### Seismic Code

- Given echo data, compute under sea map
- Computation model
  - designed for a collection of workstations
  - uses variation of RPC model
  - workers are given an independent trace to compute
    - requires little communication
    - supports load balancing (1,000 traces is typical)

#### • Performance

- max mfops =  $O((F * nz * B^*)^{1/2})$
- F single processor MFLOPS
- nz linear dimension of input array
- B<sup>\*</sup> effective communication bandwidth
  - $B^* = B/(1 + BL/w) \approx B/7$  for Ethernet (10msec lat., w=1400)
- real limit to performance was latency not bandwidth

# **Database Applications**

- Too much data to fit in memory (or sometimes disk)
  - data mining applications
  - imaging applications
    - use a fork lift to load tapes by the pallet
- Sources of parallelism
  - within a large transaction
  - among multiple transactions
- Join operation
  - form a single table from two tables based on a common field
  - try to split join attribute in disjoint buckets
    - if know data distribution is uniform its easy
    - if not, try hashing

# Parallel Search (TSP)

- may appear to be faster than 1/n
  - but this is not really the case either

#### • Algorithm

- compute a path on a processor
  - if our path is shorter than the shortest one, send it to the others.
  - stop searching a path when it is longer than the shortest.
- before computing next path, check for word of a new min path
- stop when all paths have been explored.
- Why it appears to be faster than 1/n speedup
  - we found the a path that was shorter sooner
  - however, the reason for this is a different search order!

### Ensuring a fair speedup

#### • T<sub>serial</sub> = faster of

- best known serial algorithm
- simulation of parallel computation
  - use parallel algorithm
  - run all processes on one processor
- parallel algorithm run on one processor
- If it appears to be super-linear
  - check for memory hierarchy
    - increased cache or real memory may be reason
  - verify order operations is the same in parallel and serial cases

#### Quantitative Speedup Consider master-worker one master and n worker processes communication time increases as a linear function of n $T_{p} = TCOMP_{p} + TCOMM_{p}$ $TCOMP_{p} = T_{s}/P$ $1/S_{p} = T_{p}/T_{s} = 1/P + TCOMM_{p}/T_{s}$ $TCOMM_{p}$ is P \* $TCOMM_{1}$ $1/S_{p}=1/p + p * TCOMM_{1}/T_{s} = 1/P + P/r_{1}$ where $r_1 = T_s / TCOMM_1$ $d(1/S_p)/dP = 0 \rightarrow P_{opt} = r_1^{1/2} \text{ and } S_{opt}^{-1/2} = 0.5 r_1^{1/2}$ • For hierarchy of masters - TCOMM<sub>D</sub> = (1+logP)TCOMM<sub>1</sub> $- P_{opt} = r_1 \text{ and } S_{opt} = r_1 / (1 + \log r_1)$

#### MPI

- Goals:
  - Standardize previous message passing:
    - PVM, P4, NX
  - Support copy free message passing
  - Portable to many platforms
- Features:
  - point-to-point messaging
  - group communications
  - profiling interface: every function has a name shifted version
- Buffering
  - no guarantee that there are buffers
  - possible that send will block until receive is called
- Delivery Order
  - two sends from same process to same dest. will arrive in order
  - no guarantee of fairness between processes on recv.

## **MPI Communicators**

- Provide a named set of processes for communication
- All processes within a communicator can be named
  - numbered from 0...n-1
- Allows libraries to be constructed
  - application creates communicators
  - library uses it
  - prevents problems with posting wildcard receives
    - adds a communicator scope to each receive
- All programs start will MPI\_COMM\_WORLD

### **Non-Blocking Functions**

#### • Two Parts

- post the operation
- wait for results
- Also includes a poll option
  - checks if the operation has finished
- Semantics
  - must not alter buffer while operation is pending

## MPI Misc.

#### • MPI Types

- All messages are typed
  - base types are pre-defined:
    - int, double, real, {,unsigned}{short, char, long}
  - can construct user defined types
    - includes non-contiguous data types
- Processor Topologies
  - Allows construction of Cartesian & arbitrary graphs
  - May allow some systems to run faster
- What's not in MPI-1
  - process creation
  - I/O
  - one sided communication

## **MPI Housekeeping Calls**

- Include <mpi.h> in your program
- If using mpich, ...
- First call MPI\_Init(&argc, &argv)
- MPI\_Comm\_rank(MPI\_COMM\_WORLD, &myrank)
  - Myrank is set to id of this process
- MPI\_Wtime
  - Returns wall time
- At the end, call MPI\_Finalize()

# **MPI Communication Calls**

#### • Parameters

- var a variable
- num number of elements in the variable to use
- type {MPI\_INT, MPI\_REAL, MPI\_BYTE}
- root rank of processor at root of collective operation
- dest rank of destination processor
- status variable of type MPI\_Status;
- Calls (all return a code check for MPI\_Success)
  - MPI\_Send(var, num, type, dest, tag, MPI\_COMM\_WORLD)
  - MPI\_Recv(var, num, type, dest, MPI\_ANY\_TAG, MPI\_COMM\_WORLD, &status)
  - MPI\_Bcast(var, num, type, root, MPI\_COMM\_WORLD)
  - MPI\_Barrier(MPI\_COMM\_WORLD)

CMSC 714 – F10 (lect 3)