

Neural Networks

CMSC 422

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What we have learned so far ...

Classification Problem:



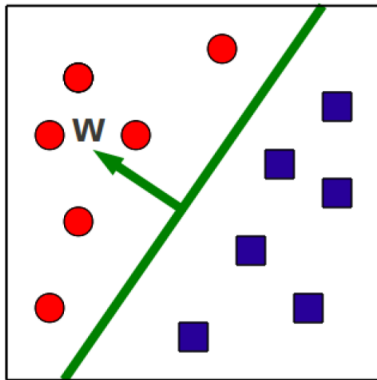
Decision
trees

KNNs

Perceptron

Empirical Risk
Minimization

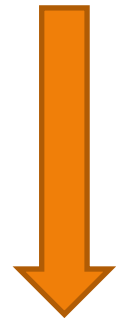
Maximum
Likelihood



Linear model
($w^t x + b$)



0-1 loss \rightarrow
Hinge loss

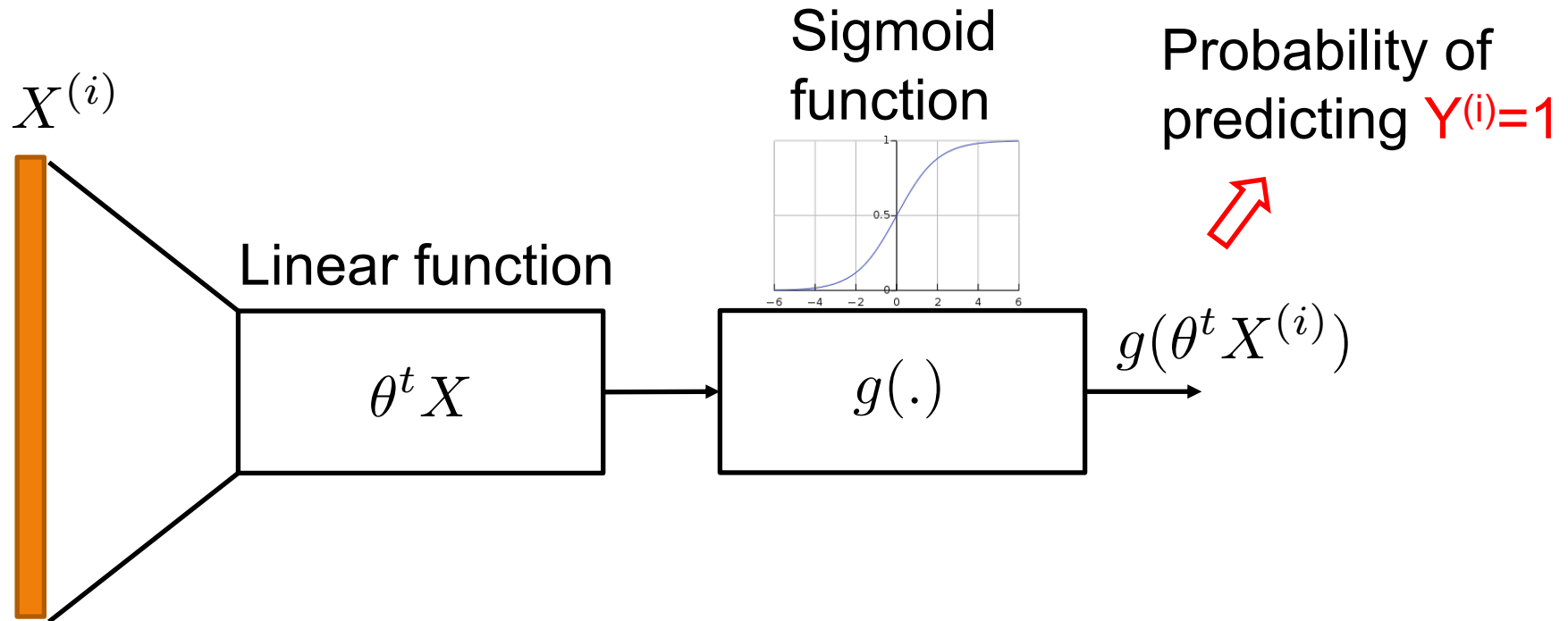


**Cross-
entropy** loss

Why did we restrict our models to linear ($w^t x + b$)?

- Optimizations turned out to be **convex**.
- Why this is important?
- An efficient method (Stochastic GD) to find the global optimizer
- What do we lose by restricting ourselves to linear models?

Recall the logistic regression

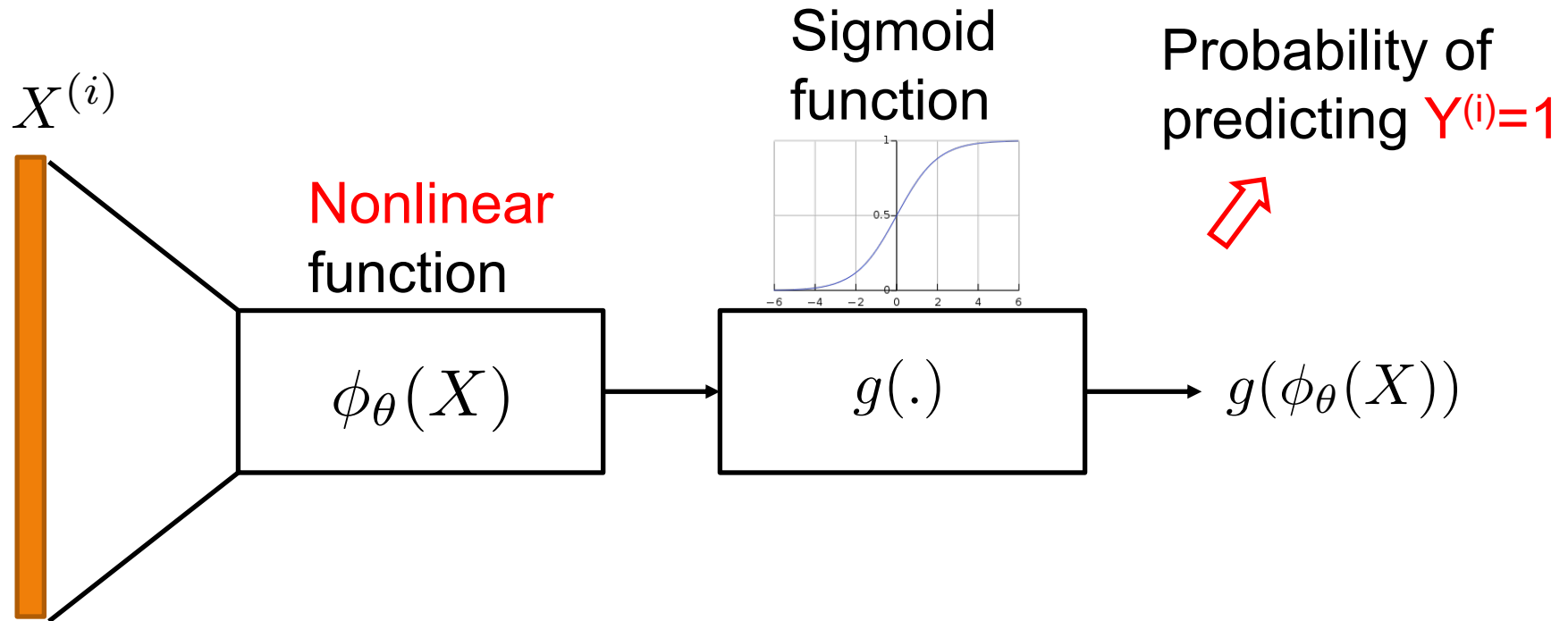


Is $X \rightarrow Y$ model linear? **No!**

Pick model parameters using cross-entropy loss optimization

$$\max_{\theta} \sum_{i=1}^N Y^{(i)} \log g(\theta^t X^{(i)}) + (1 - Y^{(i)}) \log(1 - g(\theta^t X^{(i)}))$$

Linear \rightarrow Nonlinear



Is $X \rightarrow Y$ model linear? **No!**

Pick model parameters using cross-entropy loss optimization

$$\max_{\theta} \sum_{i=1}^N Y^{(i)} \log g(\phi_{\theta}(X^{(i)})) + (1 - Y^{(i)}) \log(1 - g(\phi_{\theta}(X^{(i)})))$$

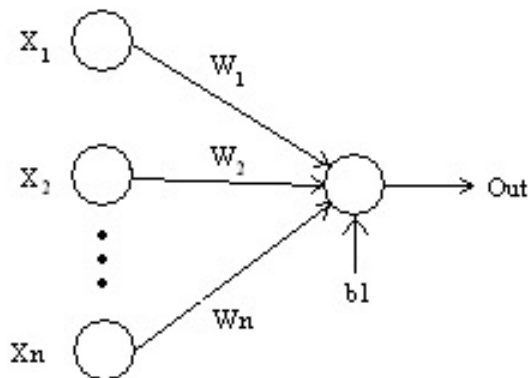
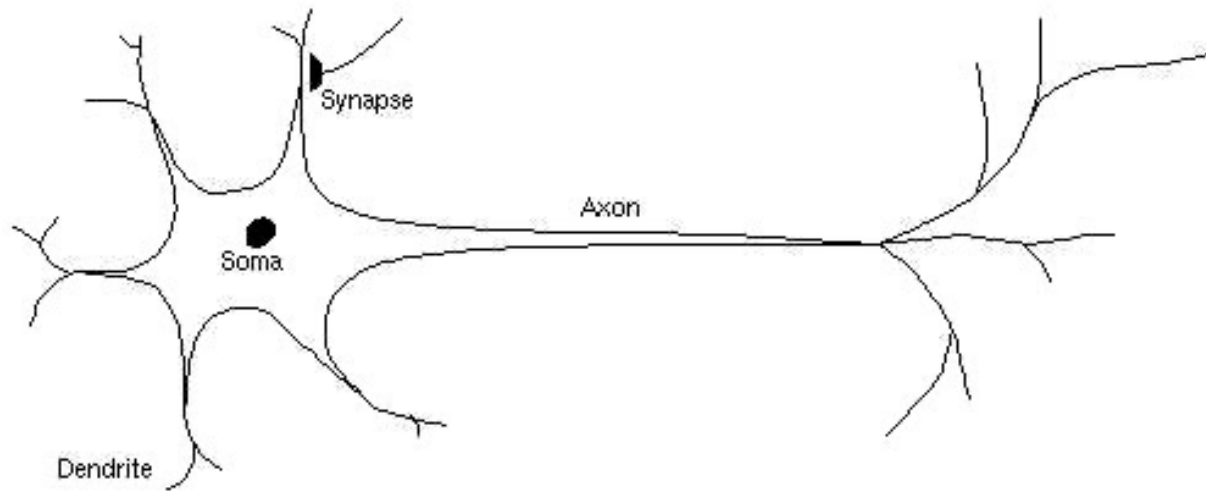
Two Questions

- What is a “good” family of nonlinear functions to consider?
- How to solve the resulting optimization?
Can we still use stochastic GD?

Neural Networks

- What are Neural Networks?
- Why are neural networks powerful?

Aside: biological inspiration



Analogy: the
perceptron
as a neuron

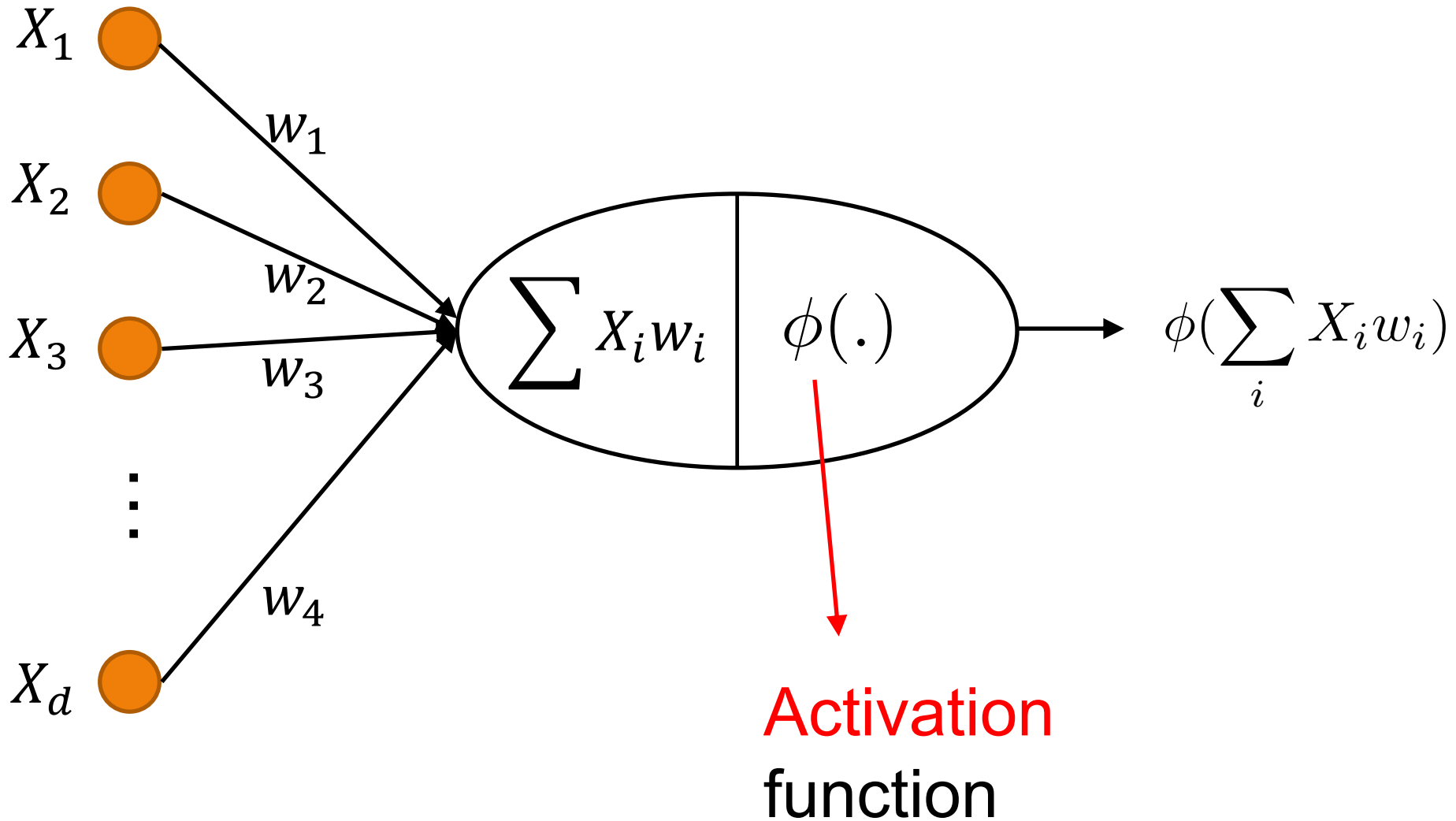
History of Neural Networks

- 1943: McCulloch and Pitts proposed a model of a neuron
- 1960s: Widrow and Hoff explored Perceptron networks (which they called "Adelines") and the delta rule.
- 1957: Frank Rosenblatt invents the **Perceptron**
1962: Rosenblatt proved convergence of the perceptron training rule.
- 1969: Minsky and Papert showed that the Perceptron cannot deal with nonlinearly-separable data sets---even those that represent simple function (e.g., X-OR)
- 1970-1985: Very little research on Neural Nets
- 1986: Invention of Back Propagation [Rumelhart & McClelland; Parker; Werbos] which can learn nonlinearly-separable data sets.
- Since 1985: A lot of research in Neural Nets!
- Geoff Hinton

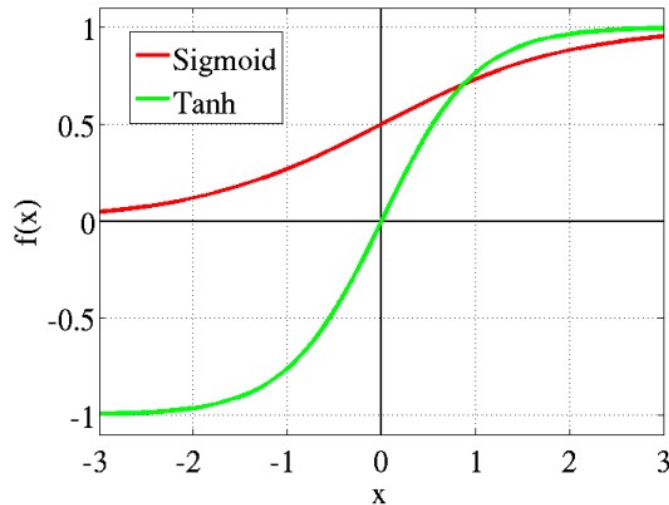
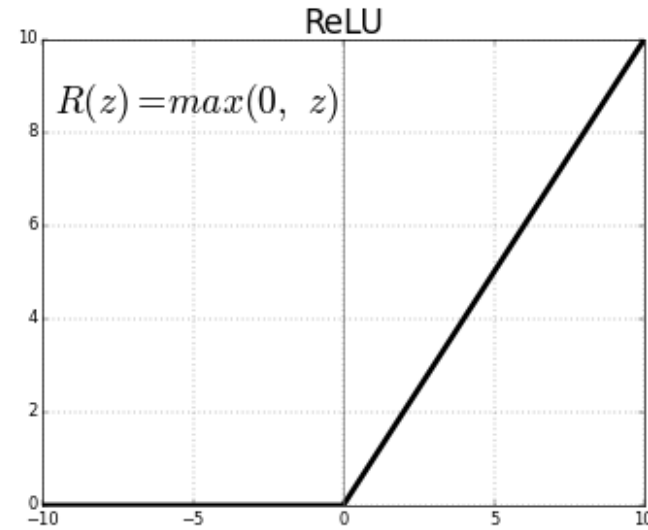
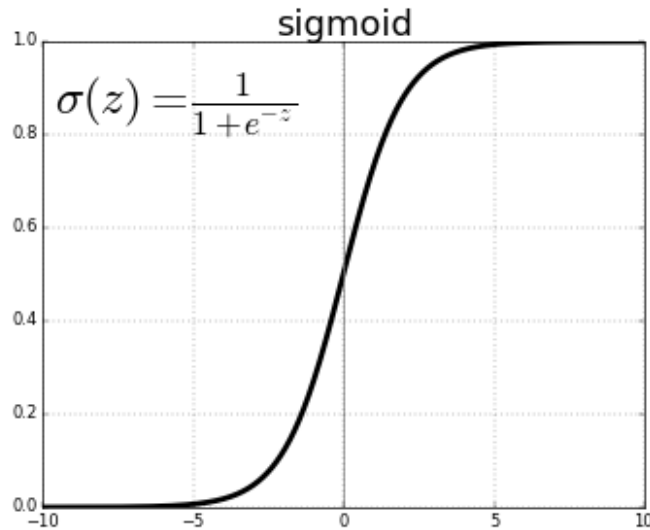
Neural networks

- Neural networks are made up of **nodes** or **units**, connected by **links**
- Each link has an associated **weight** and **activation level**
- Each node has an **input function** (typically summing over weighted inputs), an **activation function**, and an **output**

Neural Unit




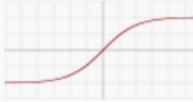
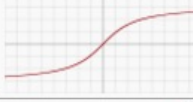






Popular Activation Functions

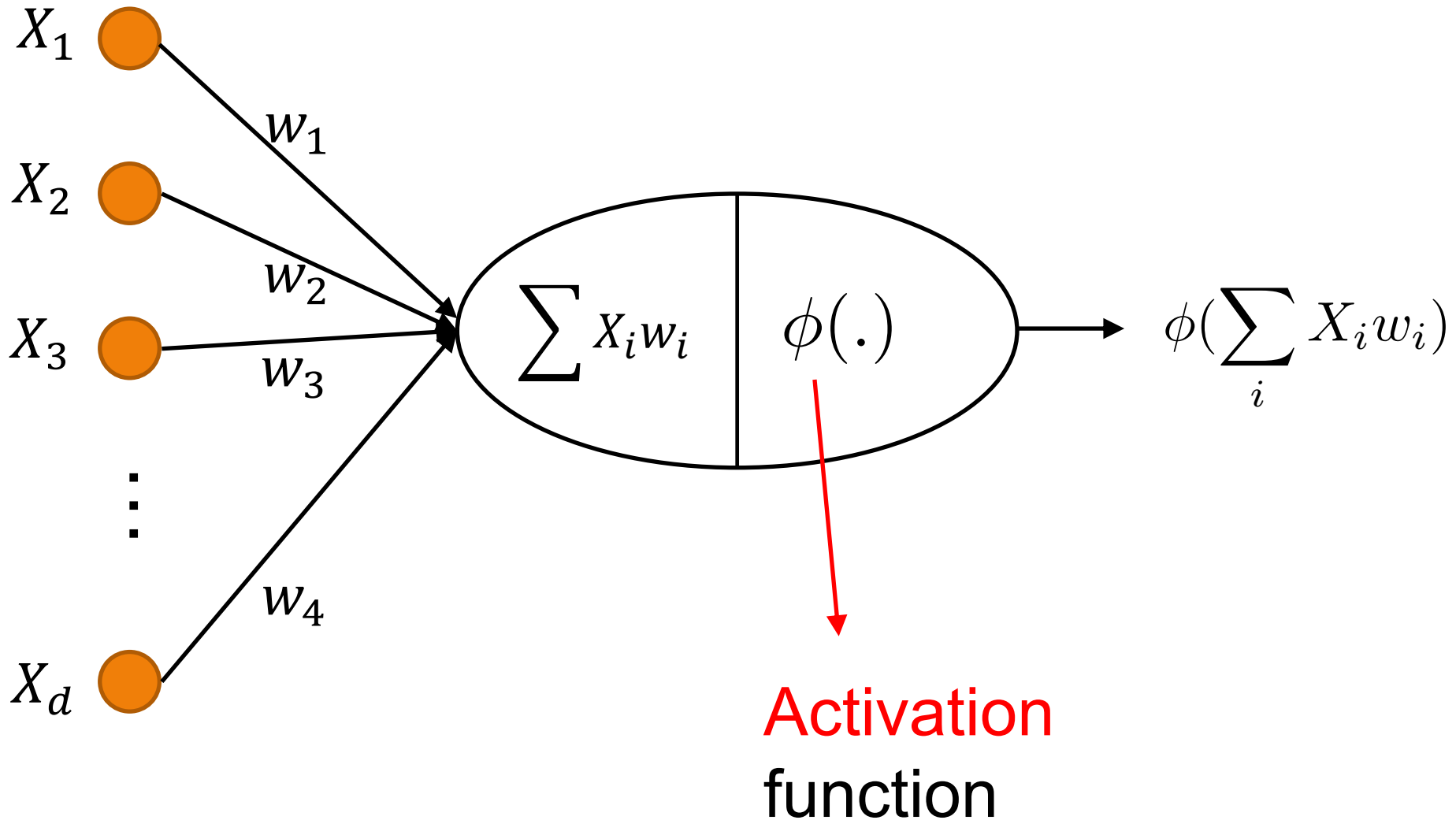


Q: how to choose a proper activation function?

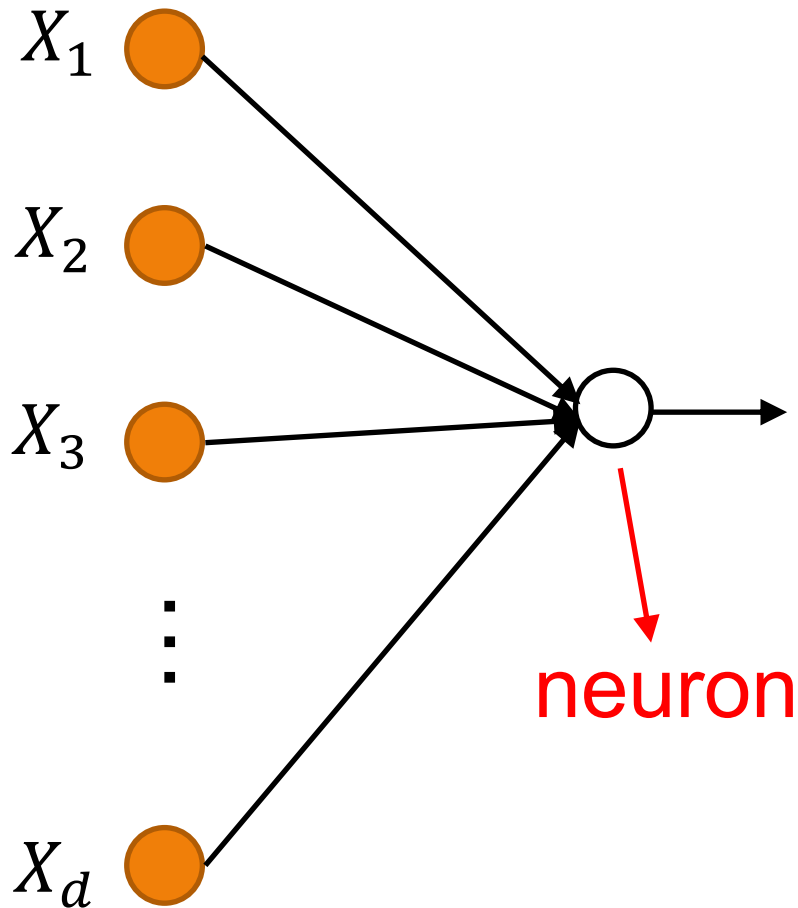
So many more activation functions

Name	Plot	Equation	Derivative
Identity		$f(x) = x$	$f'(x) = 1$
Binary step		$f(x) = \begin{cases} 0 & \text{for } x < 0 \\ 1 & \text{for } x \geq 0 \end{cases}$	$f'(x) = \begin{cases} 0 & \text{for } x \neq 0 \\ ? & \text{for } x = 0 \end{cases}$
Logistic (a.k.a Soft step)		$f(x) = \frac{1}{1 + e^{-x}}$	$f'(x) = f(x)(1 - f(x))$
TanH		$f(x) = \tanh(x) = \frac{2}{1 + e^{-2x}} - 1$	$f'(x) = 1 - f(x)^2$
ArcTan		$f(x) = \tan^{-1}(x)$	$f'(x) = \frac{1}{x^2 + 1}$
Rectified Linear Unit (ReLU)		$f(x) = \begin{cases} 0 & \text{for } x < 0 \\ x & \text{for } x \geq 0 \end{cases}$	$f'(x) = \begin{cases} 0 & \text{for } x < 0 \\ 1 & \text{for } x \geq 0 \end{cases}$
Parametric Rectified Linear Unit (PReLU) [2]		$f(x) = \begin{cases} \alpha x & \text{for } x < 0 \\ x & \text{for } x \geq 0 \end{cases}$	$f'(x) = \begin{cases} \alpha & \text{for } x < 0 \\ 1 & \text{for } x \geq 0 \end{cases}$
Exponential Linear Unit (ELU) [3]		$f(x) = \begin{cases} \alpha(e^x - 1) & \text{for } x < 0 \\ x & \text{for } x \geq 0 \end{cases}$	$f'(x) = \begin{cases} f(x) + \alpha & \text{for } x < 0 \\ 1 & \text{for } x \geq 0 \end{cases}$
SoftPlus		$f(x) = \log_e(1 + e^x)$	$f'(x) = \frac{1}{1 + e^{-x}}$

Lets make the picture more
concise



Lets make the picture more
concise

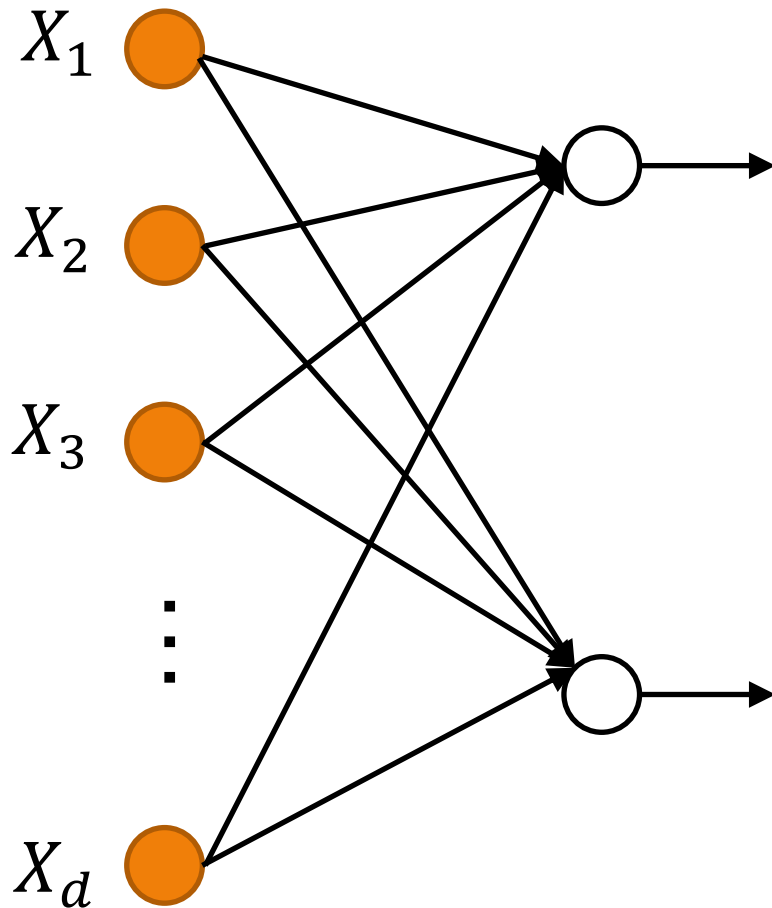


Implicitly we always
assume

- Edges have **weights**
- Neurons have **activations**

Q: can we make the
function more complex
(i.e. higher
representation power)?

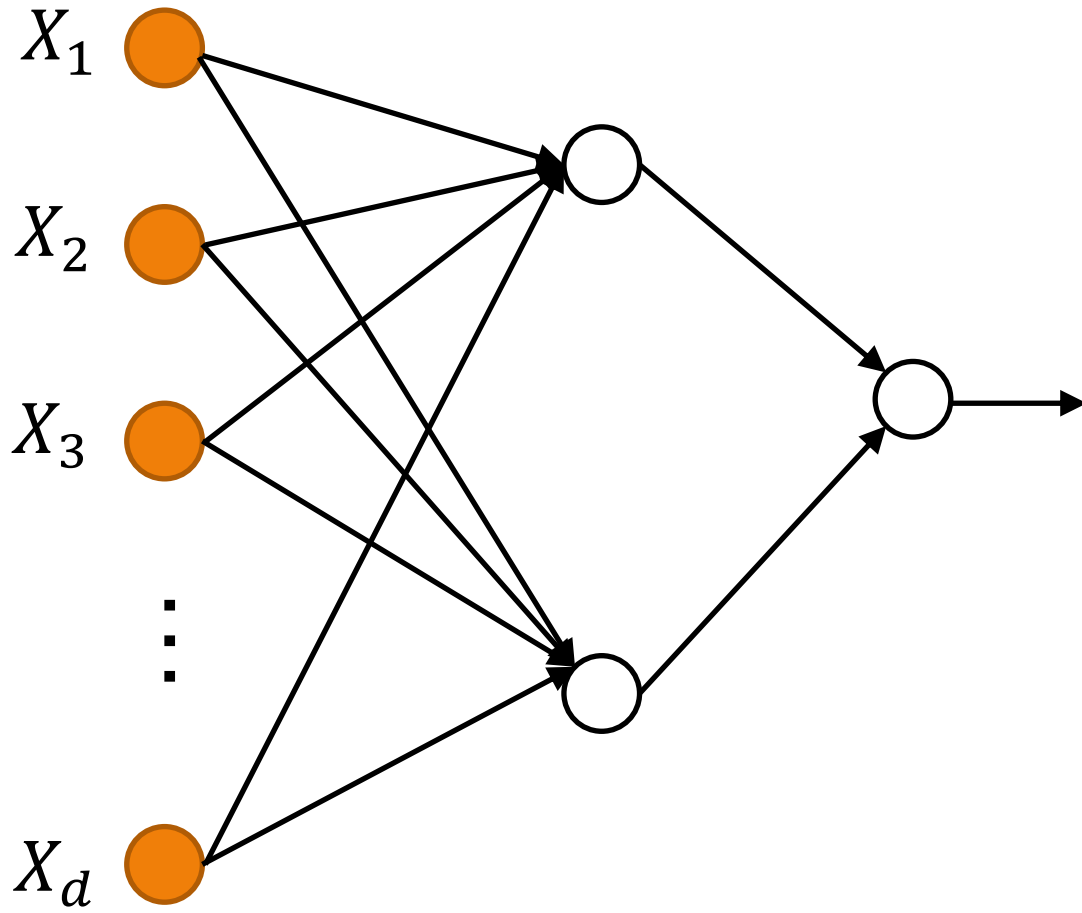
Lets add one more neuron



But my desired function
is from **d**-dimension to
one dimension.

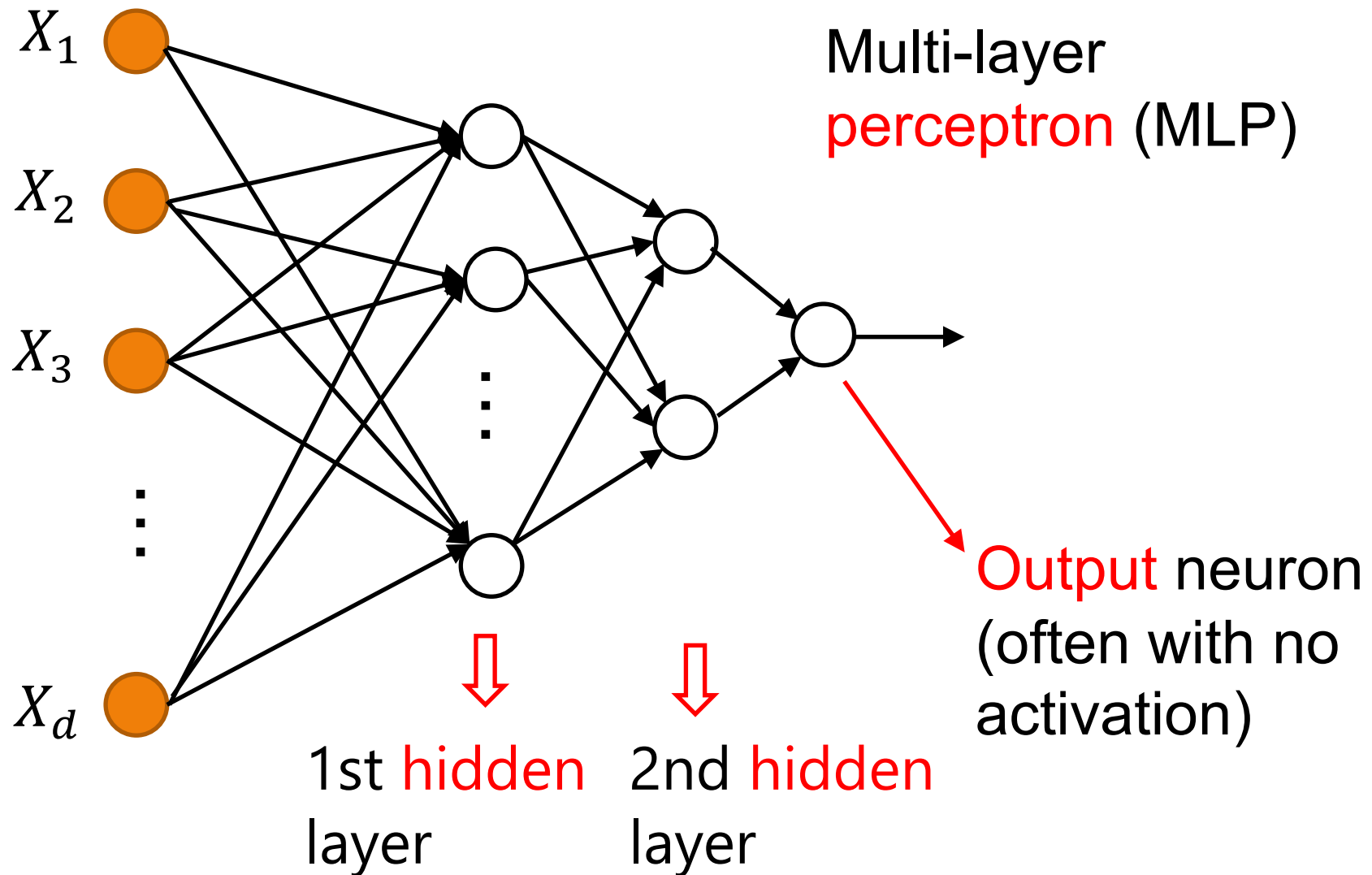
How can I resolve this?

Lets add one more neuron



Can we add more neurons?

Multi-Layer Neural Network

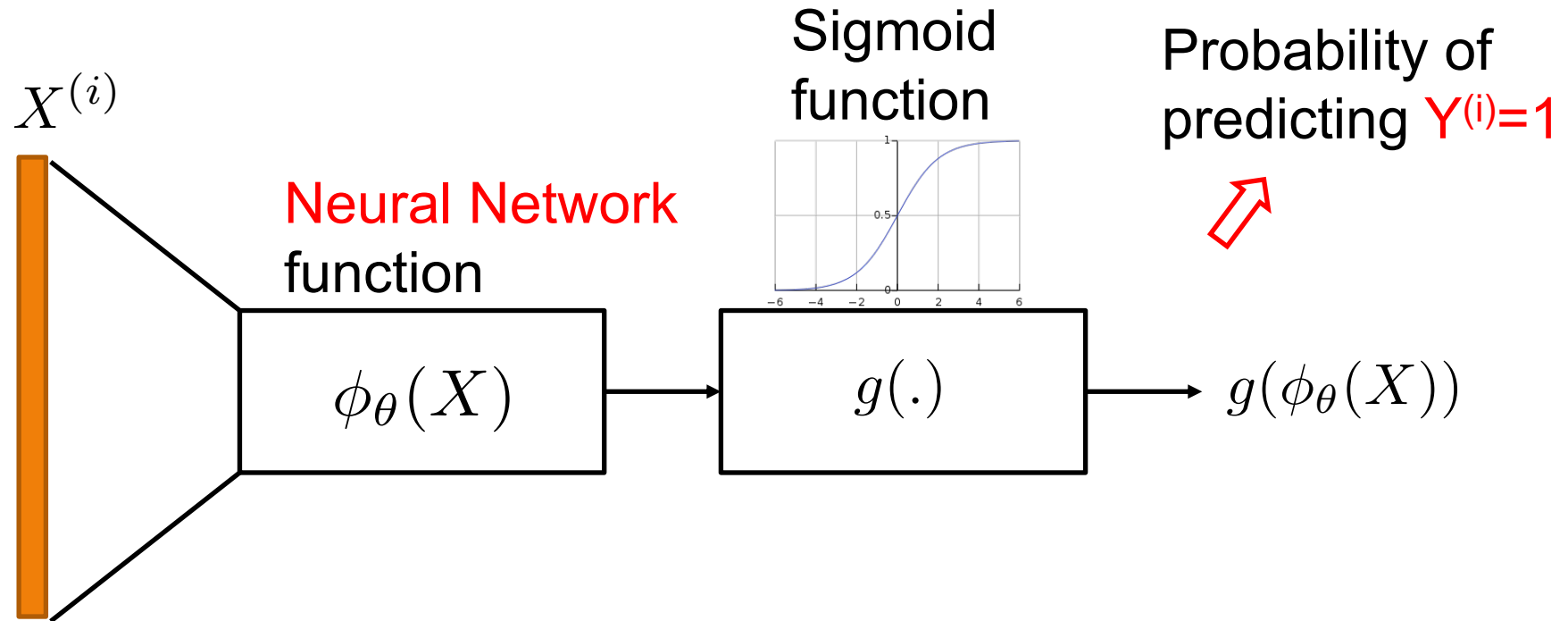


Two-Layer Networks are Universal Function Approximators

- Theorem (Th 9 in CIML):

Let F be a continuous function on a bounded subset of D -dimensional space. Then there exists a two-layer neural network \hat{F} with a finite number of hidden units that approximates F arbitrarily well. Namely, for all x in the domain of F , $|F(x) - \hat{F}(x)| < \epsilon$.

Classification using Neural Network



What is θ ?

Pick model parameters using cross-entropy loss optimization

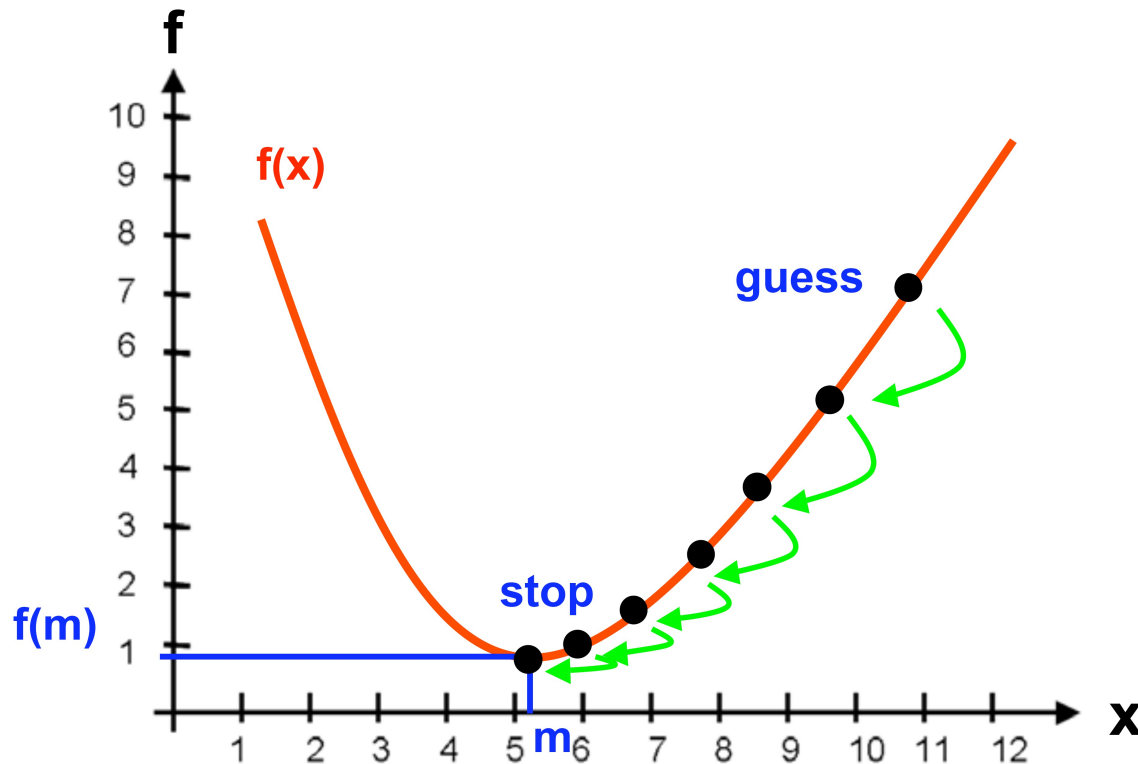
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Neural Networks
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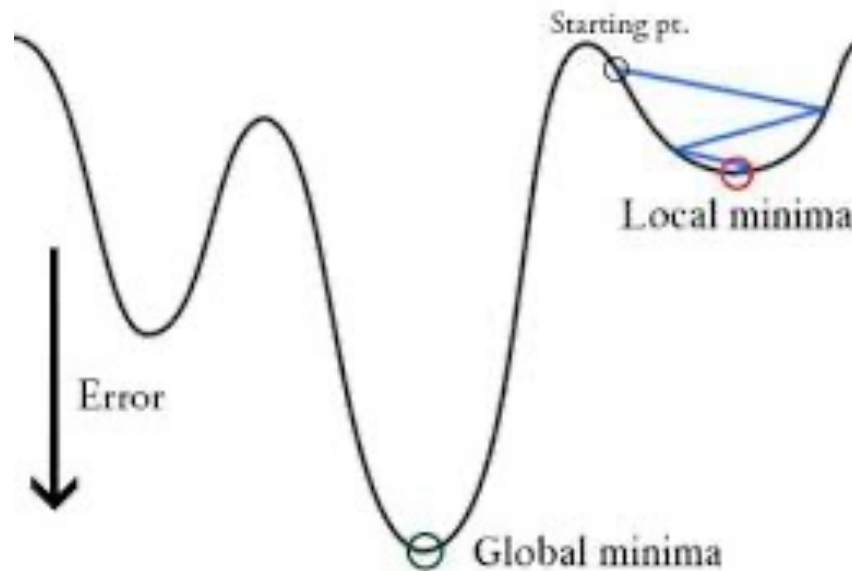
Stochastic Gradient Descent

If the objective of optimization is **convex**



Stochastic Gradient Descent

If the objective of optimization is **non-convex**



In practice, SGD even in a non-convex deep learning optimization performs well. Why?

Stochastic Gradient Descent

What do we need to be able to use SGD in deep learning?

Computation of the **gradient** of the loss function with respect to model parameters

Next lecture, an efficient algorithm for this task!