# CMSC 714
# Lecture 13
# GPUs

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# Notes

- Research project proposal due Monday, March 31, 7PM
  - By email to me – 1 proposal from each group
  - Be sure to include a project name, participants, and a 1-2 page project description
  - Questions?
- MPI project grades posted
- Ryan is working on CUDA project grading
- Midterm exam rescheduled to April 15, in class

# Somewhat Recent (2016) NVIDIA GPU architecture

- Targeted at both HPC workloads and deep learning
  - Supports double precision (64-bit) FP all the way to half-precision (16-bit)
- 6 Graphics Processing Clusters (GPCs), each with 10 Streaming Multiprocessors (SMs), 8 512-bit memory controllers, 4 stacks of HBM2 DRAM (16GB)
- Each SM has 64 CUDA (SIMD) cores, partitioned into 2 32-core blocks, 4 texture units (mainly for graphics operations on bitmap images), 256KB registers
- Each memory controller has 512KB L2 cache, 2 controllers for each HBM2 memory stack

# A Streaming Multiprocessor (SM)

- 2 blocks of 32 single-precision (FP32) cores (or 32 total double-precision (FP64)), each with instruction buffer, warp scheduler (warp is a set of SIMD threads), 2 dispatch units
  - And 64KB shared memory per SM plus an L1 cache – to gather data for all threads of a warp before loading into registers
  - 4MB L2 cache is shared across all SMs
- Atomic memory operations
  - For shared memory operations (synchronization) between threads/warps (even on different GPUs), using Unified Memory and NVLink

# Additional features

- RDMA via GPUDirect
  - To allow other devices (e.g., Infiniband, SSD) to directly access memory on multiple GPUs – can help with MPI latency for sends/receives to/from GPU memory
- HBM2 memory
  - Provides very high bandwidth DRAM by directly connecting stacks of memory dies vertically, with vias (holes) through the dies to connect them to the GPU die
  - 4-8 DRAM dies per stack, up to 8 Gb per die, up to 180GB/sec per stack, max 4 stacks per GPU
  - SECDED error correction

# Additional features

- NVLink high speed interconnect
  - High speed bus connecting pairs (or more) of GPUs, much higher bandwidth than PCIe – 40GB/sec bidirectional bandwidth
  - Helps support shared memory across GPUs – full support for atomic operations across GPUs
  - For even higher bandwidth, can combine up to 4 links into 1 connection – 160GB/sec
  - Can also be used to connect to NVLink-enabled CPU
- Unified Memory
  - Basically gives single virtual address space across GPU and CPU memory, so physical pages can be mapped from both sides
  - Helps limit copies, and with irregular memory accesses in warps
  - For performance, still need to maintain locality
  - Simplifies user programs, since no special memory allocator needed
  - Paging mechanism guarantees global coherency across GPU and CPU memory

# More recent GPUs - Ampere

- Recent focus on machine learning (ML) training and inference applications
  - Focusing on deep neural networks (DNNs) of various types
  - Training is the really computationally expensive part
  - Very high performance obtained by DL-specific data types and instructions – FP32, FP16, INT8, and INT4, BFLOAT16
  - Most recent Ampere architecture added support for sparse data computations (of a very specific type needed for DL training and inference)

# HPC Features in Ampere

- Added some support for barrier operations to ease coordination of asynchronous tasks (so more flexibility), and for collective operations
- Tensor core support for FP64 (double precision floating point) operations
- Higher bandwidth NVLink (up to 600GB/s off chip)
  - To scale up connect up to 8 GPUs
- Application performance still limited by memory bandwidth, even with new generations of HBM
- Paper notes that until recently the GPU programming model has been UMA (any SM can access any memory available in a GPU at same speed), but that can no longer be sustained
  - Programs (and programmers) have to be aware of NUMA to get the best performance

# GPUs vs. CPUs

- Study targeting throughput computing
  - Also called streaming applications sometimes, or data parallel
- Architectural limits to parallelism
  - CPUs have limited number of cores
  - GPUs have limited capabilities, e.g., no caches (not true now)
- End results, on a set of representative benchmarks, is that GPU performs 2.5X faster than CPU
  - Application kernels include linear algebra (SGEMM from BLAS), Monte Carlo, Convolution, FFT, SAXPY (from BLAS), Lattice Boltzman (CFD), Constraint Solver, Sparse Matrix/Vector Multiply, Collision Detection (virtual environments), Radix Sort, Ray Casting, Index Search, Histogram, Bilateral Filter (image processing)
  - Platforms are Intel Core i7 CPU (4 hyper-threaded cores, 4-wide SIMD units, and caches) and NVIDIA GTX280 GPU (array of 30 SMs, each with 8 scalar processing units and local memory)

# GPUs vs. CPUs

- Main advantage of CPU is caches
  - For fast single thread performance, but also helps with multi-threaded apps
  - Disadvantage is complexity, limiting number of cores per chip
  - Also have fast synchronization
- Main advantage of GPU is high throughput
  - each instruction for an SM executes on 8 scalar units (32 data elements)
  - Disadvantage is need to move data explicitly into (small) SM memory from large shared memory
  - Also have support for gather/scatter from memory and special functional units (e.g., texture sampling, math ops)
- Performance measurements for GPU assume data already in GPU memory (from other GPU computations)
- Overall performance of GPU (geometric mean) is 2.5X of CPU ($n^{th}$ root of product of speedups)
  - Why? Because they optimized both CPU and GPU versions of the kernels