

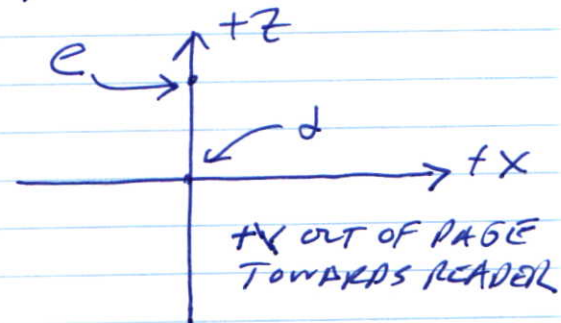
## CMCS 427 CAMERA MATRIX EXAMPLES

These examples show:

- Computing a camera matrix
- Testing a computation by using simple values

Example 1: CAMERA AT  $(0, 0, 100)$

$$\begin{aligned} \text{Set } c &= at = (0, 0, 100) \\ d &= 100kAt' = (0, 0, 0) \\ up &= \langle 0, 1, 0 \rangle \end{aligned}$$



$$\text{NOW } z_c = c - d = \langle 0, 0, 100 \rangle$$

$$\bar{z}_c = \langle 0, 0, 1 \rangle$$

$$\bar{x}_c = \bar{up} \times \bar{z}_c = \begin{vmatrix} i & j & k \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{vmatrix} = \langle 1, 0, 0 \rangle$$

$$\bar{y}_c = \bar{z}_c \times \bar{x}_c = \begin{vmatrix} i & j & k \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{vmatrix} = \langle 0, 1, 0 \rangle$$

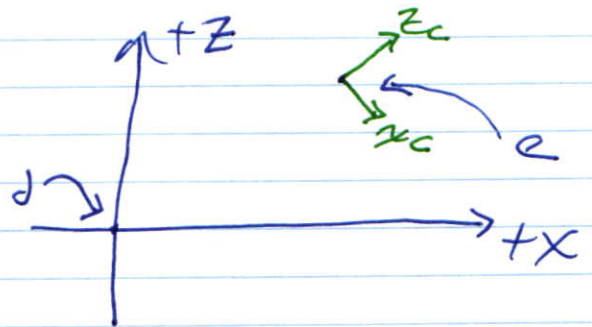
$$\text{And } C = \begin{bmatrix} x_c & y_c & z_c & c \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & +100 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\text{So } C^{-1} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -100 \\ 0 & 0 & 0 & 1 \end{bmatrix} \text{ by inspection}$$

$$\text{If } C = \begin{bmatrix} R & T \\ 0 & 1 \end{bmatrix} \text{ then } C^{-1} = \begin{bmatrix} R^T & -R^T \cdot T \\ 0 & 1 \end{bmatrix}$$

## Example 2: CAMERA OUT DIAGONAL

$$\begin{aligned} \text{Set } c = at &= (100, 0, 100) \\ d = 100kAt &= (0, 0, 0) \\ op &= \langle 0, 1, 0 \rangle \end{aligned}$$



$$\text{Now } z_c = c - d = (100, 0, 100)$$

$$\bar{z}_c = \langle +.71, 0, +.71 \rangle$$

$$\bar{x}_c = op \times \bar{z}_c = \begin{vmatrix} i & j & k \\ 0 & 1 & 0 \\ .71 & 0 & .71 \end{vmatrix} = \langle +.71, 0, -.71 \rangle$$

( $.71 \approx \frac{1}{\sqrt{2}}$ )

$$\bar{y}_c = \bar{z}_c \times \bar{x}_c = \begin{vmatrix} i & j & k \\ .71 & 0 & .71 \\ +.71 & 0 & -.71 \end{vmatrix} = \langle 0, -(-\frac{1}{2} + \frac{1}{2}), 0 \rangle$$

$$= \langle 0, 1, 0 \rangle$$

And

$$C = \begin{bmatrix} x_c & y_c & z_c & c \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} +.71 & 0 & +.71 & 100 \\ 0 & 1 & 0 & 0 \\ -.71 & 0 & +.71 & 100 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$C^{-1} = \begin{bmatrix} x_c & -x_c \cdot c \\ y_c & -y_c \cdot c \\ z_c & -z_c \cdot c \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} R^T & -R^T \cdot T \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} +.71 & 0 & -.71 & -\langle .71, 0, .71 \rangle \cdot \langle 100, 0, 100 \rangle \\ 0 & 1 & 0 & -\langle 0, 1, 0 \rangle \cdot \langle 100, 0, 100 \rangle \\ +.71 & 0 & +.71 & -\langle +.71, 0, +.71 \rangle \cdot \langle 100, 0, 100 \rangle \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} +.71 & 0 & -.71 & ~~+100\sqrt{2}~~ & 0 \\ 0 & 1 & 0 & 0 & 0 \\ +.71 & 0 & +.71 & -100 \times \sqrt{2} & 0 \end{bmatrix}$$