# CMSC 330: Organization of Programming Languages

# Memory Management and Garbage Collection

#### **Memory Attributes**

Memory to store data in programming languages has the following lifecycle

- Allocation
  - When the memory is allocated to the program
- Lifetime
  - How long allocated memory is used by the program

#### Memory Management in C

```
int q = 5;
int *foo(int y) {
  int *z = malloc(sizeof(int));
  *z = y+g;
  return z;
int main() {
  int *p = foo(3);
  free(p);
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Static memory – (global variable g) at a fixed address, never freed

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(parameter y, local variables p, z) allocated at start of function call, freed when function returns

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**Heap memory** – allocated when needed (by malloc), and freed (by free) when no longer needed

#### Memory Management in Ruby, Java, OCaml

- Local variables live on the stack
  - Storage reclaimed when method returns

- Objects, closures, tuples, etc. live on the heap
  - Ruby, Java: Created with calls to Class.new
  - OCaml: Allocation happens implicitly

Heap objects never explicitly freed: automatic memory management (garbage collection)

#### Manual vs. Automatic Recovery

- Manual memory management is
  - Efficient requires less storage overall
  - Error prone programmers can easily make mistakes, leading to leaks and use-after-free errors, which have security ramifications
- Automatic memory management is
  - Less efficient in space usage and latency than manual management
  - Easy to use, more compositional no worries about when an object is truly dead
    - > Avoids security problems

#### Strategy

- At any point during execution, can divide the objects in the heap into two classes
  - Live objects will be used later
  - Dead objects will never be used again
    - They are "garbage"
- ▶ Thus we need garbage collection (GC) algorithms that can
  - 1. Distinguish live from dead objects
  - 2. Reclaim the dead objects and retain the live ones

#### **Determining Liveness**

- In most languages we can't know for sure which objects are really live or dead
  - Undecidable, like solving the halting problem
- Thus we need to make a safe approximation
  - OK if we decide something is live when it's not
  - But we'd better not deallocate an object that will be used later on

#### Liveness by Reachability

- An object is reachable if it can be accessed by dereferencing ("chasing") pointers from live data
- Safe policy: delete unreachable objects
  - An unreachable object can never be accessed again by the program
    - > The object is definitely garbage
  - A reachable object may be accessed in the future
    - > The object could be garbage but will be retained anyway
    - > Could lead to memory leaks

#### Roots

- At a given program point, we define liveness as being data reachable from the root set
  - Global variables
    - What are these in Java? Ruby? OCaml?
  - Local variables of all live method activations
    - > I.e., the stack
- At the machine level
  - Also consider the register set
    - > Usually stores local or global variables
- Next
  - Techniques for determining reachability

#### Reference Counting

- Idea: Each object has count of number of pointers to it from the roots or other objects
  - When count reaches 0, object is unreachable
  - Count tracking code may be manual or automatic
- In regular use
  - C++ and Rust (manual: smart pointers), Cocoa (manual), Python (automatic)
- Invented by Collins in 1960
  - A method for overlapping and erasure of lists. *Communications* of the ACM, December 1960

#### Reference Counting Tradeoffs

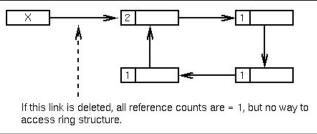
#### Advantage

- Incremental technique
  - > Generally small, constant amount of work per memory write
  - > With more effort, can even bound running time

#### Disadvantages

- Cascading decrements can be expensive
- Requires extra storage for reference counts
- Need other means to collect cycles, for which counts never go to

0



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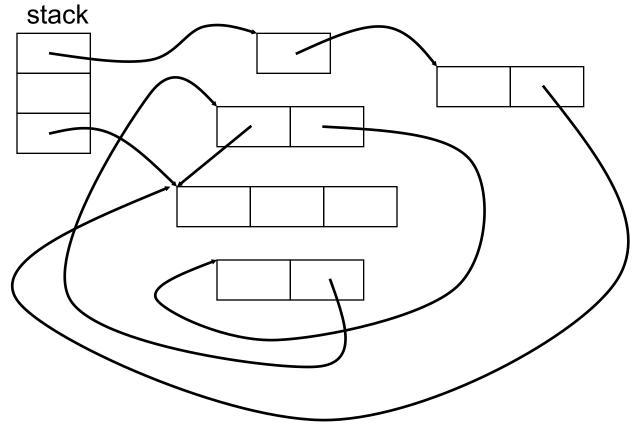
#### **Tracing Garbage Collection**

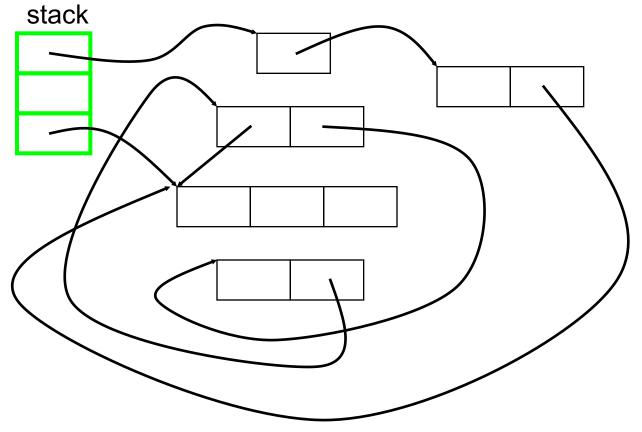
- Idea: Determine reachability as needed, rather than by stored counts, incrementally
- Every so often, stop the world and
  - Follow pointers from live objects (starting at roots) to expand the live object set
    - > Repeat until no more reachable objects
  - Deallocate any non-reachable objects
- Two main variants of tracing GC
  - Mark/sweep (McCarthy 1960) and stop-and-copy (Cheney 1970)

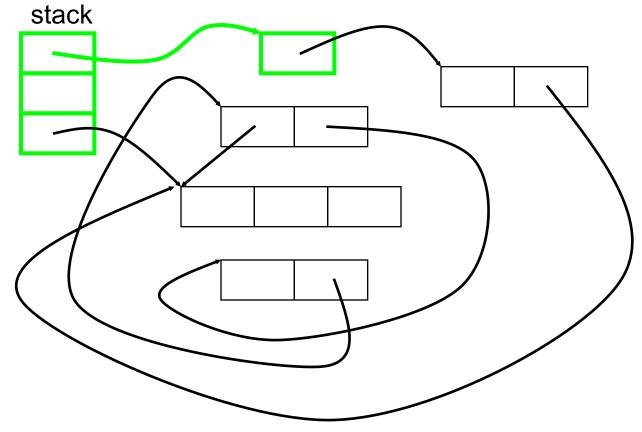
#### Mark and Sweep GC

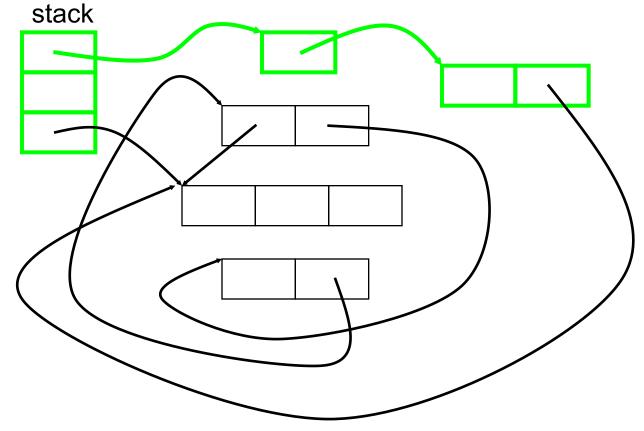
- Two phases
  - Mark phase: trace the heap and mark all reachable objects
  - Sweep phase: go through the entire heap and reclaim all unmarked objects

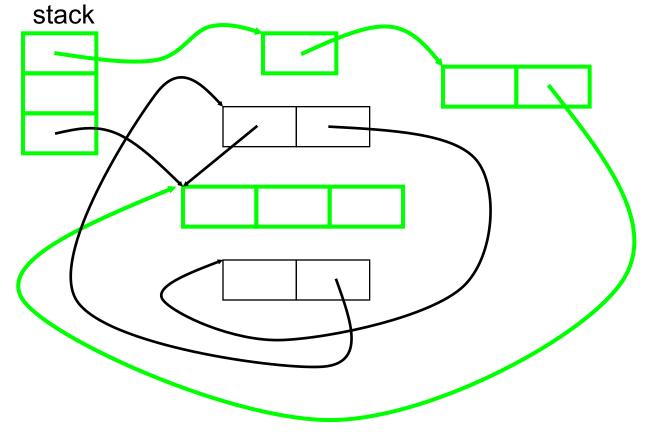
# Mark and Sweep Example

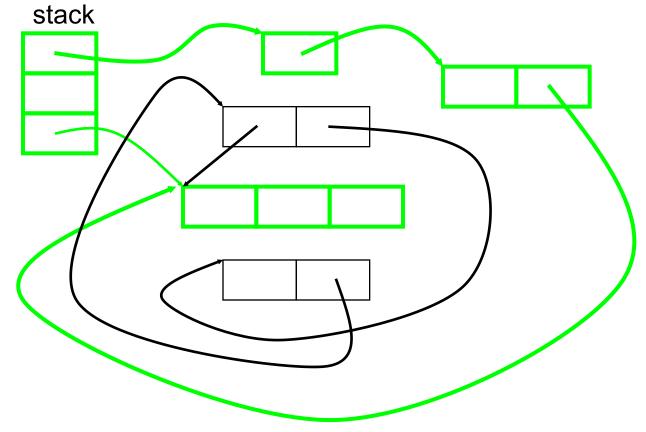


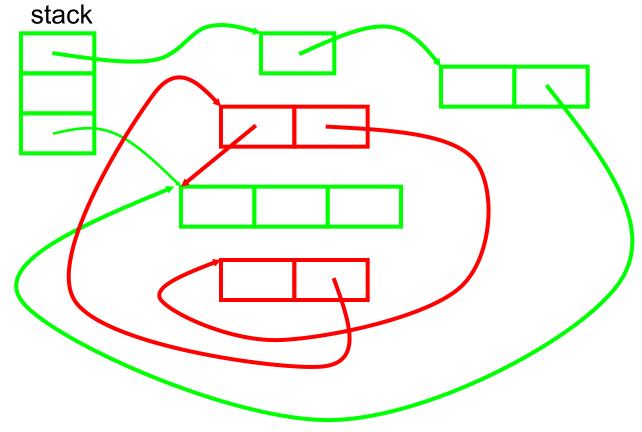




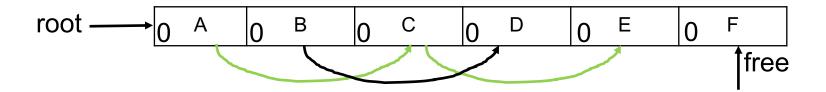




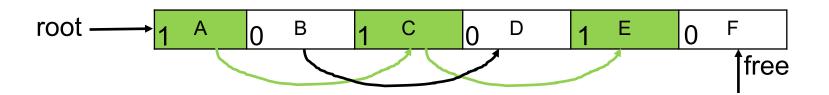




#### Mark and Sweep Example 2

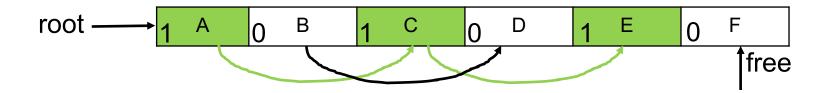


#### **After Mark**

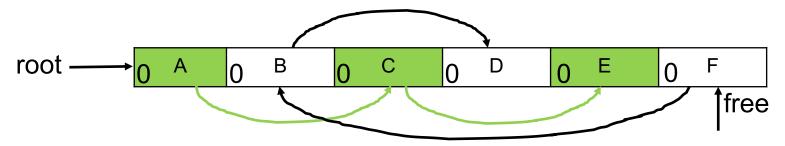


#### Mark and Sweep Example 2

#### **After Mark**



#### **After Sweep**



#### Mark and Sweep Advantages

- No problem with cycles
- Non-moving
  - Live objects stay where they are
  - Makes conservative GC possible
    - > Used when identification of pointer vs. non-pointer uncertain
    - More later

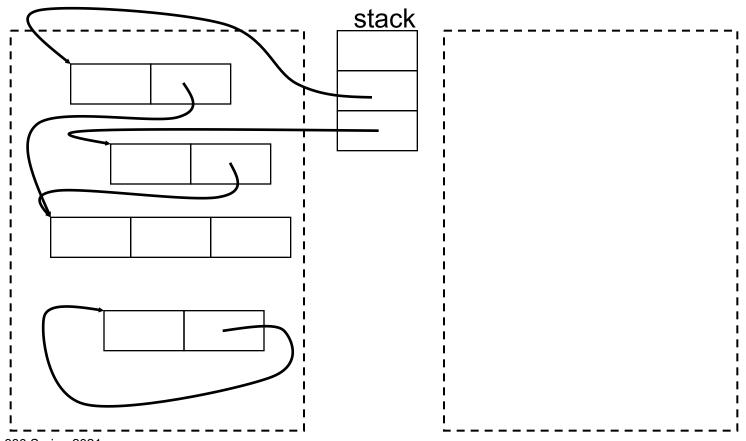
#### Mark and Sweep Disadvantages

- Fragmentation
  - Available space broken up into many small pieces
    - Thus many mark-and-sweep systems may also have a compaction phase (like defragmenting your disk)
- Cost proportional to heap size
  - Sweep phase needs to traverse whole heap it touches dead memory to put it back on to the free list

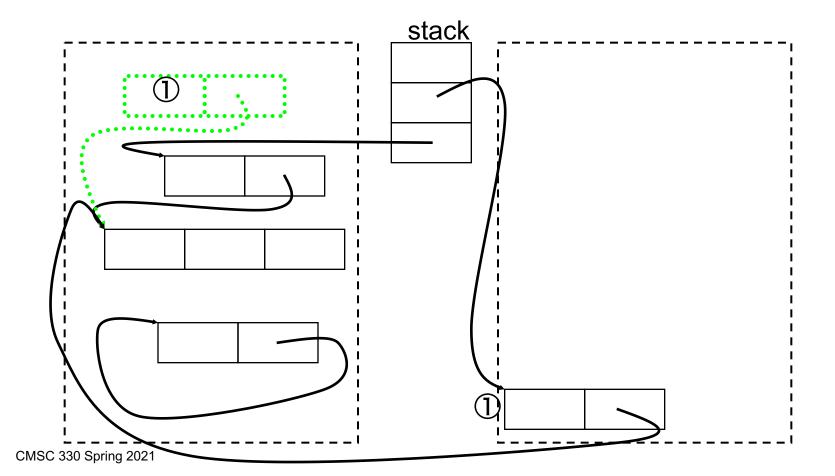
#### Copying GC

- Like mark and sweep, but only touches live objects
  - Divide heap into two equal parts (semispaces)
  - Only one semispace active at a time
  - At GC time, flip semispaces
    - 1. Trace the live data starting from the roots
    - 2. Copy live data into other semispace
    - 3. Declare everything in current semispace dead
    - 4. Switch to other semispace

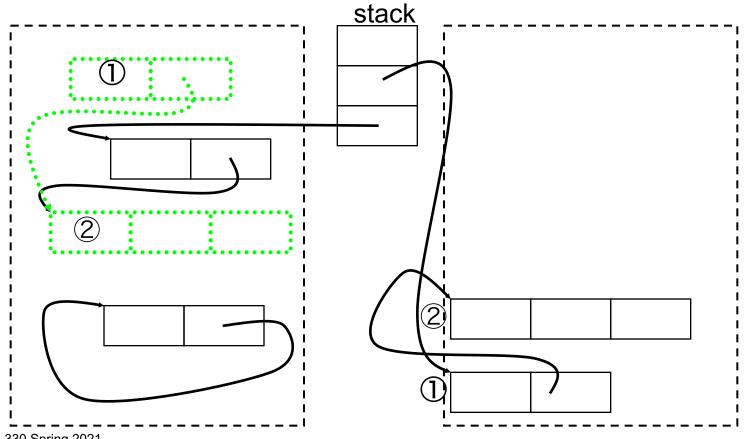
# Copying GC Example



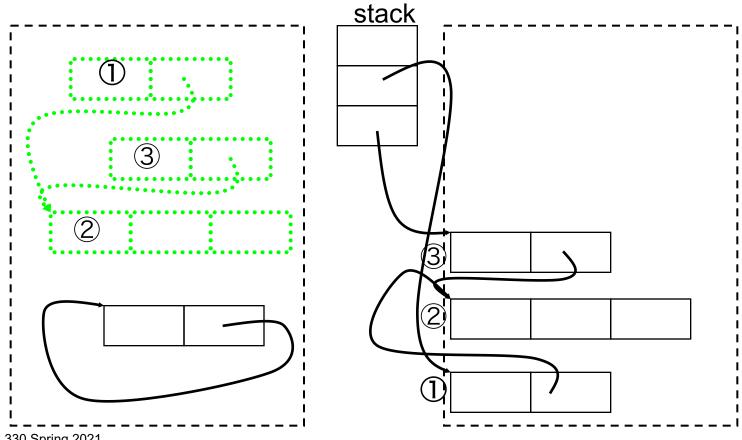
# Copying GC Example (cont.)



# Copying GC Example (cont.)



# Copying GC Example (cont.)



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#### Copying GC Tradeoffs

- Advantages
  - Only touches live data
  - No fragmentation (automatically compacts)
    - > Will probably increase locality
- Disadvantages
  - Requires twice the memory space

Which garbage collection implementation requires more storage?

A.Mark and Sweep

**B.**Copying GC

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A.Mark and Sweep

**B.**Copying GC

Which compacts the heap to prevent fragmentation?

- A. Mark and Sweep
- B. Reference Counting
- C. Copying GC

Which compacts the heap to prevent fragmentation?

- A. Mark and Sweep
- B. Reference Counting
- C. Copying GC

The computational cost of Copying GC is proportional to the heap size

A.True

**B.False** 

The computational cost of Copying GC is proportional to the heap size

A.True

**B.**False

Which of the following happens most frequently?

A.Reference Count Updating

B.Mark and Sweep checking for dead memory

C.Copying GC copying live data

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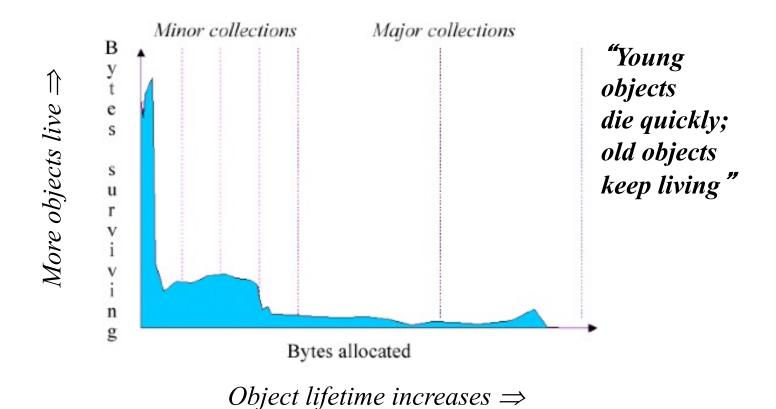
# Conservative Garbage Collection (for C)

- For C, we can't be sure which words are pointers
  - Due to incomplete type information, the use of unsafe casts, etc.
- Idea: suppose it is a pointer if it looks like one
  - Most pointers are within a certain address range, they are word aligned, etc.
  - May retain dead memory (floating point # looks like a pointer)
- Different styles of conservative collector
  - Mark-sweep: important that objects not moved
  - Mostly-copying: can move objects you are sure of

## Stop the World: Potentially Long Pause

- Both of the previous algorithms "stop the world" by prohibiting program execution during GC
  - Ensures that previously processed memory is not changed or accessed, creating inconsistency
  - But the execution pause could be too long
- ▶ How can we reduce the pause time of GC? Ideas:
  - Incremental: Collect a little at a time
  - Parallel: Do GC in multiple threads at once
  - Concurrent: Do GC while main program is running

### The Generational Principle



#### **Generational Collection**

- Long lived objects visited multiple times
  - Idea: Have more than one heap region, divide into generations
    - > Older generations collected less often
    - > Objects that survive many collections get promoted into older generations
    - Need to track pointers from old to young generations to use as roots for young generation collection
      - Tracking one in the remembered set
- One popular setup: Generational, copying GC

#### What Does GC Mean to You?

- Ideally, nothing
  - GC should make programming easier
  - GC should not affect performance (much)
- Usually bad idea to manage memory yourself
  - Using object pools, free lists, object recycling, etc...
  - GC implementations have been heavily tuned
    - > May be more efficient than explicit deallocation
- If GC becomes a problem, hard to solve
  - You can set parameters of the GC
  - You can modify your program

## **Increasing Memory Performance**

- Don't allocate as much memory
  - Less work for your application
  - Less work for the garbage collector
- Don't hold on to references
  - Null out pointers in data structures
  - Example

```
Object a = new Object;
...use a...
a = null; // when a is no longer needed
```

## Find the Memory Leak

```
class Stack {
 private Object[] stack;
 private int index;
 public Stack(int size) {
    stack = new Object[size];
  public void push(Object o) {
    stack[index++] = o;
 public void pop() {
    return stack[index--];
```

From Haggar, Garbage Collection and the Java Platform Memory Model

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    stack[index] = null; // null out ptr
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From Haggar, Garbage Collection and the Java Platform Memory Model

Answer: pop() leaves item on stack array; storage not reclaimed