| Positional | encodings |
|------------|-----------|
| | |

La self-attn is not inhumatly position aware P2 TOP P3 TID (3 III) C III favorite LLM L) absolute position info La additive embeddings by new params assoc. ul position L7 lacks position extrapolation Lannot generalize to sequences longer than max. training length

relative position

my favorite UM is Quen
houstly my favorite LLM is Quen
forestly my favorite LLM is Quen

Alibi: no position embs added to input (; L) each head can have a diff m Ly no extra params to train L) much better extrapolation to longer than max training length SLRS KOPE: rotory position enceding -2d usulization, dot product between Ruens and favorite 2 15 same as

Quen. Guontez

how do we votate a vector? Ly multiply by a rotation matrix $W_{R0,P} = \begin{bmatrix} \cos(p\theta) & -\sin(p\theta) \\ \sin(p\theta) & \cos(p\theta) \end{bmatrix}$ rotation position
free set how do we integrate rotation into alf-attraquen = Wro. 0=5 · Wq · Cquen Kfavoite = WRA11=2 · WK · Cfonoite ques . * favorite Ly due to notation matrix properties = (Wq Cquen) . WRB, 5-2 (Wk Cfavoite) this depends only

La same dot product regardless of abs. pos, as long as long as long is the same

 q^2 θ_1 θ_2 θ_3 θ_4 \cdots

Greach Dis is a constation frequently that controls rotation frequently