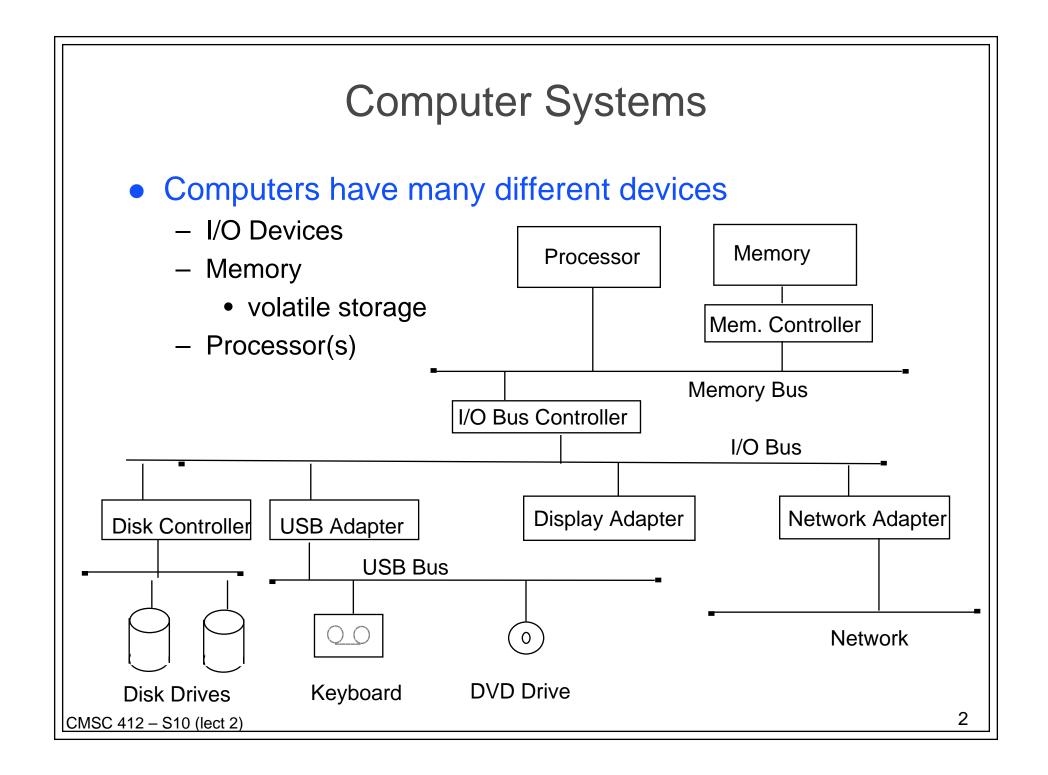
Announcements

1

- Program #0
 - its due next Friday
- Reading
 - Chapter 2
 - Chapter 3 (for Tuesday)



I/O Systems

Many different types of devices

- disks
- networks
- displays
- mouse
- keyboard
- tapes
- Each have a different expectation for performance
 - bandwidth
 - rate at which data can be moved
 - latency
 - time from request to first data back

Different Requirements lead to Multiple Buses

- Processor Bus (on chip)
 - Many Gigabytes/sec
- Memory Bus (on processor board)
 - ~10s Gigabyte per second
- I/O Bus (PCI)
 - ~1s gigabytes per second
 - buses are more complex than we saw in class
 - show PCI spec.
- Device Bus (SCSI, USB)
 - tens of megabytes per second

Issues In Busses

• Performance

- increase the data bus width
- have separate address and data busses
- block transfers
 - move multiple words in a single request
- Who controls the bus?
 - one or more bus masters
 - a bus master is a device that can initiate a bus request
 - need to arbitrate who is the bus master
 - assign priority to different devices
 - use a protocol to select the highest priority item
 - daisy chained
 - central control

CMSC 412 - S10 (lect 2)

Disks • Several types: Hard Disks - rigid surface with magnetic coating Floppy disks - flexible surface with magnetic coating - Optical (CDs and DVDs) - read only, write once, multi-write Solid State (Flash) – fast seek times, limited number of writes Hard Disk Drives: collection of platters platters contain concentric rings called tracks tracks are divided into fixed sized units called sectors - a cylinder is a collection of all tracks equal distant from the center of disk Current Performance: capacity: gigabytes to terabytes

- throughput: sustained < 20 megabytes/sec
- latency: mili-seconds

I/O Interfaces

- Need to adapt Devices to CPU speeds
- Moving the data
 - Programmed I/O
 - Special instructions for I/O
 - Mapped I/O
 - looks like memory only slower
 - DMA (direct memory access)
 - device controller can write to memory
 - processor is not required to be involved
 - can grab bus bandwidth which can slow the processor down

I/O Interrupts

• Interrupt defined

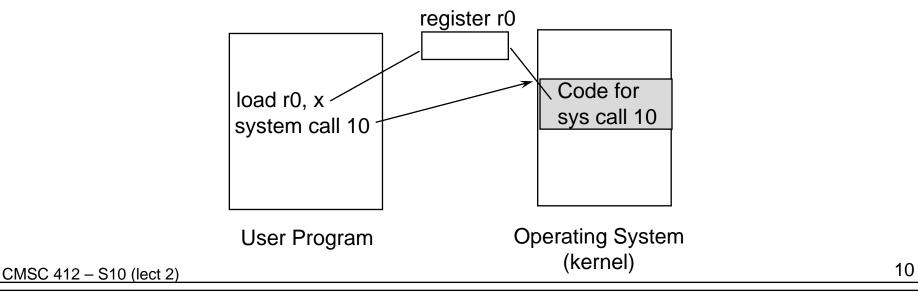
- indication of an event
- can be caused by hardware devices
 - indicates data present or hardware free
- can be caused by software
 - system call (or trap)
- CPU stops what it is doing and executes a handler function
 - saves state about what was happening
 - returns where it left off when the interrupt is done
- Need to know what device interrupted
 - could ask each device (slow!)
 - instead use an interrupt vector
 - array of pointers to functions to handle a specific interrupt

Hardware Protection

- Need to protect programs from each other
- Processor has modes
 - user mode and supervisor (monitor, privileged)
 - operations permitted in user mode are a subset of supervisor mode
- Memory Protection
 - control access to memory
 - only part of the memory is available
 - can be done with base/bound registers
- I/O Protection
 - I/O devices can only be accessed in supervisor mode
- Processor Protection
 - Periodic timer returns processor to supervisor mode

System Calls

- Provide the interface between application programs and the kernel
- Are like procedure calls
 - take parameters
 - calling routine waits for response
- Permit application programs to access protected resources



System Call Mechanism

- Use numbers to indicate what call is made
- Parameters are passed in registers or on the stack
- Why do we use indirection of system call numbers rather than directly calling a kernel subroutine?
 - provides protection since the only routines available are those that are export
 - permits changing the size and location of system call implementations without having to re-link application programs

Types of System Calls

• File Related

- open, create
- read, write
- close, delete
- get or set file attributes
- Information
 - get time
 - set system data (OS parameters)
 - get process information (id, time used)
- Communication
 - establish a connection
 - send, receive messages
 - terminate a connection
- Process control
 - create/terminate a process (including self)

System Structure

- Simple Structure (or no structure)
 - any part of the system may use the functionality of the rest of the system
 - MS-DOS (user programs can call low level I/O routines)
- Layered Structure
 - layer n can only see the functionality that layer n-1 exports
 - provides good abstraction from the lower level details
 - new hardware can be added if it provides the interface required of a particular layer
 - system call interface is an example of layering
 - can be slow if there are too many layers
- Hybrid Approach
 - most real systems fall somewhere in the middle

Policy vs. Mechanism

• Policy - what to do

- users should not be able to read other users files
- Mechanism- how to accomplish the goal
 - file protection properties are checked on open system call
- Want to be able to change policy without having to change mechanism
 - change default file protection
- Extreme examples of each:
 - micro-kernel OS all mechanism, no policy
 - MACOS policy and mechanism are bound together

Processes

• What is a process?

- a program in execution
- "An execution stream in the context of a particular state"
- a piece of code along with all the things the code can affect or be affected by.
 - this is a bit too general. It includes all files and transitively all other processes
- only one thing happens at a time within a process
- What's not a process?
 - program on a disk a process is an active object, but a program is just a file

Multi-programming

- Systems that permit more than one process at once
 - virtually all computers today
- Permits more efficient use of resources
 - while one process is waiting another can run
- Provides natural abstraction of different activities
 - windowing system
 - editor
 - mail daemon
- Preemptive vs. non-preemptive muti-programming
 - preemptive means that a process can be forced off the processor by the OS
 - provides processor protection