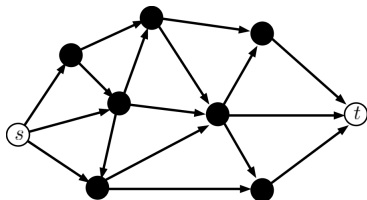


Lecture 5: How Bad is Selfish Routing?

September 13, 2016

Given:

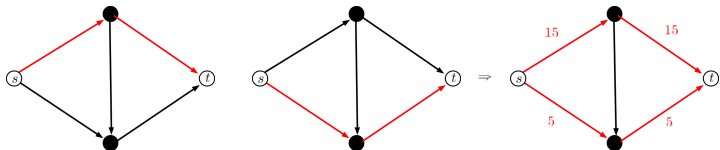
- ▶ A directed network $G(V, E)$
- ▶ A set of source-destination pairs s_i-t_i with a fixed traffic rate r_i
- ▶ A load dependent latency function $l_e : R^+ \rightarrow R^+$ for each edge.
 - ▶ non-decreasing
 - ▶ continuous



- ▶ SWM: find a way to route all traffic such that total cost $\sum_e f_e l_e(f_e)$ is minimized

A routing game

- ▶ Infinitely many players
- ▶ Each arriving at some source s_i at rate r_i
- ▶ The routes chosen by every player can be described using a vector f (the flow)



A routing game

- ▶ Let \mathcal{P} be the set of all s_i - t_i paths. For a flow f and a s_i - t_i path P :
 - ▶ f_P = flow through P
 - ▶ Cost of each player $l_P(f) = \sum_{e \in P} l_e(f_e)$, where
$$f_e = \sum_{P \in \mathcal{P}: e \in P} f_P$$
 - ▶ Cost of flow $C(f) = \sum_{P \in \mathcal{P}} f_P l_P(f) = \sum_{e \in E} f_e l_e(f_e)$
- ▶ In the absence of external traffic control, assume every player plays a selfish game

Social Welfare Maximization

Given instance (G, r, l) .

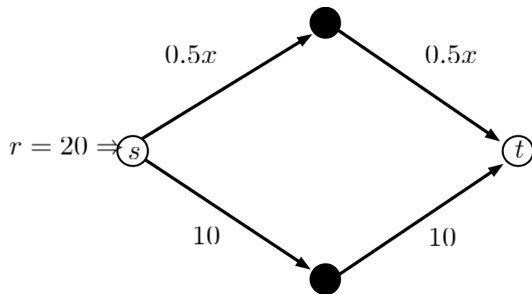
$$\text{minimize } \sum_e f_e l_e(f_e)$$

$$\sum_{P \in \mathcal{P}_i} f_P = r_i \quad \forall i$$

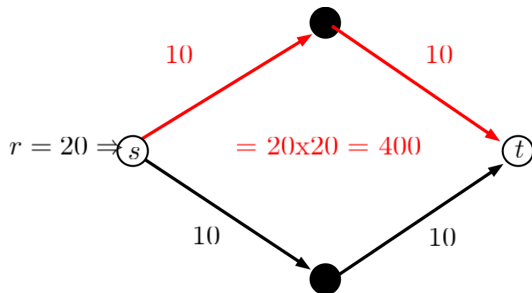
$$\sum_{P \in \mathcal{P}: e \in P} f_P = f_e \quad \forall e \in E$$

$$f_P \geq 0 \quad \forall P \in \mathcal{P}$$

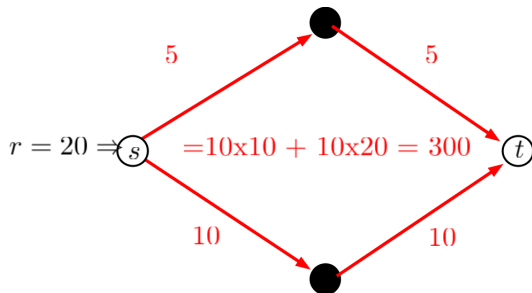
Example



Example



Example



Price of Anarchy

For an instance (G, r, l) , let f be the flow at equilibrium and f^* be the flow at social welfare max. How far is $C(f)$ from $C(f^*)$?

Result

Theorem

If f and f^ are the Nash and optimal flows for (G, r, l) with linear latency functions, then $\frac{C(f)}{C(f^*)} \leq \frac{4}{3}$*

Convex Program

Given instance (G, r, l) . Assume $l_e(x) = a_e x + b_e$. Then cost function $C(f) = \sum_e a_e f_e^2 + b_e f_e$ is convex.

$$\text{minimize } \sum_e a_e f_e^2 + b_e f_e$$

$$\sum_{P \in \mathcal{P}_i} f_P = r_i \quad \forall i$$

$$\sum_{P \in \mathcal{P}: e \in P} f_P = f_e \quad \forall e \in E$$

$$f_P \geq 0 \quad \forall P \in \mathcal{P}$$

Flows at Equilibrium

- ▶ Lemma 1.1: A feasible flow f for (G, r, l) is at Nash equilibrium (Nash flow) if for each s_i - t_i pair, $P_1, P_2 \in \mathcal{P}_i$ and $f_{P_1} > 0$, we have:

$$\sum_{e \in P_1} a_e f_e + b_e \leq \sum_{e \in P_2} a_e f_e + b_e$$

- ▶ \Rightarrow All s_i - t_i paths must have the same latency = $L_i(f)$.

$$\Rightarrow C(f) = \sum_{P \in \mathcal{P}} f_P l_P(f) = \sum_i L_i(f) r_i$$

Flows at Equilibrium

- ▶ $\frac{d}{dx} C = \sum_e 2a_e x + b_e \Rightarrow$ marginal cost.
- ▶ Lemma 1.2: A feasible flow f^* for (G, r, l) is (globally) optimal if for each pair s_i-t_i , $P_1, P_2 \in \mathcal{P}_i$, and $f_{P_1}^* > 0$, we have:

$$\sum_{e \in P_1} 2a_e f_e^* + b_e \leq \sum_{e \in P_2} 2a_e f_e^* + b_e$$

- ▶ in other words, f^* is a Nash Flow for instance (G, r, l^*) , where $l_e^*(x) = 2a_e x + b_e$

Flows at equilibrium

- ▶ Lemma 1.3: If f is a Nash flow for (G, r, l)
 - a $f/2$ is optimal for $(G, r/2, l)$
 - b marginal cost of increasing flow on a path P with respect to $f/2 =$ latency of P with respect to f

Proof.

Observe $l_e(x) = a_e x + b_e = 2a_e \frac{x}{2} + b_e = l_e^*(x/2)$.

For part a: Since f is a Nash flow it satisfies conditions of Lemma 1.1. Also, $f/2$ is feasible for instance $(G, r/2, l)$ and from Lemma 1.2, it is also optimal.

For part b: Summing over all edges in P , we have

$$l_P^*(f/2) = l_P(f)$$



Cost of Augmentation

- ▶ Lemma 1.4: If f^* is the optimal flow for (G, r, l) and $L_i^*(f^*)$ is the minimum marginal cost of increasing flow on a s_i - t_i path w.r.t f^* , then for any $\delta > 0$ a feasible flow for $(G, (1 + \delta)r, l)$ has cost $\geq C(f^*) + \delta \sum_i L_i^*(f^*)r_i$

Proof.

Let f be a feasible flow for $(G, (1 + \delta)r, l)$. Since the per edge cost $x l_e(x)$ is convex,

$$\begin{aligned} f_e l_e(f_e) &\geq f_e^* l_e(f_e^*) + (f_e - f_e^*) l_e^*(f_e^*) \\ \therefore C(f) &\geq C(f^*) + \sum_i \sum_{P \in \mathcal{P}_i} l_P^*(f^*) (f_P - f_P^*) \end{aligned}$$



Proof Outline

- ▶ From Lemma 1.3 $f/2$ is an optimal flow for $(G, r/2, l)$, where f is a Nash flow for (G, r, l) .

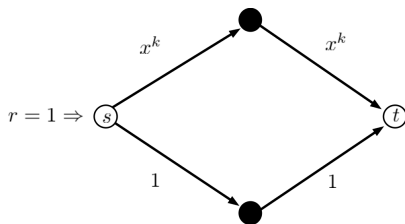
$$\begin{aligned}\therefore C(f/2) &= \sum_e \frac{1}{4} a_e f_e^2 + \frac{1}{2} b_e f_e \\ &\geq \frac{1}{4} \sum_e a_e f_e^2 + b_e f_e = \frac{1}{4} C(f)\end{aligned}$$

- ▶ We then augment the optimal flow $f/2$ for $(G, r/2, l)$ to the optimal flow f^* for (G, r, l) . Then from Lemma 1.4 ($\delta = 1$):

$$\begin{aligned}C(f^*) &\geq C(f/2) + \sum_i L_i^*(f/2) \frac{r_i}{2} \\ &\geq \frac{1}{4} C(f) + \frac{1}{2} C(f) = \frac{3}{4} C(f)\end{aligned}$$

Extensions to general latency functions

- ▶ A bad example (for large k):



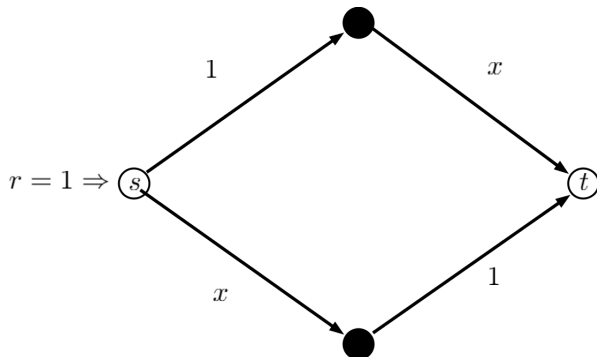
- ▶ Cost of Nash flow = 2. Cost of optimal flow ≈ 0

Extensions to general latency functions

Theorem

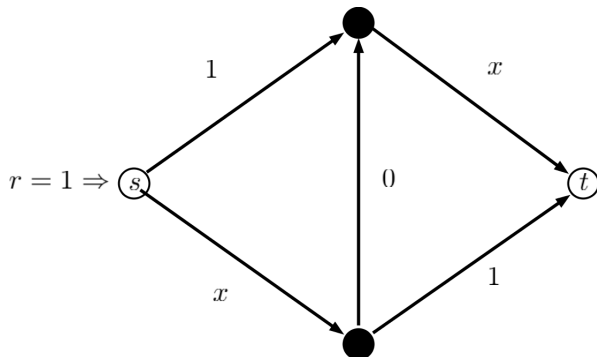
If f is a Nash flow for (G, r, l) with continuous, non-decreasing latency functions. Then the $C(f)$ is at most the cost of an optimal flow for $(G, 2r, l)$

Selfish routing and network design - Braess's Paradox



$$C(f) = C(f^*) = \frac{3}{2}$$

Selfish routing and network design - Braess's Paradox



$$C(f) = 2, C(f^*) = \frac{3}{2}$$