

CMSC 714

Lecture 15

Lamport Clocks and Race Conditions

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(with thanks to Chris Ackermann)

Notes

- OpenMP projects
 - Keon working on them, but no results until later this week or early next week
- Research project questions?
- Don't forget to send questions about readings when you are assigned

Lamport Clocks

- Distributed systems are inherently concurrent, asynchronous, and nondeterministic, so executing programs on multiple machines requires coordination
- Lamport introduced methods to define an ordering of events
- Want to create a partial ordering of events (instructions, message passing, or whatever)
- Define a *happens before* relation: $a \rightarrow b$
 - event **a** happened before event **b**
 - event **a** can causally affect event **b**

Happens Before Relation

1. If **a** and **b** are events in the same process, and **a** comes before **b**, then $\mathbf{a} \rightarrow \mathbf{b}$
 2. If **a** is sending of a message by one process and **b** is the receipt of the same message by another process, then $\mathbf{a} \rightarrow \mathbf{b}$
 3. If $\mathbf{a} \rightarrow \mathbf{b}$ and $\mathbf{b} \rightarrow \mathbf{c}$ then $\mathbf{a} \rightarrow \mathbf{c}$ (transitivity)
- Partial Order: Unordered events are *concurrent*

Logical Clocks

- Clock Condition: For any events **a**, **b**: if $a \rightarrow b$ then $C\langle a \rangle < C\langle b \rangle$
- Holds if C1 and C2 are satisfied:
 - C1. If **a** and **b** are events in Process P_i , and **a** comes before **b**, then $C_i\langle a \rangle < C_i\langle b \rangle$
 - C2. If **a** is the sending of a message by process P_i and **b** is the receipt of that message by process P_j , then $C_i\langle a \rangle < C_j\langle b \rangle$
- Implementation
 - IR1. Each process P_i increments C_i between any two successive events
 - IR2a. If event **a** is the sending of a message m by Process P_i , then the message m contains a timestamp $T_m = C_i\langle a \rangle$.
 - IR2b. Upon receiving a message m , process P_j sets C_j greater than or equal to its present value and greater than T_m .

Total Ordering

- Partial ordering not always enough
- Prioritize processes $P_i < P_j$
- Total ordering $\mathbf{a} \Rightarrow \mathbf{b}$:

If \mathbf{a} is in P_i and \mathbf{b} is in P_j , then $\mathbf{a} \Rightarrow \mathbf{b}$ iff

- $C_i\langle\mathbf{a}\rangle < C_j\langle\mathbf{b}\rangle$
- $C_i\langle\mathbf{a}\rangle = C_j\langle\mathbf{b}\rangle$ and $P_i < P_j$

Logical Clocks

- Issues with physical clocks (clock drift, etc.)
- For many purposes, it is sufficient to know the order in which events occurred
- BUT: Logical clocks cannot be used to order events outside the system

Strong Clock Condition

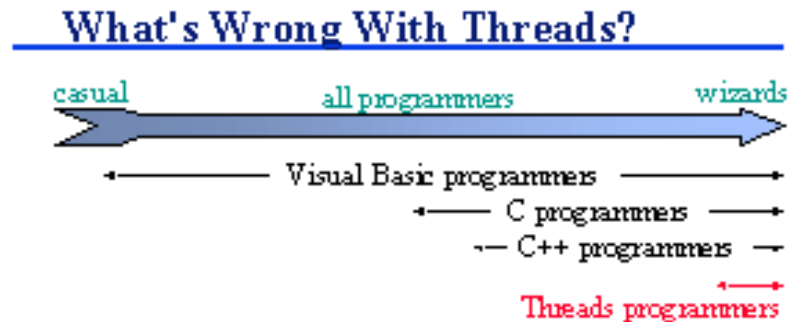
- Approach does not take into account external events
- Define new set of events \mathcal{L}
- *Strong Clock Condition:* For any events \mathbf{a} , \mathbf{b} in \mathcal{L} :
if $\mathbf{a} \Rightarrow \mathbf{b}$ then $C\langle\mathbf{a}\rangle < C\langle\mathbf{b}\rangle$
- Achieve strong clock condition with physical clocks

Physical Clocks

- Run continuously
- PC1. Clocks must run at approximately the correct rate
 - $\exists k. k \ll 1, |dC_i(t)/dt - 1| < k$
- PC2. Clocks must be synchronized
 - $|C_i(t) - C_j(t)| < \epsilon$
- Minimum message delay μ
 - $C_i(t + \mu) - C_j(t) > 0$
- Satisfying Strong Clock Condition:
 - IR1: Each event occurs at a precise instant
 - IR2:
 - If P_i sends a message m at physical time t , then m contains a timestamp $T_m = C_i(t)$.
 - Upon receiving a message m at time t' , process P_j sets $C_j(t')$ equal to the maximum of $C_j(t')$ and $(T_m + \mu_m)$

Race Conditions

- What is the problem?
 - Implementing multi-threaded programs is difficult and error prone



- Who cares?
 - Developers (and users) of multi-threaded systems
- What is the approach?
 - Provide tool support to automatically verify synchronization

Data Races

- Data Race

- More than 1 thread has read or write access to a variable without synchronization, and at least one is doing a write

- Static race detection

- Analyze the program code, so does not require that the program execute
- Difficult analysis, if *sound* (does not produce false negatives) tends to produce many false positives (lack of *completeness*)
- Getting both soundness and completeness is undecidable

Data Races (cont.)

- **Dynamic race detection**

- Analyze the events from a single program execution to determine the occurrence of a race condition in one program execution
- Can be sound and complete, but only for that execution
- Want to have the *single input, single execution (SISE)* property, so that a single execution instance is sufficient to determine the existence of a data race for a given input.
- Two basic kinds – based on happens-before (HB) relation (Lamport), and based on locksets (e.g., Eraser algorithm)

HB-based Dynamic Race Detection

- Inefficient since large amount of information is required
- Basic idea has 3 parts:
 - track the HB-relation within each thread
 - keep an access history as a sequence of logical timestamps for each shared resource (variable or memory location)
 - validate that, for every resource, critical accesses are ordered by the HB-relation
- While the analysis can be sound and complete, the article shows that with a more general notion of data races, the HB-based analysis does not report all possible data races so is not sound wrt that definition

Lockset-based Detection

- Targeted at programs that use *critical sections* as their primary synchronization model
- Validates that a program execution adheres to a programming policy, called a *locking discipline*
 - E.g., threads that access a common memory location must hold a mutual exclusion lock when performing the access
- Compliance with the locking discipline implies that executions don't have a data race
- Validation can be done with static or dynamic analysis, or both

Lockset-based algorithm

- Each thread tracks at run-time the set of locks it currently holds – i.e. via a shadow location for each variable that holds the current lockset
- On the first access to a shared variable, the shadow memory is initialized with the lockset of the current thread.
- On subsequent accesses, the lockset in shadow memory is updated by intersecting it with the lockset of the accessing thread.
- If the intersection is empty and the variable has been accessed by different threads, a potential data race is reported.
- Lockset-based detection is *sound*, and has the SISE property
- Detection is *incomplete*, since accesses that violate the locking discipline may be ordered by other means of synchronization – so can get false positives

Static Data Race Detection

- Pragmatic methods look for deviations from common programming practice
 - Examples include FindBugs for Java from UMD, RacerX for large OS codes
- Methods based on dataflow analysis
 - May-happen-in-parallel analysis (MHP) to compute the may-happen-in-parallel relation among statements in different threads
 - Inter-process precedence graph for determining anomalies in programs with post-wait synchronization
- Type-based methods
 - To model and express data protection and locking policies in data and method declarations
- Model checking
 - To explore every possible control flow-path and variable value assignment for undesired program behavior
 - Since that is computationally intractable, models of the data and program are explored