## 15-213

"The course that gives CMU its Zip!"

## Tìme Measurement Oct. 24, 2002

## Topics

- Time scales
- Interval counting
- Cycle counters
- K-best measurement scheme


## Computer Tìme Scales



Two Fundamental Time Scales

- Processor: $\quad 10^{-9}$ sec.

■ External events: $\mathbf{1 0}^{-2}$ sec.

- Keyboard input
- Disk seek
- Screen refresh

Implication

- Can execute many instructions while waiting for external event to occur
- Can alternate among processes without anyone noticing


## Measurement Challenge

## How Much Time Does Program X Require?

- CPU time
- How many total seconds are used when executing X?
- Measure used for most applications
- Small dependence on other system activities
- Actual ("Wall") Time
- How many seconds elapse between the start and the completion of X ?
- Depends on system load, I/O times, etc.


## Confounding Factors

- How does time get measured?
- Many processes share computing resources
- Transient effects when switching from one process to another
- Suddenly, the effects of alternating among processes become noticeable


## "Time" on a Computer System


real (wall clock) time

= user time (time executing instructions in the user process)

= system time (time executing instructions in kernel on behalf of user process)

= some other user's time (time executing instructions in different user's process)


We will use the word "time" to refer to user time.

cumulative user time

## Activity Periods: Light Load



- Most of the time spent executing one process
- Periodic interrupts every 10 ms
- Interval timer
- Keep system from executing one process to exclusion of others
- Other interrupts
- Due to I/O activity
- Inactivity periods
- System time spent processing interrupts
- ~250,000 clock cycles


## Activity Periods: Heavy Load



- Sharing processor with one other active process

■ From perspective of this process, system appears to be "inactive" for ~50\% of the time

- Other process is executing


## Interval Counting

## OS Measures Runtimes Using Interval Timer

- Maintain 2 counts per process
- User time
- System time

■ Each time get timer interrupt, increment counter for executing process

- User time if running in user mode
- System time if running in kernel mode


## Interval Counting Example

(a) Interval Timings

(b) Actual Times

| A | A | A | A | $120.0 \mathrm{u}+33.3 \mathrm{~s}$ |
| :---: | :---: | :---: | :---: | :---: |
| B | B |  | B | $73.3 \mathrm{l}+23.3 \mathrm{~s}$ |
| \| | | 11 |  |  |  |

## Unix time Command

```
time make osevent
gcc -02 -Wall -g -march=i486 -c clock.c
gcc -O2 -Wall -g -march=i486 -c options.c
gcc -O2 -Wall -g -march=i486 -c load.c
gcc -02 -Wall -g -march=i486 -o osevent osevent.c
0.820u 0.300s 0:01.32 84.8% 0+Ok 0+Oio 4049pf+0w
```

■ 0.82 seconds user time

- 82 timer intervals

■ 0.30 seconds system time

- 30 timer intervals
- 1.32 seconds wall time

■ 84.8\% of total was used running these processes

- $(.82+0.3) / 1.32=.848$


## Accuracy of Interval Counting



Minimum
Maximum

- Computed time $=70 \mathrm{~ms}$
- Min Actual $=60+\varepsilon$
- Max Actual = 80 - $\varepsilon$


## Worst Case Analysis

■ Timer Interval = $\delta$
$\checkmark$ Single process segment measurement can be off by $\pm \delta$
$v$ No bound on error for multiple segments
$\lambda$ Could consistently underestimate, or consistently overestimate

## Accuracy of Int. Cntg. (cont.)



Maximum

- Computed time $=70 \mathrm{~ms}$
- Min Actual $=60+\varepsilon$
- Max Actual $=80-\varepsilon$

Average Case Analysis
v Over/underestimates tend to balance out
$v$ As long as total run time is sufficiently large
$\lambda$ Min run time $\sim 1$ second
$\lambda 100$ timer intervals
v Consistently miss 4\% overhead due to timer interrupts

## Cycle Counters

■ Most modern systems have built in registers that are incremented every clock cycle

- Very fine grained
- Maintained as part of process state
" In Linux, counts elapsed global time
■ Special assembly code instruction to access
■ On (recent model) Intel machines:
- 64 bit counter.
- RDTSC instruction sets \%edx to high order 32-bits, \%eax to low order 32-bits


## Cycle Counter Period

Wrap Around Times for 550 MHz machine
■ Low order 32 bits wrap around every $2^{32} /\left(550\right.$ * $\left.10^{6}\right)=7.8$ seconds
■ High order 64 bits wrap around every $2^{64} /\left(550\right.$ * $\left.10^{6}\right)=$ 33539534679 seconds

- 1065 years

For 2 GHz machine
■ Low order 32-bits every 2.1 seconds
■ High order 64 bits every 293 years

## Measuring with Cycle Counter

## Idea

- Get current value of cycle counter
- store as pair of unsigned's cyc_hi and cyc_lo
- Compute something
- Get new value of cycle counter

■ Perform double precision subtraction to get elapsed cycles

```
/* Keep track of most recent reading of cycle counter */
static unsigned cyc_hi = 0;
static unsigned cyc_lo = 0;
void start_counter()
{
    /* Get current value of cycle counter */
    access_counter(&cyc_hi, &cyc_lo);
}
```


## Accessing the Cycle Cntr.

■ GCC allows inline assembly code with mechanism for matching registers with program variables
■ Code only works on x86 machine compiling with GCC

```
void access_counter(unsigned *hi, unsigned *lo)
{
    /* Get cycle counter */
    asm("rdtsc; movl %%edx,%O; movl %%eax,%1"
        : "=r" (*hi), "=r" (*lo)
        : /* No input */
        : "%edx", "%eax");
}
```

■ Emit assembly with rdtsc and two movl instructions

## Closer Look at Extended ASM

```
asm("Instruction String"
    : Output List
    : Input List
    : Clobbers List);
}
```

```
void access counter
    (unsigned *hi, unsigned *lo)
{
    /* Get cycle counter */
    asm("rdtsc; movl %%edx,%0; movl %%eax,%1"
        : "=r" (*hi), "=r" (*lo)
        : /* No input */
        : "%edx", "%eax");
}
```


## Instruction String

- Series of assembly commands
- Separated by ";" or " $\backslash n$ "
- Use "\%о\%" where normally would use "\%"


## Closer Look at Extended ASM

```
asm("Instruction String"
    : Output List
    : Input List
    : Clobbers List);
}
```

```
void access_counter
    (unsigned *hi, unsigned *lo)
{
    /* Get cycle counter */
    asm("rdtsc; movl %%edx,%0; movl %%eax,%1"
        : "=r" (*hi), "=r" (*lo)
        : /* No input */
        : "%edx", "%eax");
}
```


## Output List

■ Expressions indicating destinations for values $\% 0, \% 1, \ldots, \% j$

- Enclosed in parentheses
- Must be Ivalue
" Value that can appear on LHS of assignment
■ Tag "=r" indicates that symbolic value ( $\% 0$, etc.), should be replaced by register


## Closer Look at Extended ASM

```
asm("Instruction String"
    : Output List
    : Input List
    : Clobbers List);
}
```

```
void access_counter
    (unsigned *hi, unsigned *lo)
{
    /* Get cycle counter */
    asm("rdtsc; movl %%edx,%0; movl %%eax,%1"
        : "=r" (*hi), "=r" (*lo)
        : /* No input */
        : "%edx", "%eax");
}
```


## Input List

■ Series of expressions indicating sources for values $\% \mathbf{j}+1, \% \boldsymbol{j}+2$,

- Enclosed in parentheses
- Any expression returning value

■ Tag "r" indicates that symbolic value ( $\% 0$, etc.) will come from register

## Closer Look at Extended ASM

```
asm("Instruction String"
    : Output List
    : Input List
    : Clobbers List);
}
```

```
void access_counter
    (unsigned *hi, unsigned *lo)
{
    /* Get cycle counter */
    asm("rdtsc; movl %%edx,%0; movl %%eax,%1"
        : "=r" (*hi), "=r" (*lo)
        : /* No input */
        : "%edx", "%eax");
}
```


## Clobbers List

■ List of register names that get altered by assembly instruction
■ Compiler will make sure doesn't store something in one of these registers that must be preserved across asm

- Value set before \& used after


## Accessing the Cycle Cntr. (cont.)

## Emitted Assembly Code

```
    movl 8(%ebp),%esi # hi
    movl 12(%ebp),%edi # lo
#APP
    rdtsc; movl %edx,%ecx; movl %eax,%ebx
#NO_APP
    movl %ecx,(%esi) # Store high bits at *hi
    movl %ebx,(%edi) # Store low bits at *lo
```

■ Used $\%$ ecx for *hi (replacing \% 0)
■ Used \%ebx for *lo (replacing \%1)
■ Does not use \%eax or \%edx for value that must be carried across inserted assembly code

## Completing Measurement

■ Get new value of cycle counter
■ Perform double precision subtraction to get elapsed cycles
■ Express as double to avoid overflow problems

```
double get_counter()
{
    unsigned ncyc_hi, ncyc_lo
    unsigned hi, lo, borrow;
    /* Get cycle counter */
    access_counter(&ncyc_hi, &ncyc_lo);
    /* Do double precision subtraction */
    lo = ncyc_lo - cyc_lo;
    borrow = lo > ncyc_lo;
    hi = ncyc_hi - cyc_hi - borrow;
    return (double) hi * (1 << 30) * 4 + lo;
}
```


## Timing With Cycle Counter

## Determine Clock Rate of Processor

- Count number of cycles required for some fixed number of seconds

```
double MHZ;
int sleep_time = 10;
start_counter();
sleep(sleep_time);
MHZ = get_counter()/(sleep_time * le6);
```


## Time Function $\mathbf{P}$

■ First attempt: Simply count cycles for one execution of $P$

```
double tsecs;
start_counter();
P();
tsecs = get_counter() / (MHZ * 1e6);
```


## Measurement Pitfalls

Overhead

- Calling get_counter () incurs small amount of overhead
- Want to measure long enough code sequence to compensate

Unexpected Cache Effects

- artificial hits or misses
- e.g., these measurements were taken with the Alpha cycle counter:
foo1 (array1, array2, array3); /* 68,829 cycles */
foo2 (array1, array2, array3); /* 23,337 cycles */ VS.
foo2 (array1, array2, array3); /* 70,513 cycles */
foo1 (array1, array2, array3); /* 23,203 cycles */


## Dealing with Overhead \& Cache Effects

- Always execute function once to "warm up" cache
- Keep doubling number of times execute $P()$ until reach some threshold
- Used CMIN = 50000

```
int cnt = 1;
double cmeas = 0;
double cycles;
do {
        int c = cnt;
        P(); /* Warm up cache */
        get_counter();
        while (c-- > 0)
            P();
        cmeas = get_counter();
        cycles = cmeas / cnt;
        cnt += cnt;
    } while (cmeas < CMIN); /* Make sure have enough */
return cycles / (1e6 * MHZ);
```


## Multitasking Effects

Cycle Counter Measures Elapsed Time

- Keeps accumulating during periods of inactivity
- System activity
- Running other processes

Key Observation
■ Cycle counter never underestimates program run time

- Possibly overestimates by large amount

K-Best Measurement Scheme

- Perform up to $\mathbf{N}($ e.g., 20) measurements of function

■ See if fastest K (e.g., 3) within some relative factor $\varepsilon$ (e.g., 0.001)


## K-Best Validation



Very good accuracy for < 8ms
$\checkmark$ Within one timer interval
$v$ Even when heavily loaded

Less accurate of $>10 \mathrm{~ms}$
■ Light load: ~4\% error

- Interval clock interrupt handling
- Heavy load: Very high error

Subtract Timer Overhead
v Estimate overhead of single interrupt by measuring periods of inactivity
v Call interval timer to determine number of interrupts that have
-27- Occurred

Better Accuracy for $\boldsymbol{>}$ 10ms
■ Light load: 0.2\% error
■ Heavy load: Still very high error

## K-Best on NT

$K=3, \varepsilon=0.001$



Acceptable accuracy for $<50 \mathrm{~ms}$
v Scheduler allows process to run multiple intervals

Less accurate of >10ms

- Light load: 2\% error

■ Heavy load: Generally very high error

## Time of Day Clock

- Unix gettimeofday () function

■ Return elapsed time since reference time (Jan 1, 1970)
■ Implementation

- Uses interval counting on some machines
» Coarse grained
- Uses cycle counter on others
"Fine grained, but significant overhead and only 1 microsecond resolution

```
#include <sys/time.h>
#include <unistd.h>
    struct timeval tstart, tfinish;
    double tsecs;
    gettimeofday(&tstart, NULL);
    P();
    gettimeofday(&tfinish, NULL);
    tsecs = (tfinish.tv_sec - tstart.tv_sec) +
        1e6 * (tfinish.tv_usec - tstart.tv_usec);
```


## K-Best Using gettimeofday



## Linux

- As good as using cycle counter
- For times > 10 microseconds


## Windows

- Implemented by interval counting
- Too coarse-grained


## Measurement Summary

Timing is highly case and system dependent

- What is overall duration being measured?
$\bullet>1$ second: interval counting is OK
- << 1 second: must use cycle counters

■ On what hardware / OS / OS version?

- Accessing counters
" How gettimeofday is implemented
- Timer interrupt overhead
- Scheduling policy

Devising a Measurement Method

- Long durations: use Unix timing functions

■ Short durations

- If possible, use gettimeofday
- Otherwise must work with cycle counters
- K-best scheme most successful

