

Procedural shapes

CMSC425.01 Spring 2019

Administrivia

- Exam graded, solutions posted
- Project 2b due Tuesday, April 16th

Today's question

How to create interesting shape assets

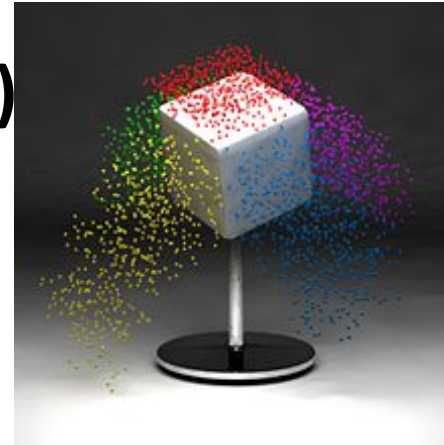
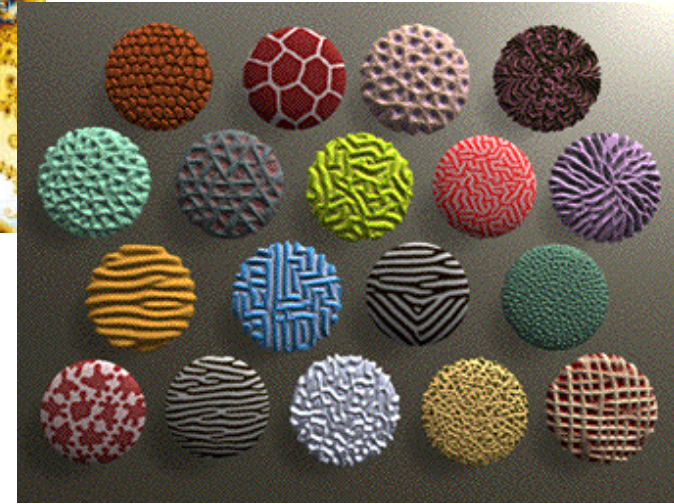
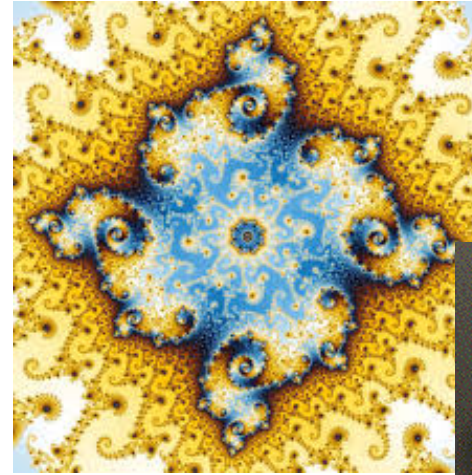
Autogenerating terrain, objects, animations

- Why
 - Efficiency – faster than by hand
 - Variety – generate variations on a template
 - LOD – Generate level of detail as needed (*billboarding* in Unity)
- How:
 - Offline procedural generation: create, store mesh, add
 - Online – during game: shape represented by subroutine/object, not a fixed
- What:
 - 3D shapes, 2D textures
 - Fake real (eg, trees), non-real things



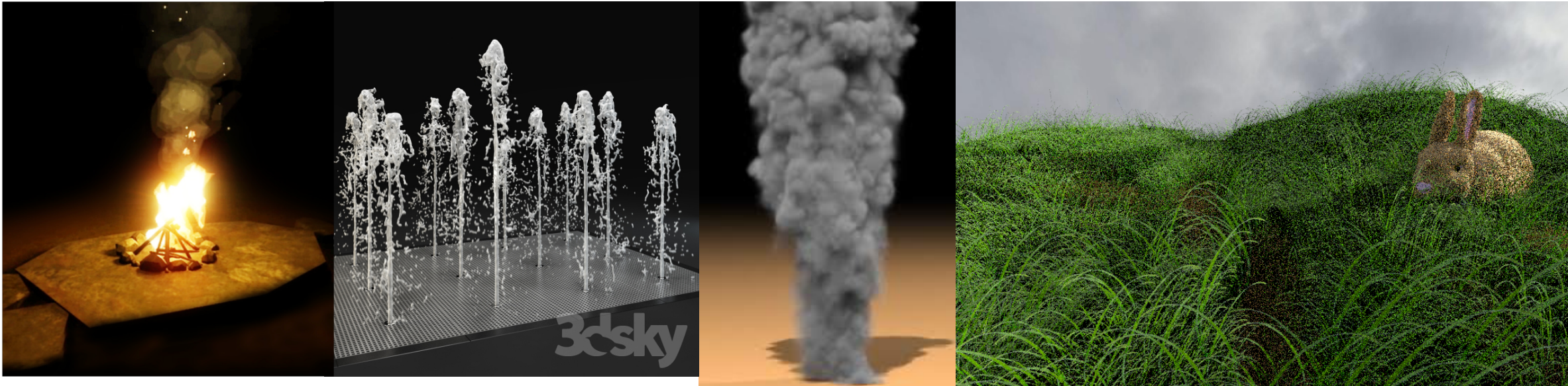
“Fractal” examples

- *Midpoint displacement terrain*
- Particle systems
- **Lindermeyer Systems (L-systems)**
- Perlin noise
- Attractor sets
- *Iterated function systems (IFS)*
- *Reaction-diffusion textures*
- *Recursive fractals*



Particle systems (no Mount lecture)

- Reeves, *Particle Systems A Technique for Modeling a Class of Fuzzy Objects*, 1983
 - <https://www.lri.fr/~mbl/ENS/IG2/devoir2/files/docs/fuzzyParticles.pdf>
- Used for fire, explosions, smoke, water, hair, grass, and more ...



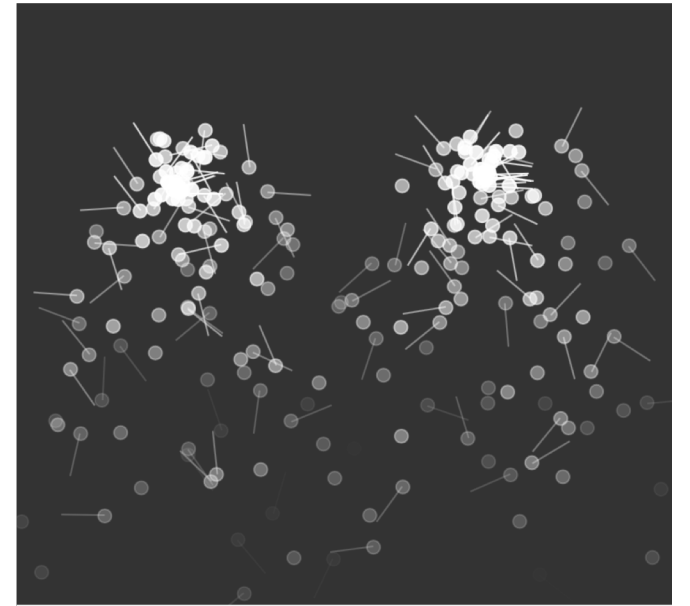
Particle system basics

- Shiffman, Nature of Code link:
- <https://natureofcode.com/book/chapter-4-particle-systems/>
- Khan Academy
- <https://www.khanacademy.org/computing/computer-programming/programming-natural-simulations/programming-particle-systems/a/particle-types>
- <https://processing.org/examples/multipleparticlesystems.html>

Particle properties

- Motion
 - Position
 - Forces (gravity, wind, explosion/impetus, friction)
- Lifetime
- Rendering
 - Color/size as function of position/motion
 - Rendering style and persistence

```
class Particle {  
    PVector position;  
    PVector velocity;  
    PVector acceleration;  
    float lifespan;  
}
```



Basic algorithm

- Step 1: Generate new particles
 - Apply constraints on initial velocity
- Step 2: Retire particles past their lifetime
- Step 3: Simulate motion for all existing particles
 - Apply forces to get acceleration
 - Apply acceleration to get motion
 - Move
 - Handle collisions

Dynamics of particle interaction

- Karl Sims 1989. Modeling
- <https://vimeo.com/114622025>
- SIGGRAPH 2014
- <https://vimeo.com/94622661>

Forces

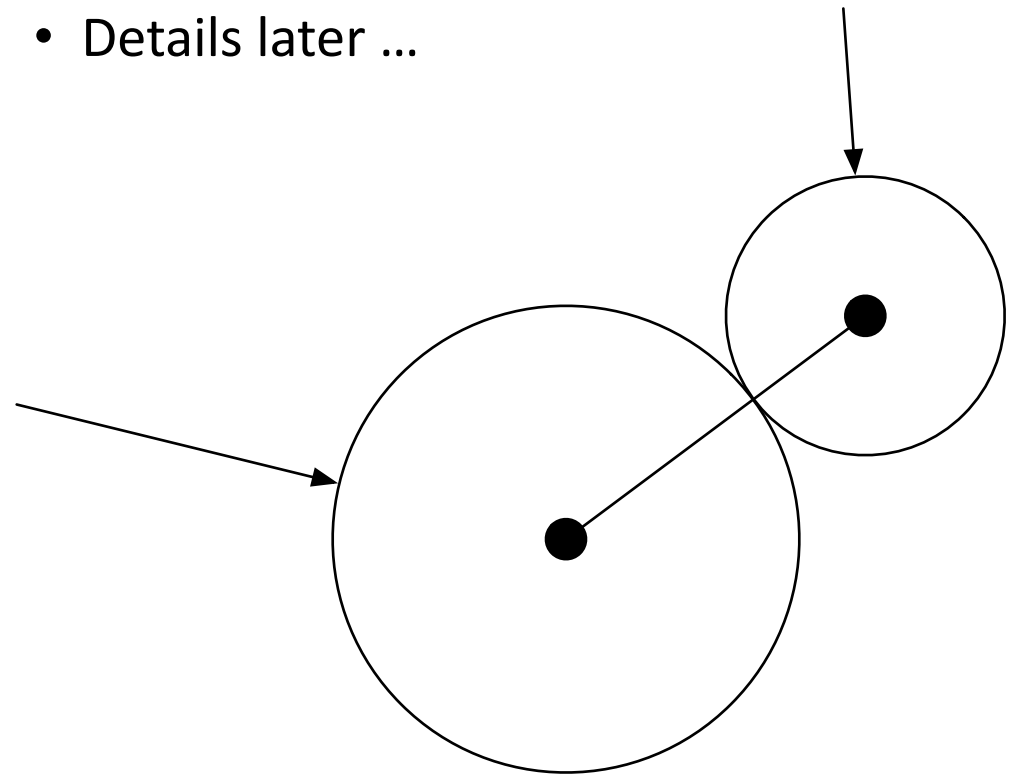
- From environment: gravity, viscosity (drag)
- From objects in scene: repulsion, attraction forces; collisions
- From fellow particles: spring, flocking

Bouncy Bubbles

- https://processing.org/examples/bouncy_bubbles.html

```
void move() {  
    vy += gravity;  
    x += vx; y += vy;  
    if (x + diameter/2 > width)  
    { // Hit right wall  
        x = width - diameter/2;  
        vx *= friction;  
    }  
}
```

- Elastic collision
- Details later ...



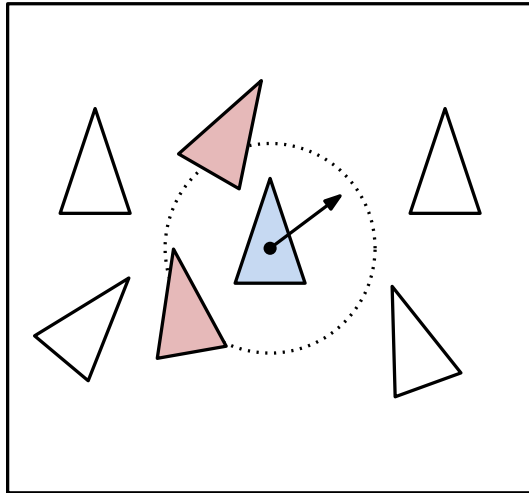
Flocking force (Mount

- For textiles, bird flocks, other common motion
- <https://www.youtube.com/watch?v=gUF7ObEat0U>
- Boids
- Craig Reynolds 1986



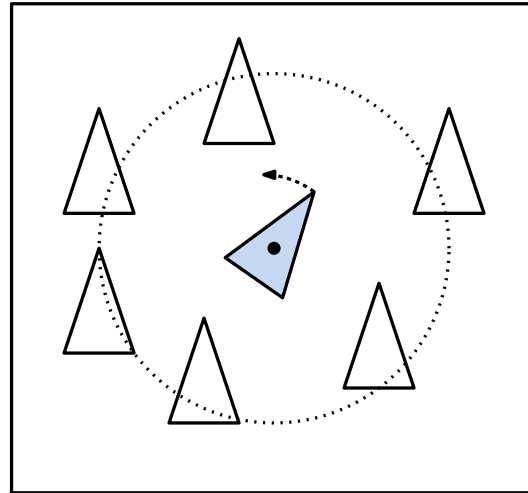
Flocking forces

Separation



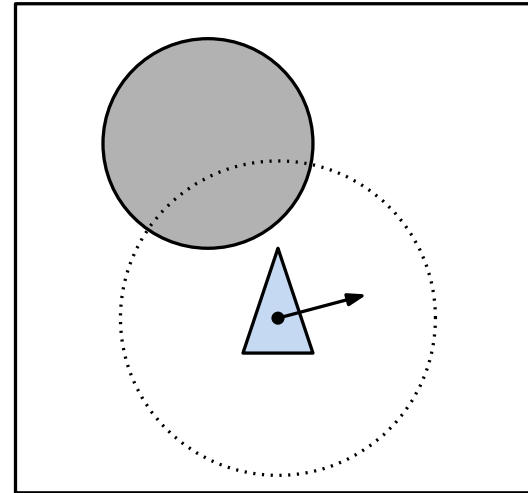
(a)

Alignment



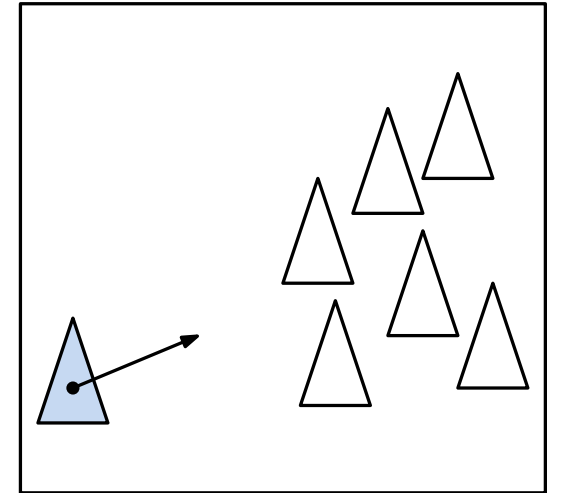
(b)

Avoidance



(c)

Cohesion



(d)

Forces on boids

- Compute forces F_i at time t
- Compute acceleration vector a_i
 - Scale forces by mass i
- Compute velocity from acceleration
- Compute position from velocity

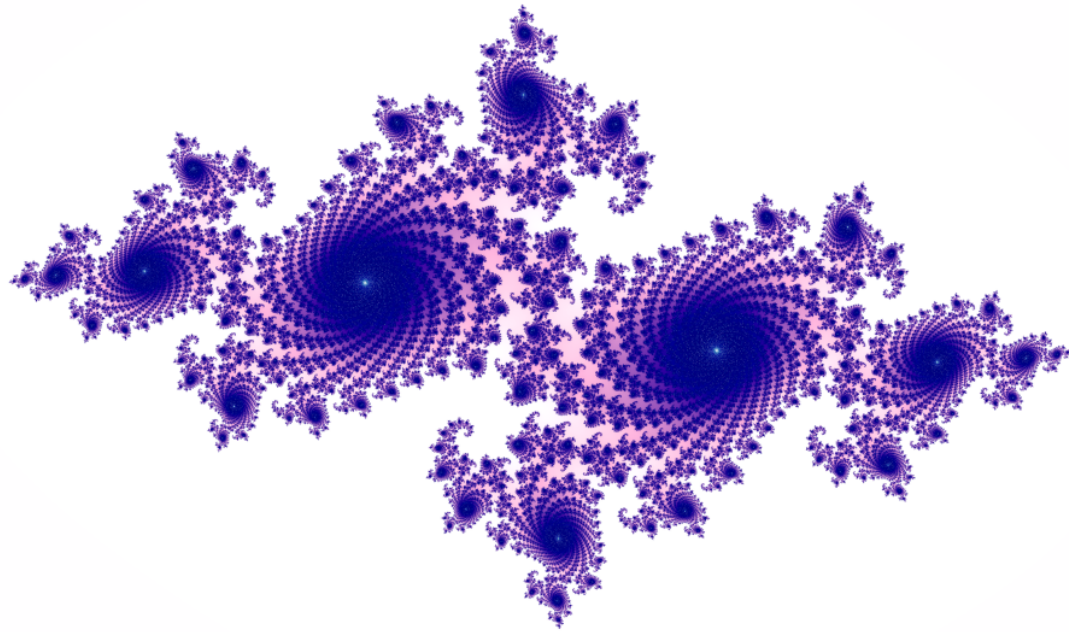
$$\vec{a}_i(t) \leftarrow \frac{\vec{F}_i(t)}{m_i}.$$

$$\vec{v}_i(t + \Delta) \leftarrow \vec{v}_i(t) + \Delta \cdot \vec{a}_i(t).$$

$$p_i(t + \Delta) \leftarrow p_i(t) + \Delta \cdot \vec{v}_i(t + \Delta)$$

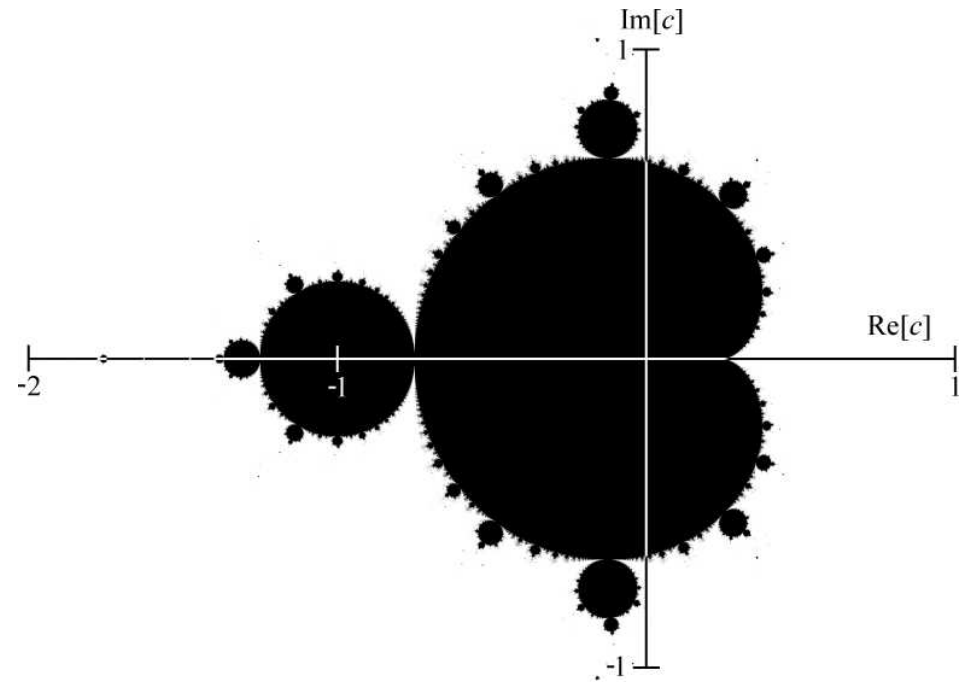
Iterated Functions and Attractor sets

Julia set



(a)

Mandelbrot set



(b)

Iterate complex function

- Complex numbers review

Modulus

$$\sqrt{a^2 + b^2}.$$

- Definition

$$a + bi, \text{ where } i^2 = -1.$$

- Addition

$$(a + bi) + (c + di) = (a + c) + (b + d)i,$$

- Multiplication

$$(a + bi)(c + di) = ac + adi + bci + bdi^2 = (ac - bd) + (ad + bc)i.$$

Iterate complex function

- Iterate simple function of z

$$z_i \leftarrow z_{i-1}^2 + c \quad \text{for } i = 1, 2, 3, \dots$$

