac{A, y:\alpha, x:\alpha \vdash \text{if } p \text{ then } x \text{ else } y : \alpha}{A, y:\alpha \vdash \lambda x. \text{if } p \text{ then } x \text{ else } y : }$$



$$\frac{A, y:\alpha, x:\text{int} \vdash \text{if } p \text{ then } x \text{ else } y : \text{int}}{A, y:\alpha \vdash \lambda x. \text{if } p \text{ then } x \text{ else } y : \text{int} \rightarrow \text{int}}$$

- The choice of the type of x depends on the type environment
 - In the first derivation, x and y have the same type; if we generalize the type of x , they could have different types
 - Thus we cannot generalize the type of x

Generalization Rule

$$\frac{A \vdash e : t \quad \alpha \notin FV(A)}{A \vdash e : \forall \alpha. t}$$

- We can generalize any type variable that is unconstrained by the environment
 - Warning: This won't quite work with refs

Another Justification

- Suppose we have
 - $A \vdash e : t$ and $\alpha \notin FV(A)$
- Then let u be any type. By induction, can show
 - $A[\alpha \mapsto u] \vdash e : t[\alpha \mapsto u]$
 - But then since $\alpha \notin FV(A)$, that's equivalent to
 - $A \vdash e : t[\alpha \mapsto u]$

Polymorphic Type Inference

- We'd like to extend our algorithm to polymorphic type inference
 - Performance generalization and instantiation automatically (and deterministically)
- Major problem: Our system for polymorphism is too expressive

Hindley-Milner Polymorphism

- Restrict polymorphism to only the “top level”
 - Introduce polymorphism at **let**
 - Fully instantiate at use of a polymorphic type
- Here is our new language
 - $e ::= n \mid x \mid \lambda x.e \mid e e \mid \text{let } x = e \text{ in } e$
 - $t ::= \alpha \mid \text{int} \mid t \rightarrow t$
 - $s ::= t \mid \forall \alpha.s$
 - These are *type schemes*
 - $A ::= \emptyset \mid A, x:s$
 - Notice that, according to the prior instantiation rule, we won't instantiate α with a scheme s , only a type t

Old Type Inference Rules

$$\frac{}{A \vdash n : \text{int}}$$

$$\frac{A, x:\alpha \vdash e : t' \quad \alpha \text{ fresh}}{A \vdash \lambda x.e : \alpha \rightarrow t'}$$

$$\frac{A \vdash e_1 : t_1 \quad A \vdash e_2 : t_2 \quad t_1 = t_2 \rightarrow \beta \quad \beta \text{ fresh}}{A \vdash e_1 e_2 : \beta}$$

New Type Inference Rules

- At **let**, generalize over all possible variables

$$\frac{A \vdash e1 : t1 \quad A, x : \forall \vec{\alpha}. t1 \vdash e2 : t2 \quad \vec{\alpha} = FV(t1) - FV(A)}{A \vdash \text{let } x = e1 \text{ in } e2 : t2}$$

- At variable uses, instantiate to all fresh types

$$\frac{A(x) = \forall \vec{\alpha}. t \quad \vec{\beta} \text{ fresh}}{A \vdash x : t[\vec{\alpha} \mapsto \vec{\beta}]}$$

- Here the $\vec{\alpha}$ denotes a list of type variables

Algorithm W

- A type inference algorithm that explicitly solves the equality constraints on-line
- Instead of implicit global substitution (like we used before), threads the substitution through the inference
- In practice, use previous algorithm, plus generalize at let and instantiate at variable uses.
 - Solve for the type of e_1 , generalize it, then instantiate its solution when doing inference on e_2

Example

- Parametric polymorphic type inference

let $x = \lambda x.x$ in // $x : \forall \alpha. \alpha \rightarrow \alpha$

$x \ 3;$ // $x : \beta \rightarrow \beta, \ \beta = \text{int}$

$x \ (\lambda y.y)$ // $x : \gamma \rightarrow \gamma, \ \gamma = \delta \rightarrow \delta$

- This would be untypable in a monomorphic type system

Kinds of Polymorphism

- We've just seen parametric polymorphism
 - System F and Hindley-Milner style polymorphism
- Another popular form is subtype polymorphism
 - As in OO programming
 - These two can be combined (e.g., Java Generics)
- Some languages also have *ad-hoc polymorphism*
 - E.g., + operator that works on ints and floats
 - E.g., overloading in Java

Polymorphism and References

- Suppose we want polymorphism in our imperative language

- $e ::= x \mid n \mid \lambda x.e \mid e \ e \mid \text{ref } e \mid !e \mid e := e$
- $s ::= t \mid \forall \alpha.s$
- $t ::= \alpha \mid \text{int} \mid t \rightarrow t \mid \text{ref } t$

- What if we try our standard rule?

$$\frac{A \vdash e1 : t1 \quad A, x : \forall \vec{\alpha}. t1 \vdash e2 : t2 \quad \vec{\alpha} = \text{FV}(t1) - \text{FV}(A)}{A \vdash \text{let } x = e1 \text{ in } e2 : t2}$$

Naive Generalization is Unsound

- Example (due to Tofte)

let $r = \text{ref } (\lambda x.x)$ in // $r : \forall \alpha. \text{ref } (\alpha \rightarrow \alpha)$

$r := \lambda x.x+1$; // checks; use r at $\text{ref } (\text{int} \rightarrow \text{int})$

$(!r) \text{ true}$ // oops! checks; use r at $\text{ref}(\text{bool} \rightarrow \text{bool})$

- α should not be generalized, because later uses of r may place constraints on it
- Nobody realized there was a problem for a long time

Solution: The Value Restriction

- Only allow *values* to be generalized
 - $v ::= x \mid n \mid \lambda x.e$
 - $e ::= v \mid e\ e \mid \text{ref } e \mid !e \mid e := e$

$$\frac{A \vdash v : t1 \quad A, x : \forall \alpha. t \vdash e2 : t2 \quad \alpha = \text{FV}(t) - \text{FV}(A)}{A \vdash \text{let } x = v \text{ in } e2 : t2}$$

- Intuition: Values cannot later be updated
- This solution due to Wright and Felleisen
 - Tofte found a much more complicated solution

Benefits of Type Inference

- Handles higher-order functions
- Handles data structures smoothly
- Works in infinite domains
 - Set of types is unlimited
- No forward/backward distinction
- Polymorphism provides context-sensitivity

Drawbacks to Type Inference

- Flow-insensitive
 - Types are the same at all program points
 - May produce coarse results
 - Type inference failure can be hard to understand
- Polymorphic type inference may not scale
 - Exponential in worst case
 - Seems fine in practice (witness ML)