

Name:

Directory ID:

University ID:

Midterm 2

CMSC 430

Introduction to Compilers

Fall 2018

Instructions

This exam contains 14 pages, including this one. Make sure you have all the pages. Write your name, directory ID, and university ID number on the top of this page, and write your directory ID at the bottom left of *every* page, before starting the exam.

Write your answers on the exam sheets. If you finish at least 15 minutes early, bring your exam to the front when you are finished; otherwise, wait until the end of the exam to turn it in. Please be as quiet as possible.

If you have a question, raise your hand. If you feel an exam question assumes something that is not written, write it down on your exam sheet. Barring some unforeseen error on the exam, however, you shouldn't need to do this at all, so be careful when making assumptions.

Question	Score	Max
1		20
2		20
3		20
4		20
5		20
Total		100

Question 1. Short Answer (20 points).

a. (3 points) Briefly describe the difference between a function call and a system call. Explain whether the two have the same calling convention and why or why not.

Answer: Function calls transfer control from one function to another, within the program's own code or between the code and a library. System calls are used when the program needs the operating system kernel to perform some computation or action on its behalf, with privilege.

The conventions for function calls and system calls are typically different. One is defined by the language or compiler for interoperability of program modules. The other is defined by the operating system and must be followed by all programs, regardless of implementation language.

b. (3 points) Briefly describe two code generation techniques for compiling C switch statements. Explain how the two techniques compare, i.e., in what situation(s) one technique should be favored over the other.

Answer:

- Cascaded if-then-else. Check each option in succession.
- Binary search. Order the guards and then use a search algorithm.
- Jump table. Use the guard as an index into code or a set of code pointers.

Jump tables are most effective when the guards are “dense”, i.e., when they are numerically close. Jump tables are more time efficient, since they require only a single constant-time operation to compute the code location. However, they can be inefficient for space if the guards are spread out. Other answers that describe memory or time efficiency, or ease of implementation, are also acceptable.

c. (3 points) Briefly describe symbolic execution and name one application of the technique. What is the fundamental challenge that prevents exhaustive symbolic execution for most real-world programs?

Answer: Symbolic execution is a program analysis technique that treats program inputs as symbolic variables, rather than concrete values. Program expressions are computed in terms of the symbolic variables and execution is logically forked at branch points to represent all possible paths. Symbolic execution can simultaneously explore multiple paths that a program could take under different inputs, without testing every possible input. It is a popular technique with testing and bug finding tools.

The primary challenge is path/state space explosion. Real programs have an exponential number of paths, making it impossible to symbolically execute every path. Therefore, approximation, path pruning, and search strategies have become a critical component of real symbolic execution systems.

d. (5 points) The following C program contains two functions, `bar()` and `foo()`. `bar()` calls `foo()`. Draw a representation of a 32-bit x86 stack just after the assignment on line 9 is executed. Include as much stack history as you can infer from the code snippet. Clearly indicate the current “top” of the stack (`esp`), the current frame pointer (`ebp`), and which direction the stack grows. You can assume the code is compiled without any optimizations and that `main()` calls `bar()`. If you make any other assumptions, state those as well.

```

1  int bar(int x, int y) {
2      int z;
3      z = foo(x + 10, y - 10);
4      return z;
5  }
6
7  int foo(int a, int b) {
8      int c = 100;
9      int d = a * b + c;
10     // ...
11     return d;
12 }
```

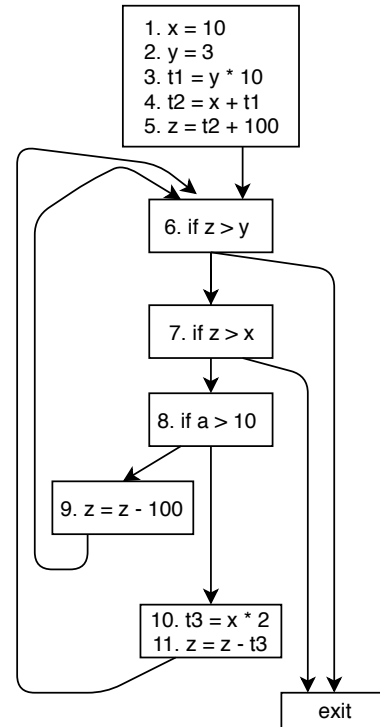
Registers	Stack	Notes
	higher addresses go up ↑	
Answer:	...	
	main's local variables	main's activation record
	...	
	y	arguments to <code>bar</code> , pushed in reverse order
	x	
	main's return address	bar's activation record
	main's saved <code>ebp</code>	
	z	bar's local variables
	...	register save space
	b = y - 10	arguments to <code>foo</code> , pushed in reverse order
	a = x + 10	
	bar's return address	foo's activation record
	ebp → bar's saved <code>ebp</code>	
	c = 100	foo's local variables
	esp → d = a * b + c	
	↓ stack grows down	esp could also point lower if space was pre-allocated

e. (6 points) Translate the following program to 3-address code. Draw the control-flow graph for the resulting program.

```

x = 10
y = 3
z = x + (y * 10) + 100
while ((z > y) && (z > x)) {
    if (a > 10) {
        z = z - 100
    } else {
        z = z - x * 2
    }
}

```



Question 2. Code Generation (20 points). Below (left) is a set of types representing a small machine instruction set, followed by (right) a type representing expression ASTs for a small language.

<pre> n type instr = ILoad of reg * val (* dst, src *) IStore of id * reg (* dst, src *) IAdd of reg * reg * reg (* dst, src1, src2 *) ISub of reg * reg * reg (* dst, src1, src2 *) IIfZero of reg * int (* guard, target *) IJump of int (* target *) IMov of reg * reg (* dst, src *) </pre>	<pre> type expr = EInt of int (* integers *) Eld of string (* variables *) EAdd of expr * expr (* addition *) ESub of expr * expr (* subtraction *) EAssn of string * expr (* assignment *) ESeq of expr * expr (* sequences *) EWhile of expr * expr (* while loops *) EDoWhile of expr * expr (* do-while loops *) </pre>
--	--

The instruction set has direct support for named locations (i.e., variables), which can be read from or written to via the `ILoad` and `IStore` instructions, respectively. `ILoad` also supports loading a register with a constant integer. `IAdd` and `ISub` implement register addition and subtraction, respectively. In both cases, the result is stored in a register. The `IJump` (absolute jump) and `IIfZero` (conditional jump) instructions adjust the PC relative to the current instruction's PC. `IMov` copies the value stored in one register to another. The machine supports an unlimited number of registers.

The expressions `EInt` and `Eld` represent constant integers and variables, respectively. `EAdd` and `ESub` are the standard binary addition and subtraction expressions. `EAssn` represents an assignment to a variable. `ESeq` is the sequence of two expressions. The expression `EWhile(e1, e2)` executes the body `e2` as long as the guard `e1` is not zero, and the whole expression evaluates to 0. `EDoWhile(e1, e2)` executes `e1` until `e2` becomes non-zero. Note that a do-while loop always executes the body `e1` at least once (so it evaluates `e1`; checks if `e2` is non-zero; if not evaluates `e1` again; etc). The loop itself should evaluate to 0.

Question is on the next page.

Write a function `comp_expr : expr → reg * (instr list)` that takes a single expression and returns the output register and a list of instructions that compute the expression. You may define as many helper functions as you need, and you may also use OCaml standard library functions.

```

let next_reg =
  let n = ref 0 in
  fun () → (let temp = !n in n:=!n+1; temp)

let rec comp_expr = function
| EInt n → let r = next_reg () in
  (r, [ILoad ('Reg r, 'Int n)])

| EAdd (e1, e2) →
  let (r1, p1) = comp_expr e1 in
  let (r2, p2) = comp_expr e2 in
  let r = next_reg () in
  (r, p1 @ p2 @ [IAdd ('Reg r, 'Reg r1, 'Reg r2)])

| ESub (e1, e2) →
  let (r1, p1) = comp_expr e1 in
  let (r2, p2) = comp_expr e2 in
  let r = next_reg () in
  (r, p1 @ p2 @ [ISub ('Reg r, 'Reg r1, 'Reg r2)])

| Eld x →
  let r = next_reg () in
  (r, [ILoad ('Reg r, 'Id x)])

| EAssn (x, e) →
  let (r, p) = comp_expr e in
  (r, p @ [IStore ('Id x, 'Reg r)])

| ESeq (e1, e2) →
  let (r1, p1) = comp_expr e1 in
  let (r2, p2) = comp_expr e2 in
  (r2, p1 @ p2)

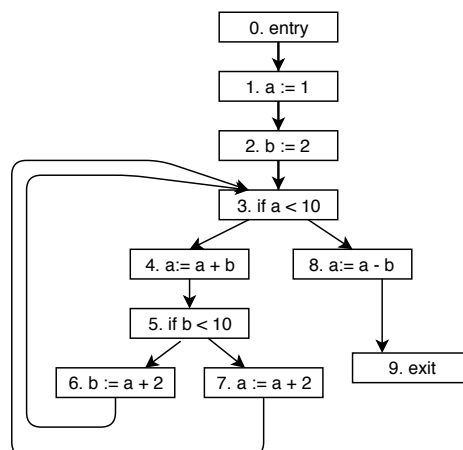
| EWhile (e1, e2) →
  let (r1, ccode) = comp_expr e1 in
  let (r2, ecode) = comp_expr e2 in
  let r3 = next_reg () in
  let length = List.length ecode in
  let clength = List.length ccode in
  let guard = [IfZero ('Reg r1, length+1)] in
  let loopback = [IJmp (-1 * (length + clength + 2))] in
  let return_zero = [ILoad ('Reg r3, 'Int 0)] in
  (r3, List.concat [ccode; guard; ecode; loopback; return_zero])

| EDoWhile (e1, e2) →
  let (r1, ccode) = comp_expr e1 in
  let (r2, ecode) = comp_expr e2 in
  let r3 = next_reg () in
  let length = List.length ecode in
  let clength = List.length ccode in
  let guard = [IfZero ('Reg r2, 1)] in
  let loopback = [IJmp (-1 * (length + clength + 2))] in
  let returnzero = [ILoad ('Reg r3, 'Int 0)] in
  (r3, List.concat [ecode; ccode; guard; loopback; returnzero])

```

Question 3. Data Flow (20 points).

In the following table, show each iteration of *reaching definitions* for the control-flow graph on the right. For each iteration, list the statement taken from the worklist in that step, the value of *out* computed for that statement, and the new worklist at the end of the iteration. You may or may not need all the iterations; you may also add more iterations if needed. Do not add the entry node to the worklist.



Use \emptyset for the set of no definitions, and \top for the set of all definitions. What is \top ?

$\top =$ 1(a), 2(b), 4(a), 6(b), 7(a), 8(a)

What are the initial *out*'s for each statement?

Stmt	0	1	2	3	4	5	6	7	8
Initial out	\emptyset	\emptyset	\emptyset	\emptyset	\emptyset	\emptyset	\emptyset	\emptyset	\emptyset

Iteration	0	1	2	3	4
Stmt taken from worklist	N/A	1	2	3	4
out of taken stmt	N/A	1(a)	1(a),2(b)	1(a),2(b)	2(b),4(a)
New worklist	1,2,3,4,5,6,7,8	2,3,4,5,6,7,8	3,4,5,6,7,8	4,5,6,7,8	5,6,7,8

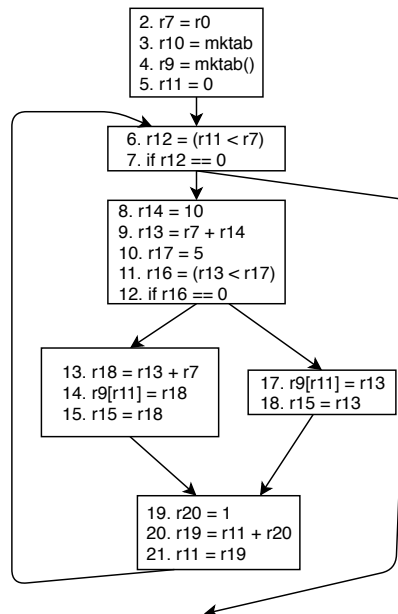
Iteration	5	6	7	8	9
Stmt taken from worklist	5	6	3	4	5
out of taken stmt	2(b),4(a)	4(a),6(b)	1(a),2(b),4(a),6(b)	2(b),4(a),6(b)	2(b),4(a),6(b)
New worklist	6,7,8	3,7,8	4,7,8	5,7,8	6,7,8

Iteration	10	11	12	13	14
Stmt taken from worklist	6	7	3	4	8
out of taken stmt	4(a),6(b)	2(b),6(b),7(a)	1,2,4,6,7	2(b),4(a),6(b)	2(b),6(b),8(a)
New worklist	7,8	3,8	4,8	8	\emptyset

Question 4. Optimization (20 points). Below are (left) a Simpl function that I wrote to test my project 4 and (right) the RubeVM code that my compiler generated.

<pre> 1 def foo(x) 2 t = mktab(); 3 i = 0; 4 while (i < x) do 5 a = x + 10; 6 if a < 5 then 7 t[i] = a + x 8 else 9 t[i] = a 10 end; 11 i = i + 1 12 end 13 end </pre>	<pre> 1 foo: 2 mov r7, r0 3 const r10, mktab 4 call r10, 9, 8 5 const r11, 0 6 lt r12, r11, r7 7 if_zero r12, 15 8 const r14, 10 9 add r13, r7, r14 10 const r17, 5 11 lt r16, r13, r17 12 if_zero r16, 4 13 add r18, r13, r7 14 wr_tab r9, r11, r18 15 mov r15, r18 16 jmp 2 17 wr_tab r9, r11, r13 18 mov r15, r13 19 const r20, 1 20 add r19, r11, r20 21 mov r11, r19 22 jmp -17 23 const r21, 0 24 ret r21 </pre>
---	---

In the space below, identify two (2) *local* and two (2) *global* optimizations that could be applied to this code. Clearly identify the type of optimization, the code location, and how the code would change. Hint: you may want to convert the RubeVM code to a more familiar three-address form and draw a control-flow graph first.



a. (5 points) Local optimization 1

Answer: Using the hint, we converted the RubeVM code into a CFG (see previous page). Now we can easily see statements 13-15 can leverage copy propagation – we don't need to use `r18` at all. The block becomes:

Three-address	RubeVM
13. <code>r15 = r13 + 7</code>	13. <code>add r15, r13, r7</code>
14. <code>r9[r11] = r15</code>	14. <code>wr tab r9, r11, r15</code>
15. <code><removed></code>	15. <code><removed></code>

b. (5 points) Local optimization 2

Answer: Copy propagation, like above, but to remove `r19`. The block becomes:

Three-address	RubeVM
19. <code>r20 = 1</code>	19 <code>const r20, 1</code>
20. <code>r11 = r11 + r20</code>	20 <code>add r11, r11, r20</code>
21. <code><removed></code>	21 <code><removed></code>

c. (5 points) Global optimization 1

Answer: Loop invariant code motion. The assignment to variable `a` (`r17`) does not depend on any modifications inside the loop, so it can be hoisted above the loop (e.g., just after statement 5) to save cycles during the loop. Similarly, `a + x` (`r18`) is loop invariant and could be computed once, before the loop.

d. (5 points) Global optimization 2

Answer: Code specialization. There is a condition inside the loop (`a < 5, 11. lt r16, r13, r17`) that does not vary depending on the loop. We can invert the loop and conditional to make one loop for the true case and one for the false, which will run faster during the loop's execution.

Alternatively, rather than specialize the loop itself, a more complicated optimization could be performed following the code motion optimization described in part c. Since both branches of the conditional assign to the same table location `t[i]`, the conditional could be used to compute the correct right-hand side (`a` or `a + x`) and put the result in the same register. Then, the loop can just iterate through assigning to a constant value. Logically, the same as this:

```
def foo(x)
  t = mktab();
  i = 0;
  if a < 5 then
    temp = a + x
  else
    temp = a
  end;
  while (i < x) do
    t[i] = temp
    i = i + 1
  end
end
```

Question 5. Type Systems (20 points). Here is the simply typed lambda calculus with integers, floats, and pairs.

$$e ::= v \mid x \mid e \ e \mid (e, e) \quad v ::= n \mid f \mid \lambda x: t. e \quad t ::= \text{int} \mid \text{float} \mid t \rightarrow t \mid t \times t \quad A ::= \cdot \mid x : t, A$$

$$\begin{array}{c} \text{INT} \\ \hline A \vdash n : \text{int} \end{array} \quad \begin{array}{c} \text{FLOAT} \\ \hline A \vdash f : \text{float} \end{array} \quad \begin{array}{c} \text{VAR} \\ \hline A \vdash x : A(x) \end{array} \quad \begin{array}{c} \text{PAIR} \\ \hline \frac{A \vdash e_1 : t \quad A \vdash e_2 : t'}{A \vdash (e_1, e_2) : t \times t'} \end{array}$$

$$\begin{array}{c} \text{LAM} \\ \hline \frac{x: t, A \vdash e : t'}{A \vdash \lambda x: t. e : t \rightarrow t'} \end{array} \quad \begin{array}{c} \text{APP} \\ \hline \frac{A \vdash e_1 : t \rightarrow t' \quad A \vdash e_2 : t}{A \vdash e_1 \ e_2 : t'} \end{array}$$

a. (5 points) Draw a derivation showing that the following term is well-typed in the given type environment, where we use i instead of int and f instead of float to save space. You need not label the uses of the rules with their names.

$$A = +: i \rightarrow i \rightarrow i, \oplus: f \rightarrow f \rightarrow f$$

$$A \vdash ((\lambda x: i. \lambda y: f. (+ \ x \ 5, \oplus \ y \ 5.0)) \ 7 \ 7.0): i \times f$$

Answer:

$$\begin{array}{c} A = +: i \rightarrow i \rightarrow i, \oplus: f \rightarrow f \rightarrow f \\ B = x: i, A \\ C = y: f, x: i, A \\ \hline \frac{\frac{\frac{\overline{C \vdash +: i \rightarrow i \rightarrow i} \quad \overline{C \vdash x: i}}{C \vdash (+ \ x): i \rightarrow i} \quad \overline{C \vdash 5: i}}{C \vdash (+ \ x \ 5): i} \quad \frac{\frac{\overline{C \vdash \oplus: f \rightarrow f \rightarrow f} \quad \overline{C \vdash y: f}}{C \vdash (\oplus \ y): f \rightarrow f} \quad \overline{C \vdash 5.0: f}}{C \vdash (\oplus \ y \ 5.0): f} \\ \hline C \vdash (+ \ x \ 5, \oplus \ y \ 5.0): i \times f \\ \hline B \vdash \lambda y: f. (+ \ x \ 5, \oplus \ y \ 5.0): f \rightarrow i \times f \\ \hline A \vdash (\lambda x: i. \lambda y: f. (+ \ x \ 5, \oplus \ y \ 5.0)): i \rightarrow f \rightarrow i \times f \\ \hline A \vdash ((\lambda x: i. \lambda y: f. (+ \ x \ 5, \oplus \ y \ 5.0)) \ 7): f \rightarrow i \times f \quad \overline{A \vdash 7: i} \\ \hline A \vdash ((\lambda x: i. \lambda y: f. (+ \ x \ 5, \oplus \ y \ 5.0)) \ 7 \ 7.0): i \times f \quad \overline{A \vdash 7.0: f} \end{array}$$

b. (5 points) If we make *int* a subtype of *float*, we get the following additional type rules (note that application has been updated):

$$\begin{array}{c}
 \text{S-NUM} \quad \text{S-PROD} \quad \text{APP} \\
 \frac{}{int \leq float} \quad \frac{t_1 \leq t'_1 \quad t_2 \leq t'_2}{t_1 \times t_2 \leq t'_1 \times t'_2} \quad \frac{A \vdash e_1 : t_1 \rightarrow t'_1 \quad A \vdash e_2 : t_2 \quad t_2 \leq t_1}{A \vdash e_1 \ e_2 : t'_1} \\
 \text{S-ARROW} \\
 \hline
 t_1 \rightarrow t'_1 \leq t_2 \rightarrow t'_2
 \end{array}$$

i. (2 points) The rule S-ARROW, which extends the subtyping relationship to arrow types (functions), is incomplete. Fill in the rest of the rule.

Answer:

$$\begin{array}{c}
 \text{S-ARROW} \\
 \frac{t_2 \leq t_1 \quad t'_1 \leq t'_2}{t_1 \rightarrow t'_1 \leq t_2 \rightarrow t'_2}
 \end{array}$$

ii. (3 points) Given your rule, can $(+ : int \rightarrow int \rightarrow int)$ be used in computations where $(\oplus : float \rightarrow float \rightarrow float)$ is expected? Explain why or why not. If not, give an example of a type that can be used where \oplus is expected.

Answer: No. The \oplus function requires a *float* input. The $+$ function requires an *int*. The subtype rule for arrow requires that $float \leq int$, which is not true by the other type rules. $float \rightarrow float \rightarrow int$ is the only other type of function that can be used in place of $float \rightarrow float \rightarrow float$.

c. (10 points) Consider type inference for the simply-typed lambda calculus, this time without the float, pair, and subtyping extensions.

$$\begin{aligned} e &::= v \mid x \mid e e \\ v &::= n \mid \lambda x. e \\ t &::= \alpha \mid \text{int} \mid t \rightarrow t \\ A &::= \cdot \mid x : t, A \end{aligned}$$

$$\begin{array}{c} \text{INT} \\ \hline A \vdash n : \text{int} \end{array} \quad \begin{array}{c} \text{VAR} \\ \hline x \in \text{dom}(A) \\ \hline A \vdash x : A(x) \end{array} \quad \begin{array}{c} \text{LAM} \\ \hline x : \alpha, A \vdash e : t' \quad \alpha \text{ fresh} \\ \hline A \vdash \lambda x. e : \alpha \rightarrow t' \end{array} \quad \begin{array}{c} \text{APP} \\ \hline A \vdash e_1 : t \quad A \vdash e_2 : t' \\ t = t' \rightarrow \beta \quad \beta \text{ fresh} \\ \hline A \vdash e_1 e_2 : \beta \end{array}$$

i. (5 points) Draw a derivation showing type inference applied to the following term. Use subscripts to distinguish new instances of type inference variables. For example, $\alpha_1, \alpha_2, \beta_1, \beta_2$, etc.

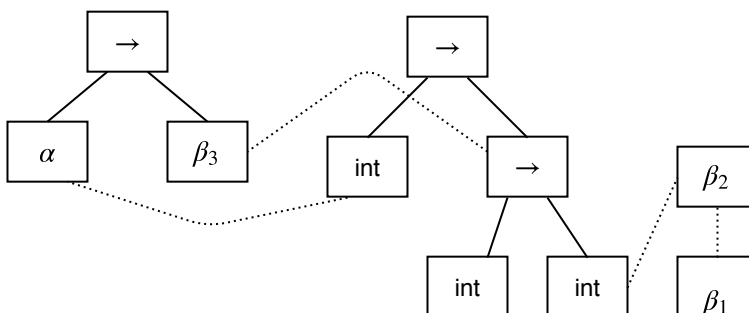
$$+ : \text{int} \rightarrow \text{int} \rightarrow \text{int} \vdash (\lambda x. + x 5) 37$$

Answer:

$$\begin{aligned} A &= + : i \rightarrow i \rightarrow i \\ B &= x : \alpha, A \end{aligned}$$

$$\begin{array}{c} \frac{\frac{\frac{B \vdash + : \text{int} \rightarrow \text{int} \rightarrow \text{int} \quad B \vdash x : \alpha \quad i \rightarrow i \rightarrow i = \alpha \rightarrow \beta_3}{B \vdash (+x) : \beta_3}}{B \vdash (+ x 5) : \beta_2}}{A \vdash (\lambda x. + x 5) : \alpha \rightarrow \beta_2} \quad \frac{\frac{\frac{B \vdash 5 : \text{int} \quad \beta_3 = \text{int} \rightarrow \beta_2}{\alpha \rightarrow \beta_2 = \text{int} \rightarrow \beta_1}}{A \vdash 37 : \text{int}}}{A \vdash (\lambda x. + x 5) 37 : \beta_1} \end{array}$$

ii. (3 points) Draw a union find data structure representing the constraints.



Answer:

iii. (2 points) Write down a solution to the associated constraints.

$$\text{Answer: } \alpha = \beta_2 = \beta_1 = \text{int} \quad \beta_3 = \text{int} \rightarrow \text{int}$$

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