

**Your Homework Assignment**  
CMSC/AMSC 661 Spring 2005  
**Waves, Part 1**  
**Due May 10**

In this homework, we model forced vibrations of a stretched string or membrane. We use a hyperbolic PDE solver, a Helmholtz solver, eigenvalues and eigenfunctions, and Fourier transforms.

### The Problem

Suppose we take a membrane – for example, a flat piece of balloon material, or the skin of a drum, or a valve in a heart.

Now apply a force to the membrane, so that the membrane vibrates. Our goal is to be able to predict the shape of the membrane as a function of time.

### The Model

The model for this problem is the [wave equation](#)

$$u_{tt} - c^2 \Delta u = f$$

where  $(x, u(x, t))$  gives the coordinates of the membrane at time  $t$ , and  $f(x, t)$  defines the force exerted on the membrane at  $x$  at time  $t$ .

The constant  $c$  is the speed of propagation of waves in the medium.

In order to make the solution unique, we specify initial conditions  $u(x, 0)$  and  $u_t(x, 0)$  and boundary conditions  $u(0, t) = u(1, t) = 0$ . The boundary conditions say that the membrane's position is fixed along the boundary.

Sometimes the solution to the wave equation can be computed through the [Helmholtz equation](#).

**Problem 1.** (No points. Exercise only, to get ready for Problem 2, but it may show up on a quiz.) Consider the problem

$$u_{tt} - c^2 \Delta u = e^{-i\omega t} f(x)$$

with initial conditions  $u(x, 0) = u_t(x, 0) = 0$  for  $x \in \Omega$ . Assume that the solution is of the form  $u = e^{-i\omega t} z(x)$ . Substitute this solution into the equation to obtain a problem of the form of the [Helmholtz equation](#)

$$-\Delta z - \kappa^2 z = g$$

with  $z$  given on the boundary of  $\Omega$ . How are  $g$  and  $\kappa$  defined?

**Problem 2.** (20) (Fast solvers) Consider the Helmholtz equation

$$-\Delta z - \kappa^2 z = g$$

in a 2-dimensional region  $\Omega$  with  $z = 0$  on the boundary of  $\Omega$ .

Let  $\Omega$  be the unit square, and discretize using (second-order accurate) finite differences, obtaining a matrix equation

$$\mathbf{A}z = \mathbf{g}$$

where  $z$  and  $g$  contain values of  $z$  and  $g$  at the mesh points.

Write a well-documented Matlab function `z = helmsolve(kappa,g)` that uses the method in the “Notes on Fast Poisson Solvers” to solve this linear system, where  $g$  is a two-dimensional array of values  $g(x_k, y_j)$ ,  $k, j = 1, \dots, n$ , where  $x_k = k/(n+1)$ ,  $y_j = j/(n+1)$ . The output array  $z$  should contain the values of the computed solution at the mesh points  $(x_k, y_j)$ ,  $k, j = 1, \dots, n$ .

The Matlab routines `dst` and `idst` will be useful.

For debugging, it may be useful to generate the 2-dimensional Laplacian matrix  $A$  of size  $n^2 \times n^2$ :

```
A1 = spdiags([-ones(n,1), 2*ones(n,1), -ones(n,1)], -1:1, n, n);
en = speye(n);
A = kron(A1, en) + kron(en, A1);

h = 1/(n+1);
A = A/(h*h);
```

But do not include this code in your submission.

**Submission instructions:** Submit your Matlab file as a plain-text email attachment. I will grade your submission by

- Looking at the code, to see that the algorithm is efficient, correct and well documented.
- Running your code on some test problems.

Therefore, make sure that your inputs and outputs match the specifications exactly.