

Assignment 1

CMSC 726: Machine Learning
August 27th, 2019

Name:

1. Problem 9.1 from the text book.

2. Let $J(\theta) = \frac{1}{2} \sum_{i=1}^m (\theta^T \mathbf{x}^{(i)} - y^{(i)})^2$

- Compute $\nabla_{\theta} J(\theta)$ and $\nabla_{\theta}^2 J(\theta)$.
- Show that $J(\theta)$ is convex.
- Under what conditions on input samples, $J(\theta)$ is strictly convex?

3. Let $\{\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(m)}\}$ be m i.i.d samples drawn from a Gaussian distribution $\mathcal{N}(\mu_{\text{true}}, \sigma_{\text{true}}^2 \mathbf{I})$ where parameters μ_{true} and σ_{true} are unknown. A common approach to estimate model parameters is maximum likelihood estimation (MLE).

- The likelihood function $L(\mu, \sigma)$ is defined as the probability of observing samples $\{\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(m)}\}$ from the distribution $\mathcal{N}(\mu, \sigma^2 \mathbf{I})$. Write down the likelihood function in this case.
- Argue that $\operatorname{argmax}_{\mu, \sigma} L(\mu, \sigma) = \operatorname{argmax}_{\mu, \sigma} \log L(\mu, \sigma)$.
- By maximizing the log likelihood function, compute MLE estimates of model parameters.

4. Compute $\nabla_{\mathbf{X}} \operatorname{Tr}[\mathbf{A} \mathbf{X} \mathbf{B} \mathbf{X}^T \mathbf{C} \mathbf{X} \mathbf{D}] = ?$

- Hint 1:** if $dy = \operatorname{Tr}[\mathbf{A}(d\mathbf{X})]$, then the $\frac{dy}{d\mathbf{X}} = \mathbf{A}^T$.
- Hint 2:** The trace is invariant to cyclic permutations. For example, $\operatorname{Tr}[\mathbf{A}_1 \mathbf{A}_2 \mathbf{A}_3] = \operatorname{Tr}[\mathbf{A}_3 \mathbf{A}_1 \mathbf{A}_2] = \operatorname{Tr}[\mathbf{A}_2 \mathbf{A}_3 \mathbf{A}_1]$. In general, $\operatorname{Tr}[\mathbf{A}_1 \mathbf{A}_2 \dots \mathbf{A}_n] = \operatorname{Tr}[\mathbf{A}_k \mathbf{A}_{k+1} \dots \mathbf{A}_n \mathbf{A}_1 \dots \mathbf{A}_{k-1}]$, $1 \leq k \leq n$.
- Hint 3:** $\operatorname{Tr}[\mathbf{A}] = \operatorname{Tr}[\mathbf{A}^T]$.
- Hint 4:** The following is a solution for a simplified version of the problem. To compute $\nabla_{\mathbf{X}} \operatorname{Tr}[\mathbf{A} \mathbf{X} \mathbf{B} \mathbf{X}^T]$, we can write

$$\begin{aligned} d \operatorname{Tr}[\mathbf{A} \mathbf{X} \mathbf{B} \mathbf{X}^T] &= \operatorname{Tr}[d(\mathbf{A} \mathbf{X} \mathbf{B} \mathbf{X}^T)] \\ &= \operatorname{Tr}[\mathbf{A} d(\mathbf{X}) \mathbf{B} \mathbf{X}^T] + \operatorname{Tr}[\mathbf{A} \mathbf{X} \mathbf{B} d(\mathbf{X}^T)] \quad (\text{using the product rule of derivatives}) \\ &= \operatorname{Tr}[\mathbf{B} \mathbf{X}^T \mathbf{A} d(\mathbf{X})] + \operatorname{Tr}[\mathbf{A} \mathbf{X} \mathbf{B} d(\mathbf{X}^T)] \quad (\text{using the cyclic permutation property for the first term}) \\ &= \operatorname{Tr}[\mathbf{B} \mathbf{X}^T \mathbf{A} d(\mathbf{X})] + \operatorname{Tr}[d(\mathbf{X}) \mathbf{B}^T \mathbf{X}^T \mathbf{A}^T] \quad (\text{using the transpose invariance property for the second term}) \\ &= \operatorname{Tr}[\mathbf{B} \mathbf{X}^T \mathbf{A} d(\mathbf{X})] + \operatorname{Tr}[\mathbf{B}^T \mathbf{X}^T \mathbf{A}^T d(\mathbf{X})] \quad (\text{using the cyclic permutation property for the second term}) \\ &= \operatorname{Tr}[(\mathbf{B} \mathbf{X}^T \mathbf{A} + \mathbf{B}^T \mathbf{X}^T \mathbf{A}^T) d(\mathbf{X})]. \end{aligned}$$

Therefore, using **Hint 1**, we have $\nabla_{\mathbf{X}} \operatorname{Tr}[\mathbf{A} \mathbf{X} \mathbf{B} \mathbf{X}^T] = \mathbf{A}^T \mathbf{X} \mathbf{B}^T + \mathbf{A} \mathbf{X} \mathbf{B}$.

5. (Programming Assignment) Let $\mathbf{x} \in \mathbb{R}^n$ and $z \in \mathbb{R}$ be zero-mean independent Gaussian random variables with covariance matrices \mathbf{I} and σ^2 , respectively. That is, $\mathbf{x} \sim \mathcal{N}(0, \mathbf{I})$ and $z \sim \mathcal{N}(0, \sigma^2)$. Define $y = \theta^T \mathbf{x} + \theta_0 + z$. In this assignment, we want to use stochastic gradient descent (SGD) to compute a linear regression model between \mathbf{x} and y . Write a Python code to do the following:
- Let $n = 4$, $\sigma^2 = 1/4$, $\theta = [1, 1/2, 1/4, 1/8]^T$ and $\theta_0 = 2$. Generate $m = 10,000$ i.i.d. *training* samples from $\mathbb{P}_{X,Y}$. That is $\{(\mathbf{x}^{(1)}, y^{(1)}), \dots, (\mathbf{x}^{(m)}, y^{(m)})\}$.
 - Use SGD with a batch size of 10 to estimate model parameters. Plot the Mean-Squared Error (MSE) vs. the number of iterations.
 - Generate m new i.i.d. *test* samples from $\mathbb{P}_{X,Y}$. Use estimated parameters to compute the MSE on the test set.
 - Repeat parts (a)-(c) using $m = 10$. How do training and test errors change? Why?