

Deploying PAWS

Field Optimization of
the Protection
Assistant for Wildlife
Security

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Presentation:
[Rock Stevens](#), 9/20/2016

1.

Motivation

Protection
Assistant for
Wildlife Security
(PAWS)

What is PAWS?

- ▶ Poaching threatens species & ecosystems
- ▶ Deploy more effective defense

- ▶ “Green security games”
- ▶ Repeated Stackelberg
- ▶ Patrols (D) vs. Poachers (A) WRT animal densities



Uganda

Malaysia



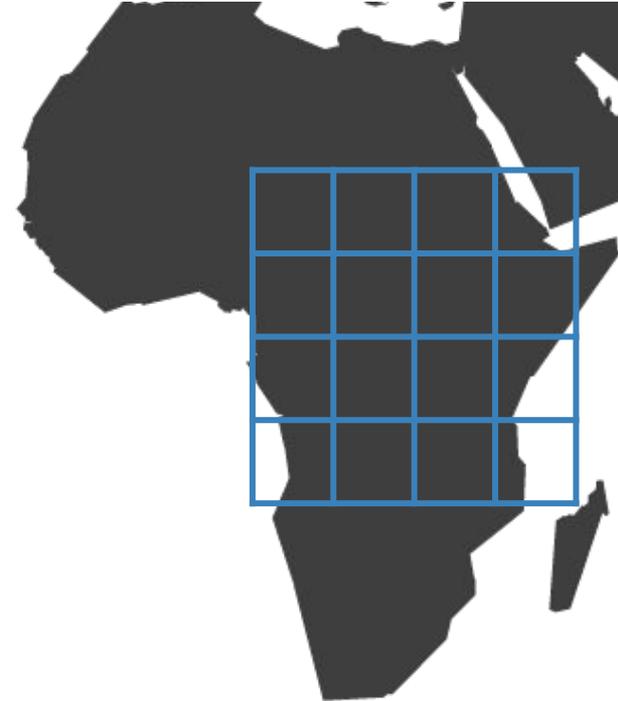
PAWS
Deployment

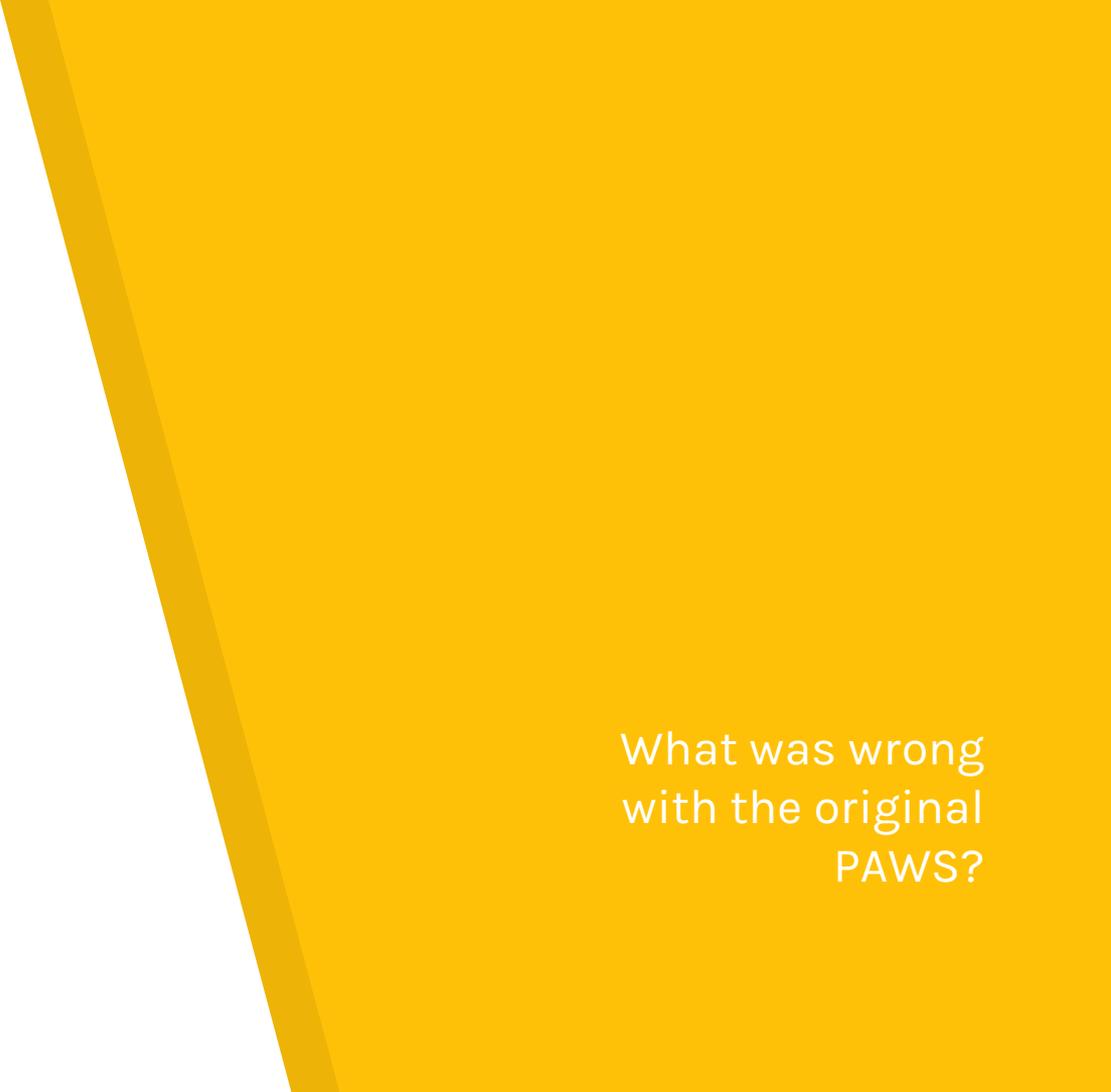
Defender strategy

$$\mathbf{c} = \langle c_i \rangle \quad c_i \rightarrow \text{probability that defender resource is deployed at target } i$$

Attacker Utility	Attacker penalty for i defense	Attacker reward for i undefended
	$U_i^a = c_i U_{p,i}^a + (1 - c_i) U_{r,i}^a$	
Defender Utility	Defender reward for i defense	Attacker penalty for i undefended
	$U_i^d = c_i U_{r,i}^d + (1 - c_i) U_{p,i}^d$	

- ▶ Zero-sum game
- ▶ Attacker reward is determined by animal density





2.

PAWS-Initial

What was wrong
with the original
PAWS?

PAWS-Initial issues

- ▶ Ignores topology
- ▶ Assumes known / fixed animal density
- ▶ Cannot scale
- ▶ Scheduling constraints

We can make it better!

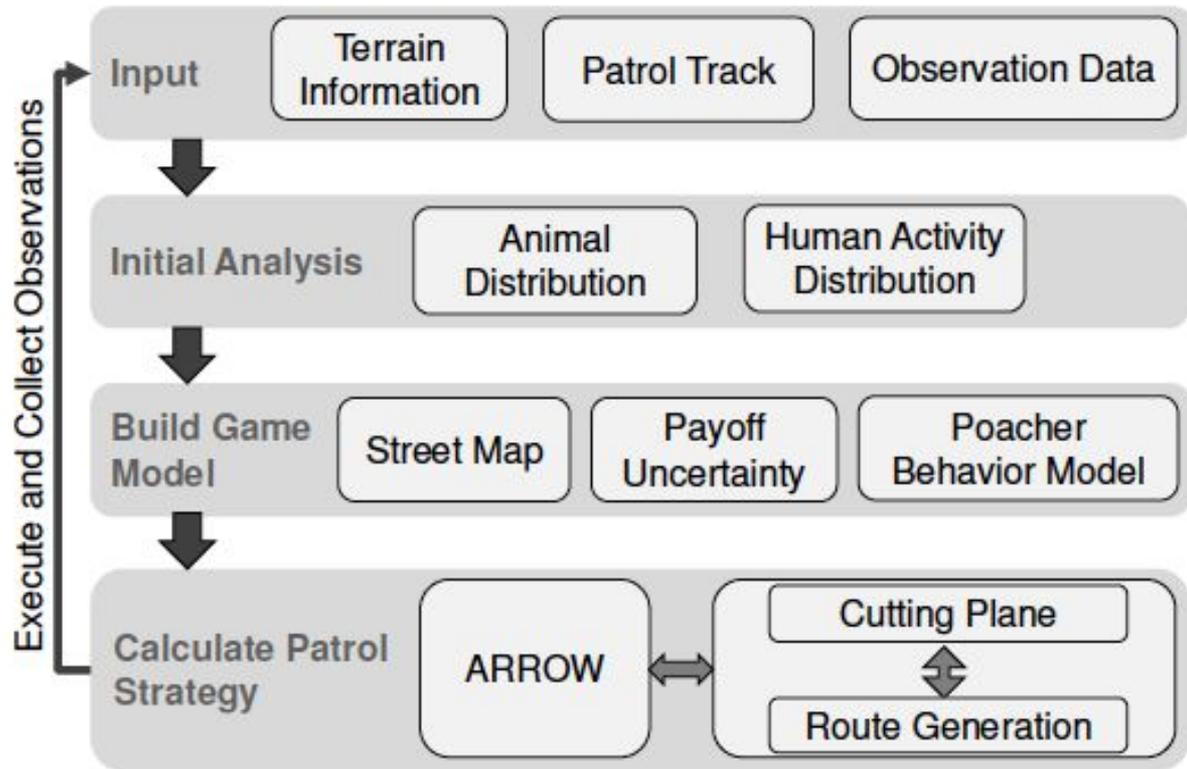
3.

PAWS

PAWS 2.0

PAWS improvements

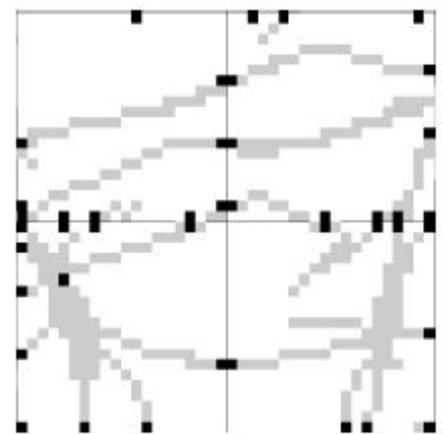
- ▶ “Street maps” include topology
 - ▷ It drives decisions!!!
- ▶ Handle uncertainty with concept of minimax regret
- ▶ Increase scalability with cutting plane framework
- ▶ Build in temporal and terrain constraints



- ▶ Iterative, self-adjusting feedback

Building the **Street Map**

- ▶ 1km x 1km targets, 50m x 50m raster pieces
- ▶ 50m contour lines
- ▶ Determine the accessibility type for each raster piece
- ▶ Define Key Access Points (KAPs)
 - ▷ Each grid cell can be reached
 - ▷ Borders + Logical Points
- ▶ Find route segments to link the KAPs
 - ▷ Connect locally with weighted distance metrics WRT elevation



Calculating Defender Strategies

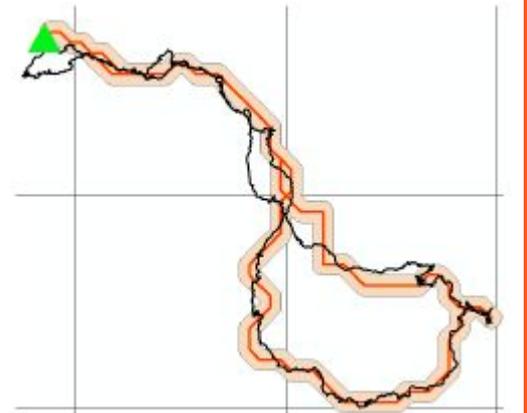
- ▶ Include routes over entire conservation area
- ▶ Start & Stop at basecamps
- ▶ Account for payoff uncertainty
- ▶ Bounded rationality of poachers

ARROW + BLADE address these issues

- ▶ ARROWS **minimizes regret** or **utility loss** for the patrollers but doesn't consider routes
- ▶ BLADE iteratively optimizes routes to cover targets of high value

PAWS IRL

- ▶ 4-5 day patrols w/ 3-7 patrollers
- ▶ Recommended patrol close to actual guided path
- ▶ Reliable for real-world implementations



4.

Synthesis and Opinion

Can we make it
better?

Can we make PAWS better???

- ▶ Logistical constraints
 - ▷ Food, water, GPS signal
- ▶ **Attention** is a finite resource
- ▶ Improved definition of defended