

CMSC330

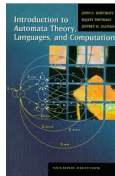
Finite Automata 2

Last Lecture

- Finite automata
 - Alphabet, states...
 - $(\Sigma, Q, q_0, F, \delta)$
- Types
 - Deterministic (DFA)
 -
 - Non-deterministic (NFA)
 -
- Reducing RE to NFA
 - Concatenation
 -
 - Union
 -
 - Closure
 -

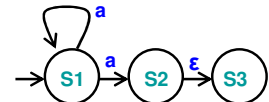
This Lecture

- Reducing NFA to DFA*
 - ϵ -closure
 - Subset algorithm
- Minimizing DFA*
 - Hopcroft reduction
- Complementing DFA
- Implementing DFA*



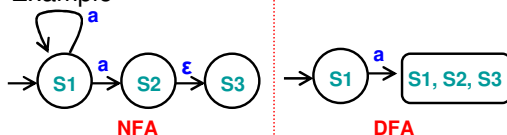
How NFA Works

- When NFA processes a string
 - NFA may be in several possible states
 - Multiple transitions with same label
 - ϵ -transitions
- Example
 - After processing "a"
 - NFA may be in states
 - S1
 - S2
 - S3



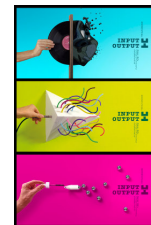
Reducing NFA to DFA

- NFA may be reduced to DFA
 - By explicitly tracking the set of NFA states
- Intuition
 - Build DFA where
 - Each DFA state represents a set of NFA states
- Example



Reducing NFA to DFA (cont.)

- Reduction applied using the **subset** algorithm
 - DFA state is a subset of set of all NFA states
- Algorithm
 - Input
 - NFA $(\Sigma, Q, q_0, F_n, \delta)$
 - Output
 - DFA $(\Sigma, R, r_0, F_d, \delta)$
 - Using
 - ϵ -closure(p)
 - move(p, a)



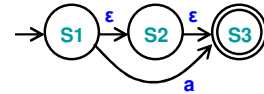
ϵ -transitions and ϵ -closure

- We say $p \xrightarrow{\epsilon} q$
 - If it is possible to go from state p to state q by taking only ϵ -transitions
 - If $\exists p, p_1, p_2, \dots, p_n, q \in Q$ such that
 - $\{p, \epsilon, p_1\} \in \delta, \{p_1, \epsilon, p_2\} \in \delta, \dots, \{p_n, \epsilon, q\} \in \delta$
- ϵ -closure(p)
 - Set of states reachable from p using ϵ -transitions alone
 - Set of states q such that $p \xrightarrow{\epsilon} q$
 - ϵ -closure(p) = $\{q \mid p \xrightarrow{\epsilon} q\}$
 - Note
 - ϵ -closure(p) always includes p
 - ϵ -closure($\cdot$) may be applied to set of states (take union)



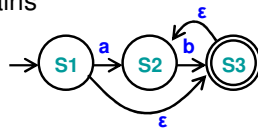
ϵ -closure: Example 1

- Following NFA contains
 - $S1 \xrightarrow{\epsilon} S2$
 - $S2 \xrightarrow{\epsilon} S3$
 - $S1 \xrightarrow{a} S3$
- ϵ -closures
 - ϵ -closure($S1$) = $\{S1, S2, S3\}$
 - ϵ -closure($S2$) = $\{S2, S3\}$
 - ϵ -closure($S3$) = $\{S3\}$
 - ϵ -closure($\{S1, S2\}$) = $\{S1, S2, S3\} \cup \{S2, S3\}$

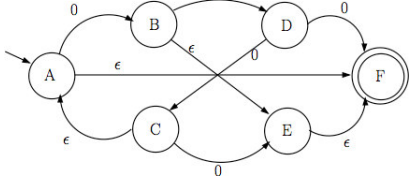


ϵ -closure: Example 2

- Following NFA contains
 - $S1 \xrightarrow{\epsilon} S3$
 - $S3 \xrightarrow{\epsilon} S2$
 - $S1 \xrightarrow{a} S2$
 - $S2 \xrightarrow{b} S3$
 - $S2 \xrightarrow{\epsilon} S1$
- ϵ -closures
 - ϵ -closure($S1$) = $\{S1, S2, S3\}$
 - ϵ -closure($S2$) = $\{S2\}$
 - ϵ -closure($S3$) = $\{S2, S3\}$
 - ϵ -closure($\{S2, S3\}$) = $\{S2\} \cup \{S2, S3\}$



ϵ -closure: Practice

- Find ϵ -closures for following NFA
 
- Find ϵ -closures for the NFA you construct for
 - The regular expression $(0|1^*)111(0^*|1)$

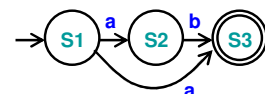
Calculating $\text{move}(p, a)$

- $\text{move}(p, a)$
 - Set of states reachable from p using exactly one transition on a
 - Set of states q such that $\{p, a, q\} \in \delta$
 - $\text{move}(p, a) = \{q \mid \{p, a, q\} \in \delta\}$
 - Note $\text{move}(p, a)$ may be empty $\emptyset$
 - If no transition from p with label a

MOVE

$\text{move}(p, a)$: Example 1

- Following NFA
 - $\Sigma = \{a, b\}$
- Move
 - $\text{move}(S1, a) = \{S2, S3\}$
 - $\text{move}(S1, b) = \emptyset$
 - $\text{move}(S2, a) = \emptyset$
 - $\text{move}(S2, b) = \{S3\}$
 - $\text{move}(S3, a) = \emptyset$
 - $\text{move}(S3, b) = \emptyset$



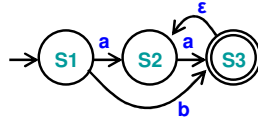
move(p,a) : Example 2

- Following NFA

- $\Sigma = \{a, b\}$

- Move

- $\text{move}(S1, a) = \{S2\}$
- $\text{move}(S1, b) = \{S3\}$
- $\text{move}(S2, a) = \{S3\}$
- $\text{move}(S2, b) = \emptyset$
- $\text{move}(S3, a) = \emptyset$
- $\text{move}(S3, b) = \emptyset$



NFA $\rightarrow$ DFA Reduction Algorithm

- Input NFA $(\Sigma, Q, q_0, F_n, \delta)$,
Output DFA $(\Sigma, R, r_0, F_d, \delta)$
- Algorithm
 - Let $r_0 = \epsilon\text{-closure}(q_0)$, add it to R // DFA start state
 - While $\exists$ an unmarked state $r \in R$ // process DFA state r
 - Mark r // each state visited once
 - For each $a \in \Sigma$ // for each letter a
 - Let $S = \{s \mid q \in r \ \& \ \text{move}(q,a) = s\}$ // states reached via a
 - Let $e = \epsilon\text{-closure}(S)$ // states reached via ϵ
 - If $e \notin R$ // if state e is new
 - Let $R = R \cup \{e\}$ // add e to R (unmarked)
 - Let $\delta = \delta \cup \{r, a, e\}$ // add transition $r \xrightarrow{a} e$
 - Let $F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$ // final if include state in F_n



NFA $\rightarrow$ DFA Example 1

- Start = $\epsilon\text{-closure}(S1) = \{\{S1, S3\}\}$

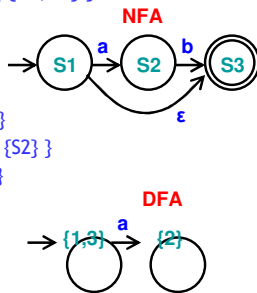
- $R = \{\{S1, S3\}\}$

- $r \in R = \{S1, S3\}$

- $\text{Move}(\{S1, S3\}, a) = \{S2\}$

- $e = \epsilon\text{-closure}(\{S2\}) = \{S2\}$
- $R = R \cup \{S2\} = \{\{S1, S3\}, \{S2\}\}$
- $\delta = \delta \cup \{\{S1, S3\}, a, \{S2\}\}$

- $\text{Move}(\{S1, S3\}, b) = \emptyset$



NFA $\rightarrow$ DFA Example 1 (cont.)

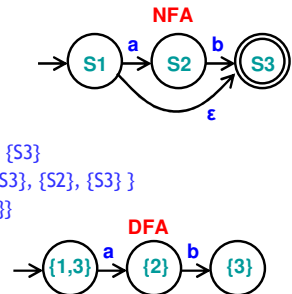
- $R = \{\{S1, S3\}, \{S2\}\}$

- $r \in R = \{S2\}$

- $\text{Move}(\{S2\}, a) = \emptyset$

- $\text{Move}(\{S2\}, b) = \{S3\}$

- $e = \epsilon\text{-closure}(\{S3\}) = \{S3\}$
- $R = R \cup \{S3\} = \{\{S1, S3\}, \{S2\}, \{S3\}\}$
- $\delta = \delta \cup \{\{S2\}, b, \{S3\}\}$



NFA $\rightarrow$ DFA Example 1 (cont.)

- $R = \{\{S1, S3\}, \{S2\}, \{S3\}\}$

- $r \in R = \{S3\}$

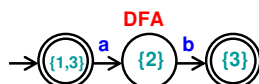
- $\text{Move}(\{S3\}, a) = \emptyset$

- $\text{Move}(\{S3\}, b) = \emptyset$

- $F_d = \{\{S1, S3\}, \{S3\}\}$

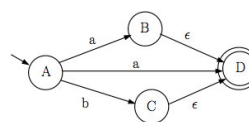
- Since $S3 \in F_n$

- Done!

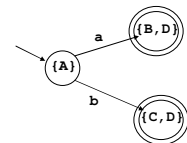


NFA $\rightarrow$ DFA Example 2

- NFA



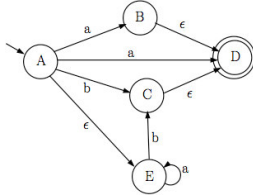
- DFA



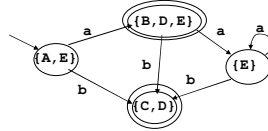
$R = \{\{A\}, \{B, D\}, \{C, D\}\}$

NFA → DFA Example 3

• NFA



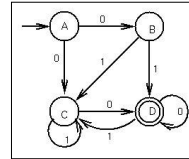
• DFA



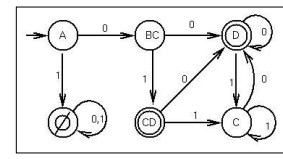
$$R = \{ \{A, E\}, \{B, D, E\}, \{C, D\}, \{E\} \}$$

Equivalence of DFAs and NFAs

- Any string from $\{A\}$ to either $\{D\}$ or $\{CD\}$
 - Represents a path from A to D in the original



NFA



DFA

Equivalence of DFAs and NFAs (cont.)

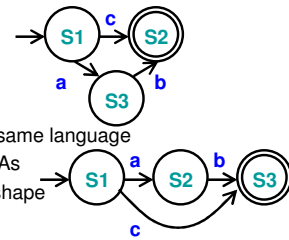
- Can reduce any NFA to a DFA using subset algorithm
- How many states in the DFA?
 - Each DFA state is a subset of the set of NFA states
 - Given NFA with n states, DFA may have 2^n states
 - Since a set with n items may have 2^n subsets
 - Corollary
 - Reducing a NFA with n states may be $O(2^n)$



Minimizing DFA



- Result from CS theory
 - Every regular language is recognizable by a minimum-state DFA that is **unique** up to state names
- In other words
 - For every DFA, there is a unique DFA with minimum number of states that accepts the same language
 - Two minimum-state DFAs have **same** underlying shape



Minimizing DFA: Hopcroft Reduction



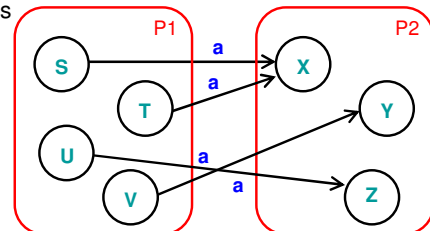
- Intuition
 - Look for states that can be distinguished from each other
 - End up in different accept / non-accept state with identical input
- Algorithm
 - Construct **initial partition**
 - Accepting & non-accepting states
 - Iteratively **refine partitions** (until partitions remain fixed)
 - Split a partition if members in partition have transitions to different partitions for same input
 - Two states x, y belong in same partition if and only if for all symbols in Σ they transition to the same partition
 - Update transitions & remove dead states

J. Hopcroft, "An $n \log n$ algorithm for minimizing states in a finite automaton," 1971

Splitting Partitions

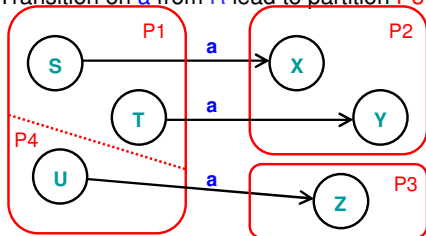


- No need to split partition $\{S, T, U, V\}$
 - All transitions on a lead to identical partition $P2$
 - Even though transitions on a lead to different states



Splitting Partitions (cont.)

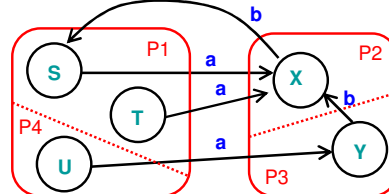
- Need to split partition $\{S, T, U\}$ into $\{S, T\}, \{U\}$
 - Transitions on a from S, T lead to partition $P2$
 - Transition on a from U lead to partition $P3$



Resplitting Partitions

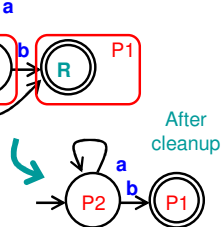


- Need to reexamine partitions after splits
 - Initially no need to split partition $\{S, T, U\}$
 - After splitting partition $\{X, Y\}$ into $\{X\}, \{Y\}$
 - Need to split partition $\{S, T, U\}$ into $\{S, T\}, \{U\}$



Minimizing DFA: Example 1

- DFA
- Initial partitions
 - Accept $\{R\} \rightarrow P1$
 - Reject $\{S, T\} \rightarrow P2$
- Split partition? → Not required, minimization done
 - move(S,a) = T → P2 move(S,b) = R → P1
 - move(T,a) = T → P2 move(T,b) = R → P1



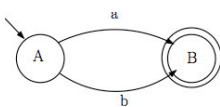
Minimizing DFA: Example 2

- DFA
- Initial partitions
 - Accept $\{R\} \rightarrow P1$
 - Reject $\{S, T\} \rightarrow P2$
- Split partition? → Yes, different partitions for B
 - move(S,a) = T → P2 move(S,b) = T → P2
 - move(T,a) = T → P2 move(T,b) = R → P1

DFA already minimal

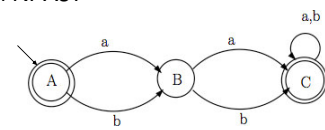
Complement of DFA

- Given a DFA accepting language L
 - How can we create a DFA accepting its complement?
 - Example DFA
 - $\Sigma = \{a, b\}$



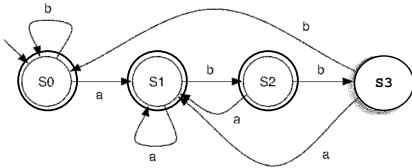
Complement of DFA (cont.)

- Algorithm
 - Add explicit transitions to a dead state
 - Change every accepting state to a non-accepting state & every non-accepting state to an accepting state
- Note this **only** works with DFAs
 - Why not with NFAs?



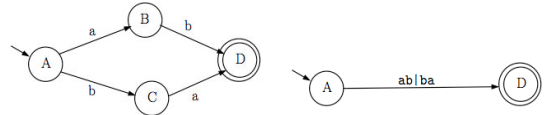
Practice

Make the DFA which accepts the complement of the language accepted by the DFA below.



Reducing DFAs to REs

- General idea
 - Remove states one by one, labeling transitions with regular expressions
 - When two states are left (start and final), the transition label is the regular expression for the DFA



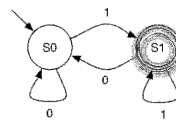
Relating REs to DFAs and NFAs

- Why do we want to convert between these?
 - Can make it easier to express ideas
 - Can be easier to implement



Implementing DFAs

It's easy to build a program which mimics a DFA



```

cur_state = 0;
while (1) {
    symbol = getchar();
    switch (cur_state) {
        case 0: switch (symbol) {
            case '0': cur_state = 0; break;
            case '1': cur_state = 1; break;
            case '\n': printf("rejected\n"); return 0;
            default: printf("rejected\n"); return 0;
        }
        break;
        case 1: switch (symbol) {
            case '0': cur_state = 0; break;
            case '1': cur_state = 1; break;
            case '\n': printf("accepted\n"); return 1;
            default: printf("rejected\n"); return 0;
        }
        break;
        default: printf("unknown state; I'm confused\n");
        break;
    }
}
  
```

Implementing DFAs (Alternative)

Alternatively, use generic table-driven DFA

```

given components (Σ, Q, q₀, F, δ) of a DFA:
let q = q₀
while (there exists another symbol s of the input string)
    q := δ(q, s);
if q ∈ F then
    accept
else reject
  
```

- q is just an integer
- Represent δ using arrays or hash tables
- Represent F as a set

Run Time of DFA

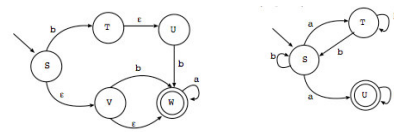
- How long for DFA to decide to accept/reject string s ?
 - Assume we can compute $\delta(q, c)$ in constant time
 - Then time to process s is $O(|s|)$
 - Can't get much faster!
- Constructing DFA for RE A may take $O(2^{|A|})$ time
 - But usually not the case in practice
- So there's the initial overhead
 - But then processing strings is fast

Regular Expressions in Practice

- Regular expressions are typically “compiled” into tables for the generic algorithm
 - Can think of this as a simple byte code interpreter
 - But really just a representation of $(\Sigma, Q_A, q_A, \{f_A\}, \delta_A)$, the components of the DFA produced from the RE
- Regular expression implementations often have extra constructs that are non-regular
 - I.e., can accept more than the regular languages
 - Can be useful in certain cases
 - Disadvantages
 - Nonstandard, plus can have higher complexity

Practice

- Convert to a DFA



- Convert to an NFA and then to a DFA

- $(0|1)^*11|0^*$

– Strings of alternating 0 and 1

- $aba^*(ba|b)$

Summary of Regular Expression Theory

- Finite automata
 - DFA, NFA
- Equivalence of RE, NFA, DFA
 - RE $\rightarrow$ NFA
 - Concatenation, union, closure
 - NFA $\rightarrow$ DFA
 - ϵ -closure & subset algorithm
- DFA
 - Minimization, complement
 - Implementation

Discussion Tomorrow

- I will be in cville
- Going through
 - regexp $\rightarrow$ NFA $\rightarrow$ DFA $\rightarrow$ minimization examples
- Quiz!
 - Your ego at work here...
 - Everything from last week (so no RE theory, no NFA/DFA)