

# Simulating Hamiltonian dynamics on a quantum computer

**Andrew Childs**

MIT Center for Theoretical Physics

27 June 2003

# Why quantum computing?

**Information is physical.**

**Physics is quantum mechanical.**

In particular: Physical systems are described by vectors in Hilbert space that evolve by unitary transformations and can be measured by projection onto orthogonal subspaces.

# The quantum circuit model

- Start in the state  $|0\rangle$
- Apply a sequence of unitary transformations  $U_1, U_2, \dots, U_k$  chosen from a universal gate set, e.g.  $\{H, T, \text{CNOT}\}$
- Measure in the computational basis

**But time is not really discrete!**

# Hamiltonian dynamics

Quantum systems evolve according to the Schrödinger equation:

$$i\frac{d}{dt}|\psi(t)\rangle = H(t)|\psi(t)\rangle$$

$H(t)$  is the **Hamiltonian**.

$H=H^\dagger$  so that the time evolution is *unitary*:

$$\frac{d}{dt}\langle\psi|\psi\rangle = i\langle\psi|H^\dagger|\psi\rangle - i\langle\psi|H|\psi\rangle = 0$$

# Solution of Schrödinger equation

$$i \frac{d}{dt} |\psi(t)\rangle = H |\psi(t)\rangle$$

*Eigenstates* of  $H$ :  $H |\phi_j\rangle = E_j |\phi_j\rangle$  time independent

$$H = \sum_j E_j |\phi_j\rangle \langle \phi_j| \quad E_j \in \mathbb{R} \text{ since } H = H^\dagger$$

Suppose  $|\psi(0)\rangle = |\phi_j\rangle$

Then  $|\psi(t)\rangle = \exp(-i E_j t) |\phi_j\rangle$

Expand a general initial state:  $|\psi(0)\rangle = \sum_j c_j |\phi_j\rangle$

$$|\psi(t)\rangle = \sum_j c_j \exp(-i E_j t) |\phi_j\rangle = U(t) |\psi(0)\rangle$$

where  $U(t) = \exp(-i H t) = \sum_j (-i H t)^j / j!$

# Solution of Schrödinger equation

## Time dependent case

$$|\psi(t)\rangle = U(t) |\psi(0)\rangle$$

$$\text{where } U(t) = T \exp[-i \int_0^t d\tau H(\tau)]$$

time ordering operator

Special case: Suppose  $H(t)$  changes very slowly. Then the evolution is much simpler because of the *Adiabatic Theorem*. More on this later.

# Relation to the circuit model

Unitary quantum gates arise from Hamiltonian dynamics.

**Simple example:** Two level atom.

—  $|1\rangle$       Apply a laser pulse.  $H = \omega \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$   
—  $|0\rangle$

$$U(t) = e^{-iHt} = \begin{pmatrix} \cos \omega t & \sin \omega t \\ -\sin \omega t & \cos \omega t \end{pmatrix}$$

$$U(\pi/4\omega) = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix}$$

But perhaps we can use *many-body* Hamiltonians to perform interesting computations.

# Why consider Hamiltonians?

Simulating physical systems

New kinds of quantum algorithms

- Quantum walks
- Adiabatic quantum computation

Quantum analogue of the Cook-Levin Theorem (**Kitaev**: “LOCAL HAMILTONIAN is QMA-complete”)



# Efficiently realizable Hamiltonians

How do we know what Hamiltonians are legal for use in computations?

## Example:

Let  $x$  = instance of a hard problem

Let  $s_x$  = solution of  $x$

The Hamiltonian

$$H = \sum_x (|0, s_x\rangle\langle x, 0| + |x, 0\rangle\langle 0, s_x|)$$

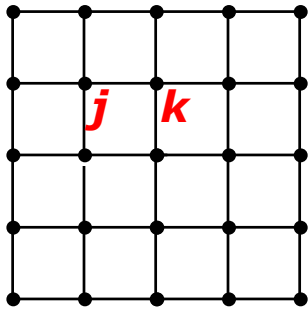
seems hard to implement!

# Efficiently realizable Hamiltonians

Two notions of efficient realizability:

1.  $H$  is the Hamiltonian of a physical system we can “easily” build

Spins arranged on a 2D lattice



$$H = \sum_{j,k} a_{jk} \sigma_z^{(j)} \sigma_z^{(k)} + \sum_j b_j \sigma_x^{(j)}$$

where  $a_{jk}=0$  for non-adjacent sites

# Efficiently realizable Hamiltonians

Two notions of efficient realizability:

**2.**  $H$  is a Hamiltonian that can be efficiently simulated in the circuit model

**Def.** A Hamiltonian  $H$  acting on  $n$  qubits can be *efficiently simulated* if for any  $\varepsilon > 0$ ,  $t > 0$  there is a quantum circuit  $U$  consisting of  $\text{poly}(n, t, 1/\varepsilon)$  gates such that  $\|U - e^{-iHt}\| < \varepsilon$ .

Note: This will include the “physically reasonable” Hamiltonians.

# Tools for simulating Hamiltonians

## Rule 1. Local Hamiltonians.

If  $H$  acts on  $O(1)$  qubits, it can be efficiently simulated.

## Rule 2. Rescaling.

If  $H$  can be efficiently simulated, then  $cH$  can be efficiently simulated for any  $c = \text{poly}(n)$ .

# Tools for simulating Hamiltonians

## Rule 3. Linear combination.

If  $H_j$  can be efficiently simulated, then  $\sum_j H_j$  can be efficiently simulated.

## Lemma. Lie product formula.

Let  $h = \max_j \|H_j\|$ . Then

$$e^{-i(H_1 + \dots + H_k)t} = (e^{-iH_1 t/r} \dots e^{-iH_k t/r})^r + O\left(\frac{kh^2 t^2}{r}\right)$$

# Lie product formula

## Proof.

By Taylor expansion,

$$e^{-iHt/r} = 1 - iHt/r + O(h^2t^2/r^2)$$

Thus

$$\begin{aligned} & (e^{-iH_1t/r} \dots e^{-iH_k t/r})^r \\ &= [1 - i(H_1 + \dots + H_k)t/r + O(kh^2t^2/r^2)]^r \\ &= [e^{-i(H_1 + \dots + H_k)t/r} + O(kh^2t^2/r^2)]^r \\ &= e^{-i(H_1 + \dots + H_k)t} + O(kh^2t^2/r) \quad \square \end{aligned}$$

# The story so far

Using **Rules 1,2,3** we can simulate many “physical” Hamiltonians.

$H$  = sum of terms, each acting on a constant number of qubits

Recall example of a spin glass:

$$H = \sum_{j,k} a_{jk} \sigma_z^{(j)} \sigma_z^{(k)} + \sum_j b_j \sigma_x^{(j)}$$

# Tools for simulating Hamiltonians

## Rule 4. Commutation.

If  $H_1, H_2$  can be efficiently simulated, then  $i[H_1, H_2]$  can be efficiently simulated.

## Rule 5. Unitary conjugation.

If  $H$  can be efficiently simulated and the unitary operation  $U$  can be efficiently implemented, then  $U^\dagger H U$  can be efficiently simulated.

**Proof.**  $e^{-iU^\dagger H U t} = U^\dagger e^{-iH t} U$  □



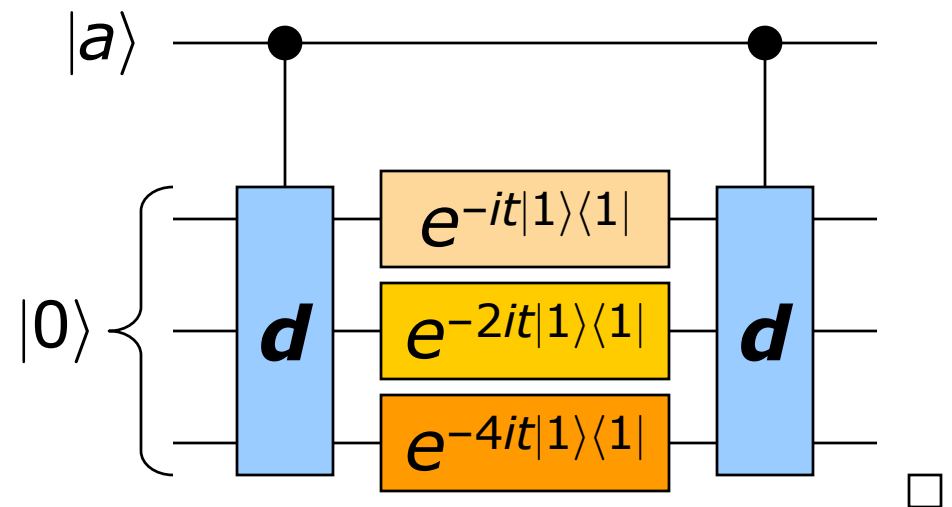
# Tools for simulating Hamiltonians

## Rule 6. Computable phase shifts.

If  $H$  is diagonal and the diagonal element  $d(a) = \langle a|H|a\rangle$  can be efficiently computed for any  $a$ , then  $H$  can be efficiently simulated.

### Proof.

$$\begin{aligned} |a, 0\rangle &\rightarrow |a, d(a)\rangle \\ &\rightarrow e^{-itd(a)} |a, d(a)\rangle \\ &\rightarrow e^{-itd(a)} |a, 0\rangle \end{aligned}$$



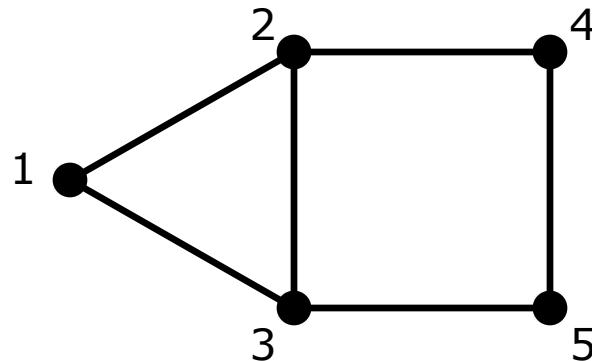
# Tools for simulating Hamiltonians

## Rule 7. Sparse Hamiltonians.

Suppose that for any  $a$ , one can efficiently compute all the values of  $b$  for which  $\langle a|H|b\rangle$  is nonzero. Then  $H$  can be efficiently simulated.

### Example:

$$H = \begin{pmatrix} 0 & 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 1 & 0 \\ 1 & 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 1 & 0 \end{pmatrix}$$



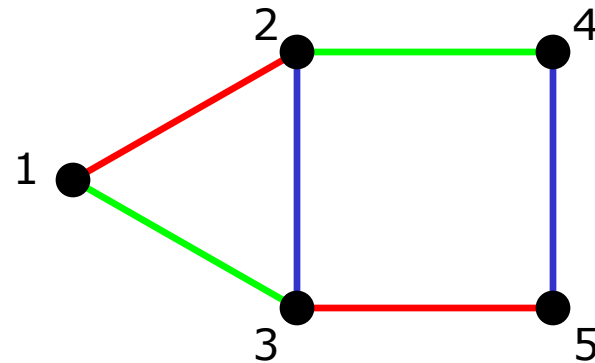
# Tools for simulating Hamiltonians

## Rule 7. Sparse Hamiltonians.

Suppose that for any  $a$ , one can efficiently compute all the values of  $b$  for which  $\langle a|H|b\rangle$  is nonzero. Then  $H$  can be efficiently simulated.

### Example:

$$H = \begin{pmatrix} 0 & 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 1 & 0 \\ 1 & 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 1 & 0 \end{pmatrix}$$



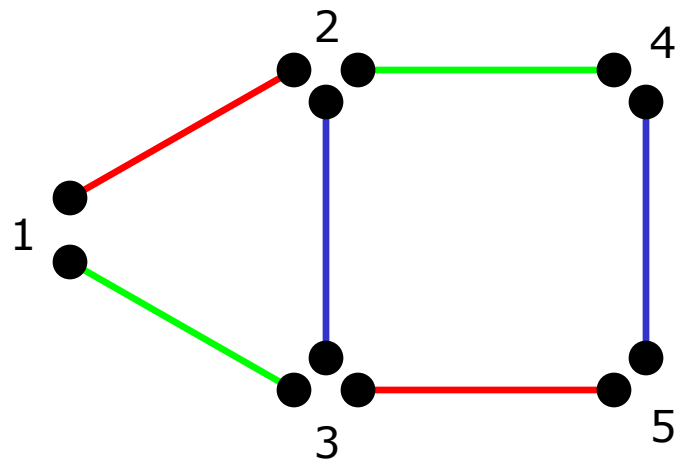
# Tools for simulating Hamiltonians

## Rule 7. Sparse Hamiltonians.

Suppose that for any  $a$ , one can efficiently compute all the values of  $b$  for which  $\langle a|H|b\rangle$  is nonzero. Then  $H$  can be efficiently simulated.

### Example:

$$H = \begin{pmatrix} 0 & 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 1 & 0 \\ 1 & 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 1 & 0 \end{pmatrix}$$



# Coloring a sparse graph

## Lemma.

Given an undirected graph  $G$  with  $N$  vertices and maximum degree  $d$ , suppose one can efficiently compute the neighbors of a given vertex. Then there is an efficiently computable function  $c(a,b)=c(b,a)$  taking  $O(d^2 \log^2 N)$  values such that for all  $a$ ,  $c(a,b)=c(a,b')$  implies  $b=b'$ .

# Coloring a sparse graph

## Proof.

Let  $\text{index}(a,b)$  be the index of  $b$  in the list of neighbors of  $a$ .

Let  $k(a,b)$  be the smallest  $k$  such that  $a \neq b \pmod{k}$ .

Note  $k(a,b) = k(b,a)$  and  $k = O(\log N)$ .

For  $a < b$ , define

$$c(a,b) := (\text{index}(a,b) \text{ index}(b,a), k(a,b), b \bmod k(a,b))$$

For  $a > b$ , define  $c(a,b) := c(b,a)$ .

Suppose  $c(a,b) = c(a,b')$ . Four cases:

- i.  $a < b, a < b'$ .  $\text{index}(a,b) = \text{index}(a,b') \Rightarrow b = b'$ .

# Coloring a sparse graph

## Proof.

Let  $\text{index}(a,b)$  be the index of  $b$  in the list of neighbors of  $a$ .

Let  $k(a,b)$  be the smallest  $k$  such that  $a \neq b \pmod{k}$ .

Note  $k(a,b) = k(b,a)$  and  $k = O(\log N)$ .

For  $a < b$ , define

$$c(a,b) := (\text{index}(a,b), \text{index}(b,a), k(a,b), b \bmod k(a,b))$$

For  $a > b$ , define  $c(a,b) := c(b,a)$ .

Suppose  $c(a,b) = c(a,b')$ . Four cases:

- i.  $a < b, a < b'$ .  $\text{index}(a,b) = \text{index}(a,b') \Rightarrow b = b'$ .
- ii.  $a > b, a > b'$ .  $\text{index}(a,b) = \text{index}(a,b') \Rightarrow b = b'$ .

# Coloring a sparse graph

## Proof.

Let  $\text{index}(a,b)$  be the index of  $b$  in the list of neighbors of  $a$ .

Let  $k(a,b)$  be the smallest  $k$  such that  $a \neq b \pmod{k}$ .

Note  $k(a,b) = k(b,a)$  and  $k = O(\log N)$ .

For  $a < b$ , define

$$c(a,b) := (\text{index}(a,b), \text{index}(b,a), k(a,b), b \bmod k(a,b))$$

For  $a > b$ , define  $c(a,b) := c(b,a)$ .

Suppose  $c(a,b) = c(a,b')$ . Four cases:

- i.  $a < b, a < b'$ .  $\text{index}(a,b) = \text{index}(a,b') \Rightarrow b = b'$ .
- ii.  $a > b, a > b'$ .  $\text{index}(a,b) = \text{index}(a,b') \Rightarrow b = b'$ .
- iii.  $a < b, a > b'$ .  $k(a,b) = k(a,b'), a = b \pmod{k}$ , contradiction.



# Coloring a sparse graph

## Proof.

Let  $\text{index}(a,b)$  be the index of  $b$  in the list of neighbors of  $a$ .

Let  $k(a,b)$  be the smallest  $k$  such that  $a \neq b \pmod{k}$ .

Note  $k(a,b) = k(b,a)$  and  $k = O(\log N)$ .

For  $a < b$ , define

$$c(a,b) := (\text{index}(a,b), \text{index}(b,a), k(a,b), b \bmod k(a,b))$$

For  $a > b$ , define  $c(a,b) := c(b,a)$ .

Suppose  $c(a,b) = c(a,b')$ . Four cases:

- i.**  $a < b, a < b'$ .  $\text{index}(a,b) = \text{index}(a,b') \Rightarrow b = b'$ .
- ii.**  $a > b, a > b'$ .  $\text{index}(a,b) = \text{index}(a,b') \Rightarrow b = b'$ .
- iii.**  $a < b, a > b'$ .  $k(a,b) = k(a,b')$ ,  $a = b \pmod{k}$ , contradiction.
- iv.**  $a > b, a < b'$ .  $k(a,b) = k(a,b')$ ,  $a = b' \pmod{k}$ , contradiction.

# Coloring a sparse graph

## Proof.

Let  $\text{index}(a,b)$  be the index of  $b$  in the list of neighbors of  $a$ .

Let  $k(a,b)$  be the smallest  $k$  such that  $a \neq b \pmod k$ .

Note  $k(a,b) = k(b,a)$  and  $k = O(\log N)$ .

For  $a < b$ , define

$$c(a,b) := (\text{index}(a,b), \text{index}(b,a), k(a,b), b \bmod k(a,b))$$

For  $a > b$ , define  $c(a,b) := c(b,a)$ .

Suppose  $c(a,b) = c(a,b')$ . Four cases:

- i.**  $a < b, a < b'$ .  $\text{index}(a,b) = \text{index}(a,b') \Rightarrow b = b'$ .
- ii.**  $a > b, a > b'$ .  $\text{index}(a,b) = \text{index}(a,b') \Rightarrow b = b'$ .
- iii.**  $a < b, a > b'$ .  $k(a,b) = k(a,b')$ ,  $a = b \pmod k$ , contradiction.
- iv.**  $a > b, a < b'$ .  $k(a,b) = k(a,b')$ ,  $a = b' \pmod k$ , contradiction.  $\square$

# Simulating a sparse Hamiltonian

## Proof. (of Rule 7)

Write  $H$  as a diagonal matrix plus a matrix with zeros on the diagonal. The diagonal part can be simulated using [Rule 6](#) and combined with the off-diagonal piece using [Rule 3](#). Thus assume  $H$  has zeros on the diagonal WLOG.

Let  $v_c(a)$  be the vertex connected to  $a$  by an edge of color  $c$ .  
Let  $x_c(a) := \text{Re} \langle a|H|v_c(a)\rangle$ ,  $y_c(a) := \text{Im} \langle a|H|v_c(a)\rangle$ .

Consider the state space  $|a,b,z\rangle$  where vertices are  $|a,0,0\rangle$ .

We can efficiently implement unitary operators

$$\begin{aligned} V_c |a,0,0\rangle &= |a, v_c(a), x_c(a)\rangle \\ W_c |a,0,0\rangle &= |a, v_c(a), y_c(a)\rangle. \end{aligned}$$

(If no such vertex,  
 $v_c(a)=11\dots 1$ ,  
 $x_c(a)=y_c(a)=0$ .)

We can efficiently simulate the Hamiltonians

$$\begin{aligned} S |a,b,x\rangle &= x |b,a,x\rangle \\ T |a,b,y\rangle &= i y |b,a,-y\rangle \end{aligned}$$

using [Rules 1,5,6](#).

# Simulating a sparse Hamiltonian

## Proof. (of Rule 7, continued)

Using Rules 3,5 we can efficiently simulate

$$\tilde{H} = \sum_c (V_c^\dagger S V_c + W_c^\dagger T W_c).$$

This has the proper action on vertices:

$$\begin{aligned} \tilde{H}|a, 0, 0\rangle &= \sum_c [V_c^\dagger S|a, v_c(a), x_c(a)\rangle \\ &\quad + W_c^\dagger T|a, v_c(a), y_c(a)\rangle] \\ &= \sum_c [x_c(a) V_c^\dagger|v_c(a), a, x_c(a)\rangle \\ &\quad + iy_c(a) W_c^\dagger|a, v_c(a), -y_c(a)\rangle] \\ &= \sum_c [x_c(a) + iy_c(a)]|v_c(a), 0, 0\rangle \quad \square \end{aligned}$$

# Example: Particle in a potential

Consider the Hamiltonian

$$H = \frac{p^2}{2m} + V(x), \quad p^2 = -\frac{d^2}{dx^2}$$

Lattice version (lattice spacing  $l$ ):

$$p^2|x\rangle = \frac{1}{l^2}(2|x\rangle - |x+1\rangle - |x-1\rangle)$$

$p^2$  is diagonal in the Fourier basis, and the unitary operator corresponding to the Fourier transform is efficiently implementable, so  $H$  can be simulated using [Rules 3,5,6](#).

Alternatively, just note that  $H$  is sparse and computable, so [Rule 7](#) applies.

# Summary

Quantum systems evolve according to the Schrödinger equation  $i\frac{d}{dt}|\psi(t)\rangle = H(t)|\psi(t)\rangle$

Such systems can be efficiently simulated by a universal quantum computer when  $H$

- Is a sum of terms, each acting on at most a constant number of qubits (Rule 1,2,3)
- Is  $i$  times the commutator of two simulable Hamiltonians (Rule 4)
- Differs from a simulable Hamiltonian by an efficiently implementable unitary transformation (Rule 5)
- Is sparse and efficiently computable (Rules 6,7)

# References

## Hamiltonian dynamics

- D. J. Griffiths, *Introduction to Quantum Mechanics* (Prentice Hall, 1994).
- R. Liboff, *Introductory Quantum Mechanics* (Addison Wesley, 1998).

## Simulating physical systems

- R. Feynman, *Simulating physics with computers*, Int. J. Theor. Phys. **21**, 219 (1982).
- S. Lloyd, *Universal quantum simulators*, Science **273**, 1073 (1996).
- S. Wiesner, *Simulations of many-body quantum systems by a quantum computer*, quant-ph/9603028.
- C. Zalka, *Simulating quantum systems on a quantum computer*, Proc. R. Soc. London A **454**, 313 (1998).
- M. A. Nielsen and I. L. Chuang, *Quantum Computation and Quantum Information* (Cambridge University Press, 2000).

## Time-independent Hamiltonian dynamics allow universal quantum computation

- R. P. Feynman, *Quantum mechanical computers*, Optics News **11**, 11 (1985).

# References

## Simulating sparse Hamiltonians

- A. M. Childs, R. Cleve, E. Deotto, E. Farhi, S. Gutmann, and D. Spielman, *Exponential algorithmic speedup by quantum walk*, quant-ph/0209131, STOC 2003.
- D. Aharonov and A. Ta-Shma, *Adiabatic quantum state generation and statistical zero knowledge*, quant-ph/0301040, STOC 2003.

## Measuring a Hermitian operator

- C. Zalka, *Simulating quantum systems on a quantum computer*, Proc. R. Soc. London A **454**, 313 (1998).
- D. S. Abrams and S. Lloyd, *A quantum algorithm providing exponential speed increase for finding eigenvalues and eigenvectors*, quant-ph/9807070, Phys. Rev. Lett. **83**, 5162 (1999).
- A. M. Childs, E. Deotto, E. Farhi, J. Goldstone, S. Gutmann, and A. Landahl, *Quantum search by measurement*, quant-ph/0204013, Phys. Rev. A **66**, 032314 (2002).

Hamiltonian dynamics in quantum algorithms:

See next lecture