

Heaps

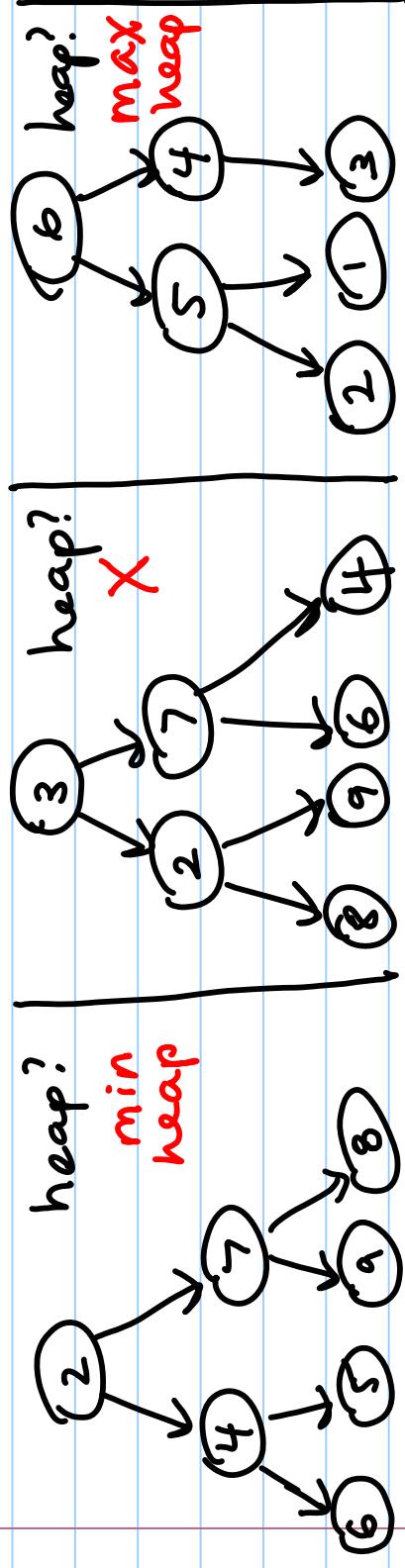
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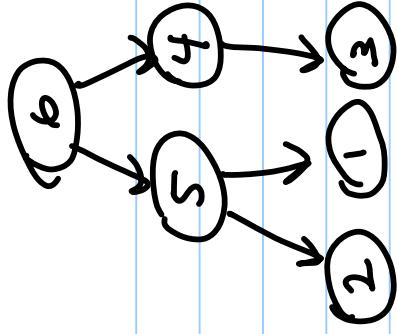
A heap is a completely filled binary tree (ok, may be not full leaves). leaves filled left and either one of

- Max-Heap
For all nodes, value of parent \geq value of self
- Min-Heap
For all nodes, value of parent \leq value of self

OR

For all nodes, value of parent \leq value of self





How long to find $\textcircled{1}$ in the heap?

worst-case search: n

worst-case height: $\log n$

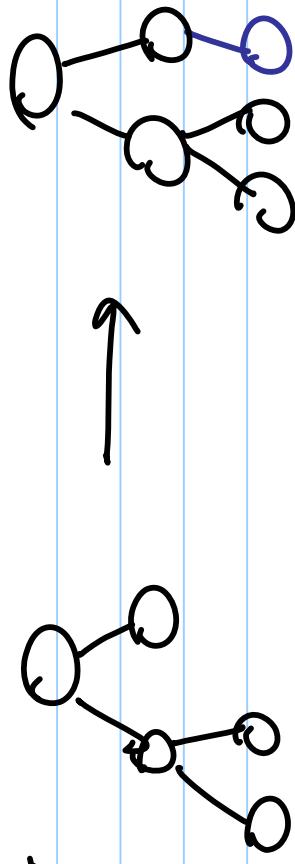
What is easy to find in a max-heap?

max is $O(1)$

Insert into a heap

- due to the structure of a heap, you always know the shape a heap will have after it goes from n to $n+1$ elements.

example:



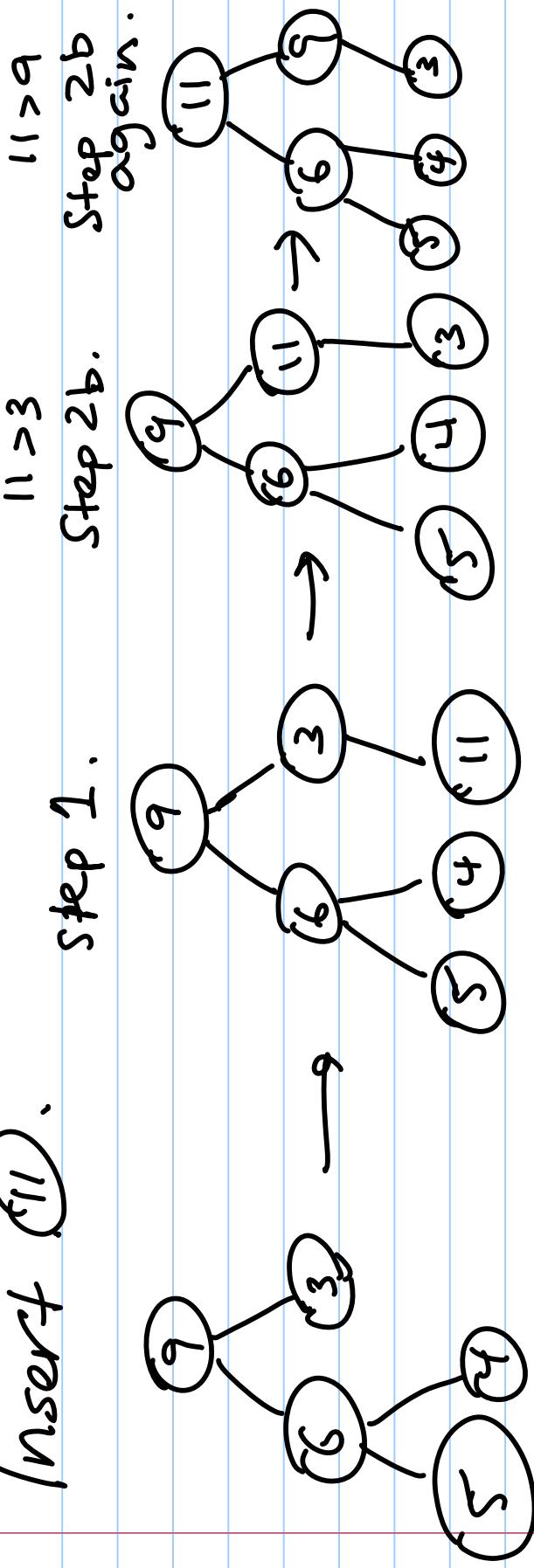
Insert into a heap

- so, to insert a node into a heap -

- ① add new node to leftmost open position in leaves
- ② adjust as needed to ensure heap property is met.
 - a) compare new node to parent.
 - b) swap if new node bigger.
- ③ Repeat until swap not needed or new node is root.

example:

Insert 11.



Step 2 called "bubbling up" the new node.

Insert routine:

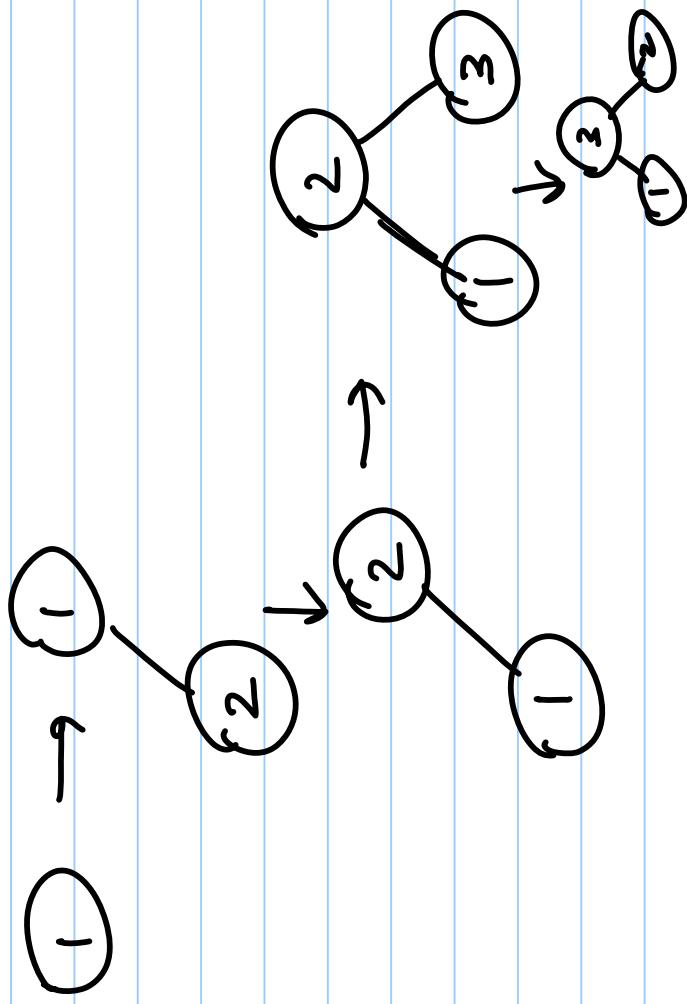
worst case \rightarrow bubble new node up all the way to root

$O(\log n)$

$\overbrace{\text{length of path from new node to root}}$

Create a heap from an array
of elements (method I):

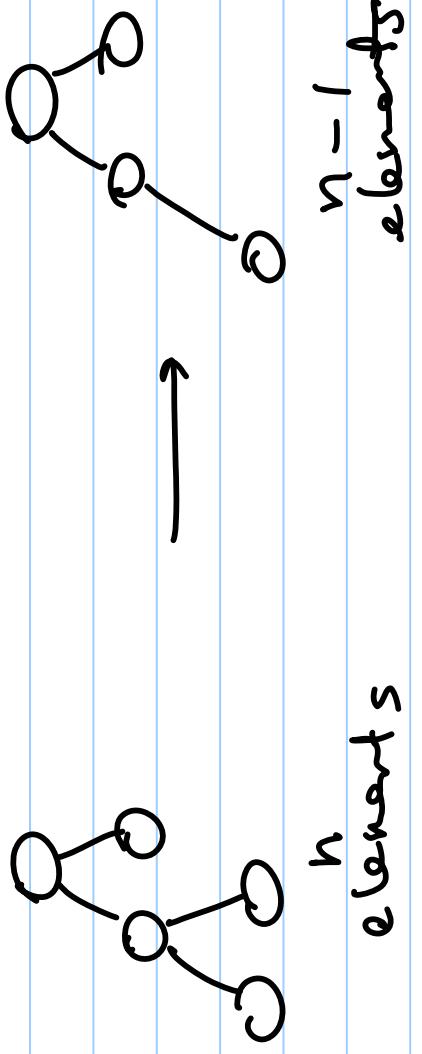
- one way is to insert n elements
into the heap one after the other



n calls to
insert.
upper bound
 $O(n \log n)$

Delete Root.

We know the shape of a heap with $n-1$ elements.



Delete Root

- ① Swap root with right most leaf
- ② Delete old root
- ③ Adjust to maintain heap property.

Let $n = \text{new root}$, $i = \emptyset$
Let largest = $\max(n, n.\text{left}', n.\text{right}')$;

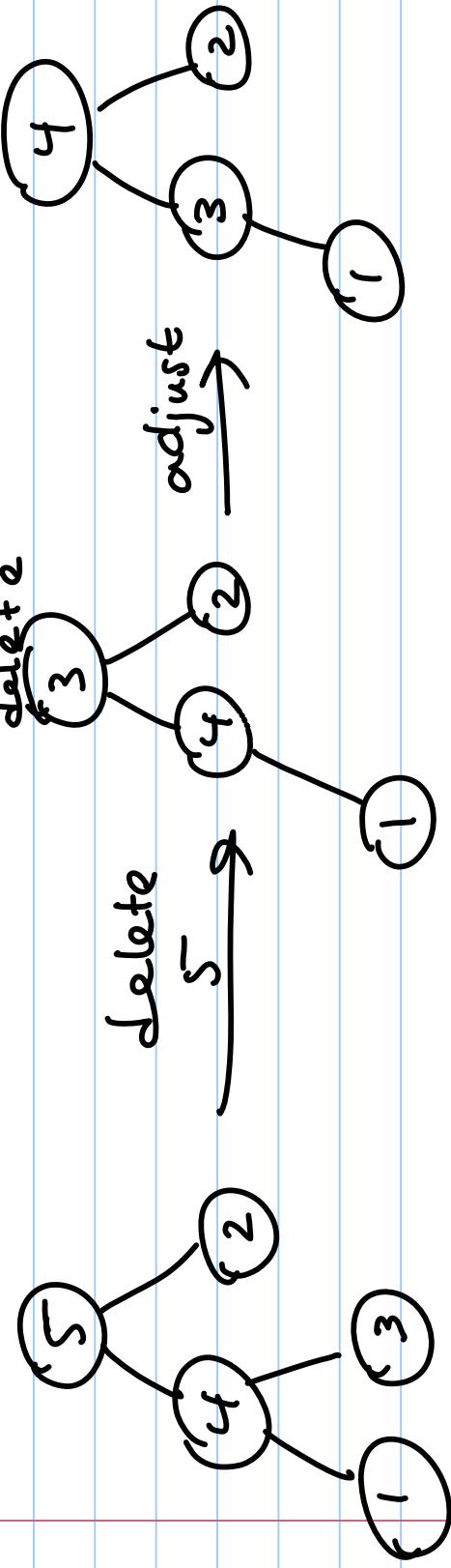
if (largest > n) {
 swap(max, n); // now on level i+1
 i++;
}

Repeat until no more swaps
or n is a leaf

Step 3

called "Bubbling Down"

swap and
delete a



Step 3b is two comparisons.

worst case - bubble down all the way
from root to leaf:
max path length $O(\log n)$
so runtime is $O(\log n)$

Another name for "Bubble Down" is Max-HEAPIFY.

1. Assume children of root are both heaps
2. Bubble down root if needed so whole data structure maintains heap property.

Heap Sort (Array A[1...n]) {

① Turn A into a max-heap.

→ ② Extract the Max using
Delete Root.

③ Repeat step 2 until only
one element
left in heap.
That element is min.

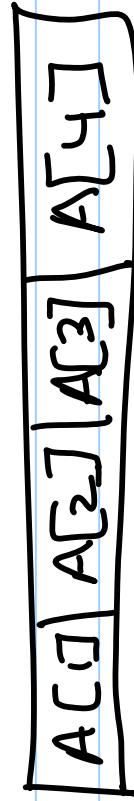
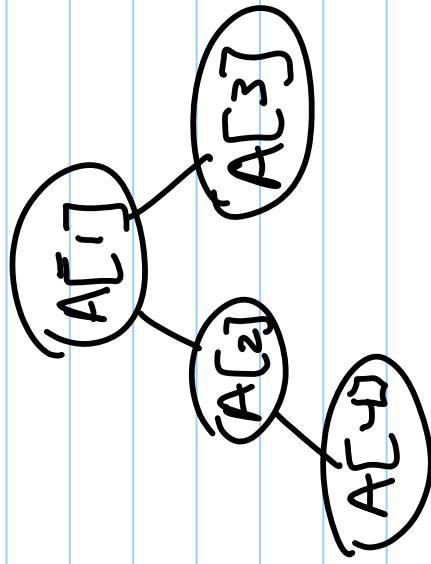
} . steps 2 and 3 called
“harvesting the heap”

Runtime of heapsort .

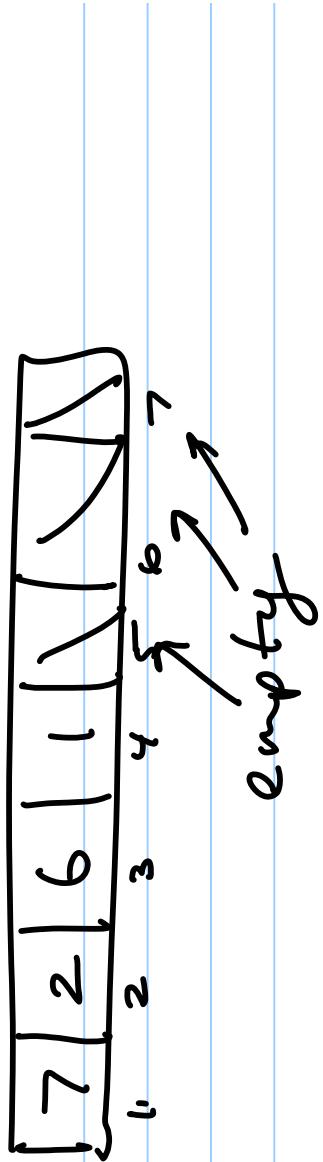
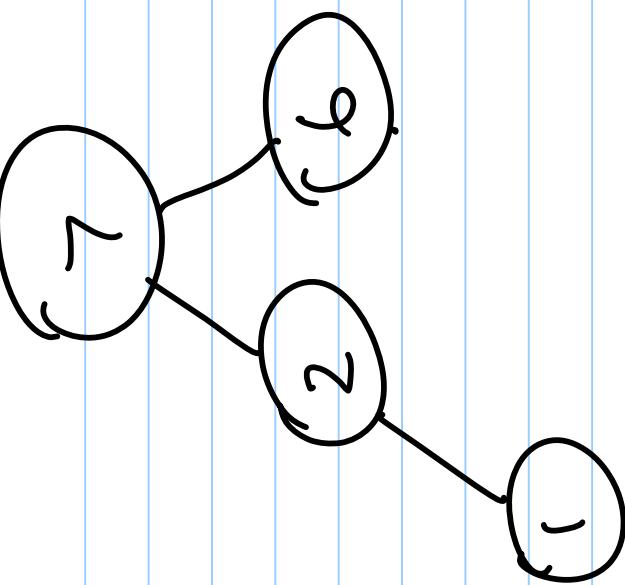
Step 1 : Build the heap:
we know upper bound is $n \log n$.

Is there a way to build in
in place?

Treat array as a heap :



Storing a tree in an array....



Index of left child: $2 \cdot \text{index of parent}$

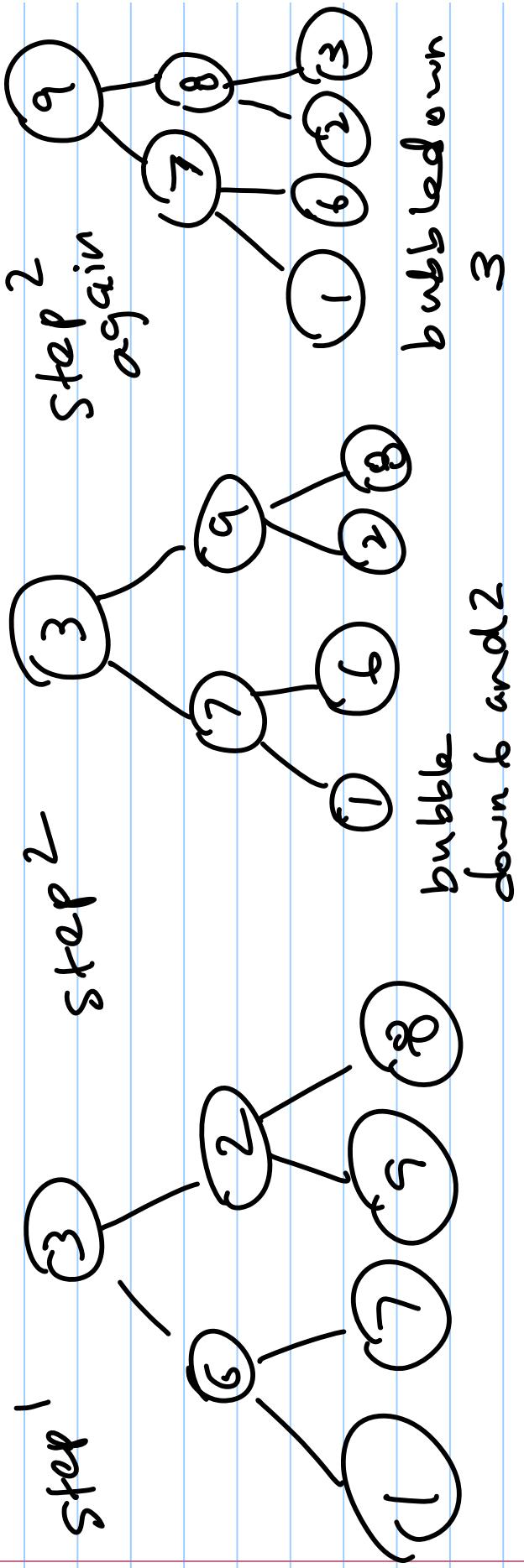
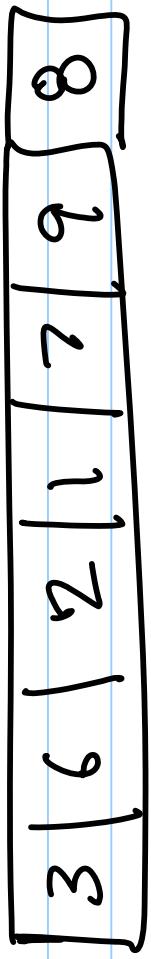
index of right child: $(2 \cdot \text{index of parent}) + 1$

(One-based indexing)

BUILD-MAX-HEAP {

- ① Treat array like a candidate heap .
 - ② All leaves are heaps, so start at level before leaves.
→ Go from left to right, calling MAX-HEAPIFY on each node.
 - ③ Repeat on all higher levels until you finish calling MAX-HEAPIFY on root.
- So you call MAX-HEAPIFY around $\frac{n}{2}$ times.

Example of Build-Max-Heap:



Steps 2 and 3: Call DeleteRoot repeatedly
(harvest heap)

Is there a way to harvest heap in place?

Yes.

Let last = n

→ Put max in A [last].
→ Treat heap as A [1 - ... (last-1)]
last --;
repeat.

Runtime of heapsort?

- ① Build heap in place -
- ② Harvest heap in place.

Worst case of Step 1: $O(n \log n)$.

But note, when at low levels,

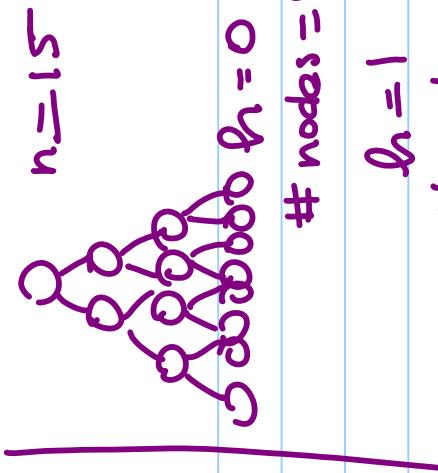
performance of MAX-HEAPIFY
is not $O(\log n)$,
because height of subtree root and
at lower level nodes $< \log n$.

Runtine of BUILD-MAX-HEAP

$$\text{is } \sum_{h=1}^{\log_2 n} (\# \text{ nodes with height } h) O(h).$$

$$= \sum_{h=1}^{\log_2 n} (\# \text{ nodes with height } h) (ah)$$

$$= \sum_{h=0}^{\log_2 n} (\# \text{ nodes with height } h) (ah)$$



$$\log_2 n = \sum_{h=0}^{\infty} \left\lceil \frac{n}{2^{h+1}} \right\rceil (\alpha h)$$

nodes = 8
 $\alpha_h = 1$
nodes = 4
 $\alpha_h = 2$
nodes = 2
 $\alpha_h = 4$

(ignora ceiling)

$$\log_2 n = \sum_{h=0}^{\infty} \left\lceil \left(\frac{1}{2}\right)^h \right\rceil$$

$$\leq \frac{1}{2} \sum_{h=0}^{\infty} \alpha_h \left(\frac{1}{2}\right)^h = \frac{1}{2} \alpha_0 \left[\frac{1}{2} \overbrace{\left(1 - \frac{1}{2}\right)^2}^{\frac{1}{2}}\right]$$

runtime \leq an

runtime $\in \Theta(n)$

Wow!

$$\text{derivation of } \sum_{k=0}^{\infty} k(x)^k = \frac{x}{(1-x)^2}, \quad x < 1$$

$$\sum_{k=0}^{\infty} (x)^k = \frac{1}{1-x}, \quad x < 1$$

$$\sum_{k=0}^{\infty} kx^{k-1} = (-1) \left(\frac{1}{(1-x)^2} \right) (-1)$$

take derivative
of both sides

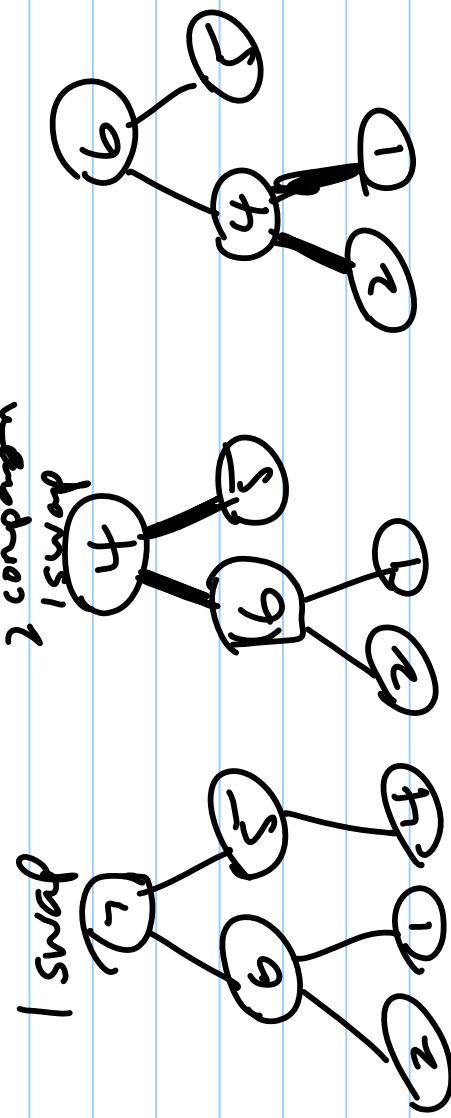
multiple
variables

$$\sum k \cdot x^k = \frac{x}{(-x)^2} - k=0$$

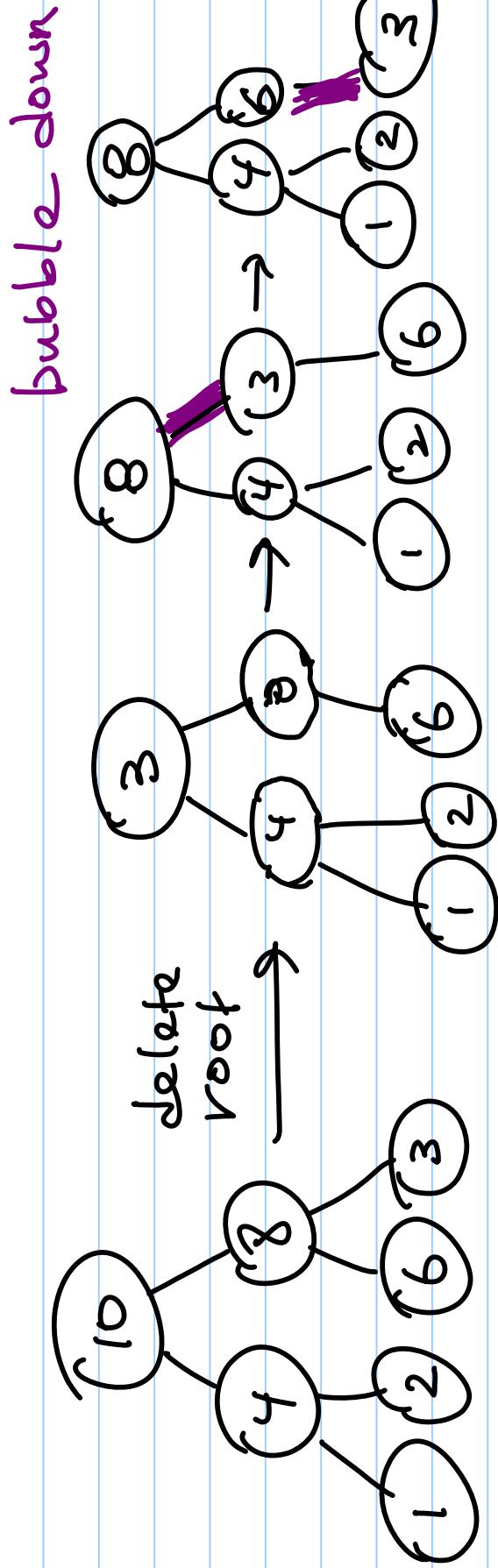
Runtime of heapsort?

- ① Build heap in place : $O(n)$
- ② Harvest heap in place:

Call Delete Root $O(n)$ times.



Each call to `DeleteRoot`
starts with a new node at the root
which could bubble all the way down
to a leaf.



worst
case

So path length for all Delete Root
calls is $\log_2 n$.

So harvesting runtime is $O(n \log n)$.

Runtime of heapsort?

① Build heap in place : $O(n)$

② Harvest heap in place: $O(n \log n)$
TOTAL RUNTIME : $O(n \log n)$

Another use of a heap
is a priority queue.

Convenient because if you have a multithreaded machine
you can return max to one thread that
needs it
and heapify in another thread.