
Due on Wednesday 26

Problem 1: Every instance of the stable matching problem allows at least one stable matching; however, in some cases more than one may exist. Design an algorithm to test whether a given instance has a single stable matching or more than one.

Problem 2: From the book: Exercise 3.10.

Problem 3: The strongly connected components algorithm presented in class seems to be more complicated than it should be. In particular, do we really need to use G^{rev} ? Consider the following simpler algorithm:

- i) call $\text{DFS}(G)$ to compute finishing times $f[u]$ for every vertex u .
- ii) call $\text{DFS}(G)$ processing vertices in the main loop in **increasing** order of $f[u]$.
- iii) output each tree in the second DFS forest as a separate component.

Prove or disprove the correctness of the above algorithm.

Problem 4: Show how to modify the DFS algorithm presented in class to compute $\text{low}[u]$ for every vertex u in $O(n + m)$ time.

Problem 5: Let G be a directed graph with vertices numbered $1 \dots n$. For a vertex i define $\text{small}(i) = \min\{j \mid j \text{ is reachable from } i\}$, that is, the smallest vertex reachable from i . Design an $O(n + m)$ time algorithm that computes $\text{small}(i)$ for *every* vertex in the graph.

Problem (extra credit): In a directed graph, a *get-stuck* vertex has in-degree $n - 1$ and out-degree 0. Assume the adjacency matrix representation is used. Design an $O(n)$ algorithm to test if a given graph has a get-stuck vertex. Yes, this problem can be solved without looking at the entire input matrix.