

CMSC 216

Introduction to Computer Systems

Lecture 11

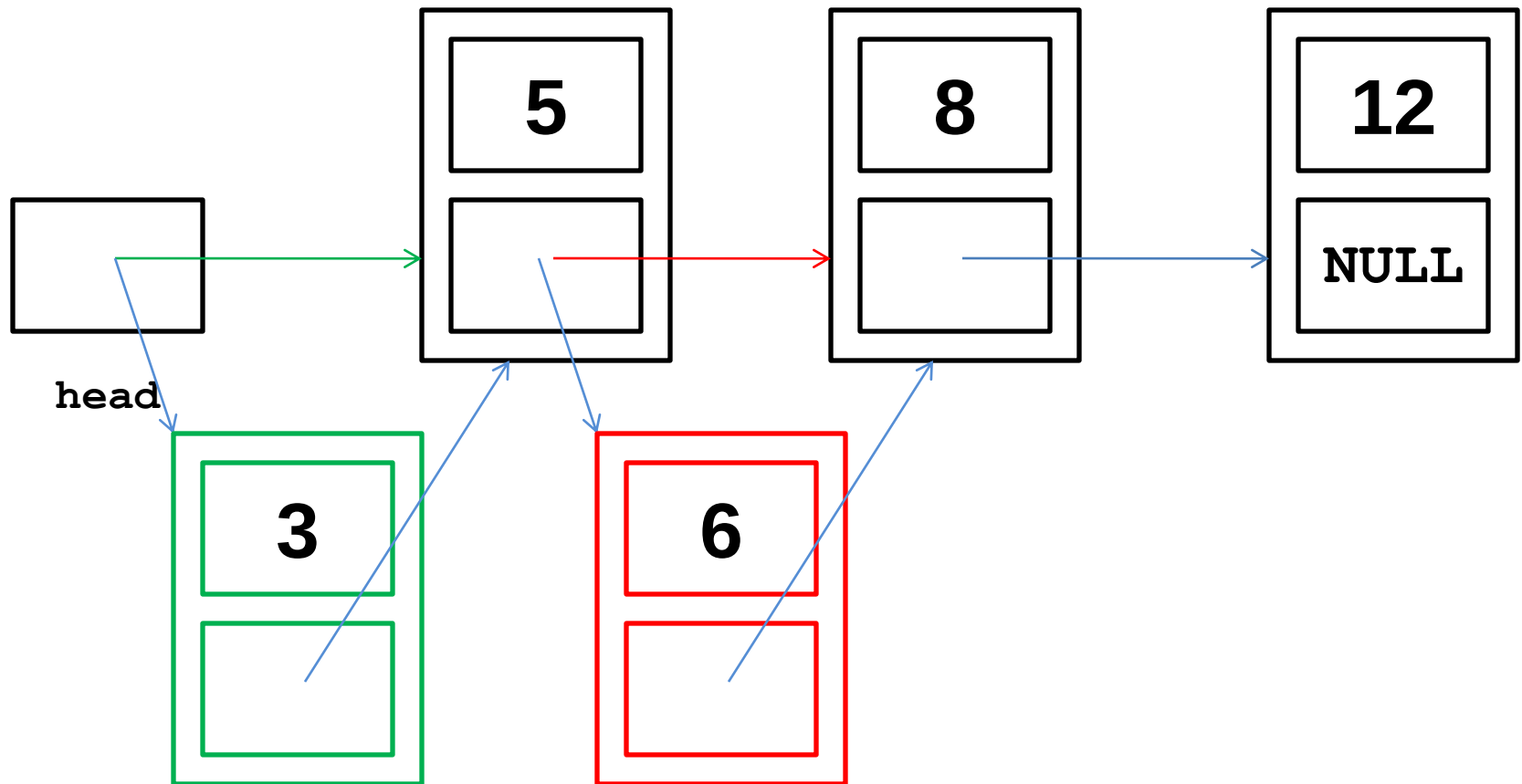
Linked Lists (cont) &

Assembly Language Programming

Administrivia

- Read Chapter 11, Reek

Deleting from a linked list



Tracing deletion

```
int delete(Node **head, int value) {
    Node *prev = NULL, *current = *head;
    while (current != NULL && current->data != value) {
        prev = current;
        current = current->next;
    }
    if (current == NULL)
        return 0; /* not found */
    if (prev != NULL)
        prev->next = current->next;
    else
        *head = current->next; /* deleted first item */
    free(current);
    return 1;
}
```

Doubly linked lists

- We can have references in both directions
- Allows use of only one pointer when performing some operations

```
typedef struct dl_node {  
    struct dl_node *prev;  
    struct dl_node *next;  
    int val;  
} DL_node;
```

Deletion from a doubly linked list

```
int delete(DL_node **root, int target) {
    DL_node *current;
    for (current = *root; current != NULL; current = current->next)
        if (current->val == target)
            break;
    if (current == NULL)
        return 0;
    if (current == *root)
        *root = current->next;
    else
        current->prev->next = current->next;
    if (current->next != NULL)
        current->next->prev = current->prev;
    free(current);
    return 1;
}
```

Chapters 3 and 4.1, Bryant and O'Hallaron

ASSEMBLY LANGUAGE

Assembly language

- The CPU uses machine language to perform all its operations
- Assembly is a much more readable translation of machine language, and it is what we work with if we need to see what the computer is doing
- Many different kinds of assembly languages; we'll focus on the Y86 language defined in the text (with minor modifications)

An example of Y86 assembly

- The summation of all integers from 1 to 1000:

```
        irmovl $0,%eax      # sum = 0
        irmovl $1,%ecx      # num = 1
Loop:   addl    %ecx,%eax    # sum += num
        irmovl $1,%edx      # tmp = 1
        addl    %edx,%ecx    # num++
        irmovl $1000,%edx   # lim = 1000
        subl    %ecx,%edx    # if lim - num >= 0
        jge     Loop        # loop again

        wrint   %eax        # printf("%d", sum)
        irmovl $10,%edx     # ch = '\n'
        wrch    %edx        # printf("%c", ch)
        halt
```

Assembling assembly

- Machine code (pure numbers) is generated by translating each instruction into binary numbers that the CPU uses
- This process is called "assembling"; conversely, we can take assembled code and disassemble it into (mostly) human readable assembly language

Assembly language concepts

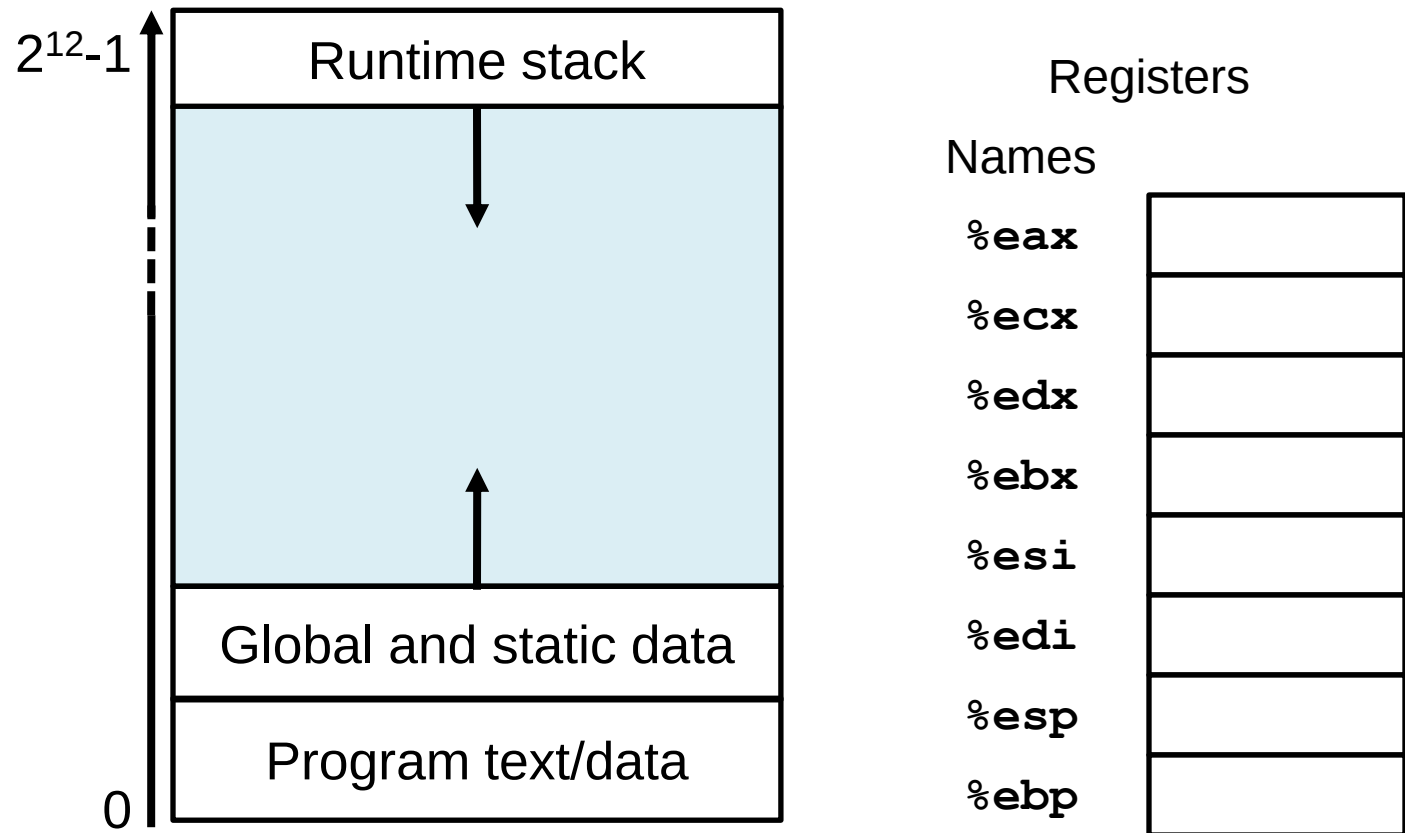
- Registers
 - Fast-access locations that the CPU uses, rather than storing all variables in memory
 - In the code we'll be examining, these are named by three-letter codes, and begin with %
 - **%eax, %ebx**
 - Y86 has 8 registers, listed on pg. 168 in Figure 3.2 (shown in another slide)
- Memory
 - Program text is here, along with any data which cannot fit in the registers
 - Since there are usually many different pieces of data involved in a program, and a limited number of registers, program variables are stored in memory when not in immediate use

Memory Organization

- Word → 4 bytes
- Address → specifies first byte in word
- Big Endian vs. Little Endian
 - Assume word has value 0x01234567
 - Assume address for value is 0x300
 - Big Endian
 - Least significant byte has **highest** address
 - 01 → 0x300
 - 23 → 0x301
 - 45 → 0x302
 - 67 → 0x303
 - “Normal layout of data”
 - Little Endian
 - Least significant byte has **lowest** address
 - 67 → 0x300
 - 45 → 0x301
 - 23 → 0x302
 - 01 → 0x303
 - Reverse of “normal layout”

Y86 program state

- 2^{12} bytes of memory (4096 bytes)
- You can set the stack to start somewhere other than 0x1000 (4096), but you have to explicitly set it (%esp is 0 by default)



Y86 Registers

- %eax, %ecx, %edx, %ebx, %esi, %edi
 - For the most part are considered general-purpose registers
 - Corresponding (IDs) 0, 1, 2, 3, 6, 7
- %es

red

p → stack pointer
 - ID → 4
- %eb

red

p → frame pointer
 - ID → 5
- Register ID 8 indicates “no register”

Instruction encoding

- In any assembly language, each instruction name has a numeric opcode associated with it; Y86 opcodes use one byte each
- Registers also have a numeric mapping, as do labels (as we just saw)
- These numbers are used to encode each instruction into a number
- In Y86, instructions have variable lengths, and **are not aligned**; most take 6 bytes, but some use fewer

Encoding examples

- In Y86, the **addl** (add integers) instruction has the opcode of **0x60**
 - 1 → “long” words (4-byte integers)
- The register names **%edx** and **%ecx** map to numbers 2 and 1, respectively
- The encoding for an **addl** instruction is specified by the Y86 instruction set as following this format (pgs. 259, 261):

byte 0		byte 1	
6	0	rA	rB

 - **addl** rA, rB
- So what would the numeric encoding of **addl %edx, %ecx** be?
 - **0x6021**
- The **subl** (subtract integers) instruction works in a similar way

Working with Y86

- Source code is usually stored in ***.ys** files
- On the Grace systems, there are two programs available in **~/216public/bin** for working with Y86 programs
- **yas** is the Y86 assembler, which creates ***.yo** files
 - Run like this: **yas prog.ys**
- **yis** is the Y86 simulator, which operates on ***.yo** files
 - Run like this: **yis prog.yo**
- You can just type **yas** and **yis** (you don't need to access them in bin)

Assembly language instructions

- These typically have an instruction name, a list of registers, and sometimes have a constant value too
- Example: `simple.ys`
 - Let's run `yas simple.ys`
 - Run the simulator `yis simple.yo`
 - PC → Program Counter
 - Address of instruction to be executed
 - CC → Condition codes (single-bit flags set by logical or arithmetic instruction
 - Z (Zero), S (Negative), O (Overflow)
 - Words (4-bytes) stored in little-endian
 - Let's see the contents of `simple.yo`

halt

- Without a **halt** instruction, the simulator will attempt to read in possibly invalid instructions

Assembler directives

Directive	Effect
<code>.pos number</code>	Subsequent lines of code start at address number
<code>.align number</code>	Align the next line to a number -byte boundary
<code>.long number</code>	Put number at the current address in memory

- These can be used to set up memory in various places in the address space
- `.pos` can put sections of code in different places in memory
- `.align` should be used before setting up a static variable
- `.long` can be used to initialize a static variable

Y86 data movement instructions

Instruction	Effect	Description
irmovl V,R	$\text{Reg}[R] \leftarrow V$	Immediate-to-register move
rrmovl rA,rB	$\text{Reg}[rB] \leftarrow \text{Reg}[rA]$	Register-to-register move
rmmovl rA,D(rB)	$\text{Mem}[\text{Reg}[rB]+D] \leftarrow \text{Reg}[rA]$	Register-to-memory move
mrmovl D(rA),rB	$\text{Reg}[rB] \leftarrow \text{Mem}[\text{Reg}[rA]+D]$	Memory-to-register move

- **irmovl** is used to place known numeric values (labels or numeric literals) into registers
- **rrmovl** copies a value between registers
- **rmmovl** stores a word in memory
- **mrmovl** loads a word from memory
- **rmmovl** and **mrmovl** are the only instructions that access memory - Y86 is a load/store architecture

Examples of data movement

```
irmovl $55,%edx      # d = 55
rrmovl %edx,%ebx     # b = d
irmovl Array,%eax    # a = Array
rmmovl %ebx,4(%eax)  # a[1] = 55
mrmovl 0(%eax),%ecx  # c = a[0]
halt
```

```
.align 4
```

Array:

```
.long 0x6f
```

```
.long 0x84
```

Data movement example, cont.

- Assembler output:

```
0x000: 308237000000 | irmovl $55,%edx      # d = 55
0x006: 2023          | rrmovl %edx,%ebx     # b = d
0x008: 30801c000000 | irmovl Array,%eax    # a = Array
0x00e: 403004000000 | rmmovl %ebx,4(%eax)  # a[1] = 55
0x014: 501000000000 | mrmovl 0(%eax),%ecx  # c = a[0]
0x01a: 10           | halt
0x01c:              |
0x01c:              | .align 4
0x01c:              | Array:
0x01c: 6f000000     | .long 0x6f
0x020: 84000000     | .long 0x84
```

- Simulator output:

Stopped in 6 steps at PC = 0x1b. Exception 'HLT', CC Z=1 S=0 O=0

Changes to registers:

%eax:	0x00000000	0x0000001c
%ecx:	0x00000000	0x0000006f
%edx:	0x00000000	0x00000037
%ebx:	0x00000000	0x00000037

Changes to memory:

0x0020: 0x00000084	0x00000037
--------------------	------------

Y86 input/output instructions

Instruction	Effect	Description
<code>rdch R</code>	<code>scanf("%c", &Reg[R])</code>	Read character
<code>rdint R</code>	<code>scanf("%d", &Reg[R])</code>	Read integer
<code>wrch R</code>	<code>printf("%c", Reg[R])</code>	Write character
<code>wrint R</code>	<code>printf("%d", Reg[R])</code>	Write integer

- All these instructions are extensions to Y86 we've added to the ones in the book
- These are what allow you to interact with the simulator and write more interesting programs

I/O example

- Assembler output:

```
0x000: f208      | rdint  %eax      # a = 65 (via scanf())
0x002: f038      | rdch   %ebx      # b = 'B' (via scanf())
0x004: f308      | wrint  %eax      # printf("%d", a)
0x006: f108      | wrch   %eax      # printf("%c", a)
0x008: f338      | wrint  %ebx      # printf("%d", b)
0x00a: f138      | wrch   %ebx      # printf("%c", b)
0x00c: 30810a000000 | irmovl $10,%ecx # c = 10
0x012: f118      | wrch   %ecx      # printf("%c", c)
0x014: 10        | halt
```

- Simulator run:

```
$ echo 65B | yis io.yo
```

```
65A66B
```

```
Stopped in 9 steps at PC = 0x15.  Exception 'HLT', CC Z=1 S=0 O=0
```

```
Changes to registers:
```

```
%eax:  0x00000000      0x00000041
%ecx:  0x00000000      0x0000000a
%ebx:  0x00000000      0x00000042
```

```
Changes to memory:
```