## Classification with Nearest Neighbors

CMSC 422

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Slides adapted from MARINE CARPUAT

#### What we know so far

#### **Decision Trees**

• What is a decision tree, and how to induce it from data

#### **Fundamental Machine Learning Concepts**

- Difference between memorization and generalization
- What inductive bias is, and what is its role in learning
- What underfitting and overfitting means
- How to take a task and cast it as a learning problem
- you should never ever touch your test data!!

#### Today's Topics

- Nearest Neighbors (NN) algorithms for classification
  - K-NN, Epsilon ball NN
- Fundamental Machine Learning Concepts

   Decision boundary

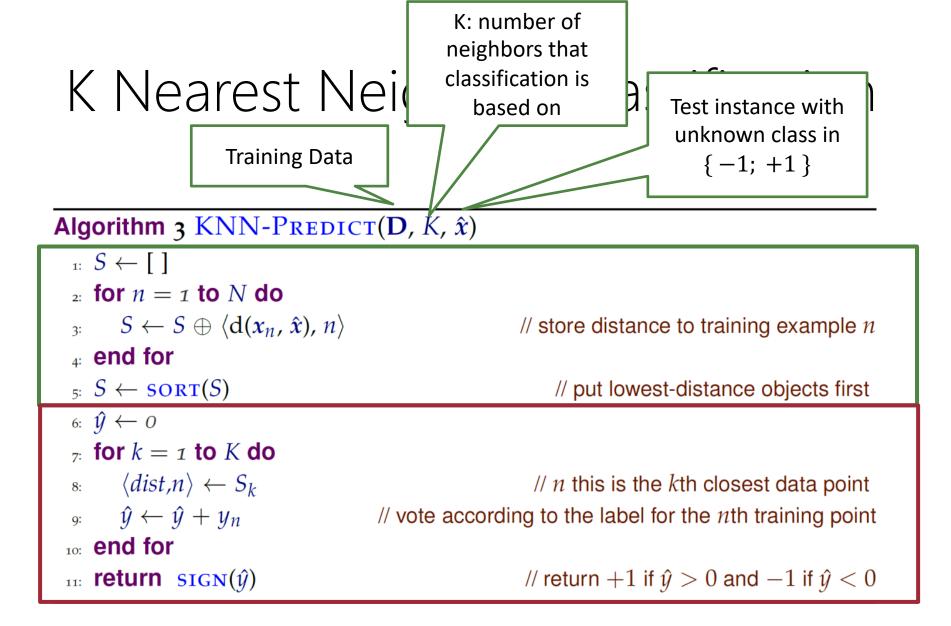
Intuition for Nearest Neighbor Classification

This "rule of nearest neighbor" has considerable elementary intuitive appeal and probably corresponds to practice in many situations. For example, it is possible that much medical diagnosis is influenced by the doctor's recollection of the subsequent history of an earlier patient whose symptoms resemble in some way those of the current patient.

(Fix and Hodges, 1952)

Intuition for Nearest Neighbor Classification

- Simple idea
  - Store all training examples
  - Classify new examples based on most similar training examples



## 2 approaches to learning

#### Eager learning (eg decision trees)

- Learn/Train
  - Induce an **abstract model** from data
- Test/Predict/Classify
  - Apply learned model to new data

#### Lazy learning (eg nearest neighbors)

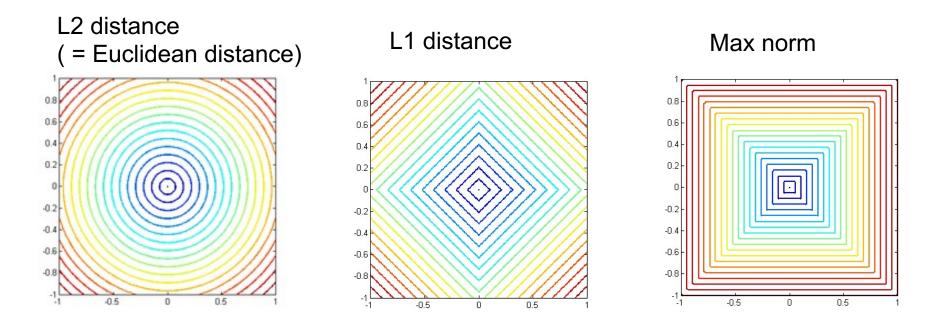
- Learn
  - Just store data in memory
- Test/Predict/Classify
  - Compare new data to stored data
- Properties
  - Retains all information seen in training
  - Complex hypothesis space
  - Classification can be very slow

### Components of a k-NN Classifier

- Distance metric
  - How do we measure distance between instances?
  - Determines the layout of the example space
- The k hyperparameter
  - How large a neighborhood should we consider?
  - Determines the complexity of the hypothesis space

#### Distance metrics

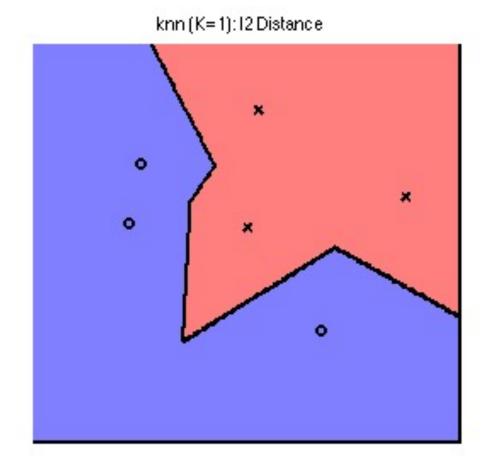
- We can use any distance function to select nearest neighbors.
- Different distances yield different neighborhoods



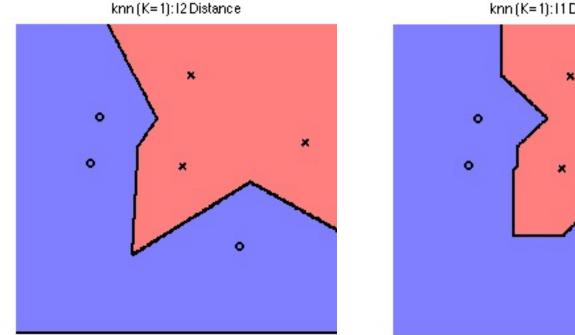
### Decision Boundary of a Classifier

- It is the line that separates positive and negative regions in the feature space
- Why is it useful?
  - it helps us visualize how examples will be classified for the entire feature space
  - it helps us visualize the complexity of the learned model

#### Decision Boundaries for 1-NN



#### Decision Boundaries change with the distance function



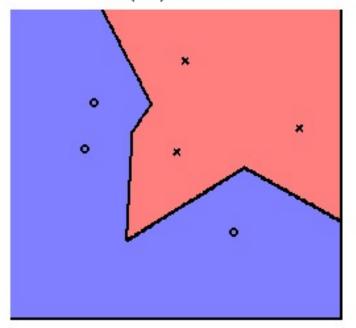
knn (K=1):11 Distance

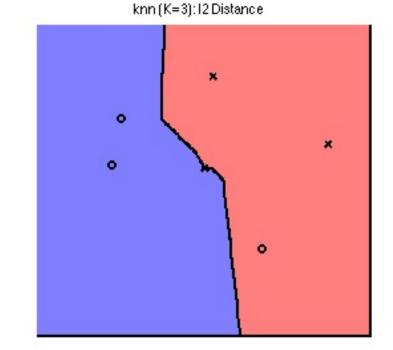
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## Decision Boundaries change with K

knn (K=1):12 Distance





## The k hyperparameter

- Tunes the complexity of the hypothesis space
  - If k = 1, every training example has its own neighborhood
  - If k = N, the entire feature space is one neighborhood!
- Higher k yields smoother decision boundaries
- How would you set k in practice?

# What is the inductive bias of k-NN?

- Nearby instances should have the same label
- All features are equally important
- Complexity is tuned by the k parameter

Variations on k-NN: Weighted voting

- Weighted voting
  - Default: all neighbors have equal weight
  - Extension: weight neighbors by (inverse) distance

## Variations on k-NN: Epsilon Ball Nearest Neighbors

- Same general principle as K-NN, but change the method for selecting which training examples vote
- Instead of using K nearest neighbors, use all examples x such that  $distance(\hat{x}, x) < c$

 $distance(\hat{x}, x) \leq \varepsilon$ 

#### Exercise: How would you modify KNN-Predict to perform Epsilon Ball NN?

#### Algorithm 3 KNN-PREDICT(**D**, *K*, $\hat{x}$ )

```
<sup>1:</sup> S \leftarrow []
<sup>2:</sup> for n = 1 to N do
```

```
S \leftarrow S \oplus \langle \mathbf{d}(\mathbf{x}_n, \hat{\mathbf{x}}), n \rangle
```

- 4: end for
- 5:  $S \leftarrow \text{sort}(S)$
- 6:  $\hat{y} \leftarrow 0$
- 7: for k = 1 to K do
- 8:  $\langle dist, n \rangle \leftarrow S_k$
- 9:  $\hat{y} \leftarrow \hat{y} + y_n$
- ${\scriptstyle 10:}$  end for

11: return  $sign(\hat{y})$ 

// store distance to training example n

// put lowest-distance objects first

// n this is the kth closest data point // vote according to the label for the nth training point

// return +1 if  $\hat{y} > 0$  and -1 if  $\hat{y} < 0$ 

#### Recap

- Nearest Neighbors (NN) algorithms for classification
  - K-NN, Epsilon ball NN
  - Take a geometric view of learning
- Fundamental Machine Learning Concepts
   Decision boundary
  - Visualizes predictions over entire feature space
  - Characterizes complexity of learned model
  - Indicates overfitting/underfitting