

Denset k -subgraph Approximation on Intersection Graphs

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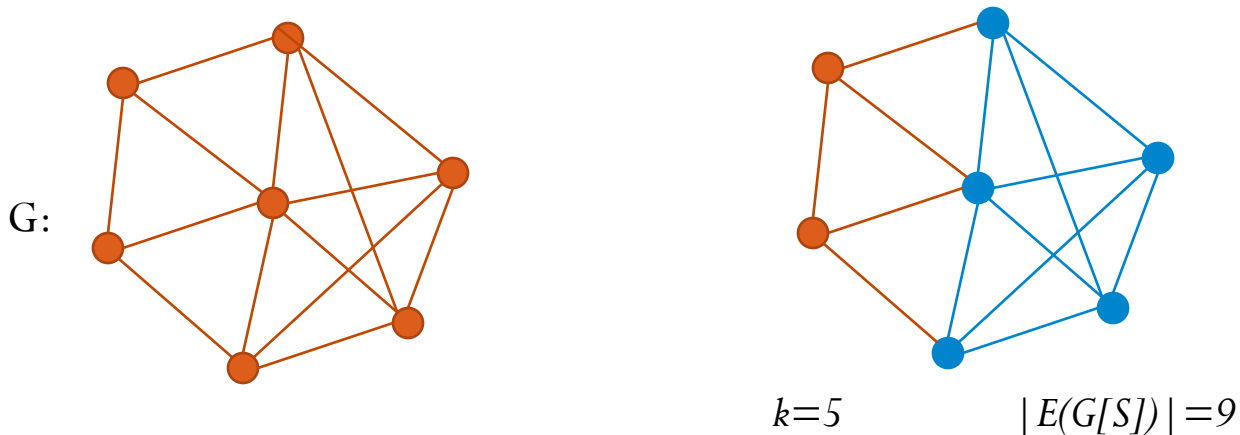
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Problem Definition

- Given:
 - An undirected graph $G(V,E)$
 - An integer k
- Goal:
 - Find a subset S of k vertices such that $|E(G[S])|$ is maximized ($G[S]$ is the subgraph of G induced by S)



Prior Work

- NP-hard: an immediate reduction from MAX-CLIQUE
- Approximability: despite a lot of efforts, it is less understood (in contrast to MAX-CLIQUE)
 - Lower bounds:
 - No PTAS under certain complexity assumption(Khot '04)
 - Upper bounds for general graphs:
 - $O(n^{0.3885})$ -approximation (Kortsarz & Peleg '93)
 - $O(n^{1/3-\epsilon})$ -approximation for some $\epsilon > 0$ (Feige et al. '01)
 - $O(n^{1/4-\epsilon})$ -approximation for any $\epsilon > 0$ (Bhaskara et al. '10)
 - $O(n/k)$ -approximation (Asahiro et al. '96)
 - n/k -approximation (Feige et al. '97)
 - Many improved bounds for special k values....

Prior Work

- Upper bounds on special graph classes :
 - PTAS for **dense instances** (Arora et al. '95)
 - PTAS for **H-minor free graphs** for any fixed H (Demaine et al '05)
 - PTIME on **trees** (Maffioli '91), **co-graphs** (Corneil & Pearl '84)
 - 3-approximation on **Chordal graphs** by greedy (Liazi et al. '08)
 - NP-hardness on chordal graph (Corneil & Pearl '84)
 - Many others....

Our Result

- We show that there is an $O(\sigma)$ -approximation for the class of graphs admitting **σ -elimination orders**

The class (with constant σ) includes:

- chordal graphs,
 - circular-arc graphs,
 - claw-free graphs,
 - line graphs of l -hypergraphs,
 - planar graphs,
 - disk graphs,
 - and the intersection graphs of fat objects
- This implies constant approximations for **ALL** above graph classes.

σ -elimination order

- The notion was introduced by K. Akcoglu et al. '02 (under name **sequentially k-independent graphs**)
- Its algorithmic aspect has drawn researchers' attention recently. (Ye & Borodin '09)
- A significant generalization of perfect elimination order for Chordal graphs.

σ -elimination order

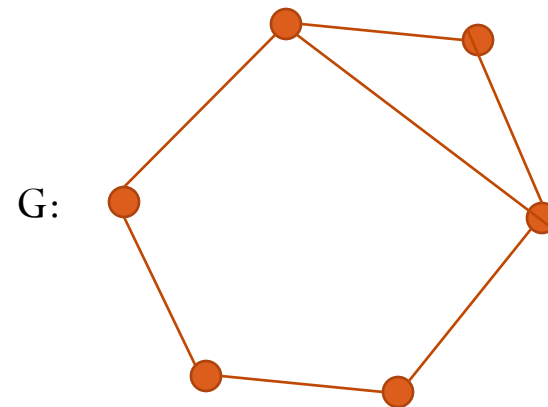
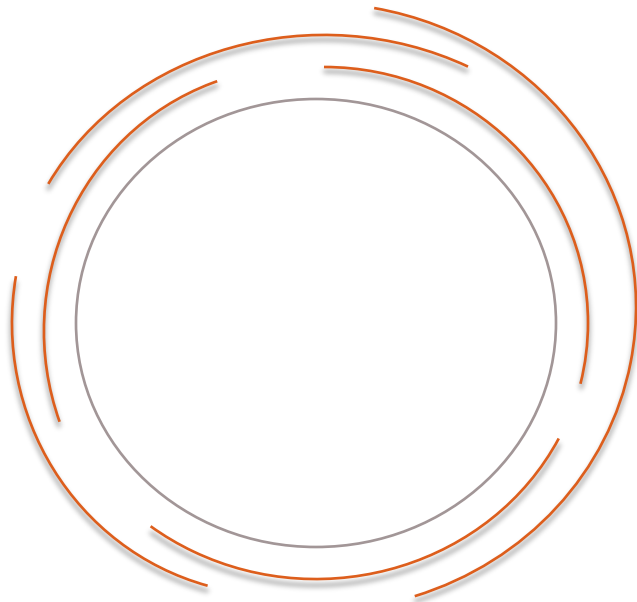
- Some Notations:
 - $pred_L(v)$: the set of neighbors of v that appear before v in the vertex ordering L
 - $\alpha(G)$: the independence number of G , i.e., the cardinality of the max independent set of G
- perfect elimination order L :
 - An ordering of all vertices such that $pred_L(v)$ is a clique
 - A graph has a perfect elimination order iff it is chordal
- σ -elimination order L :
 - An ordering of all vertices such that $\alpha(G[pred_L(v)]) \leq \sigma$
 - A perfect elimination order is a 1-elimination order

A little more on σ -elimination order

- We show that each circular-arc graph has a 2-EO
- Circular-arc graphs:

The intersection graph of those arcs:

- each arc is a node
- there is an edge between two nodes iff two corresponding arcs intersect



A little more on σ -elimination order

- 2-EO: just sort the arcs in an non-increasing order of their lengths.

Proof:

We need to prove $\alpha(\text{pred}(a)) \leq 2$ for all arc a .

Consider arc a ,

- each arc longer than a contains at least one endpoint of a
- arcs that share a common point form a clique
- therefore, neighbors of a can be partitioned into two cliques.

Densest k Subgraph Approximation

- The Maximum Density Subgraph Problem (MDSP)
 - Each vertex v has a weight $w(v)$
 - Density of S : $\rho(S) = (w(S) + |E[S]|) / |S|$
 - Find a subset S that maximizes $\rho(S)$
 - PTIME by parametric network flow (Gallo et al. '89)
- A important property:
 - For any v in S , $w(v) + \text{deg}(v, S) \geq \rho(S)$ (since otherwise we can delete v from S to get a subgraph with larger density)
 - $\text{deg}(v, S)$: degree of v in $G[S]$

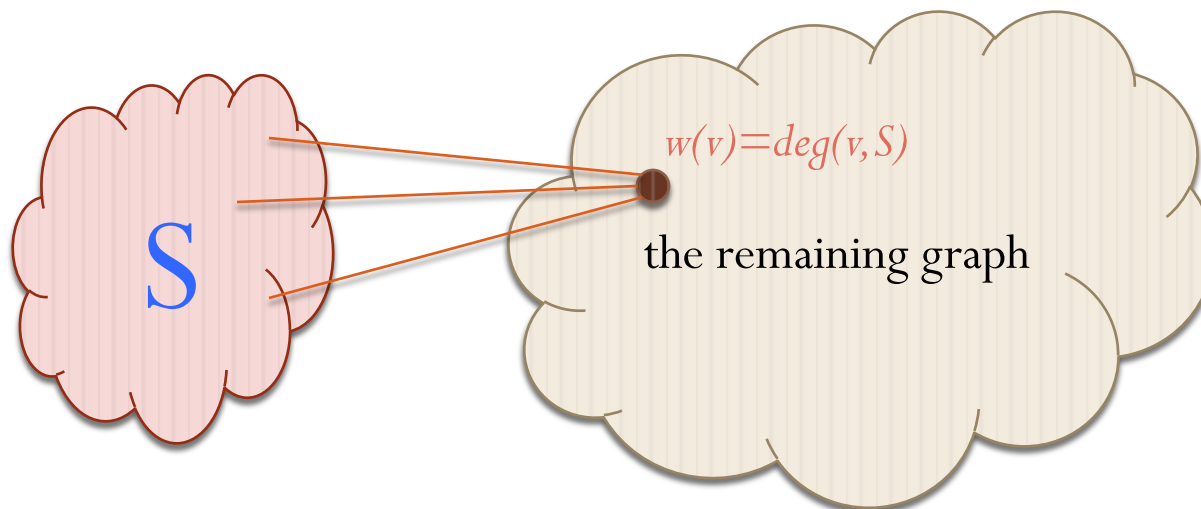
Densest k Subgraph Approximation

- Outline of the algorithm:
- **Phase1: Growing**
 - Add MDSP solution to S until $|S| > k/2$ (more details soon)
 - We can show that S has a density $\geq O(1)\rho^*$
(ρ^* : the density of OPT)
 - If $|S| \leq k$, we are done.
 - If $|S| > k$:
- **Phase 2: Shrinking**
 - We look at the σ -EO of S and find a subgraph of S s.t. the deg. of each node is $O(1)$ of the deg in $G[S]$.
 - Therefore, it is a $O(1)$ -approx.

Densest k Subgraph Approximation

- **Phase 1: Growing**

- Suppose S is the set of nodes we've already chosen
- Run MDSP on the remaining graph with vertex weight $w(v) = \text{deg}(v, S)$
 - This is used to capture the edges between S and the remaining nodes
- Repeat until $|S| \geq k$
- We can show $\text{deg}(v) > O(1) \rho^*$ for all v in S



Densest k Subgraph Approximation

- **Phase 2: Shrinking**

- Suppose we end up with $|S| \gg k$ obtained from Phase 1
- Consider the elimination order of $G[S]$
 - If there is a node v s.t. $|Pred(v)| \geq k/2$, then uniformly & randomly pick $k/2$ vertices from $Pred(v)$ is a $O(1)$ -approximation

Proof:

First notice the fact that: if $\alpha(G) = O(1)$, then $|E(G)| = O(V^2)$

Therefore, the expect number of edges in our solution SOL is

$$\sum_e Pr(e \text{ in } SOL) = O(V^2) * (k/2V) * (k/2V) = O(k^2)$$

Densest k Subgraph Approximation

- **Phase 2: Shrinking**

- Suppose we end up with $|S| \gg k$ obtained from Phase 1
- Consider the elimination order of $G[S]$
 - If there is no node s.t. $|Pred(v)| \geq k/2$

- Process EO in the *reverse order*

Either $Pred(v) = O(1)\rho^*$ or $Succ(v) = O(1)\rho^*$ (since $deg(v) = O(1)\rho^*$)

- If $Pred(v) = O(1)\rho^*$: $SOL = SOL + v + Pred(v)$
 - We add a graph where each node has $deg O(\rho^*)$
- If $Succ(v) = O(1)\rho^*$: $SOL = SOL + v$
 - v has $deg = O(\rho^*)$ in SOL

KEY:

How EO
is used to
help us

Therefore, an $O(1)$ -approximation

Open Problems

- Finding more graph classes that admit σ -EO (with small σ)
- Finding more applications for σ -EO
 - Ye & Borodin found that a few graph optimization problems are easier if the graph has $O(1)$ -EO
- Closing the huge gap for densest k subgraph
- **OPEN:** Whether densest k subgraph is NP-hard on interval graphs and planar graphs

● Thanks