

# Procedural shapes II

CMSC425.01 Fall 2019

Today's question

How to create interesting shape assets

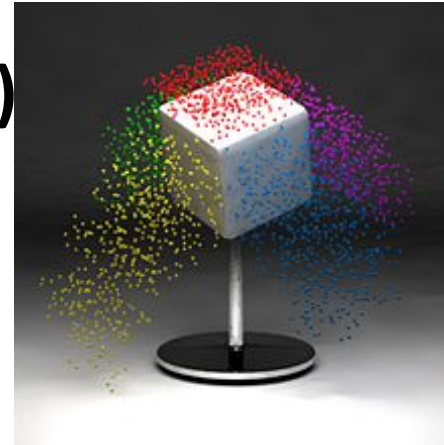
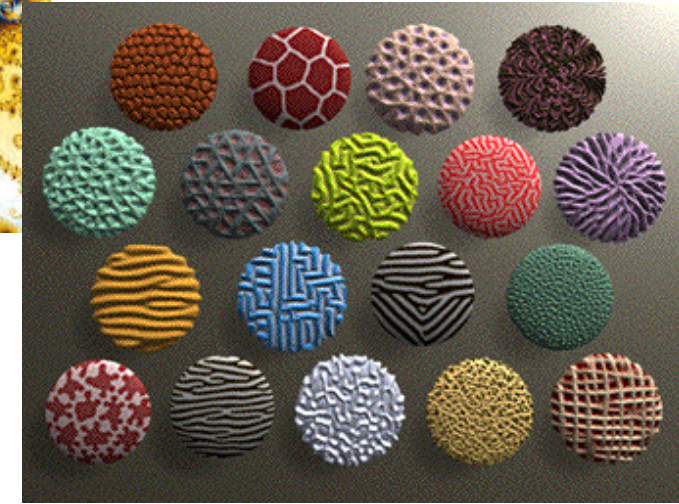
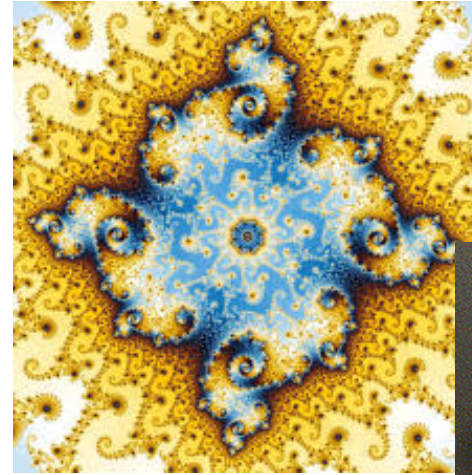
# Autogenerating terrain, objects, animations

- Why
  - Efficiency – faster than by hand
  - Variety – generate variations on a template
  - LOD – Generate level of detail as needed (*billboarding* in Unity)
- How:
  - Offline procedural generation: create, store mesh, add
  - Online – during game: shape represented by subroutine/object, not a fixed
- What:
  - 3D shapes, 2D textures
  - Fake real (eg, trees), non-real things



# “Fractal” examples

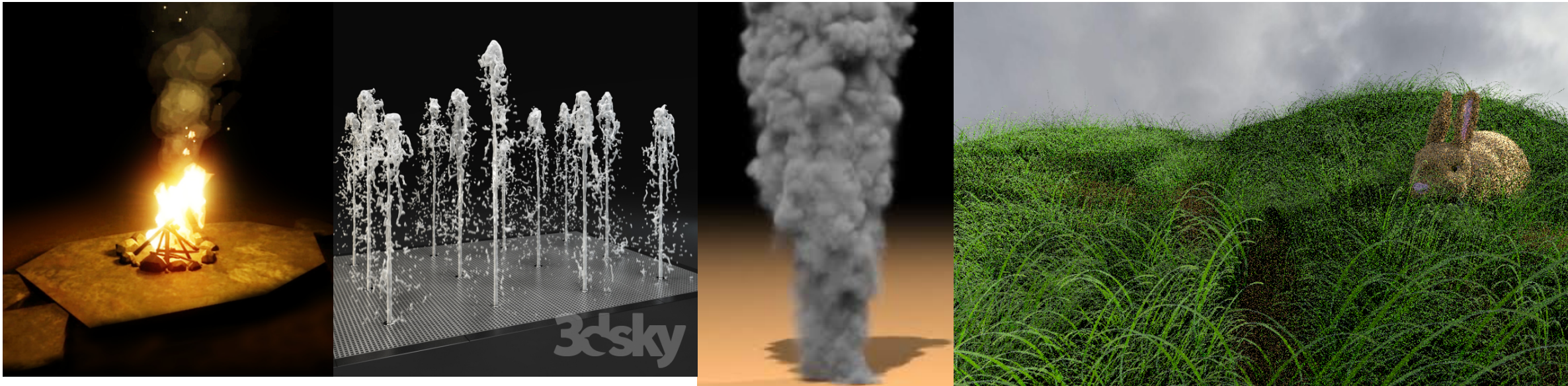
- *Midpoint displacement terrain*
- Particle systems
- **Lindermeyer Systems (L-systems)**
- Perlin noise
- Attractor sets
- *Iterated function systems (IFS)*
- *Reaction-diffusion textures*
- *Recursive fractals*





# Particle systems (no Mount lecture)

- Reeves, *Particle Systems A Technique for Modeling a Class of Fuzzy Objects*, 1983
  - <https://www.lri.fr/~mbl/ENS/IG2/devoir2/files/docs/fuzzyParticles.pdf>
- Used for fire, explosions, smoke, water, hair, grass, and more ...



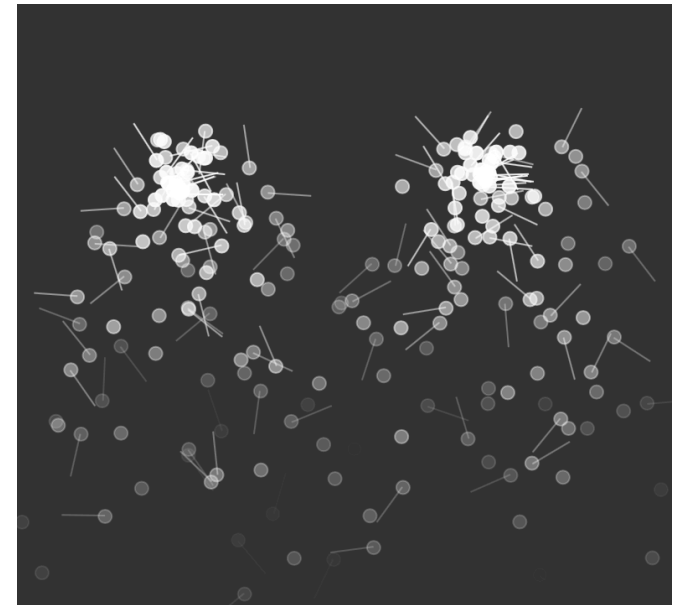
# Particle system basics

- Shiffman, Nature of Code link:
- <https://natureofcode.com/book/chapter-4-particle-systems/>
- Khan Academy
- <https://www.khanacademy.org/computing/computer-programming/programming-natural-simulations/programming-particle-systems/a/particle-types>
- <https://processing.org/examples/multipleparticlesystems.html>

# Particle properties

- Motion
  - Position
  - Forces (gravity, wind, explosion/impetus, friction)
- Lifetime
- Rendering
  - Color/size as function of position/motion
  - Rendering style and persistence

```
class Particle {  
    PVector position;  
    PVector velocity;  
    PVector acceleration;  
    float lifespan;  
};
```



# Basic algorithm

- Step 1: Generate new particles
  - Apply constraints on initial velocity
- Step 2: Retire particles past their lifetime
- Step 3: Simulate motion for all existing particles
  - Apply forces to get acceleration
  - Apply acceleration to get motion
  - Move
  - Handle collisions



# Dynamics of particle interaction

- Karl Sims 1989. Modeling
- <https://vimeo.com/114622025>
  
- SIGGRAPH 2014
- <https://vimeo.com/94622661>

# Forces

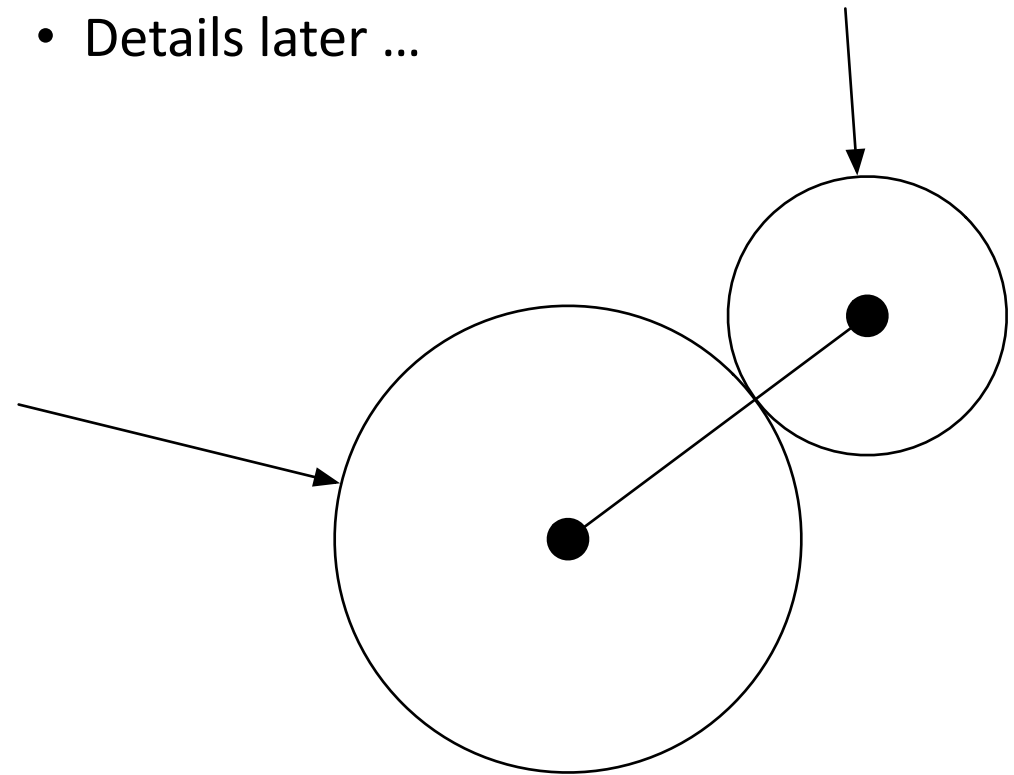
- From environment: gravity, viscosity (drag)
- From objects in scene: repulsion, attraction forces; collisions
- From fellow particles: spring, flocking

# Bouncy Bubbles

- [https://processing.org/examples/bouncy\\_bubbles.html](https://processing.org/examples/bouncy_bubbles.html)

```
void move() {  
  vy += gravity;  
  x += vx; y += vy;  
  if (x + diameter/2 > width)  
  { // Hit right wall  
    x = width - diameter/2;  
    vx *= friction;  
  }  
}
```

- Elastic collision
- Details later ...



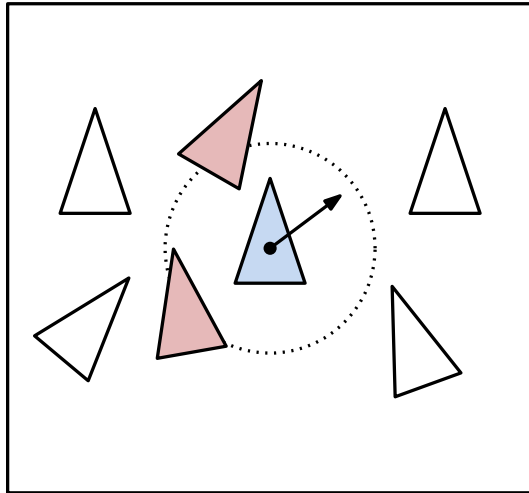
# Flocking force (Mount

- For textiles, bird flocks, other common motion
- <https://www.youtube.com/watch?v=gUF7ObEat0U>
- Boids
- Craig Reynolds 1986



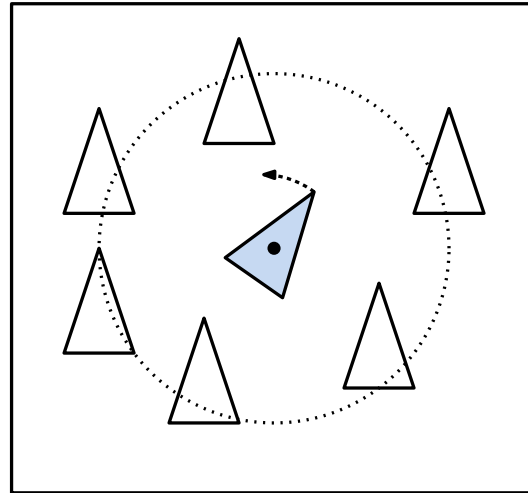
# Flocking forces

Separation



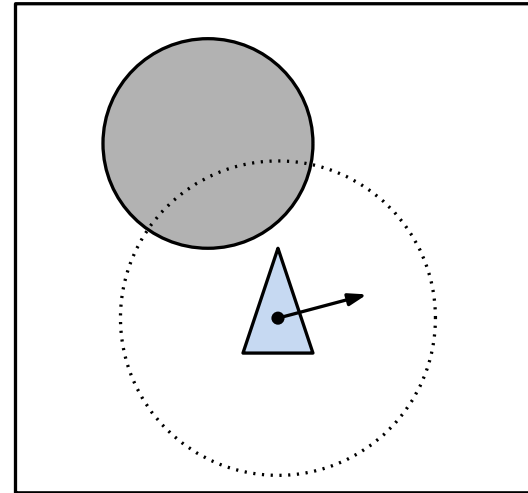
(a)

Alignment



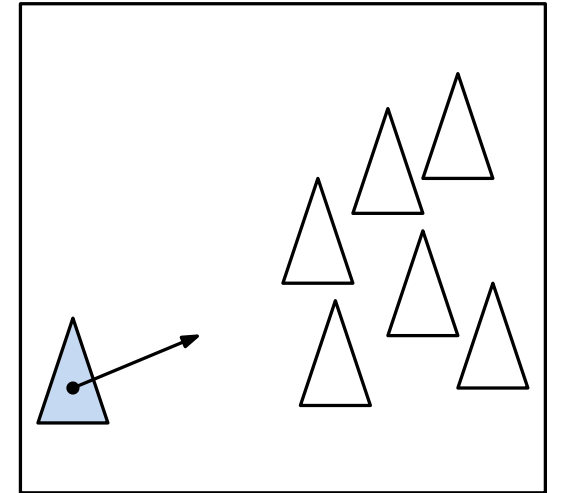
(b)

Avoidance



(c)

Cohesion



(d)

# Forces on boids

- Compute forces  $F_i$  at time  $t$
- Compute acceleration vector  $a_i$ 
  - Scale forces by mass  $i$
- Compute velocity from acceleration
- Compute position from velocity

$$\vec{a}_i(t) \leftarrow \frac{\vec{F}_i(t)}{m_i}.$$

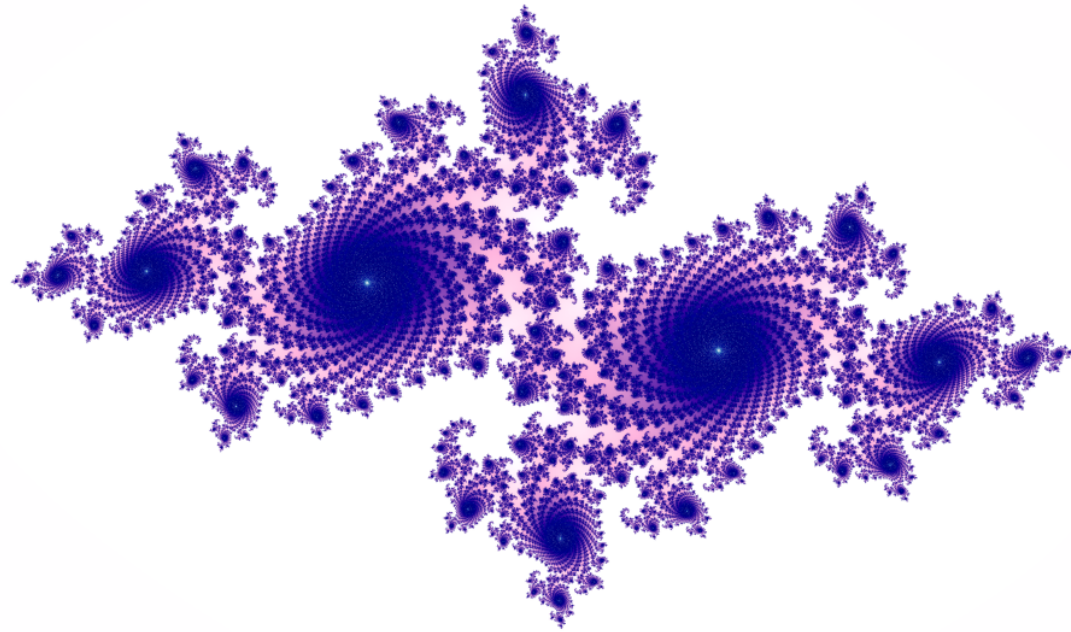
$$\vec{v}_i(t + \Delta) \leftarrow \vec{v}_i(t) + \Delta \cdot \vec{a}_i(t).$$

$$p_i(t + \Delta) \leftarrow p_i(t) + \Delta \cdot \vec{v}_i(t + \Delta)$$



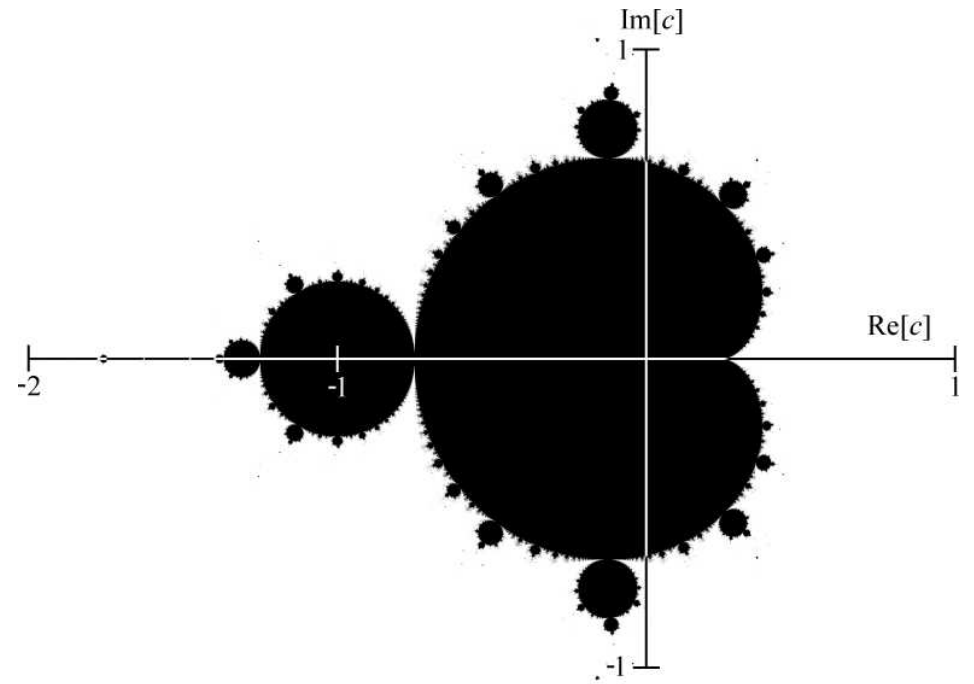
# Iterated Functions and Attractor sets

Julia set



(a)

Mandelbrot set



(b)



# Iterate complex function

- Iterate simple function of  $z$

$$z_i \leftarrow z_{i-1}^2 + c \quad \text{for } i = 1, 2, 3, \dots$$

