SESF for Time-Constrained Programs

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Time-constrained program

- statements are subject to time constraints
- Distributed program: local time constraints cause global effects
- Statement A can have two kinds of time constraints
 - only-within: A executed only within a given time interval
 - deadline: A executed within a given time
- Timing assumptions: time constraints enforced by platform
 eliminate some evolutions of the program

Timing properties: time constraints to be satsified by program

Overview – 2

- Let S be a time-constrained program
- **S** $_{\tau}$: explicit-time version of S
 - "regular" program whose evolutions satisfy timing assumptions
 - "regular" reasoning/compositionality applies to S_{τ}
- S $_{ au}$ is S with following added to environment
 - aunow: real-valued "current time" variable, readable by all
 - $\tau \operatorname{age}(\delta)$: "ageing" function that increases $\tau \operatorname{now}$ by δ
 - S_τ-transitions: S-transitions and ageing transitions
- **Epoch variables**: added to S to store times of step executions
- Timing assumptions: guards in epoch variables
 - only-within: guard on S-step
 - deadline: guard on auage (δ)
- Timing properties: assertions in epoch variables

Explict-time program of S

- Time-constrained program S
 - statements can simultaneously record value of au now
 - statements can have "only-within" blocking conditions in au now
 - S can have a deadline assumption, a predicate in au now

```
Explicit-time version of S
program S_{\tau}(.)
   real \tau now \leftarrow 0:
   sys \leftarrow startSystem(S(.)):
                                                  // only-within: guards in S
   return mysid
   output \tau age(\delta)
      oc {\delta > 0 and <deadline[\taunow | \taunow + \delta]>}
      \tau now \leftarrow \tau now + \delta
      ic {true}
```

- Let A and B be time-constrained programs
- "A implements B" is now "A_τ implements B_τ"
- Compositionality theorem holds
- Program-based implements holds
- Typical timing assumptions for implementation programs
 - delay(L,U): pass within [L,U] secs from arrival
 - dd1{U}: reach next timing assumption within U
 - <blocking construct>(U): pass within U secs since arrival or since last unblocked