

## CMSC 412 Midterm #1 (Spring 2014)

1.) (20 points) Define and explain the following terms:

a) Proportionality Principle

Complexity of task should be proportional to rarity/risk (i.e. format disk should be hard to type).

b) Process Control Block (PCB)

A data structure that stores information about a process such as its pid, open files, memory, program its running.

c) CPU protection

Ensuring the OS kernel regains control of a core back from user processes. Often done via a timer interrupt and protecting the interrupt table from user processes updating them.

d) Critical Section

A region of code requiring mutual exclusion, yet ensuring progress is made and a bound waiting time.

2.) (20 points) Given a system that provides binary semaphores (semaphores whose values is either 0 or 1). Show the code to implement counting semaphores using binary semaphores.

```
Sem mutex = 1
```

```
Sem gate = min(1, val)
```

```
Val = <initial value>
```

```
P:
```

```
  P(gate)
```

```
  P(mutex)
```

```
  Val = val - 1
```

```
  If (val > 0) v(gate)
```

```
  V(mutex)
```

```
V:
```

```
  P(mutex)
```

```
  Val = val + 1
```

```
  If (val == 1) V(gate)
```

```
  V(mutex)
```

3.) (16 Points) Scheduling

- a) Given a round robin scheduler (with a quantum of 1 unit), and the following jobs, indicate when each job completes. When a job arrives at time  $n$ , it is placed at the head of the queue of processes and can first run at time  $n+1$ .

| Job | Arrival Time | Required Time | Completion Time |
|-----|--------------|---------------|-----------------|
| A   | 0            | 6             | 11              |
| B   | 3            | 3             | 9               |
| C   | 6            | 6             | 15              |
| D   | 15           | 2             | 17              |

- b) If a scheduler moves processes to a lower priority queue if they use their full quantum, describe a counter strategy for this policy that a process could use to prevent getting put at lower priority.

Yield the processor just an epsilon before the time quantum is up.

4.) (12 points) Deadlock: Explain the four necessary conditions for deadlock.

Circular Wait, Hold & Wait, No Preemption, Mutual Exclusion.

5.) (12 points) Why do we use an interrupt/trap instruction and a number to call a system call rather than simply making it a procedure call?

A trap allow getting to higher privilege (ring 3 to 0) which permits system calls to run privileged instructions.

A system call number decouples locations in memory of the kernel from user space and allows each to evolve code independently.

6.) (20 points) In project #2, another way to handle signal delivery and signal completion is to have the kernel set the EIP to a **standard** signal processing function in user space (in libc) and have that libc function call the user's signal handler and then return to the kernel upon completion.

- a) How would the Signal function and system call need to change to handle this model?

Solution 1: No change to signal

Solution 2: put the table of handlers in user space and signal has a user space code.

- b) How would setup frame need to be changed for this?

Solution 1: setup frame also pushes the address of the handler to be called by the generic function

Solution 2: pushes the signal number so the generic function knows which one to call

- c) How would Sys\_RegDeliver need to change?

Both solutions, no longer require Sys\_RegDeliver since it was designed to provide the address of a function that is no longer needed, the standard libc function will return to kernel space. However, we need a way to register the address of the standard libc signal handler and Sys\_RegDeliver could be used for this.