## The Cook-Levin Theorem

Exposition by William Gasarch—U of MD

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#### Variants of SAT

- 1. SAT is the set of all boolean formulas that are satisfiable. That is,  $\phi(\vec{x}) \in SAT$  if there exists a vector  $\vec{b}$  such that  $\phi(\vec{b}) = TRUE$ .
- 2. CNFSAT is the set of all boolean formulas in SAT of the form  $C_1 \wedge \cdots \wedge C_m$  where each  $C_i$  is an  $\vee$  of literals.
- 3. *k*-SAT is the set of all boolean formulas in SAT of the form  $C_1 \land \cdots \land C_m$  where each  $C_i$  is an  $\lor$  of exactly *k* literals.
- 4. DNFSAT is the set of all boolean formulas in SAT of the form  $C_1 \lor \cdots \lor C_m$  where each  $C_i$  is an  $\land$  of literals.
- 5. *k*-DNFSAT is the set of all boolean formulas in SAT of the form  $C_1 \lor \cdots \lor C_m$  where each  $C_i$  is an  $\land$  of exactly *k* literals.

## **Conventions for our Turing Machines**

- 1. Tape has a left endpoint; however, the tape goes off to infinity to the right.
- 2. The alphabet has symbols  $\{0, 1, \#, \$ Y, N\}$ .
- 3. # is the blank symbol.
- 4. \$ is a separator symbol.
- 5. *Y* and *N* are only used when the machine goes into a halt state. They are YES and NO.
- 6. The input is written on the left. So the input *abba* would be on the tape as

#### $abba \# \# \# \cdots$

 The head is initially on the rightmost symbol of the input. So it he above it wold be on the *a* just before the # symbol.

Let M be a Turing Machine and  $x \in \Sigma^*$ . We represent the computation M(x) as follows:

**Example** The tape has:

 $abba#abcab#a###\cdots$ 

If the machine is in state q and the head is looking at the c then we represent this by:

 $abba#ab(c,q)ab#a###\cdots$ 

Convention—extend alphabet and allow symbols  $\Sigma \times Q$ . The symbol (c, q) means the symbol is c, the state is q, and that square is where the head of the machine is.

We need a term for strings like:

abba # ab(c,q)a

**Definition** Strings in  $\Sigma^*(\Sigma \times Q)\Sigma^*$  are configuration.

The Computation M(x) is represented by a sequence of configs. Key A config is finite since what we don't see is #.

#### Example

#### If $\delta(s, b) = (q, L)$ and $\delta(q, b) = (p, a)$

а	а	b	b	(b, s)	#
а	а	b	(b,q)	b	#
а	а	b	( <i>a</i> , <i>p</i> )	b	#

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- The left endpoint is the end of the tape.
- $\blacktriangleright$  The unseen symbols on the right are all #

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$$X = \{x \mid (\exists y)[|y| = p(|x|) \text{ AND } M(x, y) = Y]\}$$

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M(x, y) runs in time  $\leq q(|x| + |y|) = q(|x| + p(|x|)).$ 

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$$M(x, y) \text{ runs in time } \leq q(|x| + |y|) = q(|x| + p(|x|)).$$
  
Let  $t(n) = q(n + p(n))$ , a poly.

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M(x, y) runs in time  $\leq q(|x| + |y|) = q(|x| + p(|x|))$ . Let t(n) = q(n + p(n)), a poly. Here is ALL that matters:

- Numb of steps M(x, y) takes is ≤ t(|x|). Hence ≤ t(|x|) configs.
- Computation can only look at the first t(|x|) tapes squares on any config.

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## **New Convention**

**Old** Convention

$$\# | a | a | b | b | (s,b) | \#$$

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means that off to the right there are an infinite number of #. New Convention

$$\# a a b b (s,b) \# \cdots \#$$

Tape is t(|x|) long so **know** when stops. Can include entire tape. Key Config is finite since what we don't see is never used.

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### Summary of What's Important

Let  $X \in NP$  via poly q and TM M, so

$$X = \{x : (\exists y)[|y| = q(|x|) \land M(x,y) = Y]$$

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 $x \in X$  implies  $(\exists y)[|y| = q(|x|) \land M(x, y) = Y]$  implies  $(\exists C_1, \ldots, C_t)[C_1, \ldots, C_t \text{ is an accepting comp of } M(x, y)]$ 

## **Cook-Levin Theorem**

Theorem SAT is NP-complete. We need to prove two things: 1. SAT  $\in NP$ .

$$SAT = \{\phi : (\exists \vec{y}) [\phi(\vec{y}) = T]\}$$

Formally

$$B = \{(\phi, \vec{y}) : \phi(\vec{y}) = T\}$$

The satisfying assignment is the witness.

2. For all  $X \in NP$ ,  $X \leq SAT$ . This is the bulk of the proof.

## $x \in X \to \ldots$

If  $x \in X$  then there is a y of length q(|x|) such that M(x, y) = Y. If  $x \in X$  then there is a y and a sequence of configurations  $C_1, C_2, \ldots, C_t$  such that

- C<sub>1</sub> is the configuration that says 'input is x#y, and I am in the starting state.'
- For all *i*,  $C_{i+1}$  follows from  $C_i$  (note that *M* is deterministic) using  $\delta$ .
- $C_t$  is the configuration that is in state h and the output is Y.

▶ t = q(|x| + p(|x|)).

How to make all of this into a formula?

**KEY 1:** We have variables for every possible entry in every possible configuration. The variables are

$$\{z_{i,j,\sigma}: 1 \leq i,j \leq t,\sigma \in \Sigma \cup (Q \times \Sigma)\}$$

If there is an accepting sequence of configurations then  $z_{i,j,\sigma} = T$  iff the *j*th symbol in the *i*th configuration is  $\sigma$ .

## Making the $z_{i,j,\sigma}$ Make Sense

Need that for all  $1 \le i, j \le t$  there exists exactly one  $\sigma$  such that  $z_{ij\sigma}$  is TRUE.

$$\bigvee_{\sigma \in \Sigma \cup (\Sigma \times Q)} z_{i,j,\sigma}$$

for each  $\sigma \in \Sigma \cup (\Sigma \times Q)$ 

$$z_{i,j,\sigma} \to \bigwedge_{\tau \in \Sigma \cup (\Sigma \times Q) - \{\sigma\}} \neg z_{i,j,\tau}$$

#### C<sub>1</sub> is Start Config

 $C_1$  is the  $\bigwedge$  of the following:  $C_1$  starts with x. Let  $x = x_1 \cdots x_n$ .

$$z_{1,1,x_1} \land \cdots \land z_{1,n-1,x_{n-1}}, z_{1,n,(x_n,s)} \land z_{1,n+1,\$}$$

 $C_1$  then has q(|x|) non-# symbols:

$$\bigwedge_{i=n+2}^{n+q(|\mathsf{x}|)+1}\bigvee_{\sigma\in\Sigma-\{\#,\$,\mathsf{Y},\mathsf{N}\}}z_{1,i,\sigma}$$

 $C_1$  then has all blanks:

$$\wedge z_{1,q(n)+n+2,(\#,s)} \wedge \bigwedge_{i=q(n)+n+3}^{t(n)} z_{1,i,\#}$$

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#### C<sub>1</sub> is Start Config: Example

x = ab,  $p(n) = n^2$ , and q(n) = 2n|y| = 4. Input to M is of length 2 + 4 + 1 = 7, so M(x, y) runs  $\leq 2 \times 7 = 14$  steps. Formula saying  $C_1$  codes x as input is

 $z_{1,1,a} \wedge z_{1,2,b} \wedge z_{1,3,\$} \wedge$ 

 $(z_{1,4,a} \lor z_{1,4,b}) \land (z_{1,5,a} \lor z_{1,5,b}) \land (z_{1,6,a} \lor z_{1,6,b}) \land (z_{1,7,a} \lor z_{1,7,b}) \land$ 

 $z_{1,8,\#} \wedge \cdots \wedge z_{1,23,\#}$ 

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## $C_t$ is an Accept Config

**Convention** M(x, y) accepts means M(x, y) leaves a Y on the left most square and the head is on the left most square. The state in  $C_t$  is h, the halt state,

 $Z_{t,1,(Y,h)}$ 

## $C_i$ leads to $C_{i+1}$

Thought Experiment: What if  $\delta(q, a) = (p, b)$ . Then:

$\sigma_1$	(a,q)	$\sigma_2$	
$\sigma_1$	( <i>b</i> , <i>p</i> )	$\sigma_2$	

Formula is a  $\bigwedge$  over relevant  $i, j, \sigma_1, \sigma_2$  of:

$$(z_{ij\sigma_1} \wedge z_{i(j+1),(a,q)} \wedge z_{i,(j+2)\sigma_2}) \rightarrow$$

$$(z_{(i+1)j\sigma_1} \wedge z_{(i+1)(j+1),(b,p)} \wedge z_{(i+1),(j+2)\sigma_2})$$

Thought Experiment: What if  $\delta(q, a) = (p, L)$ . Then:

$\sigma_1$	(a,q)	$\sigma_2$
$(\sigma_1, p)$	а	$\sigma_2$

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One can make a formula out of this as well. (Leave for HW.)

Note that only the symbols at or near the head get changed.

Also need a formula saying that if the (i, j) spot is NOT near the head and  $z_{i,j,\sigma}$  then  $z_{i+1,j,\sigma}$ .

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## Putting it All Together

On input x you output a formula  $\phi$  constructed as follows

- 1. t(|x|) = q(|x| + p(|x|)). We call this t.
- 2. Variables  $\{z_{i,j,\tau} : 1 \leq i,j \leq t, \tau \in \Sigma \cup (\Sigma \times Q)\}.$
- 3. Formula saying:
  - 3.1 For all  $1 \le i, j \le t$ , exists ONE  $\sigma$  with  $z_{i,j,\sigma} = T$ .
  - 3.2  $C_1$  is the start config with x.
  - 3.3  $C_t$  is the accept config.
  - 3.4 For each instruction of the TM have a formula saying  $C_i$  goes to  $C_{i+1}$  if that instruction is relevant.

3.5 If head is not within 2 square of (i, j) and  $z_{ij\sigma}$  then  $z_{(i+1)j\sigma}$ .

#### Important Upshot

- If SAT ∈ P then every set in NP is in P, so we would have P = NP.
- ▶ We will soon have more NP-complete problems.
- If any NP-complete problem is in P then P = NP.
- In the year 2000 the Clay Math Institute posted seven math problems and offered \$1,000,000 for the solution to any of them. Resolving P vs NP was one of them.

1. SAT is the set of all boolean formulas that are satisfiable. That is,  $\phi(\vec{x}) \in SAT$  if there exists a vector  $\vec{b}$  such that  $\phi(\vec{b}) = TRUE$ .

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- 2. CNFSAT is the set of all boolean formulas in SAT of the form  $C_1 \wedge \cdots \wedge C_m$  where each  $C_i$  is an  $\vee$  of literals.

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- k-SAT is the set of all boolean formulas in SAT of the form C<sub>1</sub> ∧ · · · ∧ C<sub>m</sub> where each C<sub>i</sub> is an ∨ of exactly k literals.
   3-SAT is NP-complete, 2-SAT is in Poly Time.

1. DNFSAT is the set of all boolean formulas in SAT of the form  $C_1 \lor \cdots \lor C_m$  where each  $C_i$  is an  $\land$  of literals.

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- k-DNFSAT is the set of all boolean formulas in SAT of the form C<sub>1</sub> ∨··· ∨ C<sub>m</sub> where each C<sub>i</sub> is an ∧ of exactly k literals.

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- k-DNFSAT is the set of all boolean formulas in SAT of the form C<sub>1</sub> ∨··· ∨ C<sub>m</sub> where each C<sub>i</sub> is an ∧ of exactly k literals. Poly Time since DNFSAT is Poly Time.

## **CNFSAT Hard; DNFSAT Easy.** CNFSAT $\rightarrow$ DNFSAT. Collect \$1,000,000

**Idea** Given  $\phi$  in CNF form, convert to DNF form, solve DNF-SAT problem in Poly time, and now know if  $\phi$  is in SAT.

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Bad News This does not work.

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#### Show me the Money! \$1,000,000 is mine!

- Bad News This does not work.
- Good News The reason it does not work is interesting.
- Bad News I'd rather have the \$1,000,000 than be enlightened.

Vote on whether the following statement is TRUE or FALSE: There is a proof that CNFSAT  $\leq$  DNFSAT is NOT true. That is, there is NO poly time algorithm that will transform  $\phi$  in CNF form to  $\psi$  in DNF form such that  $\phi \in$  SAT iff  $\psi \in$  SAT.

Vote on whether the following statement is TRUE or FALSE: There is a proof that  $CNFSAT \leq DNFSAT$  is NOT true. That is, there is NO poly time algorithm that will transform  $\phi$  in CNF form to  $\psi$  in DNF form such that  $\phi \in SAT$  iff  $\psi \in SAT$ . TRUE, we Do have a proof!. Hard to believe.

## Work on in Breakout Rooms

Convert the following into DNF form

1. 
$$(x_1 \lor y_1)$$
  
2.  $(x_1 \lor y_1) \land (x_2 \lor y_2)$   
3.  $(x_1 \lor y_1) \land (x_2 \lor y_2) \land (x_3 \lor y_3)$   
4.  $(x_1 \lor y_1) \land (x_2 \lor y_2) \land (x_3 \lor y_3) \land (x_4 \land y_4)$ 

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Convert the following into DNF form 1.  $(x_1 \lor y_1)$ 



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- 1.  $(x_1 \lor y_1)$  $x_1 \lor y_1$
- 2.  $(x_1 \lor y_1) \land (x_2 \lor y_2)$

Convert the following into DNF form

- $1. (x_1 \lor y_1) \\ x_1 \lor y_1$
- 2.  $(x_1 \lor y_1) \land (x_2 \lor y_2)$  $(x_1 \land x_2) \lor (x_1 \land y_2) \lor (y_1 \land x_2) \lor (y_1 \lor y_2).$

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3.  $(x_1 \lor y_1) \land (x_2 \lor y_2) \land (x_3 \lor y_3)$ 

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 $1. (x_1 \lor y_1) \\ x_1 \lor y_1$ 

2. 
$$(x_1 \lor y_1) \land (x_2 \lor y_2)$$
  
 $(x_1 \land x_2) \lor (x_1 \land y_2) \lor (y_1 \land x_2) \lor (y_1 \lor y_2).$   
3.  $(x_1 \lor y_1) \land (x_2 \lor y_2) \land (x_3 \lor y_3)$ 

$$(x_1 \wedge x_2 \wedge x_3) \wedge (x_1 \wedge x_2 \wedge y_3) \wedge (x_1 \wedge y_2 \wedge x_3) \wedge (x_1 \wedge y_2 \wedge y_3) \wedge$$

$$(y_1 \wedge x_2 \wedge x_3) \wedge (y_1 \wedge x_2 \wedge y_3) \wedge (y_1 \wedge y_2 \wedge x_3) \wedge (y_1 \wedge y_2 \wedge y_3)$$

$$4. (x_1 \vee y_1) \wedge (x_2 \vee y_2) \wedge (x_3 \vee y_3) \wedge (x_4 \wedge y_4)$$

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2. 
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 $(x_1 \land x_2) \lor (x_1 \land y_2) \lor (y_1 \land x_2) \lor (y_1 \lor y_2).$ 

$$5. (x_1 \lor y_1) \land (x_2 \lor y_2) \land (x_3 \lor y_3)$$

$$(x_1 \wedge x_2 \wedge x_3) \wedge (x_1 \wedge x_2 \wedge y_3) \wedge (x_1 \wedge y_2 \wedge x_3) \wedge (x_1 \wedge y_2 \wedge y_3) \wedge$$

$$(y_1 \wedge x_2 \wedge x_3) \wedge (y_1 \wedge x_2 \wedge y_3) \wedge (y_1 \wedge y_2 \wedge x_3) \wedge (y_1 \wedge y_2 \wedge y_3)$$

4.  $(x_1 \lor y_1) \land (x_2 \lor y_2) \land (x_3 \lor y_3) \land (x_4 \land y_4)$ Not going to do it but it would take 16 clauses.