

Implements and Compositionality

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November 6, 2014

- Definitions and conventions
- Definition of “program A implements program B ”
- Compositionality theorem
 - if
 - C uses A implements D
 - A' implements A
 - then
 - $C[A/A']$ implements D
 - $C[A/A']$ satisfies any property of $C - A$
- Program version of “ A implements B ”
 - B : service w/o internal nondeterminism
- Program version of “ A implements B ”
 - B : service with internal nondeterminism

Definitions and Conventions

Implements: evolution-based definition

Compositionality theorem

Program-based implements: internally-deterministic service

Program-based implements: internally-nondeterministic service

- Input is **allowed** at a state if its input assumption holds
- Evolution is **allowed** if each of its inputs is allowed
- Evolution is **complete** if it satisfies progress assumption
- Input is **acceptable** at a state if does not cause fault
 - aka **accepts** input
- Transition is **enabled** at a state if it is outgoing from the state
- **ext**(x): io sequence of x // same as $io(x)$

- For program B and evolution x of program A
 - x **safe wrt** B :
 x is fault-free and
 B has evolution y st $\text{ext}(x) = \text{ext}(y)$
 - x **complete wrt** B :
 x is fault-free and
 B has complete evolution y st $\text{ext}(x) = \text{ext}(y)$
- For composite system $C \supseteq$ composite system P
 - state/transition/evolution u of $C \rightarrow$ image $u.P$ on P

- **ff**: fault-free
- **x.end**: end state of evolution x
- **A.progress**: progress assumption of program A
- **swrt**: safe wrt
- **cwrt**: complete wrt
- **fin**: finite

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- programs A, B
- x : A -evolution swrt B
- t : A -transition

// conventions

■ A implements B

Safety

- if B 's instantiation ff then A 's instantiation ff
- for finite x , input e of B , $x \circ \langle e \rangle$ swrt B :
 A accepts e at x .end
- for finite x , output or internal t enabled at x .end:
 t is ff and if t outputs e then $x \circ \langle e \rangle$ is swrt B

Progress

- for x satisfying A .progress: x cwrt B

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- programs A, C, D, A', C'
- C instantiates A
- C implements D
- A' implements A
- C' : C with A replaced by A'
- $\hat{C}$: composite system $C - A$

■ Theorem 7.1

- C' implements D
- // C' equivalent to C wrt $\hat{C}$ -properties

if x' is an evolution of C' safe wrt D ,
then C has an evolution x st $x.\hat{C}$ equals $x'.\hat{C}$

if x' also satisfies $C'.\text{progress}$, then x satisfies $C.\text{progress}$

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Proof of program-based implements theorem

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Proof of externalizer theorem 7.3

Proof of externalizer theorem 7.4

- Let x' be evolution of C' swrt D
- Show A has evolution x_A with ioseq of $x'.A'$
- Stitch x_A and $x'.\hat{C}$ into an evolution x of C
- Show: if x' violates “ C' implements D ”
then x violates “ C implements D ”
- Details for lemma 7.1, outlines for the rest

// $x'.\hat{C}$, $x'.A'$

// lemma 7.1

■ Conventions

- for C : evolutions x, y , transition t
- for C' : x', y', t'
- for A : x_A, y_A, t_A :
- for A' : x'_A, y'_A, t'_A

Lemma 7.1: if x' is safe wrt D , then $x'.A'$ is safe wrt A

Proof: induction on $\#$ transitions in x'

■ Base case: C' instantiation is fault-free

- holds if C' instantiation does not start A' // $C\text{-impl-}D$
- holds if C' instantiation starts A' // $C\text{-impl-}D, A'\text{-impl-}A$

■ Let $y' = x' \circ \langle t' \rangle$ be safe wrt D

- x' safe wrt D
- $x'.A'$ safe wrt A // induction hyp
- $\exists x_A$ st $\text{ext}(x_A) = \text{ext}(x'.A')$ // swrt defn
- $\exists x$ st $x.A = x_A$ and $x.\hat{C} = x'.\hat{C}$ // stitching x_A and $x'.\hat{C}$

- Consider different cases of t'
- t' not involving A'
 - $t'.\widehat{C}$ enabled at $x'.\widehat{C}.\text{end}$, hence at $x.\widehat{C}.\text{end}$
 - $t'.\widehat{C}$ ff if output or internal // $C\text{-impl-}D, x' \text{ swrt } D$
 - $t'.\widehat{C}$ ff if input // $C\text{-impl-}D, y' \text{ swrt } D$
 - so y' ff, so $y'.A'$ ff and swrt A
- output t' involving A'
 - $t'.A'$ output transition of A'
 - $y'.A'$ ff and swrt A // $A'\text{-impl-}A, x'.A' \text{ swrt } A$
- internal t' involving A' : same as t' output

- input t' involving A' , rcving input e
 - $x' \circ \langle e \rangle$ swrt D , hence $x \circ \langle e \rangle$ swrt D // y' swrt D
 - so A accepts e at $x.A.end$ // $C\text{-impl-}D$
 - so A' accepts e at $x'.A'.end$ // $A'\text{-impl-}A$
 - so $t'.A'$ ff, so $y'.A'$ swrt A
- composite internal t' : A' outputs e to $\hat{C}$
 - $t'.A'$ output transition of A'
 - $x'.A' \circ \langle e \rangle$ swrt A // $A'\text{-impl-}A$
 - $t'.\hat{C}$ ff // A can output e at $x.end$, $C\text{-impl-}D$
 - so $t'.A'$ ff, so $y'.A'$ swrt A
- composite internal t' : A' inputs e from $\hat{C}$
 - similar

- Let x' be swrt D
- Let x_A be st $\text{ext}(x_A) = \text{ext}(x'.A')$ // $\exists$ by lemma 7.1
- Let x be stitch of x_A and $x'.$ $\widehat{C}$
- Suppose $x' \circ t'$ violates C' -impl- D safety
 - if t' of $\widehat{C}$: not C -impl- D // due to $\widehat{C}$ at $x.\widehat{C}.\text{end}$
 - if t' of A'
 - if due to A' : not A' -impl- A
 - if not due to A' : not C -impl- D
 - if t' is $\widehat{C}$ - A' interaction: similar
- Suppose x' satisfies C' -impl- D safety but not progress
 - then x satisfies C -impl- D safety but not progress

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- B: service program **without internal params**
- A: candidate implementation program
- $\bar{B}$: service inverse program
- $A\bar{B}$: closed program of A-system **a** and $\bar{B}$ -system **$\bar{b}$**

■ Theorem 7.2

- “A implements B” safety condition holds
iff $A\bar{B}$ is fault-free
iff $A\bar{B}$ satisfies for every $ic\{P\}$ in $\bar{b}$
 $Inv(\text{thread at } \bar{b}.ic\{P\}) \Rightarrow \bar{b}.P$
- “A implements B” progress condition holds
iff $A\bar{B}$ satisfies $\bar{b}.\text{progress}$

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Proof of externalizer theorem 7.3

Proof of externalizer theorem 7.4

if $\overline{AB}$ ff then “A implements B” safety holds

- assume “A implements B” safety does not hold
- exists finite x_A swrt B with a faulty extension t_A
 - A cannot accept input e swrt B, or
 - A does faulty internal/output transition, or
 - A outputs f not swrt B
- exists finite x_B with same ioseq as x_A
- exchange inputs and outputs in x_B to get $x_{\overline{B}}$
- stitch $x_{\overline{B}}$ and x_A to get $x_{\overline{AB}}$,
at the end of which the faulty t_A is doable
- so $\overline{AB}$ is faulty

// swrt defn

if “A implements B” safety holds then $\overline{AB}$ ff

- assume $\overline{AB}$ has ff evolution $x_{\overline{AB}}$ and faulty extension $t_{\overline{AB}}$
- $x_{\overline{AB}}.a$ is ff evol of A
- $x_{\overline{AB}}.\bar{b}$ is ff evol of $\bar{B}$
- exchange inputs and outputs in $x_{\overline{AB}}.\bar{b}$ to get x_B of B
- if $t_{\overline{AB}}.a$ is faulty (input, internal, output) transition:
“A implements B” does not hold
- if $t_{\overline{AB}}.a$ is ff but outputs e not accepted by $\bar{B}$:
B does not accept e at $x_B.\text{end}$
no other B-evolution with ioseq of x_B // internally deterministic
so output not swrt B, so “A implements B” does not hold

Given $\bar{A}\bar{B}$ ff:

$\bar{A}\bar{B}$ satisfies $\bar{B}.\text{progress}$ iff “A implements B” progress holds

- if “A implements B” safety but not progress holds
then $\bar{A}\bar{B}$ does not satisfy $\bar{B}.\text{progress}$
 - similar to “if” safety proof
- if $\bar{A}\bar{B}$ does not satisfy $\bar{B}.\text{progress}$
then “A implements B” progress does not hold
 - similar to “only if” safety proof

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- Given
 - B: service program with internal params (in output parts)
 - A: candidate implementation program
- Construct B-externalized ($\hat{B}$)
 - augment output with any internal parameter values
 - $\text{call/ret}(\text{extparam}) \rightarrow \text{call/ret}(\text{extparam}, \text{intparam})$
- Construct A-externalized ($\hat{A}$)
 - $\text{call/ret}(\text{extparam}) \rightarrow \text{call/ret}(\text{extparam}, \text{intparam})$
 - add auxiliary code to compute *intparam* value
 - i.e., augment A with an auxiliary externalizer fn Ψ
 - $\text{call/ret}(\text{extparam}) \rightarrow \text{call/ret}(\text{extparam}, \Psi)$
- Check for “ $\hat{A}$ implements $\hat{B}$ ” using theorem 7.2

■ Theorem 7.3

- if safety condition of “ $\hat{A}$ implements $\hat{B}$ ” holds
then safety condition of “ A implements B ” holds
- if progress condition of “ $\hat{A}$ implements $\hat{B}$ ” holds
then progress condition of “ A implements B ” holds

■ Theorem 7.4

- if A implements B then
there is an externalizer Ψ s.t. $\hat{A}$ implements $\hat{B}$

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Theorem 7.3: if $\hat{A}$ implements $\hat{B}$ then A implements B

■ Externalizer Ψ is auxiliary

■ so evol x of A maps 1-1 to evol $\hat{x}$ of $\hat{A}$ ★

■ Let x be evolution of A swrt B

■ Show that $\hat{x}$ is swrt $\hat{B}$

// lemma 7.6

■ So extension of $\hat{x}$ is swrt $\hat{B}$

// $\hat{A}$ -impl- $\hat{B}$

■ So extension of x is swrt B

// ★

■ Similarly for x cwrt B

■ x : evolution of A

■ quantity z in $A \longleftrightarrow$ quantity $\hat{z}$ in $\hat{A}$

// conventions

Let $\hat{A}$ implement $\hat{B}$. If $\text{evol } x \text{ of } A \text{ swrt } B$ then $\hat{x} \text{ swrt } \hat{B}$

Proof

■ Let $\text{evol } x$ be $\text{swrt } B$

■ x is ff

// swrt defn

■ $\hat{x}$ ff

// ★

■ inputs in $\hat{x} \text{ swrt } \hat{B}$

// $x \text{ swrt } B$, inputs same in x and $\hat{x}$

■ $\hat{x} \text{ swrt } \hat{B}$

// $\hat{A}\text{-impl-}\hat{B}$, $\hat{x}$ inputs $\text{swrt } \hat{B}$

if $\hat{A}$ -impl- $\hat{B}$ safety holds then A -impl- B safety holds

- let x be swrt B
- $\hat{x}$ swrt $\hat{B}$ // lemma 7.6
- let e be input of B st $x \circ \langle e \rangle$ swrt B
 - $\hat{x} \circ \langle e \rangle$ swrt $\hat{B}$ // $\hat{x}$ swrt $\hat{B}$, inputs same for B and $\hat{B}$
 - $\hat{A}$ accepts e at $\hat{x}.$ end // $\hat{A}$ -impl- $\hat{B}$
- let u be an output transition enabled at $x.$ end
 - $\hat{u}$ enabled at $\hat{x}.$ end // ★
 - $\hat{x} \circ \langle \hat{u} \rangle$ swrt $\hat{B}$ // $\hat{x}$ swrt $\hat{B}$, $\hat{A}$ -impl- $\hat{B}$
 - $x \circ \langle u \rangle$ swrt B // $\hat{x} \circ \langle \hat{u} \rangle$ swrt $\hat{B}$
- let u be an internal transition enabled at $x.$ end
 - like output transition w/o output e

if $\hat{A}\text{-impl-}\hat{B}$ holds then $A\text{-impl-}B$ progress holds

- let x be swrt B
- $\hat{x}$ swrt $\hat{B}$ // lemma 7.6
- let x satisfy $A.\text{progress}$
- $\hat{x}$ satisfies $\hat{A}.\text{progress}$ // A and $\hat{A}$ have same progress
- $\hat{x}$ cwrt $\hat{B}$ // $\hat{x}$ satisfies $\hat{A}.\text{progress}$, $\hat{A}\text{-impl-}\hat{B}$
- x cwrt B // B and $\hat{B}$ have same progress

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Theorem 7.4: if A implements B then $\exists \Psi$ st $\hat{A}$ implements $\hat{B}$

- Let Ψ maintain an instance $\hat{b}$ of $\hat{B}$, kept synchronized to $\hat{A}$'s ioseq thus far
 - initially, when $\hat{A}$ instantiated, instantiate $\hat{b}$
 - when $\hat{A}$ rcvs input $\hat{e}$, execute corresponding input part of $\hat{b}$
 - when $\hat{A}$ does an output whose “unhatted” part is e set $\hat{e}$ to any output that $\hat{b}$ can output
 - at least one such exists // $A\text{-impl-}B$, ioseq thus far is swrt B
- Such an externalizer ensures that $\hat{A}\text{-impl-}\hat{B}$ holds