

16 October: Project 3

Scheduler

Lots of GeekOS integration

Your algorithm can be simple or complex

Semaphores

Not much GeekOS integration—more like pipes

Some care is needed on P and V

Both: You choose your design

Scheduling (1)

Thread A is running along. It's been on the CPU for a long time.

- Timer interrupt! The handler runs. (More on this, next slide.)
 - Each timer interrupt is one “tick”
 - `Timer_Interrupt_Handler` in `timer.c`
 - Don't worry about timer events
- `kthread` structure records the number of ticks it's had the `cpu`
- If `numTicks >= quantum`, set `g_needReschedule`

Scheduling (2)

The handler is actually called from `lowlevel.asm`, `Handle_Interrupt`

- Save context for `g_currentThread`
- Run the actual handler (e.g., `Timer_Interrupt_Handler`)
- Handler returns. If `g_needReschedule`:
 - Reset `numTicks` to zero
 - `Make_Runnable` on `g_currentThread`
 - puts it on the run queue
 - `Get_Next_Runnable` to choose the next thread
 - chooses thread, removes it from the run queue, returns it
 - `lowlevel.asm` does the assignment to `g_currentThread`
 - clear `g_needReschedule`
- It then calls signal handling code and resumes the new `g_currentThread`.

Scheduling (3)

Thread A was CPU bound. What about B, which just asked for a file from disk?

- B calls `Wait(someWaitQueue)`
 - adds B to whatever wait queue it indicated
 - calls `Schedule()`
- `Schedule` switches to some new thread
 - `Get_Next_Runnable` to choose a thread
 - `Switch_To_Thread` to start it

`Switch_To_Thread` is in `lowlevel.asm`, does much the same stuff as `Handle_Interrupt`.

Round Robin Scheduler

Key RR data structures and fields

- `s_runQueue`
- `kthread.priority`

`s_allThreadList` is not a scheduling structure;
you should keep it as is

Key RR functions

- `Find_Best`

What do you need to do? (1)

2 parts: the scheduler machinery, and the syscall that sets policy.

Scheduler:

- Make a flag that indicates what scheduler is in use
- If you need a different data structure, define it
- Set up your new scheduler in `Init_Scheduler`
- Change `Get_Next_Runnable` (and perhaps `Make_Runnable`) so their behavior depends on the scheduler flag
- May add to the timer interrupt handler if you need to do anything when a thread finishes its quantum

What do you need to do? (2)

Set_Scheduling_Policy:

- Set the flag
- If you are using a different data structure, when the policy changes, you must make sure kthreads are on the appropriate structure

If you're not using s_runQueue, you might want to change your Sys_PS implementation so you can still see what's runnable. However, we will not test this.

Algorithm Choice

What scheduler will you implement?

- Multilevel feedback queue
- Shortest job first
- Any other thoughts?
- Is it worth implementing a fancier data structure, like a priority queue?

Semaphores

Much less GeekOS integration than the scheduler.

You'll define and manipulate your own data structure. You may need to declare initialization functions, etc. in `sem.h`.

Wait (P) with `wait`

Signal (V) with `wake_up` or `wake_up_one`

P and V do need some care.