Announcements

• Program #1

- Additional info on elf file format is on the web
- See slide from today about project issues

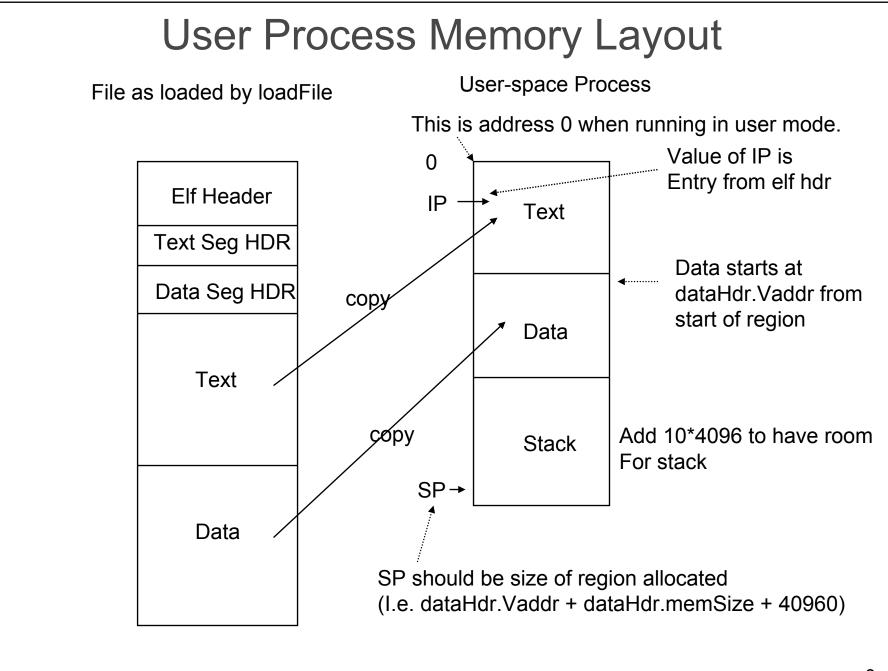
• Reading

- Chapter 6
- Chapter 7 (Tuesday)

CMSC 412 – S02 (lect6)

Project Issues

- Use one TSS for entire system
- User Space Memory layout
 - Text segment
 - Data and stack are one segment
 - Stack grows down
- Kernel component of a process
 - Has own stack (in kernel memory)
- Malloc in libuser.a
 - Write an emply malloc_Atomic in libuser.c is should call Print_String to report and error and exit



CMSC 412 – S02 (lect6)

Short-term scheduling algorithms

- First-Come, First-Served (FCFS, or FIFO)
 - as process becomes ready, join Ready queue, scheduler always selects process that has been in queue longest
 - better for long processes than short ones
 - favors CPU-bound over I/O-bound processes
 - need priorities, on uniprocessor, to make it effective

Algorithms (cont.)

• Round-Robin (RR)

- use preemption, based on clock time slicing
 - generate interrupt at periodic intervals
- when interrupt occurs, place running process in Ready queue, select next process to run using FCFS
- what's the length of a time slice
 - short means short processes move through quickly, but high overhead to deal with clock interrupts and scheduling
 - guideline is time slice should be slightly greater than time of "typical job" CPU burst
- problem dealing with CPU and I/O bound processes

Algorithms (cont.)

- Shortest Process Next (SPN)
 - non-preemptive
 - select process with shortest expected processing time
 - improves response time, but increases its variability, reducing predictability - provably decreases average waiting time
 - problem is estimating required processing time
 - risk of starving longer processes, as long as there are shorter processes around
 - not good for time sharing non-preemptive

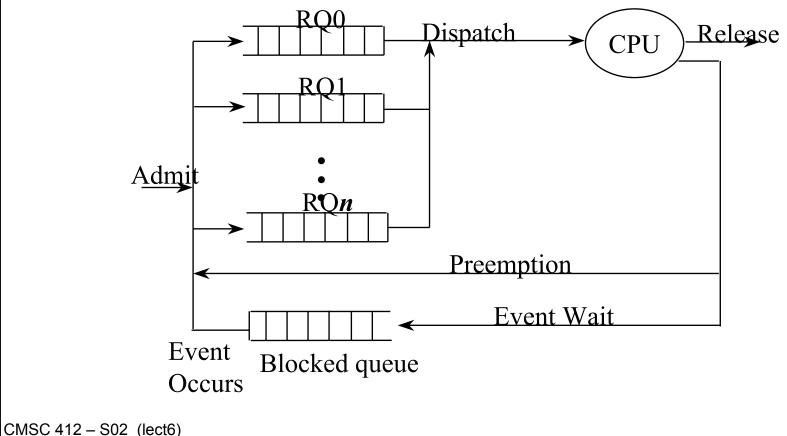
Algorithms (cont.)

- Shortest Remaining Time (SRT)
 - preemptive version of SPN
 - scheduler chooses process with shortest expected remaining process time
 - still need estimate of processing time, and can starve longer processes
 - no bias in favor of longer processes, as in FCFS
 - no extra interrupts as in RR, so reduced overhead
 - must record elapsed service times
 - should give better turnaround time than SPN

Priority Based Scheduling

• Priorities

- assign each process a priority, and scheduler always chooses process of higher priority over one of lower priority
- More than one ready queue, ordered by priorities



Priority Algorithms

- Fixed Queues
 - processes are statically assigned to a queue
 - sample queues: system, foreground, background
- Multilevel Feedback
 - processes are dynamically assigned to queues
 - penalize jobs that have been running longer
 - preemptive, with dynamic priority
 - have **N** ready queues (RQ0-RQ**N**),
 - start process in RQ0
 - if quantum expires, moved to i + 1 queue

Cooperating Processes

- Often need to share information between processes
 - information: a shared file
 - computational speedup:
 - break the problem into several tasks that can be run on different processors
 - requires several processors to actually get speedup
 - modularity: separate processes for different functions
 - compiler driver, compiler, assembler, linker
 - convenience:
 - · editing, printing, and compiling all at once

Interprocess Communication

- Communicating processes establish a link
 - can more than two processes use a link?
 - are links one way or two way?
 - how to establish a link
 - how do processes name other processes to talk to
 - use the process id (signals work this way)
 - use a name in the filesystem (UNIX domain sockets)
 - indirectly via mailboxes (a separate object)
- Use send/receive functions to communicate
 - send(dest, message)
 - receive(dest, message)