

## CMSC425 Lecture Outline March 4<sup>th</sup>

### **References:**

*Mount, Lecture 7 (or 8): Geometric Programming: Sample Solutions*

*Mount, Lecture 9: Geometric Data Structures: Enclosures and Spatial Indices*

See also previous midterm practice questions

### **Outline:**

#### I. Administrivia

- A. Hw1 due. Questions?
- B. Final project proposal. Questions?
- C. Project 1b submission issues. Will be understanding
- D. Mini-lecture videos coming on some topics

#### II. Instant HW1 and "professional" solutions to a geometric/graphics problem

- A. Many solutions given for Instant Hw1 were close, not quite right
  - Could have found error through simple test (but only one student tested!)
  - Ok in context of the class- misleading material in lecture
  - Not ok in professional context
- B. For courses, typical homework solutions
  - Focus on getting the "answer"
  - Stop when the original question is answered
- C. Professional solutions
  - Focus on getting an answer suitable for professional implementation
  - "Prove" the answer through some argument/demonstration
  - Test the answer on enough cases to be sure it works
  - Show that it's the most efficient of reasonable solutions (efficient enough)
  - Stop when the team feels they have the best solution
- D. A difference: student plagiarism vs. professional copyright/patent violations
  - Students can steal stuff (fair use) but must not plagiarize
  - Professionals can plagiarize but can't steal stuff (violate copyright/patent)
- E. Objective of class: you can read and access literature on this material
  - <http://www.realtimerendering.com/intersections.html>
  - <http://www.math.kit.edu/ianm2/lehre/am22016s/media/distance-harvard.pdf>

#### II. Applications of geometric principles to game programming problems

- A. Sources of examples
  - i. Mount Lecture 7: Geometric Programming: Sample Solutions
  - ii. Mount Practice Problems for the First Midterm (spring 2018)
  - iii. Also see previous courses, in one larger Handout pdf
- B. Observation
  - The problem may look complex but have a relatively simple solution

B. Today

- i. Shot gun simulator
- ii. Projectile shooting
- iii. Projectile direction (arrow)
- iv. Evasive action

### III. Geometric Data Structures: Colliders and collisions

Two problems:

Colliding two objects efficiently

Efficiently finding collisions in large group of objects (better than  $n^2$ )

#### A. Approximate complex shapes with approximating colliders

i. Want accurate and fast approximation

ii. If inaccurate

a. Ghost collisions

b. Bad physics

ii. If too accurate then slow

#### B. Bounding enclosures – single bodies

i. Axis-aligned bounding boxes (AABB) (also called rectilinear)

ii. General bounding boxes (rotated)

iii. Bounding spheres

iv. Bounding ellipsoids

v. Capsules

vi. k-DOPs (k-discrete oriented polytope)

vii. And – don't forget an object represented by a single point

#### C. Collisions

i. The more types of enclosures you support, the more type\*type collisions you must support

ii. AABB-AABB

iii. General box-box

iv. Sphere-sphere

v. Capsule-Capsule

#### D. Compound objects and hierarchical representations

R-trees

#### E. Data structures for many objects

##### A. Grid

i. Store in array

ii. In hash map

iii Linear allocation

a. Morton order

b. Hibert order

##### B. Spatial trees

i. Quadtree (Octree)

ii. K-d tree