

Räcke from FRT:

Note that in FRT after removing steiner nodes, we can put $d_T(u,v) = d_G(u,v)$ to have dominance property and possibly decrease the distortion.

Similarly we can use $c(e_T) = \sum_{e' \in \delta(e_T)} c(e')$ [$e' \in \delta(e_T) = (u,v)$ means u, v belong to two different component of T after removing e_T]

So in both cases we really care about the tree structure and **NOT** really the weights on trees.

In FRT, we want to minimize the distortion $\frac{d_T(e)}{d_G(e)}$ where $d_T(e) = \sum_{e' \in \text{unique path}(e)} d_G(e')$

In Räcke, we want to minimize the congestion $\frac{\text{load}_T(e)}{c_G(e)}$ where $\text{load}_T(e) = \sum_{e' \in \text{int}(e)} T_{e'e}$

$$\begin{aligned} \text{load}_T(e) &= \sum_{e_T \in E_T: e \in M_E(e_T)} c(e_T) = \sum_{e_T \in E_T: e \in M_E(e_T)} \sum_{e' \in E(G): e' \in \delta(e_T)} c_{e'} \\ &= \sum_{e' \in E(G)} \sum_{\substack{e_T \in \text{unique path}(e') \\ e \in M_E(e_T)}} c(e') = \sum_{e' \in E(G)} T_{e'e} c(e') \end{aligned}$$

where $T_{e'e}$ is the number of times e appears in $M_E(e')$.

Lmt: For every $p \geq 1$ and every family of trees, there is a probabilistic mapping with distortion at most p if and only if for every non negative coefficients α_e where $\sum_{e \in E(G)} \alpha_e = 1$, there is a tree T such that $\sum_{e \in E(G)} \alpha_e \frac{d_T(e)}{d_G(e)} \leq p$

[or equivalently $\sum_{e \in E(G)} \alpha_e \frac{d_T(e)}{d_G(e)} \leq p \sum_{e \in E(G)} \alpha_e$ if $\sum_{e \in E(G)} \alpha_e \neq 1$ because of scaling].

Proof: uses the minmax theorem with two player T_{tree} who choose the tree and player E_{edge} who choose an edge. $M_{Te} = \frac{d_T(e)}{d_G(e)}$, where M_{Te} is the payoff vector. (note that since it is a zero-sum game payoff for the tree player is - payoff for the edge player.)

A mixed strategy for the tree player is a probability distribution α_T over all trees while a mixed strategy for the edge player is a probability distribution α_e over all edges. The min-max theorem says $\min_T \max_{\alpha_e} \sum_T \sum_e \alpha_e M_{Te} = \max_{\alpha_e} \min_T \sum_T \sum_e \alpha_e M_{Te}$

The lemma follows from this.

lm 2: For every $\rho \geq 1$ and every family of trees, there is a probabilistic mapping with congestion at most ρ if and only if for every non-negative coefficient β_e , there is a tree T such that $\sum_{e \in E(G)} \beta_e \frac{\text{load}_T(e)}{c_G(e)} \leq \rho \sum_{e \in E(G)} \beta_e$.

Pf: similar to pf of lm 1 and thus omitted.

Main Thm: For every $\rho \geq 1$ and family of trees (1) and (2) are equivalent

(1): For every collection of lengths $d_G(e)$ there is a probabilistic mapping with distortion at most ρ

(2) For every collection of capacities $c_G(e)$, there is a probabilistic mapping with congestion at most ρ .

Pf: We prove (2) from (1) and the reverse is similar.

Assume (1). Thus by lm 1: for every non-negative coefficient α_e , there is a tree T such that $\sum_{e \in E(G)} \alpha_e \frac{d_T(e)}{d_G(e)} \leq \rho$. Thus $\sum_{e \in E(G)} \alpha_e \frac{d_G(e)}{d_G(e)} \leq \rho \sum_{e \in E(G)} \alpha_e$ for every coefficient α_e (*)

Now we need to prove there is a probabilistic mapping from E using trees with congestion at most ρ . by lm 2: it suffices to prove that for every non-negative coefficient β_e , there is a tree T such that $\sum_{e \in E(G)} \beta_e \frac{\text{load}_T(e)}{c_G(e)} \leq \rho \sum_{e \in E(G)} \beta_e$. Thus $\sum_{e \in E(G)} \beta_e \frac{\text{load}_T(e)}{c_G(e)} \leq \rho \sum_{e \in E(G)} \beta_e$ (**)

~~should be~~ $\sum_{e \in E(G)} \beta_e \frac{\text{load}_T(e)}{c_G(e)} \leq \rho \sum_{e \in E(G)} \beta_e$ should be correct for every non-negative coefficient β_e . (***)

Now choosing $\alpha_e = \beta_e$ and $d_G(e) = \frac{\beta_e}{c_G(e)}$ (and likewise $d_G(e) = \frac{\beta_e}{c_G(e)}$) and substituting in inequality (**), we obtain (***) \square

[note that in general $T: E \rightarrow \mathbb{P}$ maps to every edge $e \in E$ a path $P \in \mathbb{P}$ and $T_{e'}$ counts the number of times the edge e' appears on the path $T(e)$.

since there $O(\log n)$ for trees and $\tilde{O}(\log n)$ for subtrees, we obtain the same results for congestion. We can obtain a polynomial algorithm by duality (min max).

Note that if we consider embedding into subtrees then $T_{e'}$ is one if e' appears in the path unique to e in the tree and zero otherwise.

Application to Min Bisection:

Min Bisection: given a graph G with $n=2k$ vertices partition the vertices in two parts with k vertices with minimum width (total capacity of edges with end-points in different sides of bipartization)

algo: find the best solution in ~~each~~ ^{each} of the spanning trees of the distribution and take the best. (in trees we can solve it with dynamic program).

First note that $\text{load}_T(e) \stackrel{\text{def}}{=} \sum_{e \in T} c_e$ in this case is sum of capacities of edges at G with one end-point in each part $S(e)$ in T (for $e \notin T$ the load is zero)

note that if opt_i is the mapping of opt in tree T_i (delete the edges of opt if they exist in T_i), in this case we pay $\text{load}_T(e)$. Due to probabilistic embedding

$$O(\log n) \text{opt} \geq \sum_T P_T \text{opt}_T \geq \sum_T P_T C_T \geq \sum_T P_T C^* \geq C^* \geq \frac{1}{\sum_i \lambda_i} \sum_i \lambda_i \text{load}_{T_i}(e) \stackrel{\text{embedding}}{\leq} O(\log n) C_e$$

where C_T is the best solution for tree T and C^* is the best overall solution in T^*

note that now if we map C^* back into graph G , and we cut all edges in $\text{load}_{T^*}(e)$ then we have a solution of cost at most C^* , since the load

terms count every edge of G cut by the solution corresponding to C^* at least once and perhaps multiple times and also possibly count edges of G not in the bipartization (this is the domination property) \square

We can obtain $O(\log n)$ approximation instead of $\tilde{O}(\log n)$ if we use embedding into probabilistic trees and not subtrees.

note that roughly speaking $\text{distance} = \frac{1}{\text{capacity}}$ in these arguments and this is the main intuition.