

Announcements

- Program #2 due today
- Midterm #2 is next Tuesday
 - same time and place as last time

Command Line Arguments

- `int main(int argc, char *argv[])`
 - `argc` - number of arguments (including program name)
 - `argv` - array of command line arguments
 - `argv[0]` - command invoked to start program
 - `argv[n]` - n'th command line argument
- **Example:**
 - `./foo -file myfile -help`
 - `argv[0] = "./foo"`
 - `argv[1] = "-file"`
 - `argv[2] = "myfile"`
 - `argv[3] = "-help"`

Programming Command Line Arguments

- Generally, want arguments to be accepted in any order

- ./foo -file myfile -help
- ./foo -help -file myfile

- Solution:

- Table driven command line parsing
 - Example of a common pattern, table drive parsing
- Declare a structure
 - fields describe each valid option

```
typedef enum { Flag, StrParam, IntParam };
```

```
typedef struct {
```

```
    char *name;
```

```
    optionTypes options;
```

```
    void *parameter;
```

```
} option;
```

Command Line Arguments Continued

```
int debugFlag, limit;  
char *inputFileName;  
optionTable = [] {  
    { "-debug", Flag, &debugFlag },  
    { "-file", StrParam, &inputFileName },  
    { "-limit", IntParam, &limit },  
    .... /* other options go here */  
};  
  
int optionCount = sizeof(optionTable)/sizeof(option);
```

Project 1B Using Table Driven Parsing

```
typedef struct {  
    char *name;  
    int opCode;  
    int numRegisters;  
    int usesMem;  
} opInfo;  
  
static opInfo opTable[] = {  
    { "Load",  1, 1, 1 },  
    { "Move",  2, 2, 0 },  
    { "Store",  3, 1, 1 },  
    { "Add",    4, 3, 0 },  
    { "Halt",   5, 0, 0 },  
    { "Negate", 6, 1, 0 },  
    { "Branch", 7, 2, 1 },  
    { "Bnn",    8, 1, 1 },  
    { "Input",  10, 1, 0 },  
    { "Output", 11, 1, 0 },  
    { "Data",   -1, 0, 1 },  
};
```

Environment Variables

- Keyword, argument pairs
- Allow passing info into programs
- Examples:
 - PATH - used by shell to find programs
 - PRINTER - default printer to use
- Passed as the third parameter to main
 - `int main(int argc, char *argv[], char *envp[])`
 - consists of a null terminated array of characters
 - KEYWORD=VALUE stored in each one
- C helper functions:
 - `char *getenv(const char *keyword);`
 - `char *putenv(const char *string);`
 - where string is KEYWORD=VALUE

Environment Variable Example

- Shell Commands to Setup Environment:

- C Shell: `setenv FOO_CONFIG ~/foo`
- Bash: `FOO_CONFIG=~/foo`

```
main(int argc, char *argv[], char *envp[])
{
    char *configDirectory;

    configDirectory = getenv("FOO_CONFIG");

}
```

Creating New Processes

- Use fork system call
 - UNIX (and LINUX) specific
 - creates a new copy of the current process
- Syntax `int fork();`
 - returns twice
 - once from initial call
 - second time in a new process
 - return value indicates which process is which
 - 0 the "child" (new) process
 - > 0 the "parent" (original) process
 - < 0 the "parent", but not child was created (error case)

Fork Example

```
int main(int argc, char *argv[]) {  
    int pid;  
  
    pid = fork();  
    if (pid == 0) {  
        printf("I am the child\n");  
        exit(0);  
    } else if (pid > 0) {  
        printf("Created child process %d\n", pid);  
        exit(0);  
    } else {  
        printf("Error, unable to create a new process");  
        exit(0);  
    }  
}
```

Learning About Other Processes

- Wait and waitpid system call

- #include <sys/types.h>
- #include <sys/wait.h>
- pid_t wait(int *status);
 - wait until a child process terminates
- pid_t waitpid(pid_t pid, int *status, int options);
 - wait until the passed process terminates
- return is the id the the terminated process
- status fills out a status variable
 - WIFEXITED(status) - true if the child terminated normally
 - WEXITSTATUS(status) - low 8 bits of parameter to exit
 - WTERMSIG(status) - signal number that terminated process

Invoking a new program

- **exec system calls**
 - `int execl(const char *prog, char *const argv[]);`
 - run the program in the passed prog parameter
 - pass the new program argv
 - `int execlp(const char *file, char *const argv[]);`
 - like execl, but used the PATH environment variable
- **On success,**
 - new program launched, the system call does not return
- **On failure,**
 - returns -1, sets global errno to indicate cause of the error

Fork and Exec Example

```
char *args[] = { "ls", "-l", "-a", NULL };  
  
....  
pid = fork();  
if (pid == 0) {  
    ret = execvp("ls", args);  
    if (ret) {  
        perror("execvp");  
        exit(-1);  
    }  
} else if (pid > 0) { ...  
} else { ...  
}  
  
.....  
}
```

Additional I/O system Calls

- Sometimes process want to communicate
 - abstraction: pipe - one process writes, other reads
 - shell example: `ls | wc`
- `int pipe(int fildes[2]);`
 - create a pipe between two processes
 - write and read system call can use these
- Standard I/O
 - fd 0 is standard input to a process
 - fd 1 is standard output from a process
 - fd 2 is standard error output from
- `int dup2(int oldfd, int newfd);`
 - change output of one fd to another
 - `dup2(0, myfd)`
 - now all standard input comes from myfd

Changing Standard Input/Output

- Useful to combine pipe, dup2, and exec

```
....  
pipe(pipefds);  
pid = fork();  
if (pid == 0) {  
    dup2(0, pipefd[0]);  
    close(pipefd[1]);  
    ret = execvp("ls", args);  
    ....  
else if (pid > 0) {  
    dup2(1, pipefd[1]);  
    close(pipefd[0]);  
} else {  
    ....
```

A Simple Shell Program

```
while (1) {  
    ret = fgets(line, sizeof(line), stdin);  
    ...  
    /* convert line into array of arguments */  
    pid = fork();  
    if (pid == 0) {  
        ret = execvp(args[0], args);  
        if (ret) {  
            printf("Command not found\n");  
            exit(-1);  
        } else if (pid > 0) {  
            ret = waitpid(pid, &status, NULL);  
        } else { ... }  
    }  
}
```