

## CMSC425 Fall 2019

### Homework 1: Geometric exercises

#### Solutions

##### Part a. Warm up problems

1. Given the points  $p_1=(-3,4)$  and  $p_2=(20,15)$ , give the point-vector form of the ray originating at  $p_1$  and going through  $p_2$ . For what value of  $t$  is the point  $(10.8,10.6)$  on the line?

Point vector form:  $p(t) = p_1 + t(p_2 - p_1) = p_1 + t v = (-3,4) + t \langle 23,11 \rangle$

To solve this you set  $p(t) = (-3,4) + t \langle 23,11 \rangle = (10.8,10.6)$  and solve for  $t$ .  
You can do that in  $x$  or  $y$  since you have two equations and one unknown.

When  $t = 0.6$  we have  $p(0.6) = (-3,4) + (0.6) * \langle 23,11 \rangle = (10.8,10.6)$

2. How far is  $C=(5,5)$  from the line through  $A=(2,5)$  and  $B=(4,-1)$ ?

The point vector form is  $p(t) = A + t(B - A) = (2,5) + t \langle 2, -6 \rangle$

The perp vector is  $v^\perp = \langle 6,2 \rangle$ , normalized this is  $\hat{v}^\perp = \frac{\langle 6,2 \rangle}{\sqrt{40}}$

(We normalize because we want a distance).

Distance is  $d = v^\perp \cdot (C - A) = \frac{\langle 6,2 \rangle}{\sqrt{40}} \cdot (3,0) = 2.85$

3. Given the two vectors  $a=\langle 5,4 \rangle$  and  $b=\langle 3,4 \rangle$ , give  $u_1$  and  $u_2$  in the orthogonal projection of  $a$  onto  $b$ .

We have that  $u_1 = \frac{a \cdot b}{b \cdot b} b = \frac{\langle 5,4 \rangle \cdot \langle 3,4 \rangle}{\langle 3,4 \rangle \cdot \langle 3,4 \rangle} \langle 3,4 \rangle = \frac{31}{25} \langle 3,4 \rangle$

And that  $u_2 = b - u_1 = \langle 3,4 \rangle - \frac{31}{25} \langle 3,4 \rangle = \langle -0.72000, -0.96000 \rangle$

4. Give the angle between the two vectors  $u=\langle -1,1,0 \rangle$  and  $v=\langle -1,0,1 \rangle$ .

In this case we do have to normalize the two vectors, either before or as part of the calculation.

$$\cos(\theta) = \frac{\vec{v} \cdot \vec{u}}{|\vec{v}| |\vec{u}|} = \frac{\langle -1,1,0 \rangle \cdot \langle -1,0,1 \rangle}{|\langle -1,1,0 \rangle| |\langle -1,0,1 \rangle|} = 0.5000$$

$$\theta = \arccos(0.5000) = 1.0472 \text{ rad} \text{ or } 60 \text{ degrees}$$

5. Given the three points  $P_1=(1,1,1)$ ,  $P_2=(1,2,1)$ ,  $P_3=(3,0,4)$ , give a convex combination of the points in the triangle /\* any CC is ok \*/. \*\*\* ADDED BUT NOT REQUIRED. What convex combination gives the center?

The question is simple – any coefficients will work here.

Convex combination:  $\frac{1}{2}P_1 + \frac{1}{4}P_2 + \frac{1}{4}P_3$  Any three that add to 1 work.

The center would be:  $\frac{1}{3}P_1 + \frac{1}{3}P_2 + \frac{1}{3}P_3$

6. Starting with the points problem (5), compute the distance of the point  $P_4=(0,0,0)$  to the plane.

The plane is defined by a normal and a point.

The normal can be computed by the cross product of two vectors. Let  $v = P_2 - P_1 = \langle 0, 1, 0 \rangle$  and  $u = P_3 - P_1 = \langle 2, -1, 3 \rangle$  then  $n = u \times v = \langle 3, 0, -2 \rangle$   
Normalized we have  $n' = \langle 0.83205, 0.00000, -0.55470 \rangle$

A vector from the plane to the point  $P_4$  is  $w = P_4 - P_1 = \langle -1, -1, -1 \rangle$

The distance to the plane is  $\text{dist} = |w \cdot n'| = 0.27735$

7. For a vector  $v = \langle x, y \rangle$ , the 2D perp vector  $v^\perp$  can be defined as  $v_{\text{perp}} = \langle -y, x \rangle$ . Will this vector always be 90 degrees counterclockwise from  $v$ ?

Yes. The easiest argument is by quadrant. Given  $v = \langle x, y \rangle$  and  $v^\perp = \langle -y, x \rangle$

Set  $v = \langle 1, 1 \rangle$  and  $v^\perp = \langle -1, 1 \rangle$ . Yes.

Set  $v = \langle -1, 1 \rangle$  and  $v^\perp = \langle -y, x \rangle$ . Yes.

Set  $v = \langle -1, -1 \rangle$  and  $v^\perp = \langle 1, -1 \rangle$ . Yes.

Set  $v = \langle 1, -1 \rangle$  and  $v^\perp = \langle 1, 1 \rangle$ . Yes.

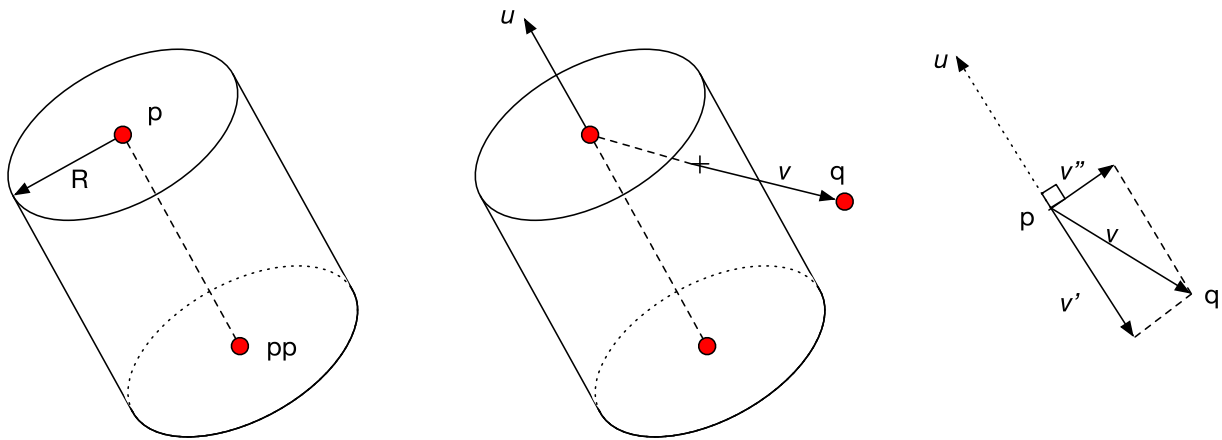
This is not a proof, just a demonstration that quadrants flip as assumed.

A better solution given by students notes that the perp vector is defined by a 90 deg rotation:

$$M * p = \begin{bmatrix} \cos 90 & -\sin 90 \\ \sin 90 & \cos 90 \end{bmatrix} * \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} * \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -y \\ x \end{bmatrix}$$

**Part b. Application**

1. **Cylinder collider.** Assume you have a cylinder collider defined by 3D points  $\mathbf{p}$  and  $\mathbf{pp}$ , that give the central axis of the cylinder, and  $R$ , which is the radius of the cylinder. The points define a unit vector  $\mathbf{u}$  as shown on the middle diagram.  $\mathbf{p}$ ,  $\mathbf{pp}$  and  $R$  are enough to define the cylinder.



Now assume you have a point  $\mathbf{q} = (q_x, q_y, q_z)$ , somewhere in 3D space (here  $\mathbf{q}$  is shown outside the cylinder but could be inside.) We want to compute whether  $\mathbf{q}$  is inside or outside the cylinder as a boolean flag. Show how to do this in mathematical notation (not code).

(a) Given the points  $\mathbf{p}$  and  $\mathbf{q}$ , show how to compute the coordinates of the vector  $\mathbf{v} = \langle v_x, v_y, v_z \rangle$  directed from  $\mathbf{p}$  to  $\mathbf{q}$ .

**Solution:**  $\mathbf{v} = \mathbf{q} - \mathbf{p} = (q_x, q_y, q_z) - (p_x, p_y, p_z)$

(b) Given (a), show how to decompose  $\mathbf{v}$  as the sum of two vectors  $\mathbf{v}'$  and  $\mathbf{v}''$  such that  $\mathbf{v}'$  is parallel to  $\mathbf{u}$  and  $\mathbf{v}''$  is perpendicular to  $\mathbf{u}$ .

**Solution:**

$$\mathbf{v}' = \frac{\mathbf{v} \cdot \mathbf{u}}{\mathbf{u} \cdot \mathbf{u}} \mathbf{u} \quad \text{and} \quad \mathbf{v}'' = \mathbf{v} - \mathbf{v}'$$

(c) Given your answer to (b), show how to compute the lengths of  $\mathbf{v}'$  and  $\mathbf{v}''$

**Solution:**

$$|\mathbf{v}'| = \left| \frac{\mathbf{v} \cdot \mathbf{u}}{\mathbf{u} \cdot \mathbf{u}} \mathbf{u} \right| \quad \text{and} \quad |\mathbf{v}''| = |\mathbf{v} - \mathbf{v}'|$$

We also need the vector  $\mathbf{u}$  which we'll define as  $\mathbf{u} = \mathbf{p} - \mathbf{pp}$

2. **Cylinder collider in code.** Assuming your answer to (1) above is correct, convert the mathematical equations into a Unity C# method that takes p, pp, R and q, and returns a Boolean true if q is in the cylinder, and false if not.

A point is in the cylinder under two conditions.

- a) The point is within a distance R from the line between p and q.
- b) The projection of the point onto the line is between the endpoints p and pp.

Pseudocode solution:

1. Compute  $v = p - q$
2. Compute  $v'$  and  $v''$  as in problem (c)
3. Compute distance d from q to line is the magnitude of  $v''$  or  $|v-v'|$
4. If  $d > R$ , reject as not in cylinder
5. Otherwise find projection of q onto line
  - 5a. Let length = distance from p to pp =  $|p-pp|$
  - 5b. Let s = sign of  $u \cdot v$
  - 5c. If  $s > 0$ , reject as the projection of q is past p
  - 5d. If  $s \leq 0$ , then
    - 6a. If  $|v'| \leq \mathbf{length}$  then accept since q projects between p and pp
    - 6b. If  $|v'| > \mathbf{length}$  reject as q projects on the line past pp.

b) Give a Unity method using Vector3 that implements a solution.

```
int inCylinder(float radius, Vector3 p, Vector3 pp, Vector3 q) {
    // Returns 1 if point in cylinder, 0 otherwise
    int result = 0;
    Vector3 u = p - pp;
    Vector3 v = q - p;
    Vector3 vprime = Vector3.dot(v,u)/Vector3.dot(u,u)*u;
    Vector3 vdblprime = v - vprime;
    float dist = Vector3.magnitude(vdblprime);
    float length = Vector3.mangitude(u);
    if (dist > R)
        result = 0; // Reject
    else {
        float length = Vector3.magnitude(u);
        float sign = (Vector3.dot(u,v) > 0) : 1 else -1;
        if (sign > 0)
            result = 0; //Reject
        else if (length > Vector3.magnitude(vprime))
            result = 0; //Reject
        else
            result = 1; // Accept
    }
    return result;
}
```

