CMCS427 Dot product review

Computing the dot product
The dot product can be computed via

a) Cosine rule \( a \cdot b = |a||b| \cos \theta \)
b) Coordinate-wise \( a \cdot b = ax \cdot bx + ay \cdot by \)

Exercises:
1) If \( a \cdot b, |a| \) and \( |b| \) all equal 1, what’s the angle between the vectors?

2) If \( a = \langle 2, -1 \rangle \) and \( b = \langle 3, 2 \rangle \), what is \( a \cdot b \) and what is the angle between the vectors?

3) If \( v \cdot w = \frac{1}{2} |v||w| \) what is the angle between \( u \) and \( v \)?

Properties of the dot product (dot product algebra)
The dot product is

a) Commutative \( a \cdot b = b \cdot a \)
b) Distributive \( a \cdot (b+c) = a \cdot b + a \cdot c \)
c) Non-canceling \( a \cdot b = a \cdot c \) does not mean \( b = c \) (it does give \( a \cdot (b-c) = 0 \))
d) Magnitude squared \( a \cdot a = |a|^2 \)
e) Linear with scalars \( s(a \cdot b) = sa \cdot b \)
f) From (b) and (d), linear \( a \cdot (sb+rc) = s(a \cdot b) + r(a \cdot c) \)
g) Zero if orthogonal \( a \cdot b = 0 \) if \( a \) is orthogonal to \( b \)

Example: Rewrite the magnitude of \( |a-b|^2 \) to eliminate \( a-b \)

\[
|a-b|^2 = (a-b) \cdot (a-b) = a \cdot a - a \cdot b - b \cdot a + b \cdot b = a \cdot a - 2(a \cdot b) + b \cdot b = |a|^2 - 2(a \cdot b) + |b|^2
\]

Exercises:
1) Following the example, rewrite \( |2a-b|^2 \)

2) If \( v \) is orthogonal to \( u \) and \( w \) separately, is it orthogonal to \( u+w \)?
3) Simplify the following:

a) \((v-w)\cdot w + v\cdot w\)

b) \((v+w)\cdot v - (v+w)\cdot w\)

c) \((v+w)\cdot(v+w) - 2v\cdot w\)

**Using sign of the dot product for testing angles**

If \(a\cdot b = 0\), the angle between the vectors is zero
If \(a\cdot b > 0\), the angle is acute (less than 90 degrees)
If \(a\cdot b < 0\), the angle is obtuse (greater than 90 degrees)
Note: to use this test you generally need a cut off for equal to zero, so |\(a\cdot b| < \delta\), \(\delta\) small

**Exercises:**

1) Test the following pairs: <2,1> and <-1,1>; <2,0> and <0,1>; <3.4,-3.7> and <3.7,3.3>.

2) Would the length of the vectors \(a\) and \(b\) influence the numeric sensitivity of the test? Eg, if \(a\) and \(b\) are both long vectors, does it make a difference relative to your \(\delta\) cut off?

2) The perp vector in 2D is given by \(v_{\text{perp}} = <-y,x>\) for the vector \(v = <x,y>\).

With 3D vectors it isn’t as easy to define a single perp vector - there’s an infinity of directions rotating around a vector that are candidates. But, given a 3D vector \(w=<x,y,z>\), can you define a perpendicular vector by inspection that’s like the perp vector? A vector \(w_{\text{perp}}\) such that \(w_{\text{perp}}\cdot w = 0\)?
Dot product and projection

A number of critical applications of the dot product are from using it to find projections.

• The vector projection of $a$ onto $b$ is the vector $a_1$ which is the component of $a$ in the direction of $b$.

• The scalar projection of $a$ onto $b$ is the length of $a_1$.

A starting equation is $a_1 = \frac{a \cdot b}{b \cdot b} b$ and $|a_1| = \left| \frac{a \cdot b}{b \cdot b} b \right|$

From this equation we have, if $|b|=1$, that $a_1 = (a \cdot b)\hat{b}$

This gives $|a_1| = |(a \cdot b)||\hat{b}| = |(a \cdot b)|$

Examples:

• What is the projection of $<2,3,4>$ onto $<0,1,0>$? $<0,3,0>$ with a length of 3.

  Projections onto the axes are the vector’s coordinate of that axis.

  • What is the projection of $<1,2>$ onto $<1,1>$?

    $a_1 = \frac{a \cdot b}{b \cdot b} b = \begin{pmatrix} 1.2 \\ 1 \end{pmatrix}$

    The length is $|<1.5,1.5>| = \sqrt{2((1.5)(1.5))} = 2.1213$

    • What is the projection of $<0.5,0.5>$ onto $<2,3>$?

      $a_1 = \frac{a \cdot b}{b \cdot b} b = \begin{pmatrix} 0.5 \\ 0.5 \\ 2.3 \\ 2.3 \end{pmatrix}$

      The vector projection has the following applications (among others):

      • Vector rejection. The vector $a_2$ (see above) that is the component of a orthogonal to $b$.

      • Coordinate frame resolution. The vectors $a_1$ and $a_2$ are orthogonal and represent an alternative coordinate frame to the standard x,y frame (in 2D)

      • Distance from a point to a line. The distance from a point $p$ to a line defined by point-vector.

Details of each application.

• Vector rejection

Once you have $a_1$, then $a = a_1 + a_2$ so $a_2 = a - a_1$.

Example: What is the vector rejection of $<1,2>$ onto $<1,1>$? Since $a_1 = <1.5,1.5>$, then

$a_2 = <1,2> - <1.5,1.5> = <-0.5,+0.5> \quad \text{and} \quad a_1 \cdot a_2 = 0$

• Coordinate frame resolution

Once you have $a_1$ and $a_2$, you have a pair of orthogonal vectors. If you normalize then you have an orthonormal basis for a new coordinate system (vectors are orthonormal if orthogonal and unit length).

Now

$$\vec{a}_1 = \frac{a_1}{|a_1|} = \frac{<1.5,1.5>}{\sqrt{1.5^2+1.5^2}} = <0.70711,0.70711>,$$

and

$$\vec{a}_2 = <<0.70711,+0.70711>$$
• Distance from a point to a line
If we’re given a line in point-vector form with P0 and v, then the distance from an arbitrary point P to the line is given by the length of the vector rejection $a_2$, with $a = P - P0$

$$d = |a_2| = |(P - P0) - \frac{(P - P0) \cdot v}{v \cdot v} v|$$

If v is of unit length, then

$$|a_2| = |(P - P0) - ((P - P0) \cdot v) \cdot v|$$

Example: What is distance of the point (3,4) from the line defined by P0=(0,0) and v=<1,1>?

$$d = \left| (P - P0) - \frac{(P - P0) \cdot v}{v \cdot v} v \right|$$

$$d = \left| <3,4> - <0,0> - \frac{(3,4) \cdot <1,1>}{<1,1> \cdot <1,1>} <1,1> \right|$$

$$d = \left| 3,4 - \frac{7}{2} <1,1> \right| = |<3,4> - <3.5,3.5>| = |<0.5,0.5>| = 0.70711$$

Exercises:
1) What’s the vector $a_1$ and scalar projection of $a=<3,2,1>$ onto $b=<0,2,2>$?

2) What the vector rejection $a_2$ for this example?
3) And, putting (1) and (2) together, what’s the normalized coordinate frame based on a1 and a2 for this case?

4) What’s the distance from the point (7,3) to the line given by P0=(1,2) and v=<2,1>?

5) There’s another equation for the distance from a point to a line based on the normal vector (hint: consider the perp vector if you have a line in point-vector form.) Develop an equation for the distance from a point P to a line defined by P0 and v, and then apply it to the data in (4).

Some of these exercises came from the file below. It has exercises with solutions, so is good for self-study.  https://dnichols30582.edublogs.org/files/2015/12/11.6-Solutions-1eupr84.pdf