Homography

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Feature matching



descriptors for left image feature points





descriptors for right image feature points



SIFT features

• Example



- (a) 233x189 image
- (b) 832 DOG extrema
- (c) 729 left after peak value threshold
- (d) 536 left after testing ratio of principle curvatures

Strategies to match images robustly

(a)<u>Working with individual features:</u> For each feature point, find most similar point in other image (SIFT distance)Reject ambiguous matches where there are too many similar points

(b)<u>Working with all the features:</u> Given some good feature matches, look for possible homographies relating the two images

Reject homographies that don't have many feature matches.

(a) Feature-space outlier rejection

- Let's not match all features, but only these that have "similar enough" matches?
- How can we do it?
 - SSD(patch1,patch2) < threshold</pre>
 - How to set threshold? Not so easy.



Feature-space outlier rejection

- A better way [Lowe, 1999]:
 - 1-NN: SSD of the closest match
 - 2-NN: SSD of the second-closest match
 - Look at how much better 1-NN is than 2-NN, e.g. 1-NN/2-NN
 - That is, is our best match so much better than the rest?



<u>RAndom SAmple Consensus</u>



RANSAC for estimating homography

- RANSAC loop:
- Select four feature pairs (at random)
- Compute homography H (exact)
- Compute inliers where $||p_i', Hp_i|| < \varepsilon$
- Keep largest set of inliers
- Re-compute least-squares H estimate using all of the inliers

- Pick 2 points
- Fit line
- Count inliers (3 inliers)



- Pick 2 points
- Fit line
- Count inliers (4 inliers)



- Pick 2 points
- Fit line
- Count inliers (7 inliers)



- Pick 2 points
- Fit line
- Count inliers (5 inliers)



- Use biggest set of inliers
- Least squares fit



RANSAC





red:

rejected by 2nd nearest neighbor criterion blue: Ransac outliers yellow:

inliers



RANSAC parameters

Decision Threshold: $|X' - HX| < \epsilon$

Number of trials: N

Size of the inlier set: M

Robustness

- Proportion of inliers in our pairs is g (for "good")
- Our model needs P pairs

– P=4 for homography

- Probability that we pick P inliers? g^p
- Probability that after N RANSAC iterations we have not picked a set of inliers?

$$(1-g^p)^N$$

Robustness: example

- Proportion of inliers G=0.5
- Probability that we pick P=4 inliers? $-0.5^4 = 0.0625(6\% chance)$
- Probability that we have not picked a set of inliers?

N = 100 iterations

 $(1 - 0.5^4)^{100} = 0.00157(1 \text{ chance in } 600)$

N = 1000 iterations

- $(1 0.5^4)^{100} = 0.00157(1 \text{ chance in } 10^{28})$
- 1 chance in 1e28

Robustness: example

• Proportion of inliers G=0.3



- Probability that we pick P=4 inliers?
 -0.34=0.0081 (0.8% chance)
- Probability that we have not picked a set of inliers?
 - N=100 iterations:
 - $(1-0.3^4)^{100}=0.44$ (1 chance in 2)
 - N=1000 iterations:
 - 1 chance in 3400

Robustness: example

• Proportion of inliers G=0.1



- Probability that we pick P=4 inliers?
 -0.14=0.0001 (0.01% chances, 1 in 10,000)
- Probability that we have not picked a set of inliers?
 - N=100 iterations: (1-0.14)100=0.99
 - N=1000 iterations: 90%
 - N=10,000: 36%
 - N=100,000: 1 in 22,000

Robustness: conclusions

- Effect of number of parameters of model/ number of necessary pairs
 - Bad exponential
- Effect of percentage of inliers
 - Base of the exponential
- Effect of number of iterations – Good exponential

RANSAC recap

- For fitting a model with low number P of parameters (8 for homographies)
- Loop
 - Select P random data points
 - Fit model
 - Count inliers

(other data points well fit by this model)

• Keep model with largest number of inliers

RANSAC for Homography



RANSAC for Homography



RANSAC for Homography

