Announcements

- Midterm is next Tuesday
 - Covers through lecture today (chapters 1-8)
 - can skip 4.5, 5.3-5.9, 7.7-7.9
- Project #2 is available on the web
- No office hours on next Tuesday

Deadlock Avoidance

- Require additional information about how resources are to be requested - decide to approve or disapprove requests on the fly
- Assume that each process lets us know its maximum resource request
- Safe state:
 - system can allocate resources to each process (up to its maximum) in some order and still avoid a deadlock
 - A system is in a safe state if there exists a safe sequence

Safe Sequence

- Sequence of processes <P₁, ... P_n> is a safe sequence if for each P_i, the resources that P_i can request can be satisfied by the currently available resources plus the resources held by all P_i, j<i
- If the necessary resources are not immediately available, P_i can always wait until all P_j, j<i have completed

Banker's Algorithm

- Each process must declare the maximum number of instances of each resource type it may need
- Maximum can't exceed resources available to system
- Variables:
 - n is the number of processes m is the number of resource types
 - Available vector of length m indicating the number of available resources of each type
 - Max n by m matrix defining the maximum demand of each process
 - Allocation n by m matrix defining number of resources of each type currently allocated to each process
 - Need: n by m matrix indicating remaining resource needs of each process

- Work is a vector of length m (resources)
- Finish is a vector of length n (processes)
- 1. Work = Available; Finish = false
- 2. Find an *i* such that Finish[i] = false and Need <= Work if no such i, go to 4
- 3. Work += Allocation_i; Finish[i] = true; goto step 2
- 4. If Finish[i] = true for all i, system is in a safe state

Note this requires m x n² steps

all elements in the vector are <=

Banker's Algorithm - Example

Three resources: A, B, C (10, 5, 7 instances each)

| Consider the snapshot of the system at this time | | | | Max - alloc |
|--|-------|-------|-------|-------------|
| | Alloc | Max | Avail | Need |
| | ABC | ABC | ABC | ABC |
| P0 | 0 1 0 | 753 | 3 3 2 | 7 4 3 |
| P1 | 200 | 3 2 2 | | 122 |
| P2 | 302 | 902 | | 600 |
| P3 | 211 | 222 | | 0 1 1 |
| P4 | 002 | 4 3 3 | | 4 3 1 |

System is in a safe state, since the sequence <P1, P3, P4, P2, P0> satisfy the safety criteria.

Resource Request Algorithm

- (1) If Request_i <= Need_i then goto 3
 - otherwise the process has exceeded its maximum claim
- (2) If Request_i <= Available then goto 3
 - otherwise process must wait since resources are not available
- (3) Check request by having the system pretend that it has allocated the resources by modifying the state as follows:
 - Available = Available Request_i
 - Allocation = Allocation + Request_i
 - Need_i = Need_i Request_i
- Find out if resulting resource allocation state is safe, otherwise the request must wait.

Deadlock Detection

Resource Allocation Graph

- Graph consists of vertices
 - type P = {P₁,...,P_n} represent processes
 - type R = {R₁,...,R_m} represent resources
- Directed edge from process P_i to resource type R_j signifies that a process i has requested resource type j
- request edge
- A directed edge from R_j to P_i indicates that resource R_j has been allocated to process P_i
- assignment edge

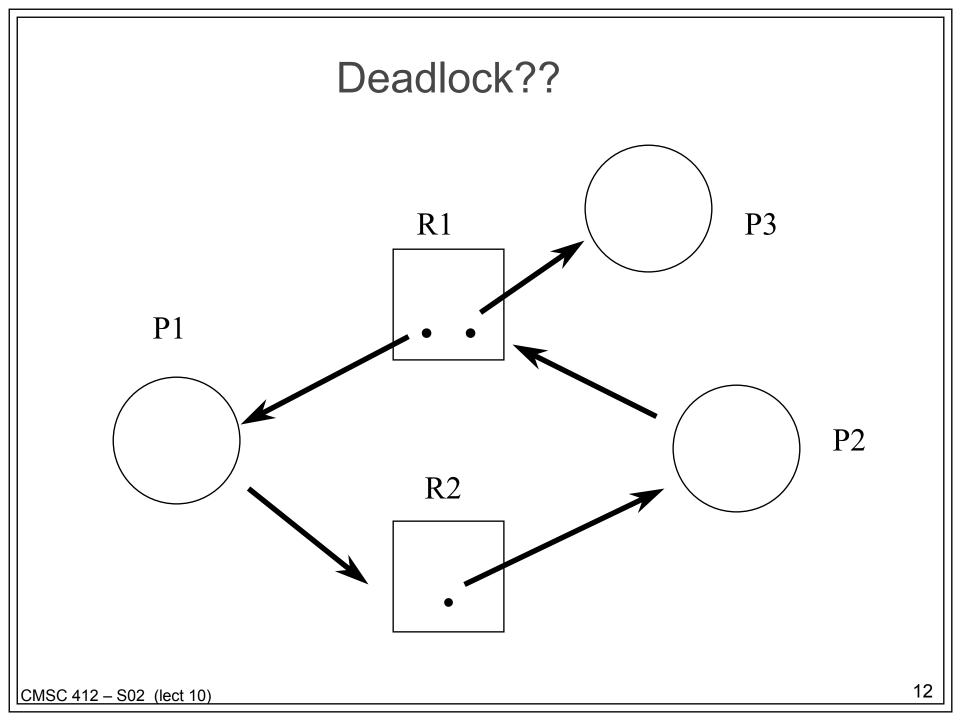
Deadlock Detection (cont.)

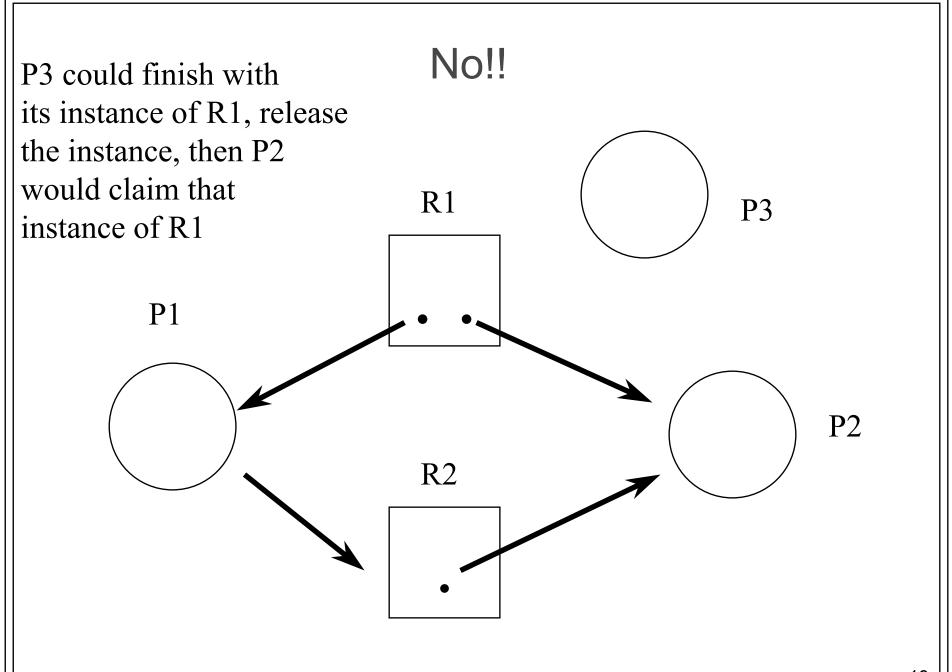
- Resource types may have more than one instance
- Each resource vertex represents a resource type.
- Each resource instance is of a unique resource type, each resource instance is represented by a "subvertex" associated with a resource vertex
 - (Silverschatz represents resource vertices by squares, resource instance "subvertices" by dots in the square.
 Process vertices are represented by circles)
- A request edge points to a resource vertex
- An assignment edge points from a resource "subvertex" to a process vertex

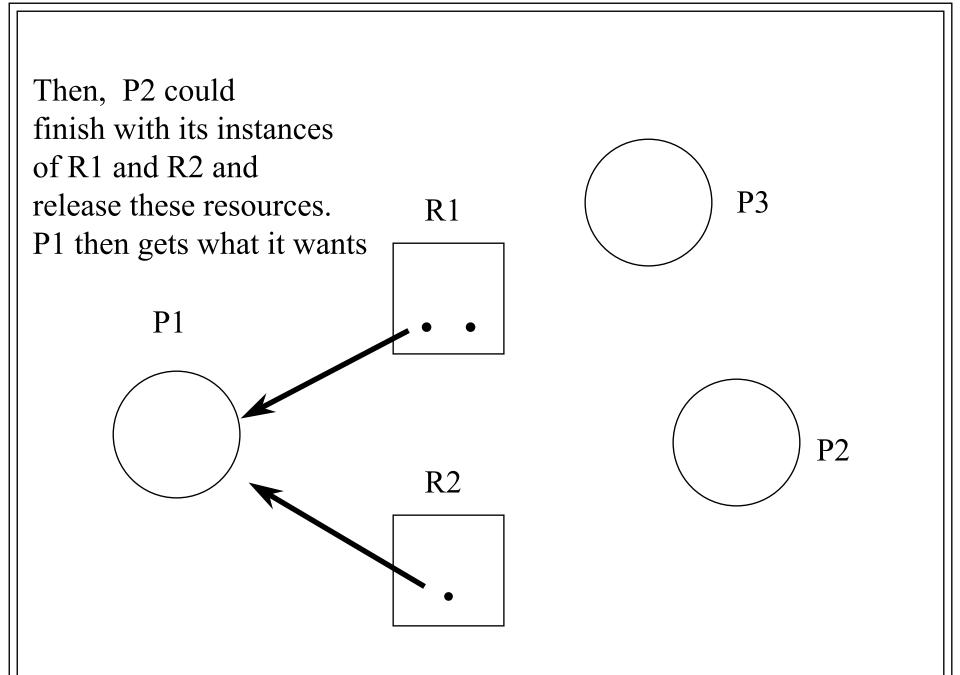
Resource Allocation Graph

- When a process P_i requests an instance of resource type R_j, a request edge is inserted into the resource allocation graph
- When the request can be fulfilled, the request edge is transformed into an assignment edge
- When the process is done using the resource, the assignment edge is deleted
- If the graph contains no cycles, no deadlock can exist

Deadlock! **R**1 P1 P2 R2







Detecting Deadlock

Work is a vector of length m (resources)
Finish is a vector of length n (processes)

- Allocation is an n x m matrix indicating the number of each resource type held by each process
- Request is an m x n matrix indicating the number of additional resources requested by each process
- 1. Work = Available; This is the difference from the Banker's algorithm.

 if Allocation[i] != 0 Finish = false else Finish = true;
- 2. Find an *i* such that Finish[i] = false and Request_i <= Work if no such i, go to 4
- 3. Work += Allocation; Finish[i] = true; goto step 2
- 4. If Finish[i] = false for some i, system is in deadlock

Note: this requires m x n² steps

Recovery from deadlock

- Must free up resources by some means
- Process termination
 - kill all deadlocked processes
 - select one process and kill it
 - must re-run deadlock detection algorithm again to see if it is freed.
- Resource Preemption
 - select a process, resource and de-allocate it
 - rollback the process
 - needs to be reset the process to a safe state
 - this requires additional state
 - starvation
 - what prevents a process from never finishing?