Announcements

- Midterm is Thursday
- Project #2 is available on the web
Deadlock Detection

• **Resource Allocation Graph**
  - Graph consists of vertices
    - type P = \{P_1,\ldots,P_n\} represent processes
    - type R = \{R_1,\ldots,R_m\} represent resources
  - Directed edge from process P_i to resource type R_j signifies that a process i has requested resource type j
    - *request edge*
  - A directed edge from R_j to P_i indicates that resource R_j has been allocated to process P_i
    - *assignment edge*
Resource types may have more than one instance
Each resource vertex represents a resource type.
Each resource instance is of a unique resource type, each resource instance is represented by a “subvertex” associated with a resource vertex
- (Silberschatz represents resource vertices by squares, resource instance “subvertices” by dots in the square. Process vertices are represented by circles)

A request edge points to a resource vertex
An assignment edge points from a resource “subvertex” to a process vertex
Resource Allocation Graph

- When a process $P_i$ requests an instance of resource type $R_j$, a request edge is inserted into the resource allocation graph.
- When the request can be fulfilled, the request edge is transformed into an assignment edge.
- When the process is done using the resource, the assignment edge is deleted.
- If the graph contains no cycles, no deadlock can exist.
Deadlock!
Deadlock??

P1

R1

R2

P2

P3
P3 could finish with its instance of R1, release the instance, then P2 would claim that instance of R1
Then, P2 could finish with its instances of R1 and R2 and release these resources. P1 then gets what it wants.
Detecting Deadlock

Work is a vector of length m (resources)
Finish is a vector of length n (processes)
- Allocation is an n x m matrix indicating the number of each resource type held by each process
- Request is an m x n matrix indicating the number of additional resources requested by each process

1. Work = Available;
   if Allocation[i] != 0 Finish[i] = false else Finish[i] = true;
2. Find an i such that Finish[i] = false and Request[i] <= Work if no such i, go to 4
3. Work += Allocation ; Finish[i] = true; goto step 2
4. If Finish[i] = false for some i, system is in deadlock

Note: this requires m x n^2 steps

This is the difference from the Banker’s algorithm.
Recovery from deadlock

- Must free up resources by some means
- Process termination
  - kill all deadlocked processes
  - select one process and kill it
    - must re-run deadlock detection algorithm again to see if it is freed.
- Resource Preemption
  - select a process, resource and de-allocate it
  - rollback the process
    - needs to be reset the process to a safe state
    - this requires additional state
  - starvation
    - what prevents a process from never finishing?